

Loop Groups and Lie 2-Algebras

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Joint work with:

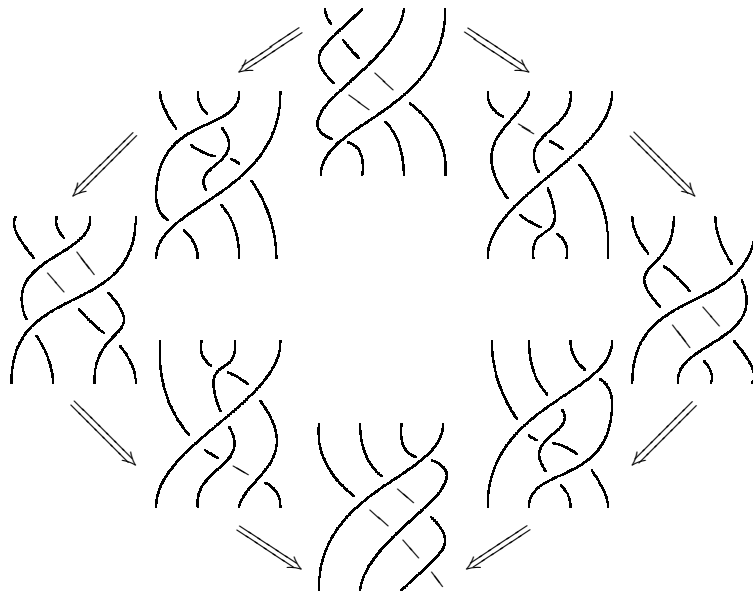
John Baez

Urs Schreiber

& Danny Stevenson

**in honor of
Ross Street's 60th birthday**

July 15, 2005



Lie 2-Algebras

A **2-vector space** L is a category in \mathbf{Vect} , the category of vector spaces.

We can also define **linear functors** between 2-vector spaces, and **linear natural transformations** between these, in the obvious way.

Theorem. The 2-category of 2-vector spaces, linear functors and linear natural transformations is equivalent to the 2-category of:

- 2-term chain complexes $C_1 \xrightarrow{d} C_0$,
- chain maps between these,
- chain homotopies between these.

Moral: Homological algebra is secretly categorified linear algebra!

A **Lie 2-algebra** consists of:

- a 2-vector space L

equipped with:

- a functor called the **bracket**:

$$[\cdot, \cdot]: L \times L \rightarrow L$$

bilinear and skew-symmetric as a function of objects and morphisms,

- a natural isomorphism called the **Jacobiator**:

$$J_{x,y,z}: [[x, y], z] \rightarrow [x, [y, z]] + [[x, z], y],$$

trilinear and antisymmetric as a function of the objects x, y, z ,

such that:

- the **Jacobiator identity** holds, meaning the following diagram commutes:

$$\begin{array}{ccc}
 & & [[w,x],y],z \\
 & \swarrow^{[J_{w,x,y},z]} & \searrow^1 \\
 [[w,y],x],z + [[w,[x,y]],z] & & [[[w,x],y],z] \\
 \downarrow^{J_{[w,y],x,z} + J_{w,[x,y],z}} & & \downarrow^{J_{[w,x],y,z}} \\
 [[[w,y],z],x] + [[w,y],[x,z]] & & [[[w,x],z],y] + [[w,x],[y,z]] \\
 + [w,[[x,y],z]] + [[w,z],[x,y]] & & \downarrow^{[J_{w,x,z},y]} \\
 \downarrow^{[J_{w,y,z},x]} & & \downarrow^{[J_{w,x,z},y]} \\
 [[[w,z],y],x] + [[w,[y,z]],x] & & [[w,[x,z]],y] \\
 + [[w,y],[x,z]] + [w,[[x,y],z]] + [[w,z],[x,y]] & & + [[w,x],[y,z]] + [[[w,z],x],y] \\
 \swarrow^{[w,J_{x,y},z]} & & \swarrow^{J_{w,[x,z],y} + J_{[w,z],x,y} + J_{w,x,[y,z]}} \\
 & & [[[w,z],y],x] + [[w,z],[x,y]] + [[w,y],[x,z]] \\
 & & + [w,[[x,z],y]] + [[w,[y,z]],x] + [w,[x,[y,z]]]
 \end{array}$$

Given a vector space V and an isomorphism

$$B: V \otimes V \rightarrow V \otimes V,$$

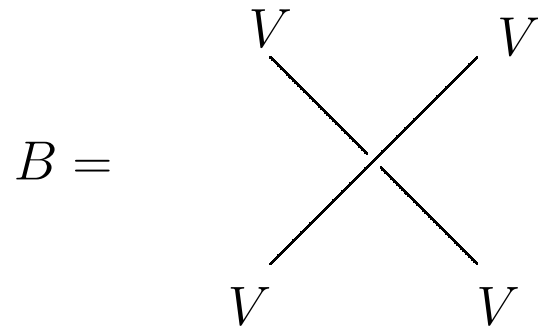
we say B is a **Yang–Baxter operator** if it satisfies the **Yang–Baxter equation**, which says that:

$$(B \otimes 1)(1 \otimes B)(B \otimes 1) = (1 \otimes B)(B \otimes 1)(1 \otimes B),$$

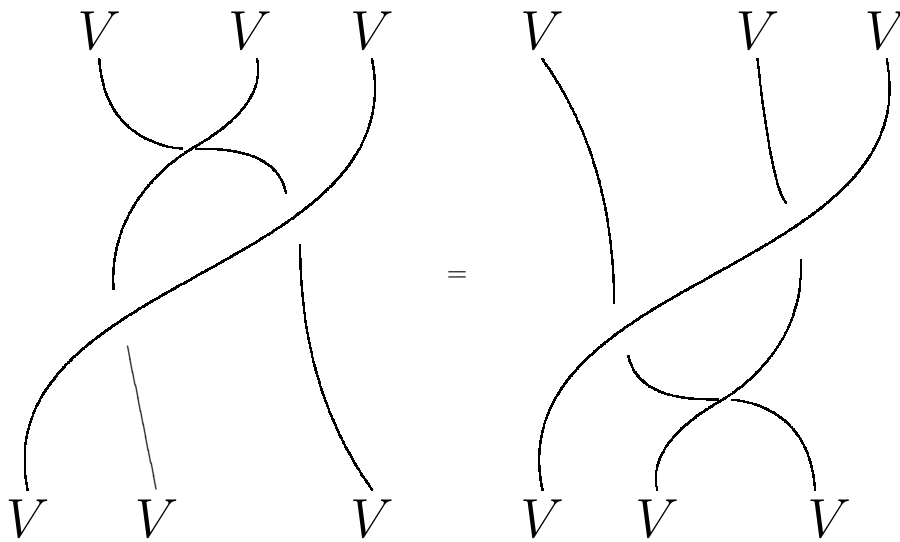
or in other words, that this diagram commutes:

$$\begin{array}{ccccc}
 & & V \otimes V \otimes V & & \\
 & \swarrow^{1 \otimes B} & & \searrow_{B \otimes 1} & \\
 V \otimes V \otimes V & & & & V \otimes V \otimes V \\
 \downarrow B \otimes 1 & & & & \downarrow 1 \otimes B \\
 V \otimes V \otimes V & & & & V \otimes V \otimes V \\
 & \searrow_{1 \otimes B} & & \swarrow_{B \otimes 1} & \\
 & & V \otimes V \otimes V & &
 \end{array}$$

If we draw $B: V \otimes V \rightarrow V \otimes V$ as a braiding:



the Yang–Baxter equation says that:



Proposition. Let L be a vector space over k equipped with a skew-symmetric bilinear operation

$$[\cdot, \cdot]: L \times L \rightarrow L.$$

Let $L' = k \oplus L$ and define the isomorphism

$$B: L' \otimes L' \rightarrow L' \otimes L' \text{ by}$$

$$B((a, x) \otimes (b, y)) = (b, y) \otimes (a, x) + (1, 0) \otimes (0, [x, y]).$$

Then B is a solution of the Yang–Baxter equation if and only if $[\cdot, \cdot]$ satisfies the Jacobi identity.

Zamolodchikov tetrahedron equation

Given a 2-vector space V and an invertible linear functor $B: V \otimes V \rightarrow V \otimes V$, a linear natural isomorphism

$$Y: (B \otimes 1)(1 \otimes B)(B \otimes 1) \Rightarrow (1 \otimes B)(B \otimes 1)(1 \otimes B)$$

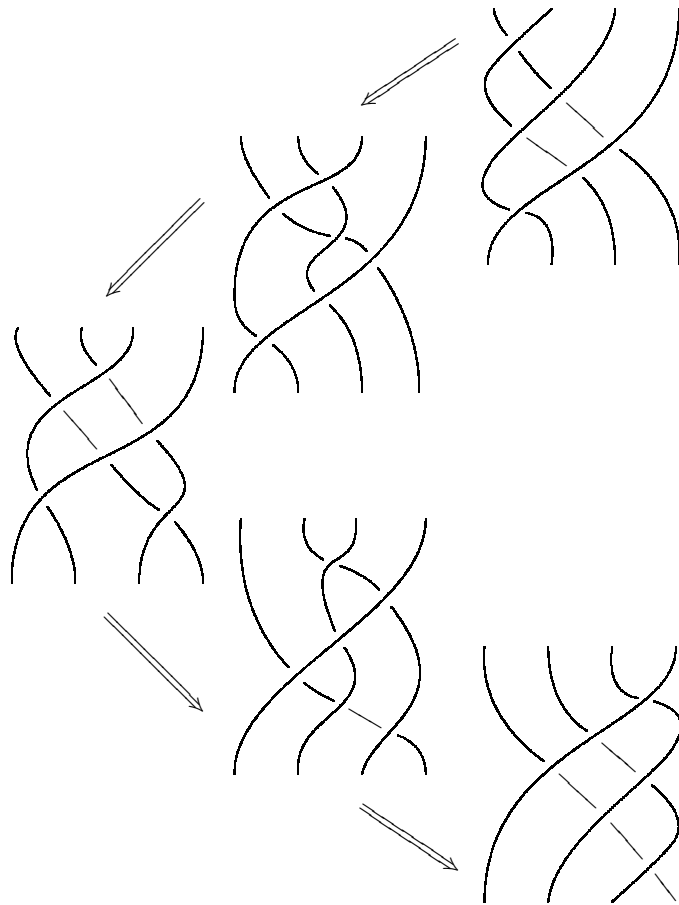
satisfies the **Zamolodchikov tetrahedron equation** if:

$$\begin{aligned} & [Y \circ (1 \otimes 1 \otimes B)(1 \otimes B \otimes 1)(B \otimes 1 \otimes 1)] [(1 \otimes B \otimes 1)(B \otimes 1 \otimes 1) \circ Y \circ (B \otimes 1 \otimes 1)] \\ & [(1 \otimes B \otimes 1)(1 \otimes 1 \otimes B) \circ Y \circ (1 \otimes 1 \otimes B)] [Y \circ (B \otimes 1 \otimes 1)(1 \otimes B \otimes 1)(1 \otimes 1 \otimes B)] \\ & \qquad \qquad \qquad = \\ & [(B \otimes 1 \otimes 1)(1 \otimes B \otimes 1)(1 \otimes 1 \otimes B) \circ Y] [(B \otimes 1 \otimes 1) \circ Y \circ (B \otimes 1 \otimes 1)(1 \otimes B \otimes 1)] \\ & [(1 \otimes 1 \otimes B) \circ Y \circ (1 \otimes 1 \otimes B)(1 \otimes B \otimes 1)] [(1 \otimes 1 \otimes B)(1 \otimes B \otimes 1)(B \otimes 1 \otimes 1) \circ Y] \end{aligned}$$

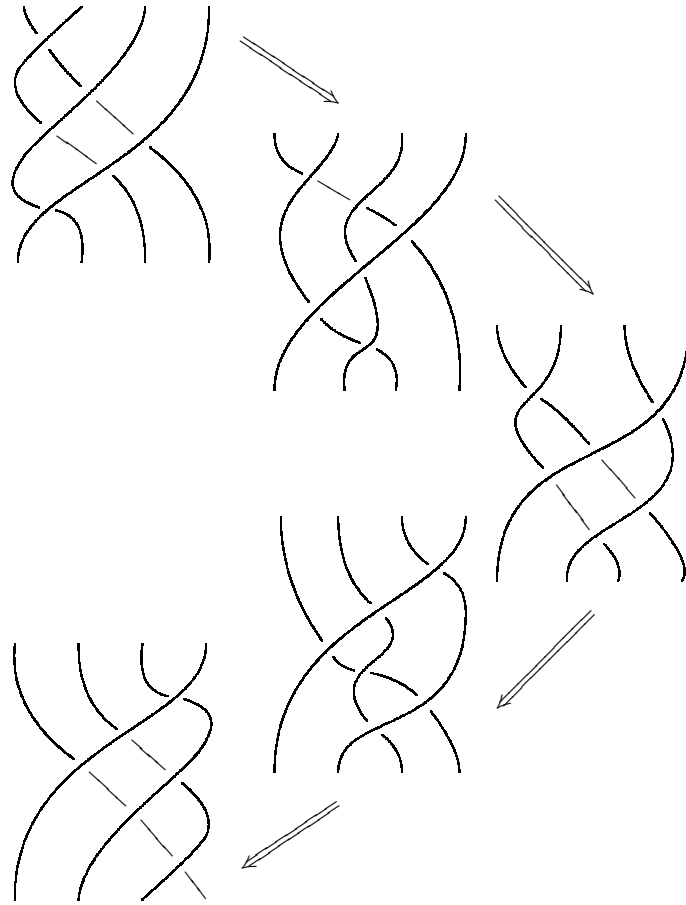
We should think of Y as the surface in 4-space traced out by the *process of performing* the third Reidemeister move:



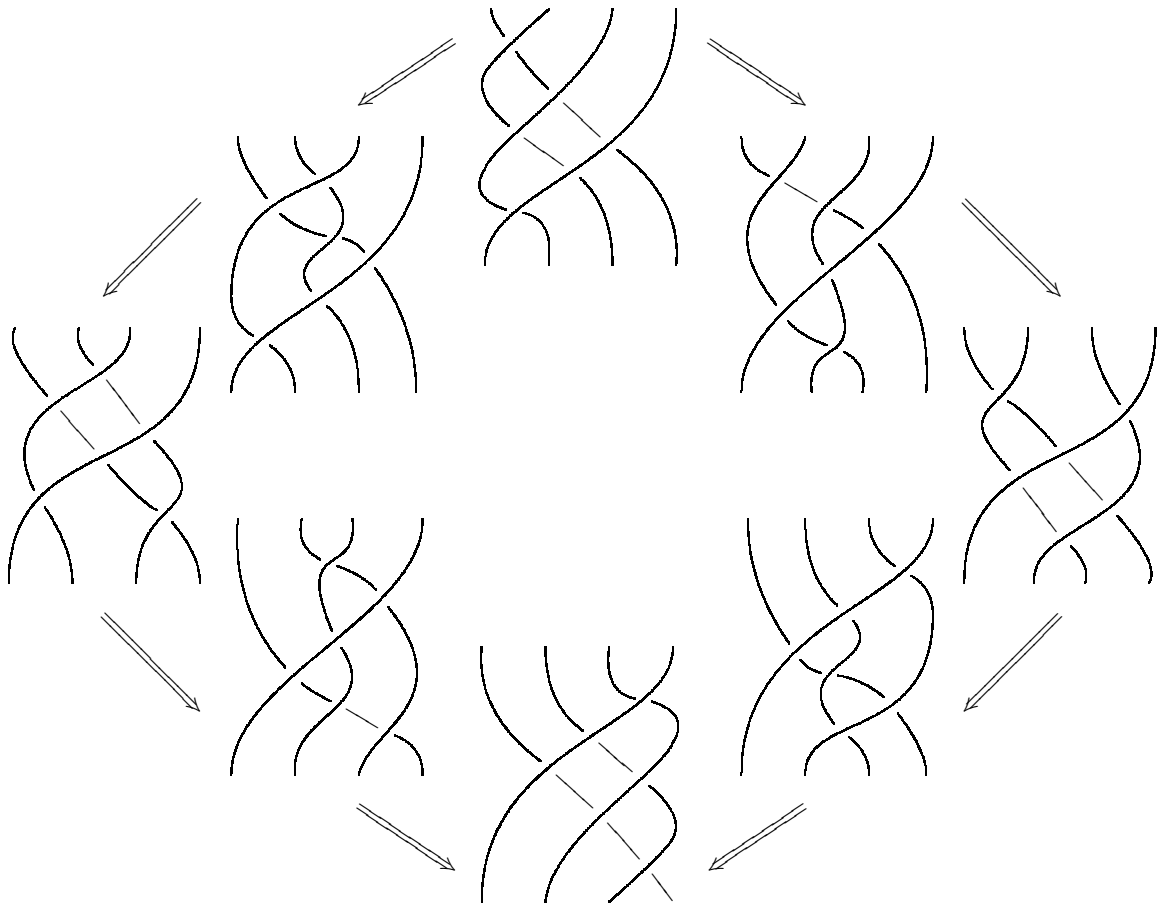
Left side of Zamolodchikov tetrahedron equation:



Right side of Zamolodchikov tetrahedron equation:



In short, the Zamolodchikov tetrahedron equation is a formalization of this commutative octagon:



Theorem. Let L be a 2-vector space, let $[\cdot, \cdot]: L \times L \rightarrow L$ be a skew-symmetric bilinear functor, and let J be a completely antisymmetric trilinear natural transformation with

$$J_{x,y,z}: [[x, y], z] \rightarrow [x, [y, z]] + [[x, z], y].$$

Let $L' = K \oplus L$, where K is the categorified ground field.

Let $B: L' \otimes L' \rightarrow L' \otimes L'$ be defined as follows:

$$B((a, x) \otimes (b, y)) = (b, y) \otimes (a, x) + (1, 0) \otimes (0, [x, y])$$

whenever (a, x) and (b, y) are both either objects or morphisms in L' . Finally, let

$$Y: (B \otimes 1)(1 \otimes B)(B \otimes 1) \Rightarrow (1 \otimes B)(B \otimes 1)(1 \otimes B)$$

be defined as follows:

$$Y = \begin{array}{c} L' \otimes L' \otimes L' \\ \downarrow p \otimes p \otimes p \\ L \otimes L \otimes L \\ \begin{array}{c} \swarrow \quad \searrow \\ (x, y, z) \\ \Downarrow J \\ \swarrow \quad \searrow \\ [[x, y], z] \quad L \quad [x, [y, z]] + [[x, z], y] \end{array} \\ \downarrow a \\ L' \otimes L' \otimes L' \\ (1, 0) \otimes (1, 0) \otimes (0, a) \end{array}$$

where a is either an object or morphism of L . Then Y is a solution of the Zamolodchikov tetrahedron equation if and only if J satisfies the Jacobiator identity.

Hierarchy of Higher Commutativity

Topology	Algebra
Crossing	Commutator
Crossing of crossings	Jacobi identity
Crossing of crossing of crossings	Jacobiator identity
⋮	⋮

We can define **homomorphisms** between Lie 2-algebras, and **2-homomorphisms** between these.

Theorem. The 2-category of Lie 2-algebras, homomorphisms and 2-homomorphisms is equivalent to the 2-category of:

- 2-term L_∞ -algebras,
- L_∞ -homomorphisms between these,
- L_∞ -2-homomorphisms between these.

The Lie 2-algebras L and L' are **equivalent** if there are homomorphisms

$$f: L \rightarrow L' \quad \bar{f}: L' \rightarrow L$$

that are inverses up to 2-isomorphism:

$$f\bar{f} \cong 1, \quad \bar{f}f \cong 1.$$

Theorem. Lie 2-algebras are classified up to equivalence by quadruples consisting of:

- a Lie algebra \mathfrak{g} ,
- an abelian Lie algebra (= vector space) \mathfrak{h} ,
- a representation ρ of \mathfrak{g} on \mathfrak{h} ,
- an element $[j] \in H^3(\mathfrak{g}, \mathfrak{h})$.

The Lie 2-Algebra \mathfrak{g}_k

Suppose \mathfrak{g} is a finite-dimensional simple Lie algebra over \mathbb{R} . To get a Lie 2-algebra having \mathfrak{g} as objects we need:

- a vector space \mathfrak{h} ,
- a representation ρ of \mathfrak{g} on \mathfrak{h} ,
- an element $[j] \in H^3(\mathfrak{g}, \mathfrak{h})$.

Assume without loss of generality that ρ is irreducible. To get Lie 2-algebras with nontrivial Jacobiator, we need $H^3(\mathfrak{g}, \mathfrak{h}) \neq 0$. By Whitehead's lemma, this only happens when $\mathfrak{h} = \mathbb{R}$ is the trivial representation. Then we have

$$H^3(\mathfrak{g}, \mathbb{R}) = \mathbb{R}$$

with a nontrivial 3-cocycle given by:

$$\nu(x, y, z) = \langle [x, y], z \rangle.$$

The Lie algebra \mathfrak{g} together with the trivial representation of \mathfrak{g} on \mathbb{R} and k times the above 3-cocycle give the Lie 2-algebra \mathfrak{g}_k .

The 2-term L_∞ -algebra V corresponding to the Lie 2-algebra \mathfrak{g}_k is given by:

- $V_0 =$ the Lie algebra \mathfrak{g} ,
- $V_1 = \mathbb{R}$,
- $d: V_1 \rightarrow V_0$ is the zero map,
- $l_2: V_0 \times V_0 \rightarrow V_0$ given by the bracket in \mathfrak{g} :

$$l_2(x, y) = [x, y],$$

and $l_2: V_0 \times V_1 \rightarrow V_1$ given by the trivial representation ρ of \mathfrak{g} on \mathbb{R} ,

- $l_3: V_0 \times V_0 \times V_0 \rightarrow V_1$ given by:

$$l_3(x, y, z) = k\langle [x, y], z \rangle$$

for all $x, y, z \in \mathfrak{g}$.

In summary: *every simple Lie algebra \mathfrak{g} gives a one-parameter family of Lie 2-algebras, \mathfrak{g}_k , which reduces to \mathfrak{g} when $k = 0$!*

Puzzle: Does \mathfrak{g}_k come from a Lie 2-group?

Suppose we try to copy the construction of \mathfrak{g}_k for a particularly nice kind of Lie group. Let G be a simply-connected compact simple Lie group whose Lie algebra is \mathfrak{g} . We have

$$H^3(G, U(1)) \xleftarrow{\iota} \mathbb{Z} \hookrightarrow \mathbb{R} \cong H^3(\mathfrak{g}, \mathbb{R})$$

Using the classification of 2-groups, we can build a skeletal 2-group G_k for $k \in \mathbb{Z}$:

- G as its group of objects,
- $U(1)$ as the group of automorphisms of any object,
- the trivial action of G on $U(1)$,
- $[a] \in H^3(G, U(1))$ given by $k \iota[\nu]$, which is nontrivial when $k \neq 0$.

Question: Can G_k be made into a Lie 2-group?

Here's the bad news:

(Bad News) Theorem. Unless $k = 0$, there is no way to give the 2-group G_k the structure of a Lie 2-group for which the group G of objects and the group $U(1)$ of endomorphisms of any object are given their usual topology.

(Good News) Theorem. For any $k \in \mathbb{Z}$, there is a Fréchet Lie 2-group $\mathcal{P}_k G$ whose Lie 2-algebra $\mathcal{P}_k \mathfrak{g}$ is equivalent to \mathfrak{g}_k .

An object of $\mathcal{P}_k G$ is a smooth path $f: [0, 2\pi] \rightarrow G$ starting at the identity. A morphism from f_1 to f_2 is an equivalence class of pairs (D, α) consisting of a disk D going from f_1 to f_2 together with $\alpha \in U(1)$.

For any two such pairs (D_1, α_1) and (D_2, α_2) there is a 3-ball B whose boundary is $D_1 \cup D_2$, and the pairs are equivalent when

$$\exp \left(2\pi i k \int_B \nu \right) = \alpha_2 / \alpha_1$$

where ν is the left-invariant closed 3-form on G with

$$\nu(x, y, z) = \langle [x, y], z \rangle$$

and $\langle \cdot, \cdot \rangle$ is the smallest invariant inner product on \mathfrak{g} such that ν gives an integral cohomology class.

The Lie 2-Algebra $\mathcal{P}_k\mathfrak{g}$

\mathcal{P}_kG is a particularly nice kind of Lie 2-group: a *strict* one! Thus, its Lie 2-algebra is easy to compute.

The 2-term L_∞ -algebra V corresponding to the Lie 2-algebra $\mathcal{P}_k\mathfrak{g}$ is given by:

- $V_0 = P_0\mathfrak{g}$
- $V_1 = \widehat{\Omega}_k\mathfrak{g} \cong \Omega\mathfrak{g} \oplus \mathbb{R}$,
- $d: V_1 \rightarrow V_0$ equal to the composite

$$\widehat{\Omega}_k\mathfrak{g} \rightarrow \Omega\mathfrak{g} \hookrightarrow P_0\mathfrak{g},$$
- $l_2: V_0 \times V_0 \rightarrow V_0$ given by the bracket in $P_0\mathfrak{g}$:

$$l_2(p_1, p_2) = [p_1, p_2],$$

and $l_2: V_0 \times V_1 \rightarrow V_1$ given by the action $d\alpha$ of $P_0\mathfrak{g}$ on $\widehat{\Omega}_k\mathfrak{g}$, or explicitly:

$$l_2(p, (\ell, c)) = ([p, \ell], 2k \int_0^{2\pi} \langle p(\theta), \ell'(\theta) \rangle d\theta)$$

for all $p \in P_0\mathfrak{g}$, $\ell \in \Omega G$ and $c \in \mathbb{R}$,

- $l_3: V_0 \times V_0 \times V_0 \rightarrow V_1$ equal to zero.

The 2-term L_∞ -algebra V corresponding to the Lie 2-algebra \mathfrak{g}_k is given by:

- $V_0 =$ the Lie algebra \mathfrak{g} ,
- $V_1 = \mathbb{R}$,
- $d: V_1 \rightarrow V_0$ is the zero map,
- $l_2: V_0 \times V_0 \rightarrow V_0$ given by the bracket in \mathfrak{g} :

$$l_2(x, y) = [x, y],$$

and $l_2: V_0 \times V_1 \rightarrow V_1$ given by the trivial representation ρ of \mathfrak{g} on \mathbb{R} ,

- $l_3: V_0 \times V_0 \times V_0 \rightarrow V_1$ given by:

$$l_3(x, y, z) = k\langle [x, y], z \rangle$$

for all $x, y, z \in \mathfrak{g}$.

The Equivalence $\mathcal{P}_k\mathfrak{g} \simeq \mathfrak{g}_k$

We describe the two Lie 2-algebra homomorphisms forming our equivalence in terms of their corresponding L_∞ -algebra homomorphisms:

- $\phi: \mathcal{P}_k\mathfrak{g} \rightarrow \mathfrak{g}_k$ has:

$$\begin{aligned}\phi_0(p) &= p(2\pi) \\ \phi_1(\ell, c) &= c\end{aligned}$$

where $p \in P_0\mathfrak{g}$, $\ell \in \Omega\mathfrak{g}$, and $c \in \mathbb{R}$.

- $\psi: \mathfrak{g}_k \rightarrow \mathcal{P}_k\mathfrak{g}$ has:

$$\begin{aligned}\psi_0(x) &= xf \\ \psi_1(c) &= (0, c)\end{aligned}$$

where $x \in \mathfrak{g}$, $c \in \mathbb{R}$, and $f: [0, 2\pi] \rightarrow \mathbb{R}$ is a smooth function with $f(0) = 0$ and $f(2\pi) = 1$.

Theorem. With the above definitions we have:

- $\phi \circ \psi$ is the identity Lie 2-algebra homomorphism on \mathfrak{g}_k , and
- $\psi \circ \phi$ is isomorphic, as a Lie 2-algebra homomorphism, to the identity on $\mathcal{P}_k\mathfrak{g}$.

What's Next?

We know how to get Lie n -algebras from Lie algebra cohomology! We should:

- Classify their representations
- Find their corresponding Lie n -groups
- Understand their relation to higher braid theory

Moreover, many other questions remain:

- Weak n -categories in Vect?
- Weakening laws governing addition and scalar multiplication?
- Weakening the antisymmetry of the bracket in the definition of Lie 2-algebra?
- What's a free Lie 2-algebra on a 2-vector space?
- Lie 2-algebra cohomology? L_∞ -algebra cohomology?
- Deformations of Lie 2-algebras?