

# **2-Vector Spaces and Groupoids**

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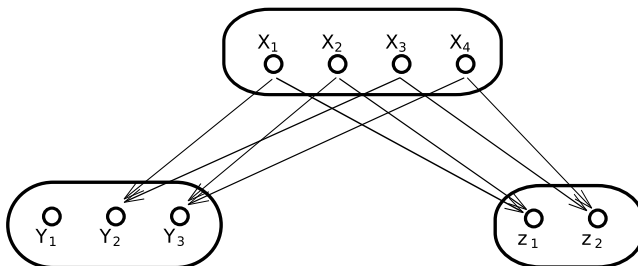
## Goal

We'll describe a (weak) 2-functor

$$\Lambda : \text{Span}(\mathbf{Gpd}) \rightarrow \mathbf{2Vect}$$

where  $\text{Span}(\mathbf{Gpd})$  is a 2-category of *spans of groupoids* and  $\mathbf{2Vect}$  is the 2-category of *Kapranov-Voevodsky 2-vector spaces*:

This is analogous to the operation of *degroupoidification*, which in turn generalizes the obvious way to get vector spaces and linear maps from spans of sets:

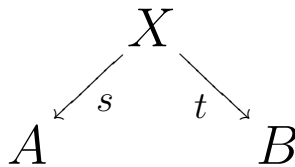


by “pulling and pushing” complex functions through the span. (This construction is ubiquitous!)

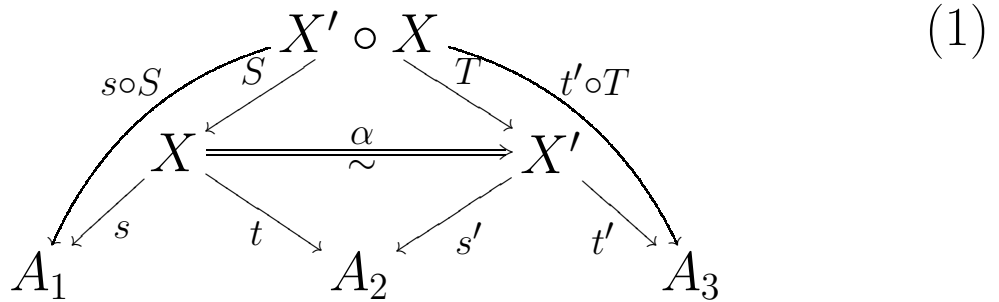
## Span(Gpd)

This bicategory has:

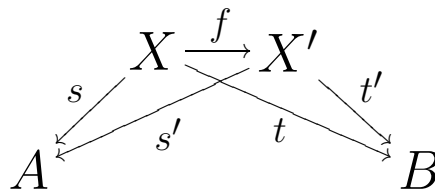
- **Objects** - Groupoids
- **Morphisms** - Spans:



with composition defined by weak pullback:



- **2-Morphisms:** Isomorphism classes of *spans of span maps*. A *span map*  $f$  between two spans consists of a compatible map of the central objects:



This bicategory has monoidal structure, and duals for morphisms and 2-morphisms.

## 2-Vector Spaces

The 2-category **2Vect** has:

- *objects*: 2-vector spaces
- *morphisms*: 2-linear maps
- *2-morphisms*: natural transformations

**Definition:** A **Kapranov–Voevodsky 2-vector space** is a  $\mathbb{C}$ -linear finitely semisimple additive category (one generated by simple objects  $x$ , where  $\text{hom}(x, x) \cong \mathbb{C}$ ). A **2-linear map** between 2-vector spaces is a  $\mathbb{C}$ -linear additive functor.

**Theorem:** Any 2-vector spaces is equivalent to **Vect<sup>k</sup>** (objects  $k$ -tuples of vector spaces, morphisms  $k$ -tuples of linear maps) for some  $k$ .

Any 2-linear map  $T : \mathbf{Vect}^n \rightarrow \mathbf{Vect}^m$  is naturally isomorphic to a map of the form

$$\begin{pmatrix} V_{1,1} & \cdots & V_{1,k} \\ \vdots & & \vdots \\ V_{l,1} & \cdots & V_{l,k} \end{pmatrix} \begin{pmatrix} W_1 \\ \vdots \\ W_k \end{pmatrix} = \begin{pmatrix} \bigoplus_{i=1}^k V_{1,i} \otimes W_i \\ \vdots \\ \bigoplus_{i=1}^k V_{l,i} \otimes W_i \end{pmatrix}$$

Any natural transformation can be written as a matrix of linear maps between the components.

## Example

Given a finite group  $G$ , the category  $\mathbf{Rep}(G)$  has:

- **Objects:** Representations of  $G$
- **Morphisms:** Intertwining operators between reps

**Theorem:** For any finite group  $G$ ,  $\mathbf{Rep}(G)$  is a 2-vector space

Any representation is a direct sum of irreducible reps - these form a *basis* for the 2-vector space.

By *Schur's Lemma*, if  $V_j$  is irreducible,

$$\mathrm{hom}(V_j, V_j) \cong \mathbb{C} \cdot 1$$

so these are indeed simple objects

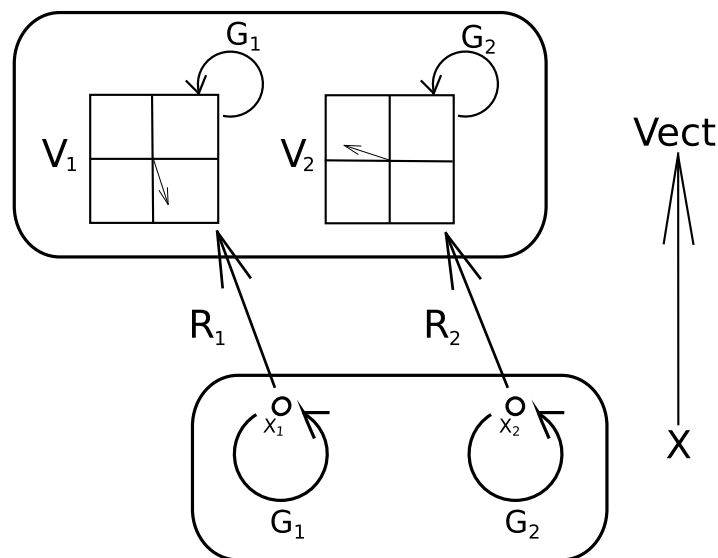
We can make a similar construction for groupoids as for groups. Taking a group  $G$  as a one-object groupoid:

$$\mathbf{Rep}(G) \cong [G, \mathbf{Vect}]$$

where we use the notation  $[X, \mathbf{Vect}] = \mathrm{hom}(X, \mathbf{Vect})$ .

**Lemma 1** *If  $\mathbf{X}$  is an essentially finite groupoid, the functor category  $\Lambda(\mathbf{X}) = [\mathbf{X}, \mathbf{Vect}]$  is a KV 2-vector space.*

Here is an illustration of a  $\mathbf{Vect}$ -valued functor on  $\mathbf{X}$ :



Note: If the automorphism groups of (isomorphism classes of) objects of  $\mathbf{X}$  are  $G_1, \dots, G_n$ , then we have

$$[X, \mathbf{Vect}] \cong \prod_j \mathbf{Rep}(G_j)$$

So the “basis elements” (simple objects) in  $[X, \mathbf{Vect}]$  are labeled by  $([x], V)$ , where  $[x]$  is an isomorphism class of objects of  $\mathbf{X}$  and  $V$  an irreducible rep of  $\mathbf{Aut}(x)$ .

**Theorem:** If  $\mathbf{X}$  and  $\mathbf{Y}$  are essentially finite groupoids, a functor  $f : \mathbf{X} \rightarrow \mathbf{Y}$  gives two 2-linear maps between the 2-vector spaces of **Vect**-presheaves:

$$f^* : \Lambda(\mathbf{Y}) \rightarrow \Lambda(\mathbf{X})$$

namely pullback along  $f$ , with  $f^*F = F \circ f$  and

$$f_* : \Lambda(\mathbf{X}) \rightarrow \Lambda(\mathbf{Y})$$

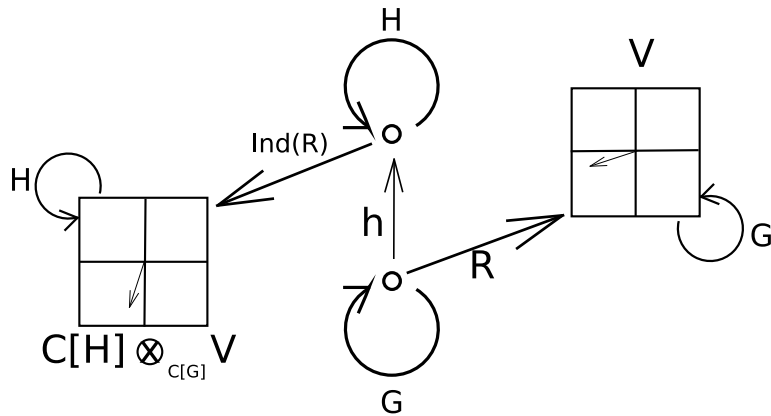
called “pushforward along  $f$ ”. Furthermore,  $f_*$  is the two-sided (and *2-linear*) adjoint to  $f^*$ .

The adjoint map

$$f_* : [X, \mathbf{Vect}] \rightarrow [Y, \mathbf{Vect}]$$

gives the *induced representation*.

Given a group homomorphism  $h : G \rightarrow H$ , and a representation  $R : G \rightarrow GL(V)$ , there is an induced representation of  $H$ , namely  $\mathbb{C}[H] \otimes_{\mathbb{C}[G]} V$ :



For a map of groupoids  $t : X \rightarrow B$ , we can push forward a **Vect**-presheaf in the same way. If more than one object is sent to the same  $b \in B$ , we get a direct sum of all their contributions. Assuming all groupoids are skeletal, this is:

$$t_*(F)(b) = \bigoplus_{t(x)=b} \mathbb{C}[Aut(b)] \otimes_{\mathbb{C}[Aut(x)]} F(x)$$

This is a direct sum over the (essential) preimage of  $b \in B$ .



## V: 2-Linear Maps for Spans

Given a span of groupoids:

$$\begin{array}{ccc}
 & X & \\
 s \swarrow & & \searrow t \\
 A & & B
 \end{array}$$

we can apply the functor  $[-, \mathbf{Vect}]$  to the whole diagram. This functor is contravariant, so we get a cospan:

$$\begin{array}{ccc}
 & [X, \mathbf{Vect}] & \\
 s^* \swarrow & & \searrow t^* \\
 \Lambda(A) & & \Lambda(B)
 \end{array}$$

Then we use these to define a 2-linear map corresponding to a span:

**Definition:** For a span of groupoids  $X : A \rightarrow B$  in  $\mathbf{Span}(\mathbf{Gpd})$  define the 2-linear map:

$$\Lambda(X) = t_* \circ s^* : \Lambda(A) \longrightarrow \Lambda(B)$$

So then:

$$\Lambda(X)(F)(b) = \bigoplus_{t(x)=b} \mathbb{C}[Aut(b)] \otimes_{\mathbb{C}[Aut(x)]} (F \circ s)(x)$$

Picking basis elements  $([a], V) \in \Lambda(A)$ , and  $([b], W) \in \Lambda(B)$ , and using that

$$\mathbb{C}[G] \cong \bigoplus_i V_i \otimes V_i^*$$

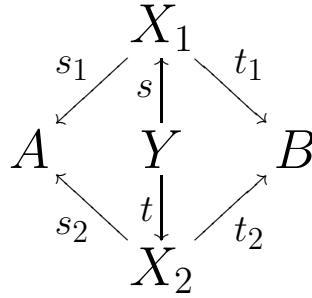
where the sum is over irreps of  $G$ , Schur's lemma means that

$$\begin{aligned} \Lambda(X)_{([a],V),([b],W)} &= \text{hom}_{Rep(Aut(b))}[t_* \circ s^*(V), W] \\ &\simeq \bigoplus_{[x] \in \underline{(s,t)^{-1}([a],[b])}} \text{hom}_{Rep(Aut(x))}[s^*(V), t^*(W)] \end{aligned}$$

by adjointness (a.k.a. Frobenius reciprocity).

## V: 2-Morphisms

Given a span between spans,  $Y : X_1 \rightarrow X_2$  for  $X_1, X_2 : A \rightarrow B$ :



we want a natural transformation

$$\Lambda(Y) : \Lambda(X_1) \rightarrow \Lambda(X_2)$$

We saw that  $\Lambda(Y)$  is given as a matrix of linear operators between corresponding entries of  $\Lambda(X_1)$  and  $\Lambda(X_2)$ :

$$\Lambda(Y)_{[[a],V),([b],W)]} : \Lambda(X_1)_{[[a],V),([b],W)]} \rightarrow \Lambda(X_2)_{[[a],V),([b],W)]}$$

This amounts to:

$$\begin{aligned} \Lambda(Y)_{[[a],V),([b],W)} &: \bigoplus_{[x_1]} \text{hom}_{\text{Rep}(\text{Aut}(x))} [s_1^*(V), t_2^*(W)] \\ &\rightarrow \bigoplus_{[x_2]} \text{hom}_{\text{Rep}(\text{Aut}(x_2))} [s_2^*(V), t_2^*(W)] \end{aligned}$$

such that for each block  $([x_1], [x_2])$ , the corresponding linear operator behaves as follows: for any intertwiner  $f \in \text{hom}[s_1^*(V), t_1^*(W)]$  we get:

$$\Lambda(Y)_{[[a],V),([b],W)}|_{([x_1],[x_2])} = \frac{|\widehat{(x_1, x_2)}|}{|\text{Aut}(x_2)|} \sum_{g \in \text{Aut}(x_2)} g f g_1$$

where we are using the Baez-Dolan groupoid cardinality of  $\widehat{(x_1, x_2)}$ , the essential preimage of  $(x_1, x_2)$  under  $(s, t)$ .

Given all this, the main fact is:

**Theorem:** The process  $\Lambda : \text{Span}(\mathbf{Gpd}) \rightarrow \mathbf{2Vect}$  is a weak 2-functor.

## Extension to Smooth Groupoids

What is different for smooth groupoids? First, the 2-vector space is generally infinite dimensional. There are different possible approaches to defining infinite-dimensional 2-vector spaces. One would involve:

**Definition:** If  $(X, \mu)$  is a measurable space  $\mathbf{Meas}(\mathbf{X})$  is the category with:

- Objects: *measurable fields of Hilbert spaces* on  $(X, \mathcal{M})$ : i.e.  $X$ -indexed families of Hilbert spaces  $\mathcal{H}_x$  with a Hilbert space of *measurable sections*
- Morphisms: *measurable fields of bounded linear maps* between Hilbert spaces,  $f_x : \mathcal{H}_x \rightarrow \mathcal{K}_x$  so that  $\|f\|$  (the operator norm of  $f$ ) is measurable.

Then  $\mathbf{Meas}$  is the 2-category of all categories  $\mathbf{Meas}(\mathbf{X})$ , and we could look for a 2-functor

$$\Lambda : \text{Span}(\mathbf{Gpd}) \rightarrow \mathbf{Meas}$$

(Another variant would involve defining a 2-category of *2-Hilbert spaces* - which are built on measure spaces, rather than measurable spaces - using a measure  $\mu$  to define an inner product as with ordinary  $L^2(X)$ . *Work in progress.*)

What changes are needed in the infinite dimensional case?

The category of measurable functors  $\mathcal{H} : \mathcal{G} \rightarrow \mathbf{Meas}$  amounts to a category of *equivariant* measurable fields of Hilbert spaces on the objects (so each  $\mathcal{H}_x$  carries a representation of  $\text{Aut}(x)$ ).

• For a span  $\mathcal{S} : \mathcal{G} \rightarrow \mathcal{G}'$ , there will be a 2-linear map given by a *direct integral*:

$$(\Lambda(\mathcal{S})(\mathcal{H}))_y = \int^{\oplus} \mathcal{H}_x \mathcal{S}_{([x],V),([y],W)} d\mu$$

Where the  $\mathcal{S}_{([x],V),([y],W)}$  are defined similarly to the above.

Generally:

- Finite product of  $\text{Rep}(\text{Aut}(x_i)) \mapsto \mathbf{Meas}_{\mathcal{G}}(\mathcal{G}^{(0)})$
- Direct sum  $\mapsto$  direct integral
- Counting measure  $\mapsto$  measure on object space
- Groupoid cardinality  $\mapsto$  volume of groupoid (requires measure and Haar system)

The algebraic part of the construction is the same...  
(We leave the rest as an exercise to the speaker.)