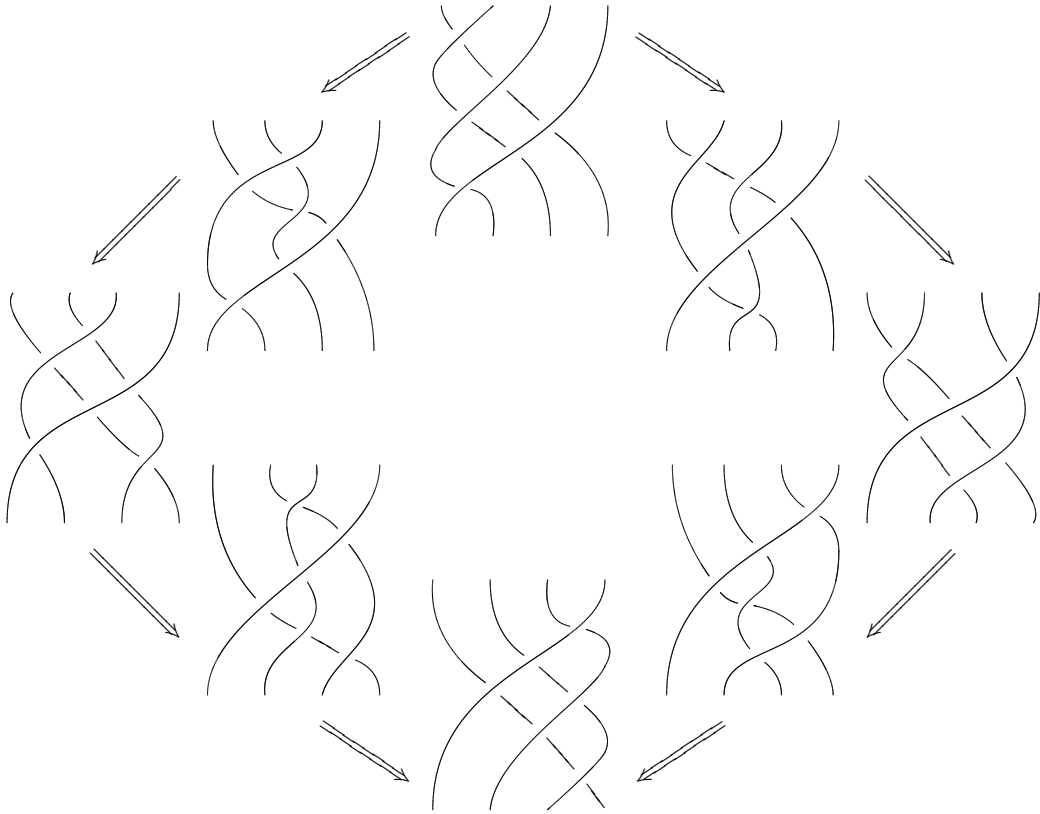


# Higher Linear Algebra

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*Higher Dimensional Algebra VI: Lie 2-algebras*  
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# Categorified vector spaces

- Kapranov and Voevodsky defined a finite-dimensional 2-vector space to be a category of the form  $\text{Vect}^n$ .
- Instead, we define a **2-vector space** to be a category in  $\text{Vect}$ .

We have a 2-category,  $2\text{Vect}$  whose:

- objects are 2-vector spaces,
  - 1-morphisms are linear functors between these,
  - 2-morphisms are linear natural transformations between these
- 
- Proposition:  $2\text{Vect} \simeq 2\text{Term}$

A **2-vector space**,  $V$ , consists of:

- a **vector space**  $V_0$  of objects,
- a **vector space**  $V_1$  of morphisms,

together with:

- **linear** source and target maps

$$s, t: V_1 \rightarrow V_0,$$

- a **linear** identity-assigning map

$$i: V_0 \rightarrow V_1,$$

- a **linear** composition map

$$\circ: V_1 \times_{V_0} V_1 \rightarrow V_1$$

such that the following diagrams commute, expressing the usual category laws:

- laws specifying the source and target of identity morphisms:

$$\begin{array}{ccc}
 V_0 & \xrightarrow{i} & V_1 \\
 & \searrow & \downarrow s \\
 & 1_{V_0} & V_0
 \end{array}
 \qquad
 \begin{array}{ccc}
 V_0 & \xrightarrow{i} & V_1 \\
 & \searrow & \downarrow t \\
 & 1_{V_0} & V_0
 \end{array}$$

- laws specifying the source and target of composite morphisms:

$$\begin{array}{ccc}
 V_1 \times_{V_0} V_1 & \xrightarrow{\circ} & V_1 \\
 p_1 \downarrow & & \downarrow s \\
 V_1 & \xrightarrow{s} & V_0
 \end{array}
 \qquad
 \begin{array}{ccc}
 V_1 \times_{V_0} V_1 & \xrightarrow{\circ} & V_1 \\
 p_2 \downarrow & & \downarrow t \\
 V_1 & \xrightarrow{t} & V_0
 \end{array}$$

- the associative law for composition of morphisms:

$$\begin{array}{ccc}
 V_1 \times_{V_0} V_1 \times_{V_0} V_1 & \xrightarrow{\circ \times_{V_0} 1} & V_1 \times_{V_0} V_1 \\
 1 \times_{V_0} \circ \downarrow & & \downarrow \circ \\
 V_1 \times_{V_0} V_1 & \xrightarrow{\circ} & V_1
 \end{array}$$

- the left and right unit laws for composition of morphisms:

$$\begin{array}{ccccc}
 V_0 \times_{V_0} V_1 & \xrightarrow{i \times 1} & V_1 \times_{V_0} V_1 & \xleftarrow{1 \times i} & V_1 \times_{V_0} V_0 \\
 & \searrow p_2 & \downarrow \circ & \swarrow p_1 & \\
 & & V_1 & & 
 \end{array}$$

## $n$ -vector spaces

- An  $(n+1)$ -**vector space** is a strict  $n$ -category in  $\mathbf{Vect}$ .

We have a  $n$ -category,  $n\mathbf{Vect}$  whose:

- objects are  $n$ -vector spaces,
- 1-morphisms are strict linear functors between these,
- 2-morphisms are strict linear natural transformations between these, ...

and so on!

- Proposition:  $(n + 1)\mathbf{Vect} \simeq (n + 1)\mathbf{Term}$

- $\bigoplus$ ,  $\bigotimes$  of  $n$ -vector spaces

**Moral:** Homological algebra is secretly categorified linear algebra!

**Questions still remain:**

- What about weak  $n$ -categories in Vect?
- What about weakening laws governing addition and scalar multiplication?

# Categorified Linear Algebra

Associative algebras	$A_\infty$ -algebras
Commutative algebras	$E_\infty$ -algebras
Lie algebras	$L_\infty$ -algebras
Coalgebras	?
Hopf Algebras	?
⋮	⋮

Given a vector space  $V$  and an isomorphism

$$B: V \otimes V \rightarrow V \otimes V,$$

we say  $B$  is a **Yang–Baxter operator** if it satisfies the **Yang–Baxter equation**, which says that:

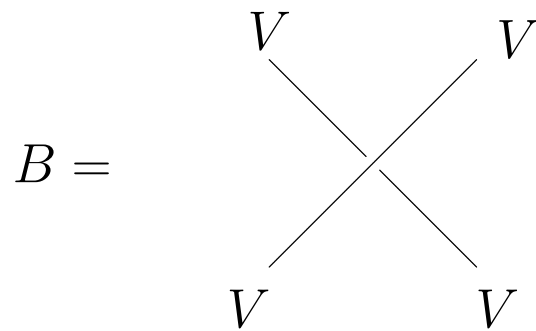
$$(B \otimes 1)(1 \otimes B)(B \otimes 1) = (1 \otimes B)(B \otimes 1)(1 \otimes B),$$

or in other words, that this diagram commutes:

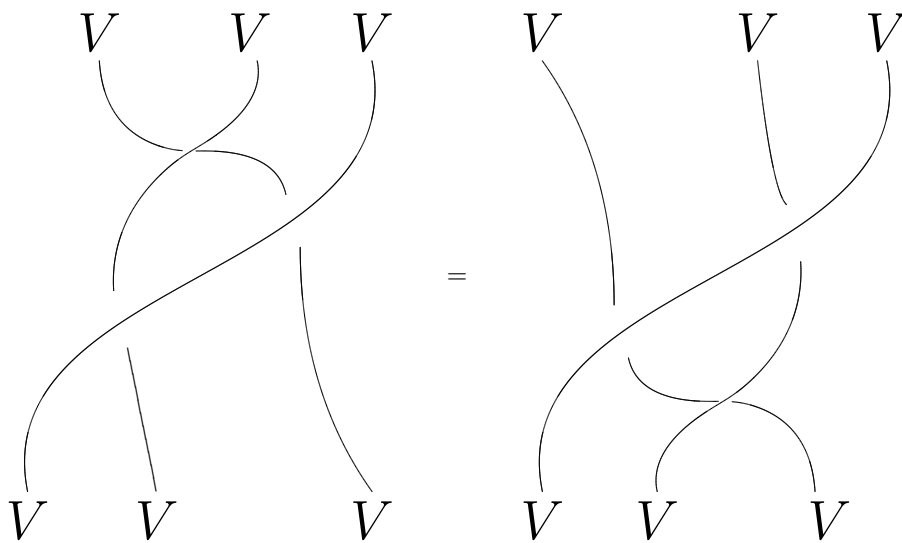
$$\begin{array}{ccccc}
 & & V \otimes V \otimes V & & \\
 & \swarrow^{1 \otimes B} & & \searrow^{B \otimes 1} & \\
 V \otimes V \otimes V & & & & V \otimes V \otimes V \\
 \downarrow^{B \otimes 1} & & & & \downarrow^{1 \otimes B} \\
 V \otimes V \otimes V & & & & V \otimes V \otimes V \\
 & \searrow^{B \otimes 1} & & \swarrow^{B \otimes 1} & \\
 & & V \otimes V \otimes V & & 
 \end{array}$$



If we draw  $B: V \otimes V \rightarrow V \otimes V$  as a braiding:



the Yang–Baxter equation says that:



**Proposition:** Let  $L$  be a vector space over  $k$  equipped with a skew-symmetric bilinear operation

$$[\cdot, \cdot]: L \times L \rightarrow L.$$

Let  $L' = k \oplus L$  and define the isomorphism

$$B: L' \otimes L' \rightarrow L' \otimes L' \text{ by}$$

$$B((a, x) \otimes (b, y)) = (b, y) \otimes (a, x) + (1, 0) \otimes (0, [x, y]).$$

Then  $B$  is a solution of the Yang–Baxter equation if and only if  $[\cdot, \cdot]$  satisfies the Jacobi identity.

## Goal

Develop a higher-dimensional analogue, obtained by categorifying everything in sight!

A **semistrict Lie 2-algebra** consists of:

- a 2-vector space  $L$

equipped with:

- a skew-symmetric bilinear functor, the **bracket**,

$$[\cdot, \cdot]: L \times L \rightarrow L$$

- a completely antisymmetric trilinear natural isomorphism, the **Jacobiator**,

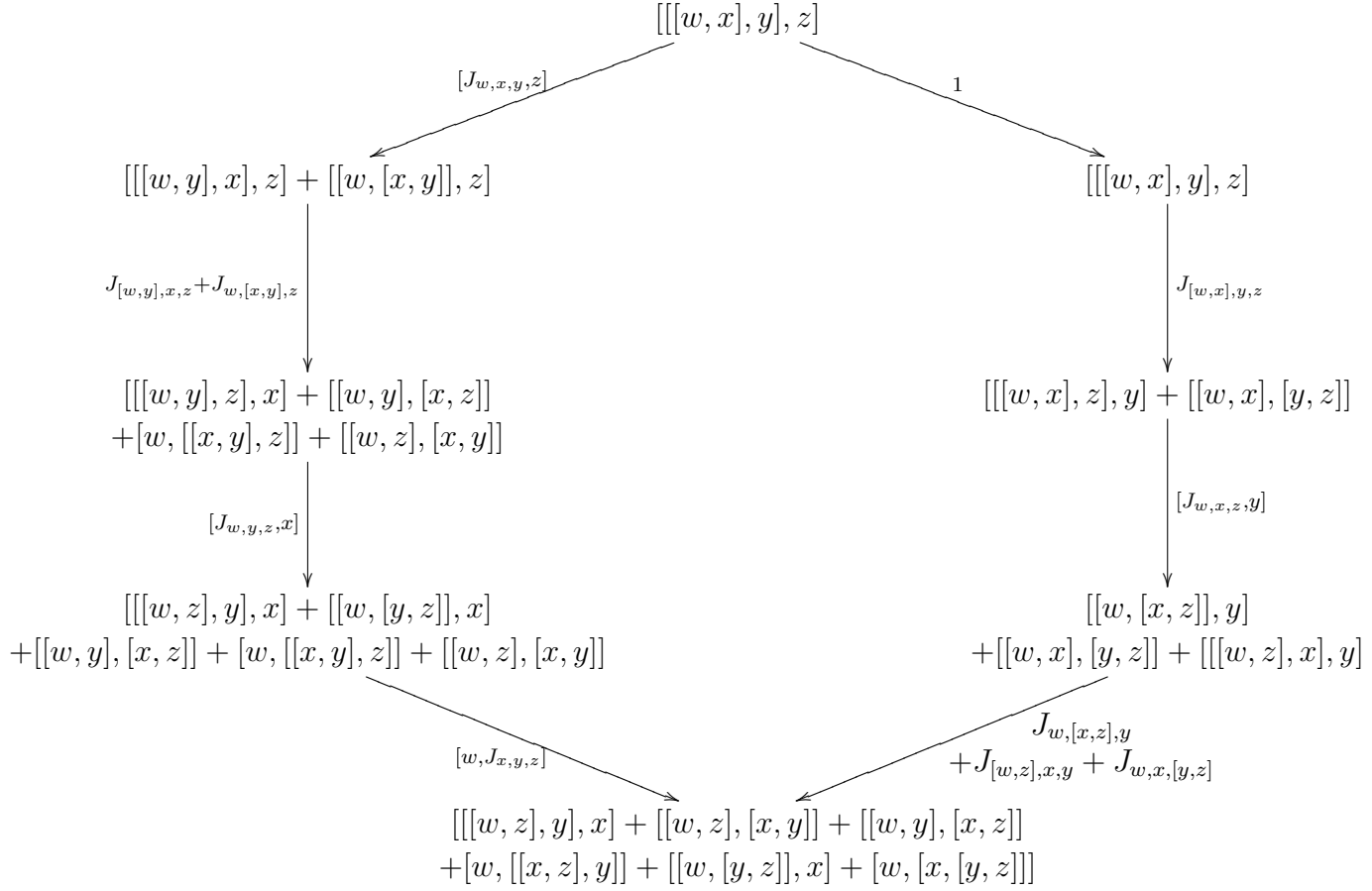
$$J_{x,y,z}: [[x, y], z] \rightarrow [x, [y, z]] + [[x, z], y],$$

that is required to satisfy:

- the **Jacobiator identity**:

$$J_{[w,x],y,z} \circ [J_{w,x,z}, y] \circ (J_{w,[x,z],y} + J_{[w,z],x,y} + J_{w,x,[y,z]}) = \\ [J_{w,x,y}, z] \circ (J_{[w,y],x,z} + J_{w,[x,y],z}) \circ [J_{w,y,z}, x] \circ [w, J_{x,y,z}]$$

for all  $w, x, y, z \in L_0$ .



# Zamolodchikov tetrahedron equation

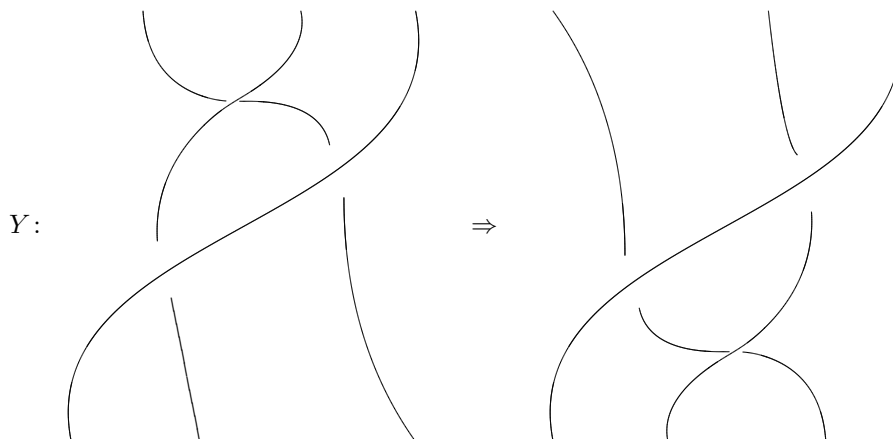
Given a 2-vector space  $V$  and an invertible linear functor  $B: V \otimes V \rightarrow V \otimes V$ , a linear natural isomorphism

$$Y: (B \otimes 1)(1 \otimes B)(B \otimes 1) \Rightarrow (1 \otimes B)(B \otimes 1)(1 \otimes B)$$

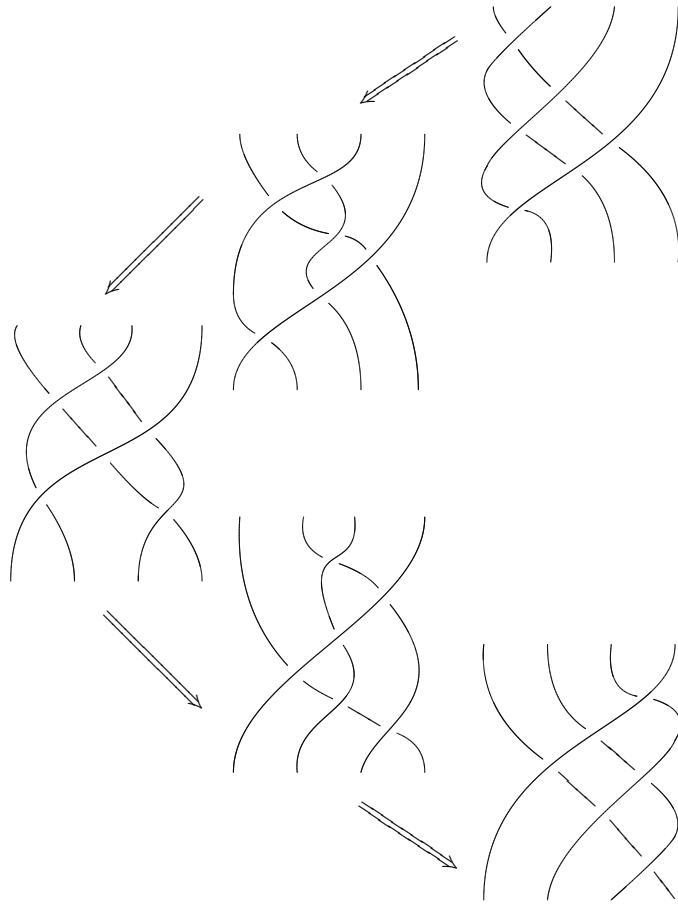
satisfies the **Zamolodchikov tetrahedron equation** if:

$$\begin{aligned} & [Y \circ (1 \otimes 1 \otimes B)(1 \otimes B \otimes 1)(B \otimes 1 \otimes 1)] [(1 \otimes B \otimes 1)(B \otimes 1 \otimes 1) \circ Y \circ (B \otimes 1 \otimes 1)] \\ & [(1 \otimes B \otimes 1)(1 \otimes 1 \otimes B) \circ Y \circ (1 \otimes 1 \otimes B)] [Y \circ (B \otimes 1 \otimes 1)(1 \otimes B \otimes 1)(1 \otimes 1 \otimes B)] \\ & = \\ & [(B \otimes 1 \otimes 1)(1 \otimes B \otimes 1)(1 \otimes 1 \otimes B) \circ Y] [(B \otimes 1 \otimes 1) \circ Y \circ (B \otimes 1 \otimes 1)(1 \otimes B \otimes 1)] \\ & [(1 \otimes 1 \otimes B) \circ Y \circ (1 \otimes 1 \otimes B)(1 \otimes B \otimes 1)] [(1 \otimes 1 \otimes B)(1 \otimes B \otimes 1)(B \otimes 1 \otimes 1) \circ Y] \end{aligned}$$

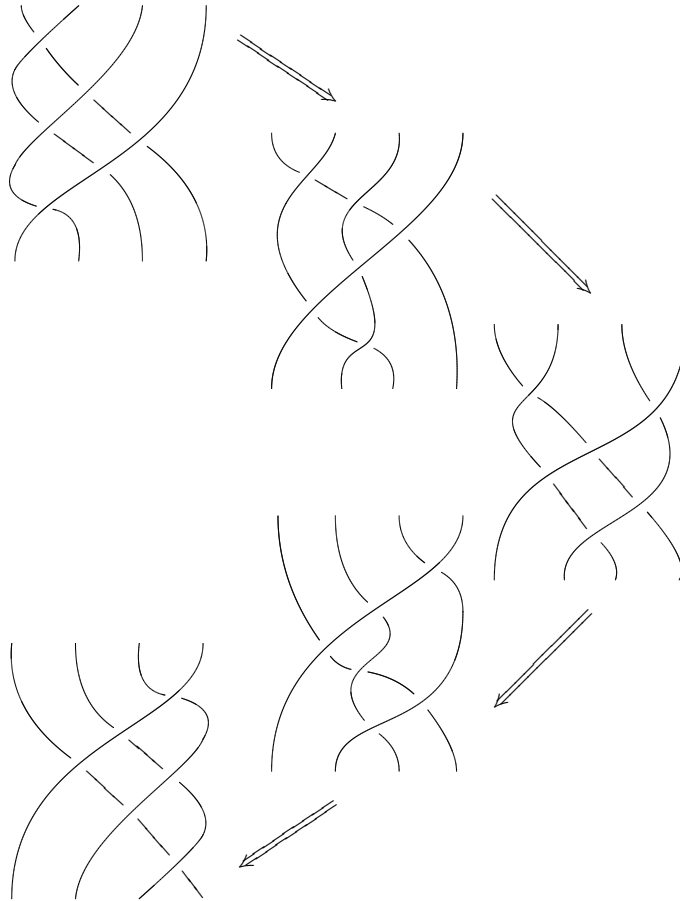
We should think of  $Y$  as the surface in 4-space traced out by the *process of performing* the third Reidemeister move:



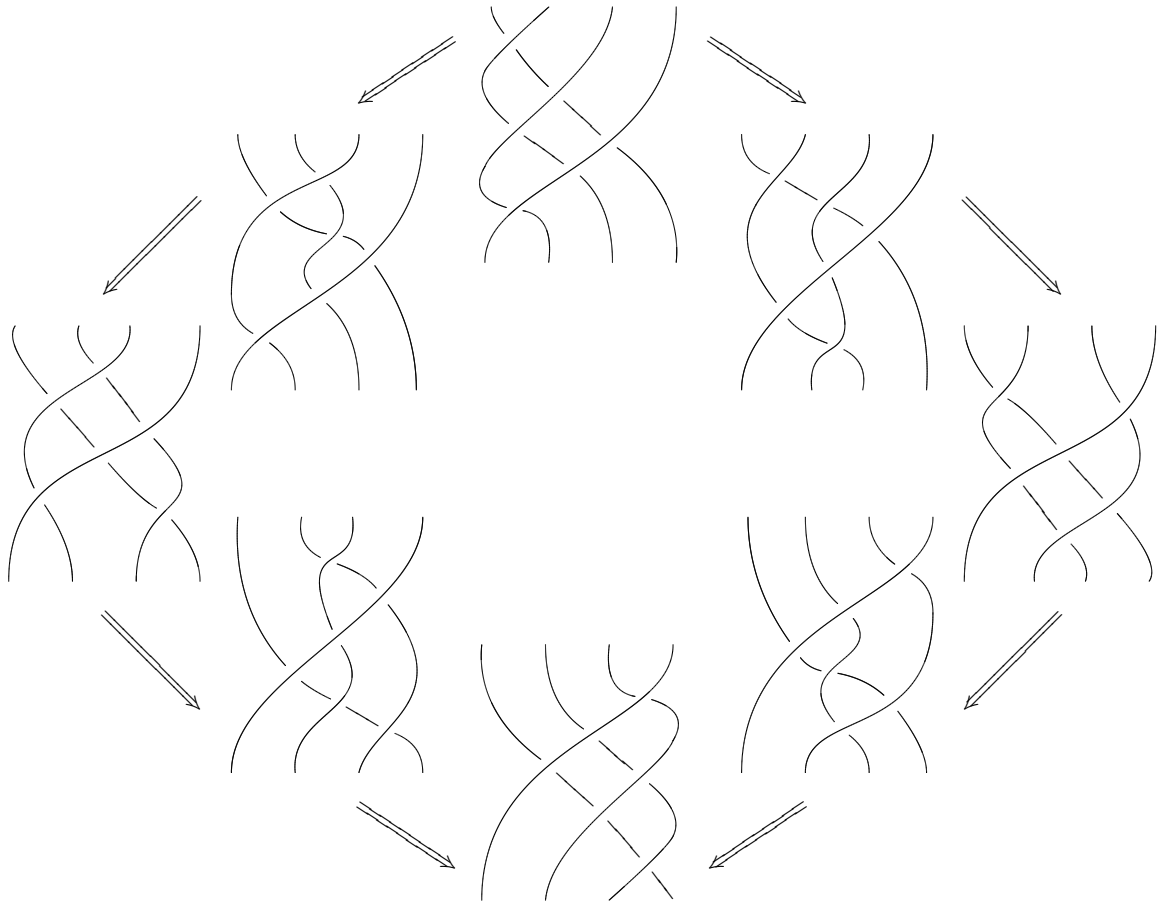
Left side of Zamolodchikov tetrahedron equation:



Right side of Zamolodchikov tetrahedron equation:



In short, the Zamolodchikov tetrahedron equation is a formalization of this commutative octagon:





**Theorem:** Let  $L$  be a 2-vector space, let  $[\cdot, \cdot]: L \times L \rightarrow L$  be a skew-symmetric bilinear functor, and let  $J$  be a completely antisymmetric trilinear natural transformation with

$$J_{x,y,z}: [[x, y], z] \rightarrow [x, [y, z]] + [[x, z], y].$$

Let  $L' = K \oplus L$ , where  $K$  is the categorified ground field.

Let  $B: L' \otimes L' \rightarrow L' \otimes L'$  be defined as follows:

$$B((a, x) \otimes (b, y)) = (b, y) \otimes (a, x) + (1, 0) \otimes (0, [x, y])$$

whenever  $(a, x)$  and  $(b, y)$  are both either objects or morphisms in  $L'$ . Finally, let

$$Y: (B \otimes 1)(1 \otimes B)(B \otimes 1) \Rightarrow (1 \otimes B)(B \otimes 1)(1 \otimes B)$$

be defined as follows:

$$Y = \begin{array}{c} L' \otimes L' \otimes L' \\ \downarrow p \otimes p \otimes p \\ L \otimes L \otimes L \\ \begin{array}{c} (x, y, z) \\ \Downarrow \\ J \\ \Downarrow \\ [[x, y], z] \quad L \quad [x, [y, z]] + [[x, z], y] \end{array} \\ \downarrow a \\ L' \otimes L' \otimes L' \\ (1, 0) \otimes (1, 0) \otimes (0, a) \end{array}$$

where  $a$  is either an object or morphism of  $L$ . Then  $Y$  is a solution of the Zamolodchikov tetrahedron equation if and only if  $J$  satisfies the Jacobiator identity.

# Hierarchy of Higher Commutativity

<b>Topology</b>	<b>Algebra</b>
Crossing	Commutator
Crossing of crossings	Jacobi identity
Crossing of crossing of crossings	Jacobiator identity
⋮	⋮

## Examples

**Theorem:** There is a one-to-one correspondence between equivalence classes of Lie 2-algebras (where equivalence is as objects of the 2-category  $\text{Lie2Alg}$ ) and isomorphism classes of quadruples consisting of a Lie algebra  $\mathfrak{g}$ , a vector space  $V$ , a representation  $\rho$  of  $\mathfrak{g}$  on  $V$ , and an element of  $H^3(\mathfrak{g}, V)$ .

**Example:** Given a finite-dimensional, simple Lie algebra  $\mathfrak{g}$  over  $\mathbb{C}$ ,  $H^3(\mathfrak{g}, \mathbb{C}) = \mathbb{C}$ , so we can construct a Lie 2-algebra with nontrivial Jacobiator consisting of:

- $L_0 = \mathfrak{g}$
- $L_1 = \text{identity morphisms}$
- $J_{x,y,z} = f(x, y, z)1_{[[x,y],z]}$  where  $f: \mathfrak{g}^3 \rightarrow \mathbb{C}$  is a nontrivial 3-cocycle

In fact, we can take  $J_{x,y,z} = \hbar \langle x, [y, z] \rangle 1$  for  $\hbar \in \mathbb{C}$ .

## Lie 2-groups

A **coherent 2-group** is a weak monoidal category  $C$  in which every morphism is invertible and every object  $x \in C$  is equipped with an adjoint equivalence  $(x, \bar{x}, i_x, e_x)$ .

A **Lie 2-group** is a coherent 2-group object in DiffCat.