Math 205B - Topology

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**Exercise 58.3.** (Pointed version.) Show that given a collection C of pointed spaces, the relation of homotopy equivalence is an equivalence relation on C.

*Proof.* Recall that two pointed spaces  $(X, x_0)$  and  $(Y, y_0)$  are homotopy equivalent if there exist maps  $f: (X, x_0) \to Y$  and  $g: (Y, y_0) \to (X, x_0)$  where  $f \circ g \simeq 1_Y$  and  $g \circ f \simeq 1_X$ . Here the relation ' $\simeq$ ' is the appropriate concept of 'homotopic' for pointed maps: that is,  $h \simeq h'$  if that there exists a *pointed* homotopy from h to h'. We need to check that homotopy equivalence is reflexive, symmetric, and transitive.

- Reflexive for all  $X \in \mathcal{C}$ ,  $1_X \colon (X, x_0) \to (X, x_0)$  gives us that  $1_X \circ 1_X = 1_X$ , so X is homotopy equivalent to X.
- Symmetric Let  $X, Y \in \mathcal{C}$ . If X is homotopy equivalent to Y, then by definition of homotopy equivalence, Y is homotopy equivalent to X. This is because the definition is symmetrical.
- Transitive Let  $X, Y, Z \in \mathcal{C}$  where X is homotopy equivalent to Y, and Y is homotopy equivalent to Z. This implies there exist  $f: X \to Y$  and  $g: Y \to X$ with  $f \circ g \simeq 1_Y$  and  $g \circ f \simeq 1_X$ . Also, there exist  $h: Y \to Z$  and  $k: Z \to Y$  with  $h \circ k \simeq 1_Z$  and  $k \circ h \simeq 1_Y$ . Now consider  $h \circ f: X \to Z$  and  $g \circ k: Z \to X$ . For each step, we use the fact that composition preserves the relation  $\simeq$ . First

$$\begin{array}{ll} h \circ f \circ g \circ k & \simeq h \circ 1_Y \circ k \\ & \simeq h \circ k \\ & \simeq 1_Z \end{array}$$

Similarly we have the other direction.

$$\begin{array}{rcl} g \circ k \circ h \circ f &\simeq g \circ 1_Y \circ f \\ &\simeq g \circ f \\ &1_X \end{array}$$

Thus X is homotopy equivalent to Z.

Therefore homotopy equivalence is an equivalence relation.

**Exercise 58.6.** Show that a retract of a contractible space is contractible

*Proof.* Let A be a retract of X, and let X be contractible. This means  $1_X$  is homotopic to a constant map, say  $f(x) = x_0$ . Let  $H: X \times I \to X$  be the homotopy from  $1_X$  to f with H(x,0) = x and  $H(x,1) = f(x) = x_0$ . If  $r: X \to A$  is the retraction of X to A, then we can consider the homotopy  $r \circ H|_A: A \times I \to A$ . This is continuous since it is the composition of continuous maps. Also  $r \circ H|_A(x,0) = r(x) = x$ , since  $x \in A$ , and  $r \circ H|_A(x,1) = r(f(x)) = r(x_0)$ . This gives us that  $1_A$  is homotopic to the constant map  $g(x) = r(x_0)$ , and so A is contractible.

**Exercise 59.3.** (a) Show that  $\mathbb{R}^1$  and  $\mathbb{R}^n$  are not homeomorphic if n > 1.

(b) Show that  $\mathbb{R}^2$  and  $\mathbb{R}^n$  are not homeomorphic if n > 2.

Proof.

- (a) We will assume that exist a map  $h: \mathbb{R}^1 \to \mathbb{R}^n$  that is a homeomorphism. We will then consider what happens If we remove 0 in  $\mathbb{R}^1$  and its image h(0) from  $\mathbb{R}^n$ .  $\mathbb{R}^1 0$  is a disconnected space, but  $\mathbb{R}^n h(0)$  is connected. Removal of a point and its image always preserves homeomorphism, thus  $\mathbb{R}^1 0$  and  $\mathbb{R}^n h(0)$  are homeomorphic. But connectedness is invariant under homeomorphism, so we have a contradiction.
- (b) We will use a similar technique for this part. Assume that there exist a map  $h: \mathbb{R}^2 \to \mathbb{R}^n$  that is a homeomorphism. We will again remove the origin from  $\mathbb{R}^2$  and the image h(0,0) from  $\mathbb{R}^n$ . Removal of a point and its image always preserves homeomorphism, thus  $\mathbb{R}^1 (0,0)$  and  $\mathbb{R}^n \{h(0,0)\}$  are homeomorphic. We now have that  $\mathbb{R}^2 \{(0,0)\}$  is homeomorphic to  $S^1$ , and  $\mathbb{R}^n \{h(0,0)\}$  is homeomorphic to  $S^{n-1}$ .  $S^1$  is not simply connected, however  $S^{n-1}$  is simply connected for n > 2. Thus since simply connectedness is invariant under homeomorphism, then  $\mathbb{R}^1 (0,0)$  and  $\mathbb{R}^n \{h(0,0)\}$  are not homeomorphic, a contradiction.