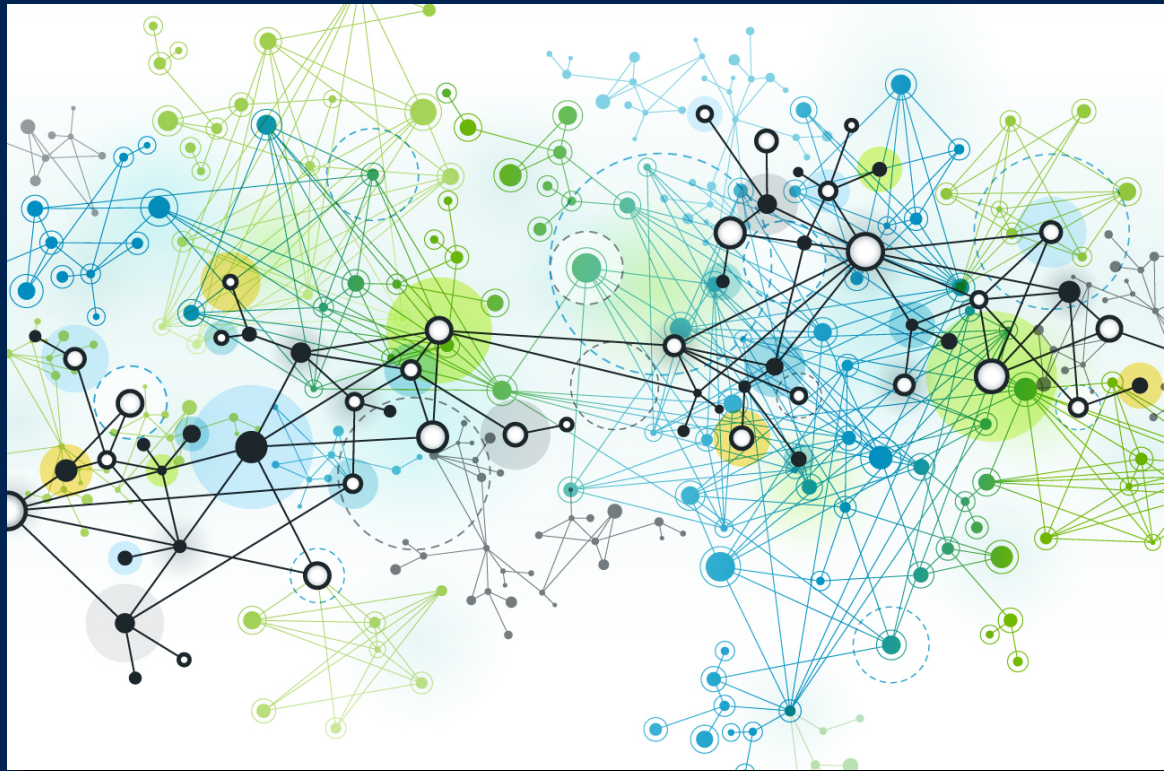


The Maximum Caliber Principle

for modeling stochastic dynamic processes



Goal: A statmech for dynamics

Input a model, predict force-flow distributions.

All Flows: Of molecules, energy, fluids, electrical currents.
In trafficking networks in biochemistry, brains & ecology.

To derive “laws”: Ohm’s law (electrical), Fick’s Law (particles),
Fourier’s Law (heat), Newtonian Fluids (momentum).

General applicability: Systems that are nonlinear; have large
fluctuations; are Far From Equilibrium; are not thermal (like traffic).

First, *Equilibrium* statmech

MAXENT: Maximize the entropy, constrained by $\langle E \rangle$

ϵ_i , model

$$\langle E \rangle = \sum p_i \epsilon_i \quad (1)$$

$$S/k = - \sum p_i \ln p_i \quad (2)$$

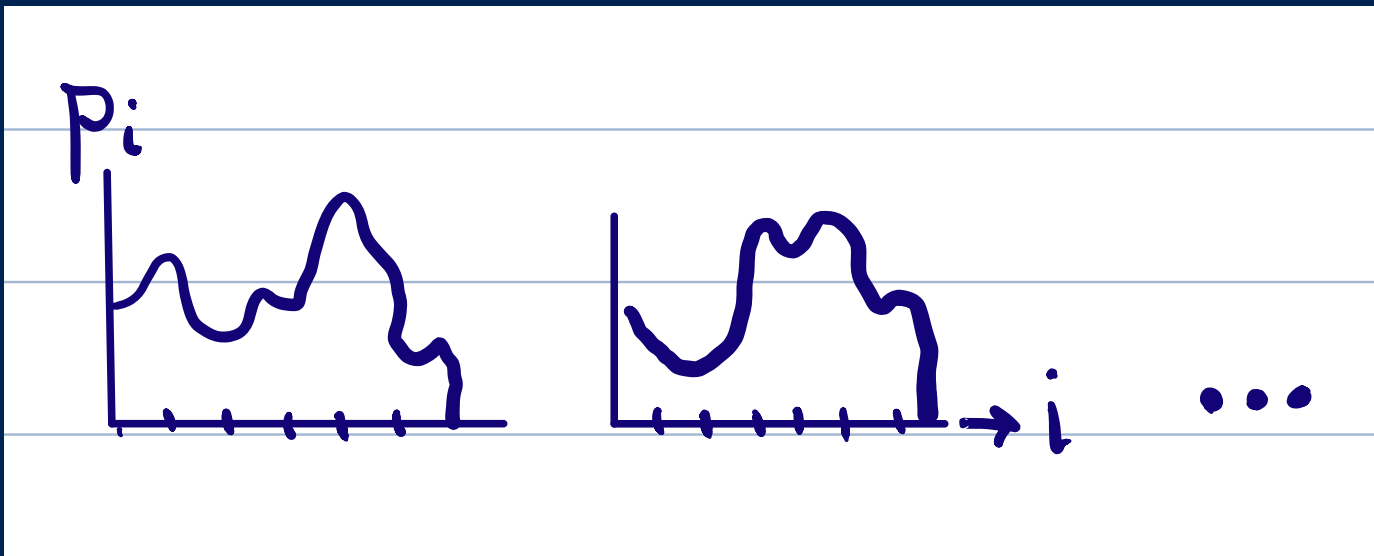
$$F = U - TS, \quad dF = 0 \quad (3)$$

$$q = \sum e^{-\epsilon_i/kT} \quad (4)$$

$$p_i = e^{-\epsilon_i/kT} / q \quad (5)$$

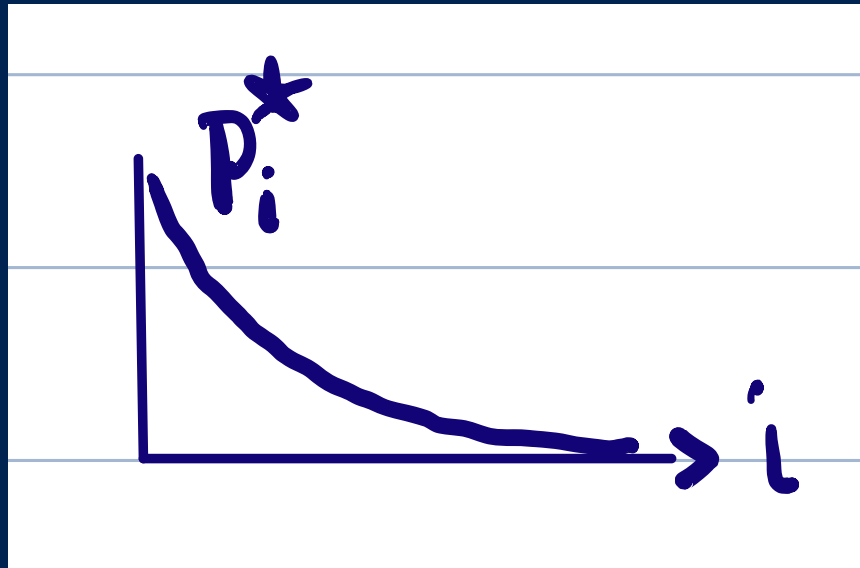
1) The math entropy

$$S_{\text{math}}\{p_i\} = - \sum_i p_i \ln p_i \quad \text{For any } \{p_i\}.$$



2) The MaxEnt entropy

$$S_{\text{maxent}}^* \{p_i^*\} = - \sum_i p_i^* \ln p_i^* \quad \text{For one } \{p_i^*\}.$$

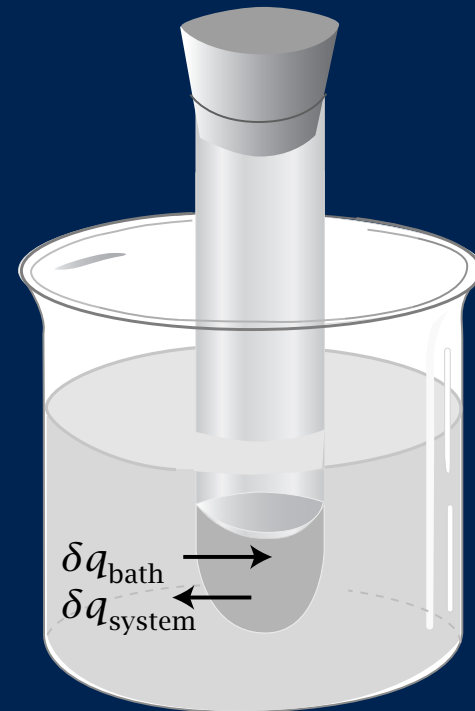


SHORE & JOHNSON 1980. Only this* entropy is useful for prediction & inference.

3) The 2nd Law entropy

$$\Delta S_{2^{\text{nd}} \text{ Law}} = \frac{\delta q_{\text{rev}}}{T}$$

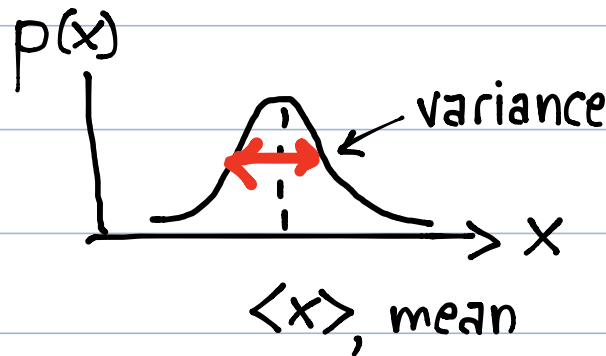
- Clausius 1854.
- It's measurable.
- Predicts equilibrium.
- Requires reversibility.
- It links energy to entropy.



The foundations of EQ statmech

Material properties come from microscopic distributions.

Beyond just averages. Sometimes, distributions matter.



- Kinetic theory of gases $\langle v^2 \rangle = 3kT/m$
- Heat capacities $C_V = \langle \Delta E^2 \rangle / kT^2$
- Random flights $\langle x^2 \rangle = 6Dt$

The brilliant insight of EQ Statmech:

$$\Delta S_{\text{maxent}}^* \{p_i\} = \Delta S_{2^{\text{nd}} \text{ Law}} \quad !!!$$

BUT:

The LHS requires $\Delta S_{\text{maxent}}^*$

And, The RHS requires EQUILIBRIUM.

Problems with traditional NET

It is not a general method for model-making.

- Limited to near-equilibrium slow systems.
- Limited to linear force-flow processes.
- Doesn't treat single- or few-agent systems.
- Doesn't derive Phenomenological Laws.

Problem (1): *Entropy Production* has no meaning

- $S(t)$, $\frac{dS}{dt}$, $S(t) = - \sum p(t) \ln p(t)$.
- dS/dt gives incorrect Kirchoff current law.

... except near equilibrium, where:

- $S(t) \rightarrow S^*$
- $p_i(t) \rightarrow p_i^* \rightarrow p_{\text{Boltzmann}}$
- $S \rightarrow S(U, V, N) \implies$ small gradients.
- No gradients \implies no Phenomenological Laws

Problem (2): Flows are linear functions of forces

$$\text{Dissipation} = \sum (F \times J) \approx J^2.$$

- Ohm's Law: Power = RI^2
- Viscous fluids: Dissipation \sim (velocity)²

BUT THIS PRECLUDES:

*Non-newtonian fluids, diodes, transistors,
feedback and delays,
Michaelis-Menten & Hill kinetics, ...*

Problem (3) Modeling noise

You can't just append random noise to a model.

Langevin models don't work for nonlinear systems.

$$\left. \begin{aligned} m \frac{dv}{dt} + \xi v &= \\ \frac{dA}{dt} + f(A) &= \end{aligned} \right\} \text{Random noise term}$$

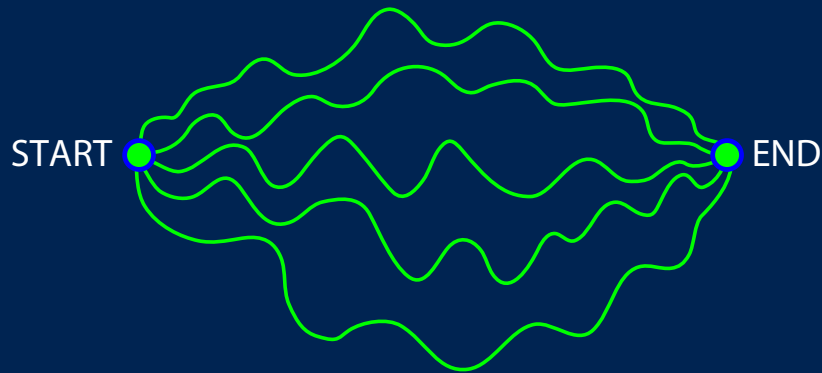
A Langevin diode will rectify its own fluctuations!

(van Kampen, 1981)

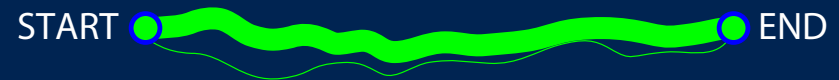
(4) MaxCal is about path entropies

not state entropies: $S_{\text{path}}^* \{p_i^*\} = - \sum_i p_i^* \ln p_i^* .$

HIGH path entropy



LOW path entropy



Max Cal is Max Ent for pathways

Maximize path entropy, constrained by rates $\langle J \rangle$.

j_i , model fluxes

$$\langle J \rangle = \sum p_i j_i \quad (1)$$

$$S = - \sum p_i \ln p_i \quad (2)$$

$$\mathcal{C} = S - \lambda \langle J \rangle, \quad d\mathcal{C} = 0 \quad (3)$$

$$q = \sum e^{-\lambda j_i} \quad (4)$$

$$p_i = e^{-\lambda j_i} / q \quad (5)$$

Is Max Cal the NESM Principle?

Some key confirmatory tests:

- **Master equations** (Stock et al, **JCP** `08).
- **Green-Kubo** (Hazoglou et al, **JCP** `15).
- **Onsager reciprocal relations** (``).
- **Prigogine Minimum Entropy Production** (``).
- **Markov models** (Ge et al, **JCP** `12).
- **Kirchoff current law** (Ghosh, **Ann Rev PChem** `20).

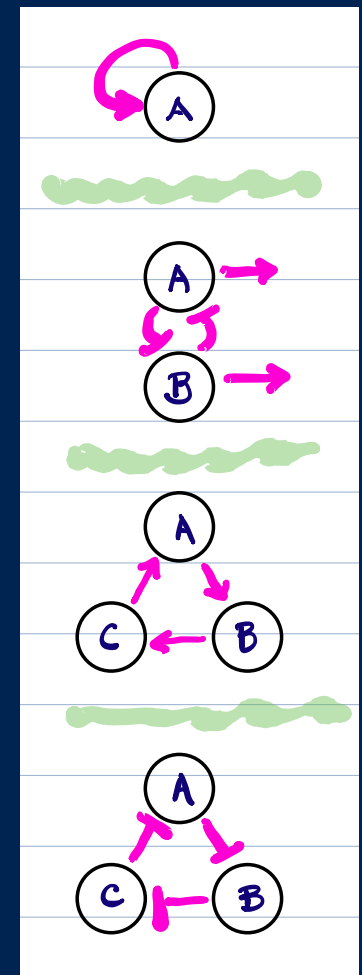
Some Max Cal modeling

- **Fick's Law, FP** (Ghosh, **AJP** `06, **JPCB** `07).
- **Single-particle reactions** (Wu **PRL** `09).
- **3-state molecular motors** (Presse **PRE** `10).
- **Find MD rxn coords** (Tiwary & Berne **PNAS** `16).
- **Dissipation in flows** (Agozzino **PRE** `19).
- **Inferring micro rates from avgs** (Dixit **JCTC** `15).
- **Infer networks from flows** (Weistuch, **PLOSCB** `20).

Dynamical nonlinearities & fluctuations

Max Cal predicts the noise from the model.

- **Positive feedback** (Ghosh **BJ** `17, **JPCB** `18).
- **Toggle switch** (Presse **JPCB** `11, **Ann Rev PC** `20).
- **Molecular motors** (Presse **PRE** `10).
- **Repressilator (oscillator, clock)** (Ghosh **JPCB** `19).



Maximum Caliber:

*A general inference principle
for dynamics and routes on pathways &
networks.*

Thanks to:

Rob Phillips

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NSF

- S Presse ..., *Rev Mod Phys*, 2013
- P Dixit ..., *J Chem Phys*, 2018
- K Ghosh ..., *Ann Rev Phys Chem*, 2020