

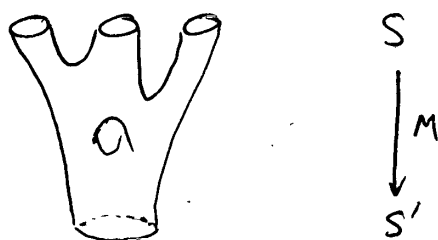
8 Feb 2005

Thm - Suppose G is a finite group. Then we get a 2d TQFT

$$Z: 2\text{Cob} \rightarrow \text{Vect}$$

from the semisimple algebra $\mathbb{C}[G]$ (the group algebra of G).

Moreover, given a spacetime $M: S \rightarrow S'$ in 2Cob :



we can compute the partition function

$$Z(M): Z(S) \rightarrow Z(S')$$

as a path integral (a finite sum) over flat G -connections on M .

Proof - We'll just do the case where M is a closed

(oriented) 2-manifold, so that $Z(M): Z(\emptyset) \rightarrow Z(\emptyset)$

is just a number.

Recall: a (finite-dim, associative) algebra is semisimple if the "Killing form"

$$g(a, b) = \text{tr}(L_a L_b)$$

$$L_a: A \rightarrow A \\ b \mapsto ab$$

is nondegenerate. To compute $Z(M)$ we pick a

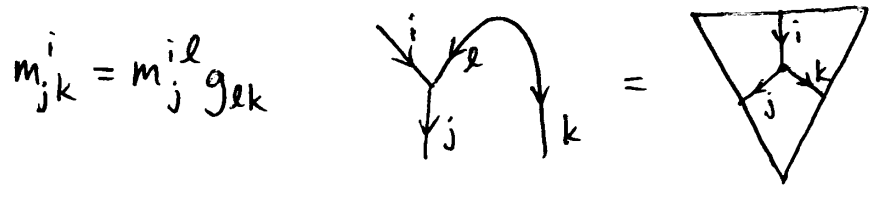
basis $e^i \in A$ and define

$$e^i e^j = m_k^{ij} e^k \quad m_k^{ij} \in \mathbb{C}$$

We raise and lower indices on m_k^{ij} using the metric:

$$g^{ij} = g(e^i, e^j)$$

& inverse metric g_{ij} s.t. $g_{ij} g^{jk} = \delta_i^k$. E.g.: we draw



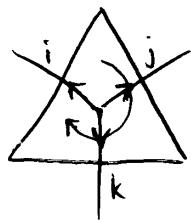
& similarly for m_{ijk} & m^{ijk} .

To compute $Z(M)$ we triangulate M , draw a "Feynman Diagram" in the dual 1-skeleton:



Then: label edges of the Feynman diagrams with indices; write a copy of m for each triangle (using incoming arrows as superscripts, outgoing as subscripts and going around ~~clockwise~~ using the orientation on M .)

e.g.:



$$m_{ijk} = m_{jki} = m_{kij}$$

and use Einstein summation convention to get a number $Z(M)$.

Now, when $A = \mathbb{C}[G]$, let's show the sum over indices gives a sum over flat G -connections on (the triangulated) M . Let's use the basis $e^i \in \mathbb{C}[G]$ corresponding to the group elements $i \in G$. Then

$$e^i e^j = e^{ij} \leftarrow \text{mult. in } G$$

$$\uparrow \text{mult. in } \mathbb{C}[G]$$

so

$$e^i e^j = m_k^{ij} e^k$$

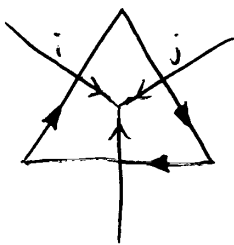
where

$$m_k^{ij} = \delta_k^{ij} = \begin{cases} 1 & ij = k \\ 0 & ij \neq k \end{cases}$$

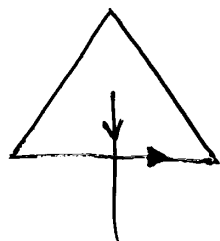
Toby: "on the left there's an implicit comma; on the right an implicit multiplication between i & j ."

(cute notation)

When we sum over indices to compute $Z(M)$, we're summing over connections on the triangulated M :



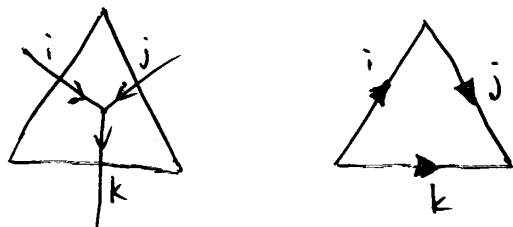
where we use the arrows on our Feynman diagram to orient the edges of M :



(via this rule)

& interpret the group elements (i, j, k, \dots) as a connection on the directed graph made of triangle edges. We're summing over all connections.

Since $m_k^{ij} = 0$ unless $ij=k$, we get a zero contribution to $Z(M)$ unless the connection is flat on this triangle



What about the other cases: m^{ijk} , m_{ijk}^i , & m_{ijk} ?

We'll see these all vanish unless the connection is flat - but let's see exactly what they are. First, let's calculate g^{ij} & g_{ij} :

$$\begin{aligned} g^{ij} &= g(e^i, e^j) = \text{tr}(L_i L_j) \\ &= \text{tr}(L_{ij}) \\ &= \sum_{k \in G} \langle e^k, L_{ij} e^k \rangle \end{aligned}$$

(inner prod s.t. e^i are o.n. basis)

$$\begin{aligned}
 &= \sum_{k \in G} \langle e^k, e^{ijk} \rangle \\
 &= \sum_{k \in G} \delta_k^{ijk} \\
 &= \sum_{k \in G} \delta_1^{ij} \quad \begin{array}{l} ijk = k \\ \updownarrow \\ ij = 1. \end{array} \\
 &= |G| \delta_1^{ij} \\
 &= |G| \delta_{j^{-1}}^i
 \end{aligned}$$

The inverse of this matrix is

$$g_{ij} = \frac{1}{|G|} \delta_{ij}^1 = \frac{1}{|G|} \delta_i^{j^{-1}}$$

Using these we get:

$$m_{jk}^i = m_j^{il} g_{lk} = m_j^{il} \cdot \frac{1}{|G|} \delta_l^{k^{-1}} = \frac{1}{|G|} m_j^{ik^{-1}} = \frac{1}{|G|} \delta_j^{ik^{-1}} = \frac{1}{|G|} \delta_{jk}^i$$

($ik^{-1} = j$ or get zero
 \updownarrow
 $i = jk$)

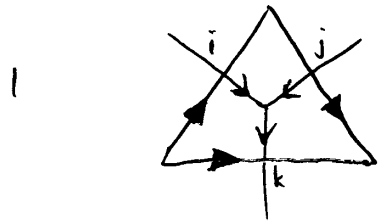
which resembles $m_k^{ij} = \delta_k^{ij}$ except
for the $\frac{1}{|G|}$ - which comes from lowering
an index. Similarly:

$$m_{ijk} = \frac{1}{|G|^2} \delta_{ikj}^1 \quad (\text{note order of indices!})$$

$$\& m^{ijk} = |G| \delta_1^{ijk}$$

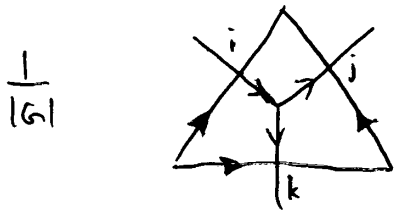
Key point for finishing the proof: In every case we get

zero unless the connection is flat:



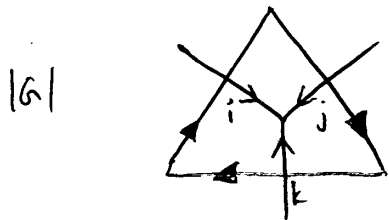
$$m_{kj}^{ij} = 0 \text{ unless } ij = k$$

$$m_{kj}^{ij} = \delta_k^{ij}$$



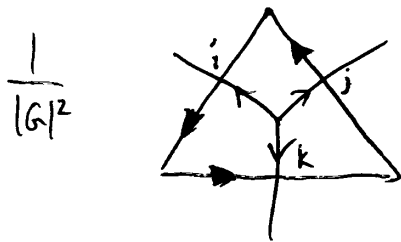
$$m_{kj}^i = 0 \text{ unless } i = kj$$

$$m_{kj}^i = \frac{1}{|G|} \delta_{kj}^i$$



$$m_{ijk} = 0 \text{ unless } ijk = 1$$

$$m_{ijk} = |G| \delta_1^{ijk}$$



$$m_{ijk} = 0 \text{ unless } ikj = 1$$

$$m_{ijk} = \frac{1}{|G|^2} \delta_{ikj}^1$$



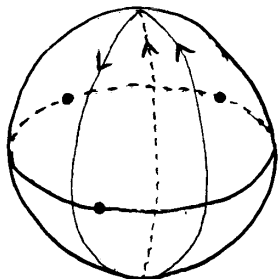
In fact: we've seen $Z(M)$ is a sum over flat connections of

$$|G| \# \triangle - \# \triangle - 2 \# \triangle$$

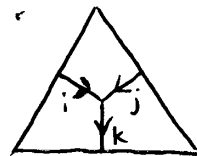
so $Z(M)$ is $\#(\text{flat } G\text{-connections})$ times this number.

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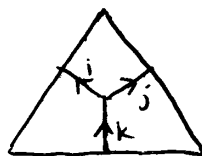
Examples:

1) $M = S^2$ triangulated with two triangles

top:

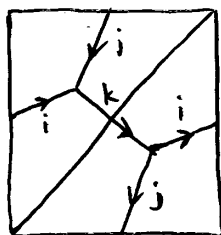
 m_{ij}^k

bottom

 m_{ij}^k

So

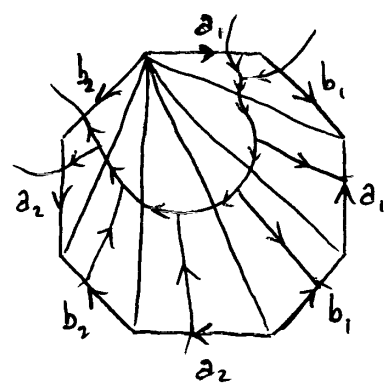
$$\begin{aligned} Z(M) &= m_{ij}^k m_{ij}^k \\ &= \frac{1}{|G|} \delta_k^{ij} \delta_{ij}^k \\ &= \frac{1}{|G|} |G|^2 = |G|. \end{aligned}$$

2) $M = T^2$ flatness
here $\Rightarrow ij=k$ flatness
here $\Rightarrow ji=k$

$$\begin{aligned} Z(M) &= m_{ij}^k m_{ji}^k \\ &= \frac{1}{|G|} \delta_k^{ij} \delta_{ji}^k \\ &= \frac{1}{|G|} |\{(i,j) \in G^2 : ij=ji\}| \end{aligned}$$

3) $M = M_g$, the surface of genus g ("g-holed torus").

E.g. $g = 2$:

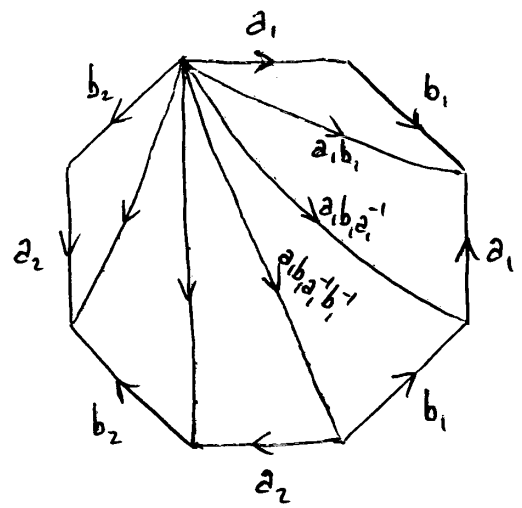


(Note: Suspiciously similar to the Euler characteristic $\chi(M_g) = |V| - |E| + |F| = 2 - 2g$)

We know $Z(M) = |A_0(M)| \cdot |G|$ (flat G -conn.)

$$\# \triangle - \# \triangle - 2\# \triangle$$

& hence a flat connection is



$a_1, a_2, b_1, b_2 \in G$
 such that $a_1 b_1 a_1^{-1} b_1^{-1} a_2 b_2 a_2^{-1} b_2^{-1} = 1$
 (since loop around the octagon is contractible)

So $A_0(M_g) = \{(a_1, b_1, \dots, a_n, b_n) : a_1 b_1 a_1^{-1} b_1^{-1} \dots = 1\} \subseteq G^{2n}$

Also $\# \triangle - \# \triangle - 2\# \triangle = -(2g-1)$

So:

$$Z(M_g) = |A_0(M_g)| |G|^{-2g+1}$$

where $|A_0(M_g)|$ is hard to calculate beyond what we've done.

Note this is even true for S^2 !

Recall: if we pick a vertex $* \in M$, $\pi_1(M)$ is the group of loops of edges based at $*$, mod simplicial homotopy:



$\pi_1(M_g)$ is generated by \bar{a}_i, \bar{b}_i with only nontrivial relation being $\bar{a}_i \bar{b}_i \bar{a}_i^{-1} \bar{b}_i^{-1} = 1$. So, a guy in $A_0(M_g)$ is just a homomorphism

$$A: \pi_1(M_g) \longrightarrow G$$

given by

$$A(\bar{a}_i) = a_i \quad \& \quad A(\bar{b}_i) = b_i$$

(It's flatness that makes $A(\gamma)$ invariant under homotopies of the loop γ , hence well-defined.)

In short, in this example

$$A_0(M) \cong \text{hom}(\pi_1(M), G)$$

but this relies on the fact that our triangulation just had one vertex! If we switch to a triangulation

with more vertices, $A_0(M)$ gets bigger but $\pi_1(M)$ is unchanged, so $\text{hom}(\pi_1(M), G)$ is unchanged.

But luckily:

Thm - If M is any connected triangulated manifold with chosen vertex $*$, we have

$$A_0(M)/g_0(M) \cong \text{hom}(\pi_1(M), G)$$

where $g_0(M) \leq g(M)$ is the group of gauge transformations

$g: V \rightarrow G$ such that $g(*) = 1 \in G$. (We've seen

that g acts on A , but this action preserves $A_0 \leq A$.)

So, the subgroup $g_0(M) \leq g(M)$ acts on $A_0(M)$.

$A_0(M)/g_0(M)$ is the set of orbits.)

Remark:

$$A(M) = \{A: E \rightarrow G\} \quad \& \quad g(M) = \{g: V \rightarrow G\}$$

but also:

- a connection A is a functor $A: PM \rightarrow G$ from the groupoid of paths in M to G
- a gauge transformation g with $gA = A'$ is a natural transformation

$$\begin{array}{ccc} & A & \\ & \downarrow g & \rightarrow G \\ PM & & \\ & A' & \end{array}$$

So we'll use the relation between the groupoid PM and the group $\pi_1 M$