

# NON-DECAYING SOLUTIONS TO THE 2D DISSIPATIVE QUASI-GEOSTROPHIC EQUATIONS

DAVID M. AMBROSE, RYAN ASCHOFF, ELAINE COZZI, AND JAMES P. KELLIHER

ABSTRACT. We consider the surface quasi-geostrophic equation in two spatial dimensions, with subcritical diffusion (i.e. with fractional diffusion of order  $2\alpha$  for  $\alpha > \frac{1}{2}$ .) We establish existence of solutions without assuming either decay at spatial infinity or spatial periodicity. One obstacle is that for  $L^\infty$  data, the constitutive law may not be applicable, as Riesz transforms are unbounded. However, for  $L^\infty$  initial data for which the constitutive law does converge, we demonstrate that there exists a unique solution locally in time, and that the constitutive law continues to hold at positive times. In the case that  $\alpha \in (\frac{1}{2}, 1]$  and that the initial data has some smoothness (specifically, if the data is in  $C^2$ ), we demonstrate a maximum principle and show that this unique solution is actually classical and global in time. Then, a density argument allows us to show that mild solutions with only  $L^\infty$  data are also global in time, and also possess this maximum principle. Finally, we introduce a related problem in which we replace the usual constitutive law for the surface quasi-geostrophic equation with a generalization of Sertfati type, and prove the same results for this relaxed model.

Compiled on Monday 25 August 2025 at 09:37 Pacific Time

## CONTENTS

1. Introduction	2
2. $L^1(\mathbb{R}^2)$ estimates for various operators	5
2.1. Littlewood-Paley operators	5
2.2. Kernels for the fractional heat equation	6
2.3. The constitutive law	7
2.4. Convolution bounds	8
3. Properties of mild solutions to $(SQG)$ and $(SSQG)$	15
3.1. Continuity in space	15
3.2. Continuity in time	17
3.3. Preservation of the constitutive law	19
3.4. Classical $(SQG)$ for smooth initial data	20
3.5. Solutions to $(SSQG)$	24
4. Existence of a Finite Time Mild Solution	25
5. Spatial Regularity of the Solution	30
5.1. Existence of first derivatives of $\theta$ and $u$	31
5.2. Existence of higher derivatives of $\theta$ and $u$	33
6. Extending the Solution	35
6.1. Improved bounds on $(\theta, u)$	35
6.2. Extending the Solution	41
Appendix A.	44

---

2020 *Mathematics Subject Classification*. Primary 76D03, 35Q86, 35A01, 35Q35.

*Key words and phrases*. Fluid mechanics, surface quasi-geostrophic equations, singular initial data, mild solutions, global solutions, non-decaying.

Acknowledgments

45

References

45

## 1. INTRODUCTION

The two-dimensional dissipative surface quasi-geostrophic equations (SQG) can be written, for  $\nu > 0$ ,  $\alpha > 0$ , and  $\Lambda = (-\Delta)^{1/2}$ , in strong form as,

$$\begin{cases} \partial_t \theta + u \cdot \nabla \theta + \nu \Lambda^{2\alpha} \theta = 0 & \text{in } [0, T] \times \mathbb{R}^2, \\ u = -\nabla^\perp \Lambda^{-1} \theta & \text{in } [0, T] \times \mathbb{R}^2, \\ \theta|_{t=0} = \theta_0 & \text{in } \mathbb{R}^2. \end{cases} \quad (SQG)$$

Without dissipation, this system was introduced by Constantin, Majda, and Tabak to model atmospheric fluid flows and as a two-dimensional analogy for the three-dimensional Euler equations [8]. In the non-dissipative case, the existence of a smooth global solution (or singularity formation) remains an open question in general. We consider the question of local and global existence of solutions to the dissipative system (SQG), in the case that the data is non-decaying. (We mention that authors differ on the choice of sign in the constitutive law, using  $\pm \nabla^\perp \Lambda \theta$ , but our choice agrees with that of [8].)

The dissipative SQG system can be subcritical, critical, or supercritical depending on the value of  $\alpha$ . We consider the subcritical case, in which  $\alpha > \frac{1}{2}$ . Other results for the subcritical case are [9], [19], [20], [28], in which various local and global existence theorems are proved on the torus or for decaying solutions in  $\mathbb{R}^2$ . Without attempting to provide an exhaustive list of references, we mention that local and global existence results have also been proved in the critical ( $\alpha = \frac{1}{2}$ ) case [1], [13], and in the supercritical case ( $0 < \alpha < \frac{1}{2}$ ) [6], [7], [11]. None of these works focused on the question considered here, which is existence theory in non-decaying function spaces such as  $L^\infty$ .

We can write the constitutive law, (SQG)<sub>2</sub>, as (see Section 2.3 for more details)

$$u(t, x) = \text{p. v. } K * \theta := \lim_{\substack{\varepsilon \rightarrow 0 \\ R \rightarrow \infty}} \int_{\varepsilon < |x-y| < R} K(x-y) \theta(t, y) dy, \quad (1.1)$$

where

$$K(x) := -\frac{1}{2\pi} \frac{x^\perp}{|x|^3} = \nabla^\perp \psi(x), \quad \psi(x) := -\frac{1}{2\pi|x|}. \quad (1.2)$$

(For ease of notation, we will often abbreviate the principle value integral in (1.1), writing  $K * \theta$ , only writing out the principal value integral when it is necessary to consider it carefully.) We will be studying solutions  $\theta \in L^\infty(\mathbb{R}^2)$ , whereas SQG is more commonly studied in  $L^2(\mathbb{R}^2)$  or similar function spaces. A space such as  $L^2(\mathbb{R}^2)$  has the advantage that  $u$  is then clearly defined; that is, the Riesz transforms in (1.1) are well-defined for  $\theta \in L^2(\mathbb{R}^2)$ , and return  $u \in (L^2(\mathbb{R}^2))^2$ . A fundamental difficulty to overcome in our setting is that Riesz transforms are unbounded on  $L^\infty$ , as is well-known.

The closest works in the literature to the present are the papers [15], [16]. In these works, Lazar studied dissipative SQG in the critical case  $\alpha = 1/2$ , proving existence of local and global weak solutions. The Lazar solutions start from data in the space  $L^\infty(\mathbb{R}^2) \cap \Lambda^s(\dot{H}_{ul}^s(\mathbb{R}^2))$ , i.e., the data is in  $L^\infty$  but is also the  $s^{\text{th}}$  derivative of a function with  $s$

derivatives in the uniformly local  $L^2$  space. This additional assumption on the data is made to induce oscillations, which allow the Riesz transforms to converge.

We take two alternative approaches to make sense of the constitutive law for non-decaying solutions. First, while convolution with  $K$  does not converge for many elements of  $L^\infty$ , we proceed for those elements of  $L^\infty$  for which the convolution does make sense. That is, in our first approach, we take initial data  $\theta_0 \in L^\infty(\mathbb{R}^2)$  for which convolution with  $K$  yields a result that is also in  $L^\infty(\mathbb{R}^2)$ . (We in fact need slightly more than this, in that we also ask that the convolution converge uniformly, in a sense to be made precise in Section 2 below.) We give several examples of such  $\theta_0$  in Section 2. Our second approach will be to introduce a relaxation of the constitutive law.

We define a new notion of mild solution for (SQG) which allows us to solve for  $\theta$  and  $u$  simultaneously, and in a sense, no longer requires us to reconstruct  $u$  from  $\theta$  at every instant. Our starting point in making this mild formulation is the work of Marchand [17] and Marchand and Lemarié-Rieusset [18], who write a mild formulation of (SQG) with a single integral equation,

$$\theta(t, x) = (G_\alpha(t) \theta_0)(x) - \int_0^t \nabla G_\alpha(t-s) \cdot (\theta(K * \theta))(s, x) ds,$$

where  $G_\alpha(t)$  is the fractional heat semigroup defined in (2.5). We replace  $K * \theta$  with  $u$  and couple this equation to a second integral relation for  $u$ , as in the next definition.

**Definition 1.1.** Let  $T \in (0, \infty)$  and let  $(\theta_0, u_0) \in (L^\infty(\mathbb{R}^2))^3$ . A pair

$$(\theta, u) \in L^\infty([0, T] \times \mathbb{R}^2) \times (L^\infty([0, T] \times \mathbb{R}^2))^2$$

is called a *mild solution* to (SQG) on  $[0, T]$  if for each  $t \in (0, T]$  one has

$$\begin{aligned} \theta(t, x) &= (G_\alpha(t) \theta_0)(x) - \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds, \\ u(t, x) &= (G_\alpha(t) u_0)(x) - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta u)(s, x) ds. \end{aligned} \tag{1.3}$$

Through Definition 1.1 we have circumvented the question of whether we can convolve the kernel  $K$  with an  $L^\infty$  function. Given bounded  $\theta_0$  and  $u_0$ , we will show that there exists  $T > 0$  and  $\theta$  and  $u$  such that (1.3) holds. This definition does not enforce any relationship between  $\theta_0$  and  $u_0$ , allowing us to utilize both of our approaches to this question without changing the definition of a mild solution. As we have said, our first approach is to consider  $\theta_0$  for which there is a  $u_0$  such that  $u_0 = K * \theta_0$ , with an additional assumption of uniform convergence. For the resulting solutions  $(\theta, u)$ , we can then show that  $u = K * \theta$  at positive times, as one would desire. The following is this local existence theorem.

**Theorem 1.2.** Let  $\theta_0 \in L^\infty(\mathbb{R}^2)$ ,  $u_0 \in (L^\infty(\mathbb{R}^2))^2$ , and fix  $\alpha > \frac{1}{2}$ . For some  $T > 0$  there exists a unique mild solution  $(\theta, u) \in (C((0, T]; L^\infty(\mathbb{R}^2)))^3$  of (SQG) with  $\theta|_{t=0} = \theta_0$  and  $u|_{t=0} = u_0$ . Moreover, if  $u_0 = \text{p.v. } K * \theta_0$  with the principal value integral converging uniformly in the sense of (2.8), the solution  $(\theta, u)$  satisfies (SQG)<sub>2</sub>.

*Proof.* See Section 4. □

We also study solutions with higher regularity. For notational clarity, we introduce three classical spaces. Let  $k \in \mathbb{N}$  and denote by  $C^k$  the space of  $k$  times differentiable functions. Let  $C_b^k(\mathbb{R}^2)$  denote the Banach space of  $k$ -times continuously differentiable bounded

functions with norm

$$\|f\|_{C_b^k} := \sum_{\beta \in \mathbb{N}^2, |\beta| \leq k} \|D^\beta f\|_{L^\infty} < \infty.$$

For  $k = 0$ ,  $C_b^0(\mathbb{R}^2)$  denotes the space of bounded continuous functions. For  $0 < \gamma < 1$ , we denote the  $\gamma$ -Hölder continuous functions  $C^\gamma(\mathbb{R}^2)$  as the subspace of  $L^\infty(\mathbb{R}^2)$  bounded by the norm

$$\|f\|_{C^\gamma} := \|f\|_{L^\infty} + \sup_{x \neq y} \frac{|f(x) - f(y)|}{|x - y|^\gamma}.$$

We are able to show that if the initial data is in the  $C_b^k$  spaces for  $k \geq 1$ , then the mild solutions preserve this regularity.

**Theorem 1.3.** *Let  $\alpha > \frac{1}{2}$  and  $k \geq 1$ . Select  $\theta_0 \in C_b^k(\mathbb{R}^2)$ ,  $u_0 \in C_b^k(\mathbb{R}^2))^2$  satisfying  $u_0 = K * \theta_0$ . Let  $(\theta, u)$  be the mild solution given by Theorem 1.2 which exists up to time  $T$ . For all  $t < T$ , we have  $D^\beta \theta(t) \in L^\infty(\mathbb{R}^2)$  and  $D^\beta u(t) \in (L^\infty(\mathbb{R}^2))^2$  for any multi-index  $\beta \in \mathbb{N}^2$  such that  $|\beta| \leq k$ .*

*Proof.* See Section 5. □

Our main results, however, are the following two global existence theorems. The first of these theorems states that if the initial data is at least twice continuously differentiable, the solution can be extended for all time. We now restrict to  $\alpha \in (\frac{1}{2}, 1]$  so that we can use maximum principles.

**Theorem 1.4.** *Let  $\alpha \in (\frac{1}{2}, 1]$  be given. Suppose  $k \geq 2$  and  $(\theta_0, u_0) \in (C_b^k(\mathbb{R}^2))^3$ . If one has  $u_0 = \text{p.v. } K * \theta_0$ , then for all  $T > 0$ , there exists a classical solution (i.e., pointwise solution) to (SQG) on  $[0, T]$  with  $(\theta(t), u(t)) \in (C_b^2(\mathbb{R}^2))^3$  for all  $t \in [0, T]$ . Further,  $\theta$  is uniformly bounded by its initial data, i.e.  $\|\theta\|_{L_{t,x}^\infty} \leq \|\theta_0\|_{L_x^\infty}$ .*

*Proof.* See Section 6.2. □

Exploiting the  $C_b^k$  solutions of Theorem 1.4 and a density argument, we then obtain our second main result, the extension of the solutions with  $L^\infty$  data to an arbitrary time.

**Theorem 1.5.** *Let  $\alpha \in (\frac{1}{2}, 1]$  be given. Suppose that  $(\theta_0, u_0) \in (L^\infty(\mathbb{R}^2))^3$ . If one has  $u_0 = \text{p.v. } K * \theta_0$ , then for arbitrary time  $T > 0$ , there exists a mild solution  $(\theta, u) \in (L^\infty([0, T] \times \mathbb{R}^2))^3$  to (SQG) on  $[0, T]$ . Further,  $\theta$  is uniformly bounded by its initial data, i.e.  $\|\theta\|_{L_{t,x}^\infty} \leq \|\theta_0\|_{L_x^\infty}$ .*

*Proof.* See Section 6.2. □

Finally, we describe our second approach to making sense of the constitutive law for non-decaying solutions, which is to introduce a version of (SQG) in which the constitutive law is relaxed; we call this a Serfati-type constitutive law. For the two-dimensional Euler equations, Serfati proved the existence and uniqueness of solutions with velocity and vorticity in  $L^\infty(\mathbb{R}^2)$  [24] (see also [3] for further exposition on Serfati's work). With vorticity in  $L^\infty$ , the constitutive law (which, for the Euler equations, is the Biot-Savart law) cannot be used to obtain the velocity from vorticity; in its place, Serfati used an integral identity relating the velocity and vorticity for a solution to the Euler equations that applies in the case of bounded vorticity. Three of the present authors and Erickson have used an analogue of the Serfati identity for inviscid SQG [2] to prove local existence of solutions of SQG in uniformly local Sobolev spaces and Hölder spaces. In addition to this analogue of the Serfati integral

identity for SQG, the work [2] also uses a related relaxation of the constitutive law involving the Littlewood-Paley operators  $\dot{\Delta}_j$  (see Section 2 below for details on the Littlewood-Paley blocks). In the present work, we use the Littlewood-Paley relaxation of the constitutive law. In the dissipative case, the new system is

$$\begin{cases} \partial_t \theta + u \cdot \nabla \theta + \nu \Lambda^{2\alpha} \theta = 0 & \text{in } [0, T] \times \mathbb{R}^2, \\ \dot{\Delta}_j u = (\dot{\Delta}_j K) * \theta & \text{in } [0, T] \times \mathbb{R}^2, \forall j \in \mathbb{Z}, \\ \theta|_{t=0} = \theta_0 & \text{in } \mathbb{R}^2, \\ \dot{\Delta}_j u_0 = (\dot{\Delta}_j K) * \theta_0 & \forall j \in \mathbb{Z}, \\ \operatorname{div} u_0 = 0 & \text{in } \mathbb{R}^2. \end{cases} \quad (SSQG)$$

If the initial data  $(\theta_0, u_0)$  satisfies  $(SSQG)_4$ , then a pair  $(\theta, u)$  satisfying (1.3) is called a *mild solution* to the Serfati-type surface quasi-geostrophic system  $(SSQG)$ . Of course, this relaxation allows additional data  $\theta_0 \in L^\infty(\mathbb{R}^2)$  to be treated. That is, if  $\theta_0 \in L^\infty(\mathbb{R}^2)$  is such that there exists  $u_0 \in (L^\infty(\mathbb{R}^2))^2$  for which  $(SSQG)_2$  holds, then we can prove the same results as for  $(SQG)$ . This is the content of the next theorem, which is treated only briefly in the remaining text, as the proof follows immediately from the proofs of the above theorems.

**Theorem 1.6.** *Let  $\theta_0 \in L^\infty(\mathbb{R}^2)$  and  $u_0 \in (L^\infty(\mathbb{R}^2))^2$  satisfy the initial data condition  $\dot{\Delta}_j u_0 = (\dot{\Delta}_j K) * \theta_0$  for all  $j \in \mathbb{Z}$ . Then the conclusions of Theorem 1.2, Theorem 1.3, Theorem 1.4, and Theorem 1.5 hold true for  $(SSQG)$ .*

*Proof.* See Section 6.2. □

The organization of the paper is as follows. In Section 2, we give various definitions and estimates related to the fractional Laplacian  $\Lambda^{2\alpha}$ , the fractional heat kernel, and the kernel  $K$ . In Section 3, we establish various *a priori* continuity and differentiability properties of mild solutions of  $(SQG)$  and  $(SSQG)$ . In Section 4, we prove the existence of a finite-in-time mild solution with  $L^\infty$  data; this is the proof of Theorem 1.2. In Section 5, we prove that  $C^k$ -regularity of the initial data is propagated in time by the mild solution; this is the proof of Theorem 1.3. In Section 6, we prove that given  $C^2$  initial data, the solution can be shown to exist for all time and corresponds to a classical solution; this is the proof of Theorem 1.4. After proving the existence of global-in-time solutions with regular data, we conclude the section by extending solutions with  $L^\infty$  initial data to be global in time, proving Theorem 1.5. Finally, in Appendix A, we prove a technical property of the fractional Laplacian.

## 2. $L^1(\mathbb{R}^2)$ ESTIMATES FOR VARIOUS OPERATORS

**2.1. Littlewood-Paley operators.** We begin with an overview of the Littlewood-Paley operators and some of their properties. There exist two functions  $\chi, \varphi \in \mathcal{S}(\mathbb{R}^d)$  with  $\operatorname{supp} \hat{\chi} \subset \{\xi \in \mathbb{R}^d : |\xi| \leq 1\}$  and  $\operatorname{supp} \hat{\varphi} \subset \{\xi \in \mathbb{R}^d : \frac{1}{2} \leq |\xi| \leq \frac{3}{2}\}$ , such that, setting  $\varphi_j(x) = 2^{jd} \varphi(2^j x)$  for all  $j \in \mathbb{Z}$ ,

$$\hat{\chi} + \sum_{j \geq 0} \hat{\varphi}_j = \hat{\chi} + \sum_{j \geq 0} \hat{\varphi}(2^{-j} \cdot) \equiv 1.$$

For  $n \in \mathbb{Z}$ , define  $\chi_n \in \mathcal{S}(\mathbb{R}^d)$  in terms of its Fourier transform  $\widehat{\chi}_n$ , where  $\widehat{\chi}_n$  satisfies

$$\widehat{\chi}_n(\xi) = \widehat{\chi}(\xi) + \sum_{j=0}^n \widehat{\varphi}_j(\xi)$$

for all  $\xi \in \mathbb{R}^d$ . For  $f \in \mathcal{S}'(\mathbb{R}^d)$ , define the operator  $S_n$  by

$$S_n f = \chi_n * f.$$

Finally, for  $f \in \mathcal{S}'(\mathbb{R}^d)$  and  $j \in \mathbb{Z}$ , define the inhomogeneous Littlewood-Paley operators  $\Delta_j$  by

$$\Delta_j f = \begin{cases} 0, & j < -1 \\ \chi * f, & j = -1 \\ \varphi_j * f, & j \geq 0, \end{cases}$$

and, for all  $j \in \mathbb{Z}$ , define the homogeneous Littlewood-Paley operators  $\dot{\Delta}_j$  by

$$\dot{\Delta}_j f = \varphi_j * f.$$

Note that  $\dot{\Delta}_j f = \Delta_j f$  when  $j \geq 0$ .

**2.2. Kernels for the fractional heat equation.** We first introduce the fractional Laplacian,  $\Lambda^{2\alpha}$ , defined in  $\mathcal{S}'(\mathbb{R}^2)$  via its Fourier transform as follows:

$$\mathcal{F}(\Lambda^{2\alpha} f)(\xi) = -|\xi|^\alpha \mathcal{F}f(\xi). \quad (2.1)$$

In most of this work, we will use the operator  $\Lambda^{2\alpha}$  with the above representation. In Section 6, however, we apply an alternative definition of the fractional Laplacian. Specifically, we let  $\Lambda_I^{2\alpha} f(x)$  denote the singular integral operator defined formally by

$$\Lambda_I^{2\alpha} f(x) := c_\alpha \lim_{\varepsilon \rightarrow 0^+} \int_{|x-y| > \varepsilon} \frac{f(x) - f(y)}{|x-y|^{2+2\alpha}} dy, \quad (2.2)$$

where  $c_\alpha > 0$  is a normalization constant,

$$c_\alpha = \frac{4^\alpha \Gamma(1+\alpha)}{\pi |\Gamma(-\alpha)|}.$$

We define the domain  $\text{Dom}(\Lambda_I^{2\alpha}, L^\infty)$  to be the set of functions  $f \in L^\infty(\mathbb{R}^2)$  for which the above limit exists and is finite for almost every  $x \in \mathbb{R}^2$ . As a consequence of Lemma A.1, the definitions of  $\Lambda^{2\alpha}$  and  $\Lambda_I^{2\alpha}$  coincide on  $C_b^2(\mathbb{R}^2)$ .

We now recall that the fractional heat kernel  $g_\alpha(t, x)$  is the solution to

$$(\partial_t + \nu \Lambda^{2\alpha}) g_\alpha = 0 \quad (2.3)$$

on  $\mathbb{R}^2$  subject to the initial condition  $g_\alpha(0, x) = \delta(x)$ . It is easily seen that the Fourier transform of  $g_\alpha(t, x)$  is given by

$$\widehat{g}_\alpha(t, \xi) = \int_{\mathbb{R}^2} g_\alpha(t, x) e^{-i\xi \cdot x} dx = e^{-\nu |\xi|^{2\alpha} t}. \quad (2.4)$$

Often in what follows, we omit the spatial argument for notational convenience and write  $g_\alpha(t) := g_\alpha(t, \cdot)$ . We denote the fractional heat semigroup acting on  $f \in L^\infty(\mathbb{R}^2)$  by

$$G_\alpha(t) f = g_\alpha(t) * f. \quad (2.5)$$

While it is known that  $g_\alpha(t, x)$  cannot be written in terms of an elementary function, for  $\alpha \in [0, 1]$  and  $t > 0$ ,  $g_\alpha(t, x)$  is a nonnegative and non-increasing radially-symmetric smooth function which satisfies the dilation relation

$$g_\alpha(t, x) = (\nu t)^{-\frac{1}{\alpha}} g_\alpha \left( 1, x(\nu t)^{-\frac{1}{2\alpha}} \right). \quad (2.6)$$

**2.3. The constitutive law.** For  $\theta \in L^\infty(\mathbb{R}^2)$ ,  $K * \theta$  is not well-defined as a convolution. Hence, we cannot obtain a constitutive law in the form  $u = K * \theta$ . To evade this restriction, we consider two modifications of the constitutive law, which we now describe.

For the first modification, we let  $A_{\varepsilon, R}(0)$  denote the annulus centered at the origin with inner radius  $\varepsilon$  and outer radius  $R$ .

Given  $\theta \in L^\infty(\mathbb{R}^2)$ , by (1.1) we mean, more precisely,

$$\begin{aligned} \text{p. v. } K * \theta(x) &:= \lim_{(\varepsilon, R) \rightarrow (0, \infty)} (\mathbb{1}_{A_{\varepsilon, R}(0)} K) * \theta(x) \\ &= \lim_{(\varepsilon, R) \rightarrow (0, \infty)} \int_{\varepsilon < |x-y| < R} K(x-y) \theta(y) dy \end{aligned} \quad (2.7)$$

for any  $x \in \mathbb{R}^2$ .

**Definition 2.1.** We say that  $\text{p. v. } K * \theta(x)$  converges *uniformly over annuli* if

$$\sup_{(r, R) \in (0, \infty)^2} \left\| (\mathbb{1}_{A_{r, R}(0)} K) * f \right\|_{L^\infty} < \infty. \quad (2.8)$$

To motivate the well-definedness of the above constitutive law, we provide a few classes of initial data as examples.

**Remark 2.2.** Define the homogeneous Besov space  $\dot{B}_{p, q}^s(\mathbb{R}^2)$  as in Definition 2.15 of [4]. One has  $\dot{B}_{\infty, 1}^0(\mathbb{R}^2) \subset L^\infty(\mathbb{R}^2)$  (see Proposition 2.39 of [4]). Moreover, as a consequence of the proof of Theorem 1.3 of [22] applied to  $\dot{B}_{\infty, 1}^0(\mathbb{R}^2)$ , one can show that  $\|R_i \theta_0\|_{\dot{B}_{\infty, 1}^0(\mathbb{R}^2)} \leq \|\theta_0\|_{\dot{B}_{\infty, 1}^0(\mathbb{R}^2)}$  for  $\theta_0 \in \dot{B}_{\infty, 1}^0(\mathbb{R}^2)$ . A simple application of Lemma 2.18 below to the Littlewood Paley expansion of  $\theta_0$  reveals that the convergence is uniform over annuli. Hence, defining  $u_0 = \text{p. v. } K * \theta_0$ , the pair  $(\theta_0, u_0)$  satisfies the constitutive law.

**Remark 2.3.** If  $f(x) \in C_c^\infty(\mathbb{R}^2)$  is any bump function, then the function

$$\theta_0(x) = \sum_{j=1}^{\infty} \sum_{i=1}^{\infty} f(x_1 - 2^i, x_2 - 2^j)$$

has a bounded Riesz transform which converges uniformly over annuli. Hence, setting  $u_0 = \text{p. v. } K * \theta_0$ , the pair  $(\theta_0, u_0)$  satisfies the constitutive law. Any variation of this function involving a sufficiently sparse sum of uniformly bounded compactly supported functions also suffices.

**Remark 2.4.** For  $r > 0$  a non-integer, let  $\psi \in C_0^{r+1}(\mathbb{R}^2)$  (that is, the space of functions with  $r+1$  bounded derivatives vanishing at infinity) and set  $u_0 = \nabla^\perp \psi$  and  $\theta_0 = \Lambda \psi$ . Then  $(\theta, u)$  will be a pair satisfying the constitutive law.

In Lemma 2.5, we show that  $K$  and  $g_\alpha$  commute, but only if we assume a kind of uniform convergence over annuli of the principal value integral.



**Lemma 2.5.** *Let  $f \in L^\infty(\mathbb{R}^2)$  and suppose that p. v.  $K * f$  exists, converges uniformly over annuli (see Definition 2.1), and lies in  $L^\infty(\mathbb{R}^2)$ . Then*

$$g_\alpha(t) * (\text{p. v. } K * f)(x) = \text{p. v. } K * (g_\alpha(t) * f)(x). \quad (2.9)$$

*Proof.* Fix  $x \in \mathbb{R}^2$  and write  $\lim_{r,R}$  for the limit in (2.7). Then,

$$\begin{aligned} g_\alpha(t) * (\text{p. v. } K * f)(x) &= \int_{\mathbb{R}^2} \left[ g_\alpha(t, x - y) \lim_{r,R} ((\mathbb{1}_{A_{r,R}(0)} K) * f)(y) \right] dy \\ &= \int_{\mathbb{R}^2} \lim_{r,R} \left[ g_\alpha(t, x - y) ((\mathbb{1}_{A_{r,R}(0)} K) * f)(y) \right] dy \\ &= \lim_{r,R} \int_{\mathbb{R}^2} \left[ g_\alpha(t, x - y) ((\mathbb{1}_{A_{r,R}(0)} K) * f)(y) \right] dy \\ &= \lim_{r,R} (g_\alpha(t) * ((\mathbb{1}_{A_{r,R}(0)} K) * f))(x) \\ &= \lim_{r,R} ((\mathbb{1}_{A_{r,R}(0)} K) * (g_\alpha(t) * f))(x) \\ &= \text{p. v. } K * (g_\alpha(t) * f). \end{aligned}$$

Above, we used (2.8) with  $g_\alpha(t) \in L^1(\mathbb{R}^2)$  to take the limit outside of the integral via the Dominated Convergence Theorem. We were able to commute the order of convolution before taking the limit, using that  $g_\alpha(t)$  and  $\mathbb{1}_{r,R}(0)K$  are in  $L^1$  while  $f \in L^\infty$ .  $\square$

In Theorem 1.6, we take a different approach to the constitutive law that avoids using the principal value integral of  $K$ . We consider, instead, a constitutive law in the form  $\dot{\Delta}_j u = (\dot{\Delta}_j K) * \theta$ , taking advantage of the following simple lemma:

**Lemma 2.6.** *For all  $j \in \mathbb{Z}$ ,  $\dot{\Delta}_j K \in \mathcal{S}(\mathbb{R}^2)$ .*

*Proof.* Taking the Fourier transform,

$$\mathcal{F}(\dot{\Delta}_j K)(\xi) = \mathcal{F}(\varphi_j * K)(\xi) = \widehat{\varphi}_j(\xi) \widehat{K}(\xi) = -i \widehat{\varphi}_j(\xi) \frac{\xi^\perp}{|\xi|}.$$

Because  $\widehat{\varphi}_j$  is in  $C^\infty(\mathbb{R}^2)$  and supported in an annulus,  $\mathcal{F}(\dot{\Delta}_j K)$  belongs to  $\mathcal{S}(\mathbb{R}^2)$ , and hence so does  $\dot{\Delta}_j K$ .  $\square$

**2.4. Convolution bounds.** We will use Lemma 2.9 below to bound the integrands appearing in our formulation of the mild solution to (SQG). The proof of Lemma 2.9 relies on the following lemma from [26]:

**Lemma 2.7** ([26]). *Fix  $\varepsilon \in [0, 1)$  and an integer  $N \geq 1$ , and assume  $f$  is a differentiable function on  $\mathbb{R}^d$  which satisfies*

- (1)  $|f(x)| \leq C(1 + |x|)^{-d-N+\varepsilon}$ ,
- (2)  $|D^\beta f(x)| \leq C(1 + |x|)^{-d-N-1+\varepsilon}$  for all  $|\beta| = 1$ ,
- (3)  $\int x^\beta f(x) dx = 0$  for all  $|\beta| < N$ .

*Then for each  $i$ ,  $1 \leq i \leq d$ ,*

$$\left| \text{p. v. } \int_{\mathbb{R}^2} K^i(x - y) f(y) dy \right| \leq C(1 + |x|)^{-d-N+\varepsilon+\delta}$$

*for every  $\delta$  satisfying  $0 < \delta < 1 - \varepsilon$ . If, in addition,  $f \in \mathcal{S}(\mathbb{R}^2)$  then the same bound applies to  $K * f$ .*



*Proof.* This follows from Theorem 3.2 of [26].  $\square$

We will utilize estimates on the fractional heat kernel to bound the mild solution to (SQG). In order to derive estimates on  $\nabla G_\alpha$  as in (1.3), we first examine the derivatives of  $g_\alpha$  at  $t = 1$ .

**Lemma 2.8.** *Let  $\alpha > 0$  then the  $k^{\text{th}}$ -order derivatives of the fractional heat kernel are in  $L_x^1(\mathbb{R}^2)$  for all  $k \in \mathbb{N}$ . Specifically,*

$$\|\nabla^k g_\alpha(1, x)\|_{L_x^1} < \infty \quad \text{and} \quad \|x \cdot \nabla^2 g_\alpha(1, x)\|_{L_x^1} < \infty.$$

*Proof.* Using the Bochner's Relation (see Corollary on page 72 of [25]), we have

$$\frac{\partial}{\partial x_j} g_\alpha^d(1, x) = -\frac{x_j}{2\pi} g_\alpha^{d+2}(1, \tilde{x}), \quad (2.10)$$

where  $g_\alpha^d(t, x)$  is the heat kernel in  $d$  dimensions and  $\tilde{x} = (x_1, x_2, \dots, x_d, 0, 0)$ . We also take note of the well-known estimate (see [5]),

$$g_\alpha^d(1, x) \lesssim \min\{1, |x|^{-d-2\alpha}\}. \quad (2.11)$$

It then follows,

$$\left| \nabla^k g_\alpha(1, x) \right| \leq \frac{|x|^k}{2\pi} g_\alpha^{d+2k}(1, \tilde{x}) \lesssim |x|^k \min\{1, |x|^{-d-2k-2\alpha}\} = \min\{|x|^k, |x|^{-d-k-2\alpha}\}, \quad (2.12)$$

which is clearly integrable. By the same argument, the second estimate follows easily.  $\square$

We are now in a position to show that the  $L_x^1$ -norms of spatial derivatives of  $g_\alpha$  decay in time, and that convolution with  $K$  preserves this decay.

**Lemma 2.9.** *For  $\alpha > 0$  and  $\beta$  a multi-index with  $k := |\beta|$  and  $j = 1, 2$ , we have*

$$\begin{cases} \|D^\beta g_\alpha(t)\|_{L^1} \leq C(k, \nu, \alpha) t^{-k/(2\alpha)} & \text{for all } \beta, \\ \|K^j * D^\beta g_\alpha(t)\|_{L^1} \leq C(k, \nu, \alpha) t^{-k/(2\alpha)} & \text{for all } k \text{ odd.} \end{cases}$$

*Proof.* We will use the dilation relation (2.6) to manipulate the norm of  $D^\beta g_\alpha(t)$  and apply the chain rule (see also Lemma 6 of [23] for an alternate proof). We write

$$\begin{aligned} \|D^\beta g_\alpha(t)\|_{L_x^1} &= \int_{\mathbb{R}^2} |D^\beta g_\alpha(t, x)| dx = \int_{\mathbb{R}^2} \left| D^\beta \left( t^{-1/\alpha} g_\alpha \left( 1, x t^{-\frac{1}{2\alpha}} \right) \right) \right| dx \\ &= \int_{\mathbb{R}^2} \left| t^{-(\frac{1}{\alpha} + \frac{k}{2\alpha})} (D^\beta g_\alpha)(1, x t^{-\frac{1}{2\alpha}}) \right| dx. \end{aligned}$$

Finally, the substitution  $u = x t^{-\frac{1}{2\alpha}}$  yields

$$\|D^\beta g_\alpha(t)\|_{L_x^1} = t^{-k/(2\alpha)} \|D^\beta g_\alpha(1)\|_{L_x^1}.$$

Invoking Lemma 2.8, we have  $D^\beta g_\alpha(1) \in L_x^1(\mathbb{R}^2)$ . To prove the second bound in Lemma 2.9, we use the dilation relation (2.6) to write

$$\begin{aligned} K^j * D^\beta g_\alpha(t, x) &= K^j * D^\beta \left( t^{-1/\alpha} g_\alpha(1, x t^{-\frac{1}{2\alpha}}) \right) \\ &= t^{-(\frac{1}{\alpha} + \frac{k}{2\alpha})} \text{p. v.} \int_{\mathbb{R}^2} K^j(z) (D^\beta g_\alpha(1)) \left( t^{-\frac{1}{2\alpha}} (x - z) \right) dz \\ &= t^{-(\frac{1}{\alpha} + \frac{k}{2\alpha})} (K^j * D^\beta g_\alpha(1)) \left( x t^{-\frac{1}{2\alpha}} \right). \end{aligned} \quad (2.13)$$

To get the last equality, we used the scaling property  $K(z) = b^2 K(bz)$  for any  $b > 0$  and the integral substitution  $u = t^{-\frac{1}{2\alpha}} z$ . Applying the substitution  $u = t^{-\frac{1}{2\alpha}} x$  again then gives

$$\left\| K^j * D^\beta g_\alpha(t) \right\|_{L_x^1} = t^{-k/(2\alpha)} \left\| K^j * D^\beta g_\alpha(1) \right\|_{L_x^1}. \quad (2.14)$$

By symmetry of  $g_\alpha$  and the fact that symmetry is preserved under the Fourier transform, when  $k = |\beta|$  is odd, we see that  $D^\beta g_\alpha(1)$  satisfies the hypotheses of Lemma 2.7, including the critical moment condition in (3) for  $N = 1$ , i.e.,

$$\int_{\mathbb{R}^2} D^\beta g_\alpha(1) dx = 0. \quad (2.15)$$

The bound for  $K^j * D^\beta g_\alpha(t)$  follows.  $\square$

**Remark 2.10.** Notice that for  $\Lambda g_\alpha(t, x)$ , the above argument holds to produce the bound

$$\|\Lambda g_\alpha(t, x)\|_{L_x^1} \leq C(\nu, \alpha) t^{-\frac{1}{2\alpha}}.$$

**Remark 2.11.** In fact, the estimate (2.9) holds for  $K^j * D^\beta g_\alpha(t)$  for even  $k := |\beta|$  as a result of Corollary 3.6.

When invoking the fractional heat equation property (2.3), it will also be necessary to have estimates available for the fractional Laplacian applied to  $g_\alpha$ .

**Lemma 2.12.** *For  $\alpha > 0$ , there exists a constant  $C(\nu, \alpha) > 0$  such that*

$$\begin{cases} \|\Lambda^{2\alpha} \nabla g_\alpha(t)\|_{L_x^1} \leq C(\nu, \alpha) t^{-(1+\frac{1}{2\alpha})}, \\ \|K * \Lambda^{2\alpha} \nabla g_\alpha(t)\|_{L_x^1} \leq C(\nu, \alpha) t^{-(1+\frac{1}{2\alpha})}. \end{cases}$$

*Proof.* First, we devise a dilation law for the tensor of  $k^{\text{th}}$ -derivatives. Observe for  $k \in \mathbb{N}$ ,

$$\begin{aligned} \nabla^k g_\alpha(t, x) &= \nabla^k \left[ t^{-1/\alpha} g_\alpha(1, xt^{-\frac{1}{2\alpha}}) \right] = t^{-1/\alpha} \nabla^k g_\alpha(1, xt^{-\frac{1}{2\alpha}}) \\ &= t^{-\frac{2+k}{2\alpha}} (\nabla^k g_\alpha)(1, xt^{-\frac{1}{2\alpha}}). \end{aligned} \quad (2.16)$$

We evaluate the norm of  $\Lambda^{2\alpha} \nabla g_\alpha(t)$  using the fractional heat property (2.3) and the dilation relation (2.16) for  $k = 1$ . We write

$$\begin{aligned} \Lambda^{2\alpha} \nabla g_\alpha(t, x) &= -\frac{1}{\nu} \frac{\partial}{\partial t} \nabla g_\alpha(t, x) = -\frac{1}{\nu} \frac{\partial}{\partial t} \left[ t^{-\frac{3}{2\alpha}} (\nabla g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) \right] \\ &= -\frac{1}{\nu} \left[ -\frac{3}{2\alpha} t^{-(\frac{3}{2\alpha}+1)} (\nabla g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) - \frac{1}{2\alpha} t^{-(\frac{3}{2\alpha}+\frac{1}{2\alpha}+1)} x \cdot (\nabla^2 g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) \right]. \end{aligned} \quad (2.17)$$

We use (2.17) to compute the  $L_x^1$ -norm of  $\Lambda^{2\alpha} \nabla g_\alpha(t)$ , giving

$$\begin{aligned} &\int_{\mathbb{R}^2} |\Lambda^{2\alpha} \nabla g_\alpha(t, x)| dx \\ &= \frac{1}{\nu} \int_{\mathbb{R}^2} \left| -\frac{3t^{-(\frac{3}{2\alpha}+1)}}{2\alpha} \nabla g_\alpha(1, xt^{-\frac{1}{2\alpha}}) - \frac{t^{-(\frac{3}{2\alpha}+\frac{1}{2\alpha}+1)}}{2\alpha} x \cdot (\nabla^2 g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) \right| dx \\ &\leq \frac{3}{2\alpha\nu} t^{-1} \int_{\mathbb{R}^2} |\nabla g_\alpha(t, x)| dx + \frac{1}{2\alpha\nu} t^{-(\frac{3}{2\alpha}+\frac{1}{2\alpha}+1)} \int_{\mathbb{R}^2} |x \cdot (\nabla^2 g_\alpha)(1, xt^{-\frac{1}{2\alpha}})| dx. \end{aligned} \quad (2.18)$$

We apply the integral substitution  $u = xt^{-\frac{1}{2\alpha}}$  to the second term of (2.18), which yields

$$\begin{aligned} \frac{1}{2\alpha\nu} t^{-(\frac{3}{2\alpha} + \frac{1}{2\alpha} + 1)} \int_{\mathbb{R}^2} \left| x \cdot (\nabla^2 g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) \right| dx \\ = \frac{1}{2\alpha\nu} t^{-(\frac{1}{2\alpha} + 1)} \int_{\mathbb{R}^2} \left| x \cdot (\nabla^2 g_\alpha)(1, x) \right| dx. \end{aligned} \quad (2.19)$$

The integral in (2.19) is bounded by Lemma 2.8. Using Lemma 2.9, we can further simplify the first term of (2.17). Indeed,

$$\frac{3}{2\alpha\nu} t^{-1} \int_{\mathbb{R}^2} |\nabla g_\alpha(t, x)| dx \leq \frac{3}{2\alpha\nu} C t^{-(\frac{1}{2\alpha} + 1)}. \quad (2.20)$$

One can then combine (2.19) and (2.20) to conclude that

$$\int_{\mathbb{R}^2} |\Lambda^{2\alpha} \nabla g_\alpha(t, x)| dx \leq C(\nu, \alpha) t^{-(1 + \frac{1}{2\alpha})}.$$

We now prove the second inequality of Lemma 2.12. For  $j = 1, 2$ , we expand  $K^j * \Lambda^{2\alpha} \nabla g_\alpha(t)$  using (2.6). We write

$$\begin{aligned} K^j * \Lambda^{2\alpha} \nabla g_\alpha(t, x) = -\frac{1}{\nu} K^j * \left[ -\frac{3}{2\alpha} t^{-(\frac{3}{2\alpha} + 1)} \nabla g_\alpha(1, xt^{-\frac{1}{2\alpha}}) \right. \\ \left. - \frac{1}{2\alpha} t^{-(\frac{3}{2\alpha} + \frac{1}{2\alpha} + 1)} x \cdot (\nabla^2 g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) \right]. \end{aligned}$$

Therefore,

$$\begin{aligned} \|K^j * \Lambda^{2\alpha} \nabla g_\alpha(t, x)\|_{L_x^1} &\leq \frac{3}{2\alpha\nu} t^{-(\frac{3}{2\alpha} + 1)} \left\| \underbrace{K^j * \nabla g_\alpha(1, xt^{-\frac{1}{2\alpha}})}_{=: [I]} \right\|_{L_x^1} \\ &\quad + \frac{1}{2\alpha\nu} t^{-(\frac{3}{2\alpha} + \frac{1}{2\alpha} + 1)} \left\| \underbrace{K^j * \left( x \cdot (\nabla^2 g_\alpha)(1, xt^{-\frac{1}{2\alpha}}) \right)}_{=: [II]} \right\|_{L_x^1}. \end{aligned} \quad (2.21)$$

For the first integral of (2.21), using  $K(x) = b^2 K(bx)$  for  $b > 0$  and the integral substitution  $u = zt^{-\frac{1}{2\alpha}}$ , we have

$$\begin{aligned} [I] &= \text{p. v.} \int_{\mathbb{R}^2} K^j(z) \nabla g_\alpha \left( 1, (x - z)t^{-\frac{1}{2\alpha}} \right) dz \\ &= t^{-1/\alpha} \text{p. v.} \int_{\mathbb{R}^2} K^j(z t^{-1/(\alpha)}) \nabla g_\alpha \left( 1, (x - z)t^{-\frac{1}{2\alpha}} \right) dz \\ &= \text{p. v.} \int_{\mathbb{R}^2} K^j(z) \nabla g_\alpha \left( 1, xt^{-\frac{1}{2\alpha}} - z \right) dz \\ &= (K^j * \nabla g_\alpha(1)) (xt^{-\frac{1}{2\alpha}}) \end{aligned}$$

Using the integral substitution  $u = xt^{-\frac{1}{2\alpha}}$ , we arrive at

$$\begin{aligned} \frac{3}{2\alpha\nu} t^{-(\frac{3}{2\alpha} + 1)} \|[I]\|_{L_x^1} &= \frac{3}{2\alpha\nu} t^{-(\frac{3}{2\alpha} + 1)} \left\| (K^j * \nabla g_\alpha(1)) (xt^{-\frac{1}{2\alpha}}) \right\|_{L_x^1} \\ &\leq \frac{3}{2\alpha\nu} t^{-(\frac{1}{2\alpha} + 1)} \|K * \nabla g_\alpha(1, x)\|_{L_x^1}. \end{aligned} \quad (2.22)$$

By Lemma 2.9,  $\|[I](x)\|_{L_x^1}$  is bounded.

For  $[II]$ , as in the proof of Lemma 2.9, we use the scaling property  $K(x) = b^2 K(bx)$  for  $b = t^{-\frac{1}{2\alpha}}$  and the integral substitution  $u = zt^{-\frac{1}{2\alpha}}$  to write

$$\begin{aligned} [II] &= \text{p.v.} \int_{\mathbb{R}^2} K^j(z) \left[ (x-z) \cdot (\nabla^2 g_\alpha) \left( 1, (x-z)t^{-\frac{1}{2\alpha}} \right) \right] dz \\ &= t^{-\frac{1}{2\alpha}} \text{p.v.} \int_{\mathbb{R}^2} K^j(t^{-\frac{1}{2\alpha}}) \left[ t^{-\frac{1}{2\alpha}} \cdot (\nabla^2 g_\alpha) \left( 1, (x-z)t^{-\frac{1}{2\alpha}} \right) \right] dz \\ &= t^{\frac{1}{2\alpha}} \text{p.v.} \int_{\mathbb{R}^2} K^j(z) \left[ (xt^{-\frac{1}{2\alpha}} - z) \cdot (\nabla^2 g_\alpha) \left( 1, (xt^{-\frac{1}{2\alpha}} - z) \right) \right] dz \\ &= t^{\frac{1}{2\alpha}} K^j * (x \cdot \nabla^2 g_\alpha(1)) (t^{-\frac{1}{2\alpha}} x). \end{aligned}$$

Observe that  $x \cdot (\nabla^2 g_\alpha)$  is an odd function via a standard symmetric argument involving the Fourier transform, and thus satisfies the conditions of Lemma 2.7. Hence,

$$\begin{aligned} \|[II]\|_{L_x^1} &= t^{\frac{1}{2\alpha}} \left\| K^j * (x \cdot \nabla^2 g_\alpha(1)) (t^{-\frac{1}{2\alpha}} x) \right\|_{L_x^1} \\ &= t^{\frac{3}{2\alpha}} \left\| K^j * (x \cdot \nabla^2 g_\alpha(1)) (x) \right\|_{L_x^1} < \infty. \end{aligned} \tag{2.23}$$

In the final line above, we use the  $L_x^1$  boundedness of  $K^j * (x \cdot \nabla^2 g_\alpha(1)) (x)$  from Lemma 2.7. Thus, we can substitute the terms (2.23) and (2.22) into (2.21). We conclude

$$\|K^j * \Lambda^{2\alpha} \nabla g_\alpha(t, x)\|_{L_x^1} \leq C(\alpha, \nu) t^{-(1+\frac{1}{2\alpha})} (\|[I]\|_{L_x^1} + \|[II]\|_{L_x^1}) < \infty,$$

as desired.  $\square$

Having proven that the expression  $K * \nabla G_\alpha$  is well-defined, we are now in a position to clarify the interpretation of the mild formulation of a solution. Recalling (1.3), we defined a mild solution as a pair of functions  $(\theta, u)$  which satisfy the coupled equations:

$$\begin{aligned} \theta(t, x) &= G_\alpha(t) \theta_0(x) - \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds, \\ u(t, x) &= G_\alpha(t) u_0(x) - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta u)(s, x) ds. \end{aligned} \tag{2.24}$$

**Definition 2.13.** We interpret the integrand in (2.24)<sub>2</sub> as follows. For any  $t > 0$  and vector function  $p : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , define

$$(K * \nabla G_\alpha(t)) \cdot p := (K * \nabla g_\alpha(t)) * \cdot p,$$

where  $K * \nabla g_\alpha(t)$  is the 2-tensor, or  $2 \times 2$  matrix,

$$\begin{bmatrix} K^1 * \partial_{x_1} g_\alpha(t) & K^2 * \partial_{x_1} g_\alpha(t) \\ K^1 * \partial_{x_2} g_\alpha(t) & K^2 * \partial_{x_2} g_\alpha(t) \end{bmatrix}, \tag{2.25}$$

and the  $\cdot$  product is given by

$$(K * \nabla g_\alpha(t)) \cdot p(s) = \begin{bmatrix} K^1 * \partial_{x_1} g_\alpha(t) * p_1 + K^2 * \partial_{x_1} g_\alpha(t) * p_2 \\ K^1 * \partial_{x_2} g_\alpha(t) * p_1 + K^2 * \partial_{x_2} g_\alpha(t) * p_2 \end{bmatrix}.$$

Each component of the matrix in (2.25), by Lemma 2.9, lies in  $L^1(\mathbb{R}^2)$ . For any  $\varphi \in (L^\infty(\mathbb{R}^2))^2$ , we then define  $(K * \nabla g_\alpha(t)) \cdot \varphi(x)$  as the convolution of an  $L^1$  matrix-field with an  $L^\infty$ -vector field, resulting in an  $L^\infty$ -vector field, whose  $i^{th}$  component,  $i = 1, 2$ , is given by  $\sum_{j=1,2} (K^j * \partial_i g_\alpha(t)) * \varphi_j$ .

It will be necessary to compute the time derivative of  $K * \nabla G_\alpha(t)$  to prove properties about the time-regularity of solutions to (SQG), as we do in Lemma 2.14.

**Lemma 2.14.** *Let  $\alpha > 0$ .  $K$  and  $\partial_t$  commute, in the sense that, for all  $t > 0$ ,*

$$\frac{\partial}{\partial t}(K * \nabla g_\alpha(t)) = -\nu K * \Lambda^{2\alpha} \nabla g_\alpha(t) \in L^1(\mathbb{R}^2).$$

First, we prove a lemma, which we will use in the proof of Lemma 2.14.

**Lemma 2.15.** *Let  $f, \nabla f \in C^\infty(\mathbb{R}^2) \cap L^1(\mathbb{R}^2) \cap L^\infty(\mathbb{R}^2)$ . Then, with  $\psi$  as in (1.2),*

$$\begin{aligned} \text{p.v. } K * f &= \psi * \nabla^\perp f, \\ \mathcal{F}(\text{p.v. } K * f) &= \widehat{K} \widehat{f}. \end{aligned} \tag{2.26}$$

*Proof.* First observe that  $\psi$  is locally integrable. By the assumption on  $f$ , we have  $\psi * \partial_j f$  exists,  $j = 1, 2$ , because

$$\psi * \partial_j f = (\mathbb{1}_{B_1(0)} \psi) * \partial_j f + (\mathbb{1}_{B_1(0)^c} \psi) * \partial_j f, \tag{2.27}$$

and the first term is an  $L^1$  function convolved with an  $L^\infty$  function, while the second part is an  $L^\infty$  function convolved with an  $L^1$  function. Hence,

$$\psi * \partial_j f(x) = \lim_{\varepsilon \rightarrow 0} I_\varepsilon(x), \quad I_\varepsilon(x) := \int_{B_\varepsilon(x)^c} \psi(x-y) \partial_j f(y) dy.$$

Integrating by parts, using that  $\partial_{y_j} \psi(x-y) = -\partial_j \psi(x-y)$ , and considering the orientation of the boundary,

$$I_\varepsilon(x) = \int_{B_\varepsilon(x)^c} \partial_j \psi(x-y) f(y) dy - \int_{\partial B_\varepsilon(x)} f(y) \psi(x-y) n_y^j ds(y) =: I_1(x) + I_2(x).$$

On the boundary,  $\psi(x-y) = -(1/2\pi)\varepsilon^{-1}$ , so

$$I_2(x) = \frac{1}{2\pi\varepsilon} \int_{\partial B_\varepsilon(x)} ((f(y) - f(x)) n_y^j ds(y) + \frac{1}{2\pi\varepsilon} f(x) \int_{\partial B_\varepsilon(x)} n_y^j ds(y).$$

The second term integrates to zero, so

$$|I_2(x)| \leq \frac{1}{2\pi\varepsilon} 2\pi\varepsilon \sup_{y \in \partial B_\varepsilon(x)} |f(x) - f(y)| \rightarrow 0 \text{ as } \varepsilon \rightarrow 0,$$

because  $f$  is continuous. Hence,  $I_\varepsilon \rightarrow \text{p.v. } \partial_j \psi * f$  as  $\varepsilon \rightarrow 0$ , giving (2.26)<sub>1</sub>.

From (2.26)<sub>1</sub> with (2.27),  $K = (-\partial_2 \psi, \partial_1 \psi) = \nabla^\perp \psi$ , and using the linearity of the Fourier transform,

$$\mathcal{F}(\text{p.v. } K * f) = \widehat{\psi \nabla^\perp f} = i \xi^\perp \widehat{\psi} \widehat{f} = \widehat{\nabla^\perp \psi} \widehat{f} = \widehat{K} \widehat{f},$$

giving (2.26)<sub>2</sub>. □

**Remark 2.16.** We can also write the first conclusion of Lemma 2.15 as  $\text{p.v. } K^j * f = (-1)^j \psi * \partial_{3-j} \psi * f$ .

**Proof of Lemma 2.14.** Write  $\langle \cdot, \cdot \rangle$  for the pairing between  $\mathcal{D}'((0, T) \times \mathbb{R}^2)$  and  $\mathcal{D}((0, T) \times \mathbb{R}^2)$ . Then

$$\left\langle \frac{\partial}{\partial t}(K * \nabla g_\alpha), \varphi \right\rangle = - \left\langle K * \nabla g_\alpha, \frac{\partial}{\partial t} \varphi \right\rangle.$$

By Lemma 2.9,  $K * \nabla g_\alpha \in L^1(\mathbb{R}^2)$ . Also,  $g_\alpha, \nabla g_\alpha \in C^\infty(\mathbb{R}^2) \cap L^1(\mathbb{R}^2) \cap L^\infty(\mathbb{R}^2)$ , since the Fourier transform of  $g_\alpha$  has spatial exponential decay (see (2.4)). Thus the pairing above is an actual integral of continuous functions, and we have, using (2.3) and Lemma 2.15,

$$\begin{aligned}
\left\langle \frac{\partial}{\partial t}(K * \nabla g_\alpha), \varphi \right\rangle &= - \int_0^T \int_{\mathbb{R}^2} (K * \nabla g_\alpha)(t, x) \frac{\partial}{\partial t} \varphi(t, x) dt dx \\
&= - \int_0^T \left( K * \nabla g_\alpha, \frac{\partial \varphi}{\partial t} \right) dt = - \int_0^T \left( \mathcal{F}(K * \nabla g_\alpha), \mathcal{F}\left(\frac{\partial \varphi}{\partial t}\right) \right) dt \\
&= - \int_0^T \left( \widehat{K} \widehat{\nabla g_\alpha}, \frac{\partial}{\partial t} \widehat{\varphi}(t) \right) dt = - \int_{\mathbb{R}^2} \int_0^T \widehat{K}(\xi) \widehat{\nabla g_\alpha}(t, \xi) \frac{\partial}{\partial t} \widehat{\varphi}(t, \xi) dt d\xi \\
&= \int_{\mathbb{R}^2} \int_0^T \widehat{K}(\xi) \frac{\partial}{\partial t} \widehat{\nabla g_\alpha}(t, \xi) \widehat{\varphi}(t, \xi) dt d\xi \\
&= \int_{\mathbb{R}^2} \int_0^T \widehat{K}(\xi) \mathcal{F}\left(\nabla \frac{\partial}{\partial t} g_\alpha\right)(t, \xi) \widehat{\varphi}(t, \xi) dt d\xi \\
&= -\nu \int_{\mathbb{R}^2} \int_0^T \widehat{K}(\xi) \mathcal{F}(\Lambda^{2\alpha} \nabla g_\alpha)(t, \xi) \widehat{\varphi}(t, \xi) dt d\xi \\
&= -\nu \int_{\mathbb{R}^2} \int_0^T \mathcal{F}(K * \Lambda^{2\alpha} \nabla g_\alpha)(t, \xi) \widehat{\varphi}(t, \xi) dt d\xi \\
&= -\nu \int_0^T (K * \Lambda^{2\alpha} \nabla g_\alpha(t, \xi), \varphi(t, \xi)) dt = \langle -\nu K * \Lambda^{2\alpha} \nabla g_\alpha, \varphi \rangle.
\end{aligned}$$

Above, we applied the Fubini-Tonelli theorem to interchange the order of integration.  $\square$

When showing that the constitutive law holds for the mild formulation, we will use the limited form of commutativity of p.v.  $K$  and  $\nabla g_\alpha$  given in Lemma 2.5. We will also need a form of associativity, as we will see in the proof of Proposition 3.9; for this, we rely on a lemma similar to Lemma 2.7 to provide a dominating  $L_x^1$  bound.

**Lemma 2.17** ([26]). *For any function  $f$  satisfying the conditions of Lemma 2.7 there exists a nonnegative function  $F \in L^1(\mathbb{R}^d)$  such that for all  $x \in \mathbb{R}^2$ ,*

$$\left| (\mathbb{1}_{A_{r,R}(0)} K^j) * f(x) \right| \leq F(x), \quad 1 \leq j \leq d,$$

*holds uniformly over  $0 < r \leq R < \infty$ .*

*Proof.* This follows from a straightforward adaptation of the proof of Theorem 3.2 of [26], which gives the result (as an explicit decay bound) for  $K^j$ .  $\square$

**Lemma 2.18.** *Let  $\alpha > 0$ . There exists a constant  $C = C(\nu, \alpha)$  such that for all  $0 < r < R < \infty$ ,*

$$\left\| (\mathbb{1}_{A_{r,R}(0)} K^j) * \partial_i g_\alpha(t) \right\|_{L^1} \leq C t^{-1/(2\alpha)}.$$

*Proof.* The proof is a simple adaptation of Lemma 2.9, using the equality  $\mathbb{1}_{A_{r,R}(0)}(az) = \mathbb{1}_{A_{r/a,R/a}(0)}(z)$  for any  $a > 0$ , and using the uniform bound in Lemma 2.17 in place of Lemma 2.7.  $\square$

## 3. PROPERTIES OF MILD SOLUTIONS TO (SQG) AND (SSQG)

In this section, we establish some properties of mild solutions to (SQG) and (SSQG) as in Definition 1.1.

Our formulation of a mild solution does not fully incorporate a form of the constitutive law; however, in Proposition 3.8, we show that if the constitutive law holds initially, then it will hold for all time. In Proposition 3.10, we motivate Definition 1.1 more fully by showing that a sufficiently regular mild solution is, in fact, a classical solution. When proving the pointwise regularity of the solution, we must establish that the divergence-free condition on  $u$  holds for all time if  $\operatorname{div} u_0 = 0$ . To that end, we need the following technical result.

**Lemma 3.1.** *Suppose that  $f \in (L^1([0, T] \times \mathbb{R}^2))^2$  with  $\operatorname{div} f(t) = 0$  in  $\mathcal{S}'(\mathbb{R}^2)$  for all  $t \in [0, T]$ . Then for all  $\psi \in L^\infty([0, T] \times \mathbb{R}^2)$  and  $t \in [0, T]$ ,*

$$\operatorname{div} \int_0^t (f * \psi)(s, x) ds = 0 \text{ in } \mathcal{S}'(\mathbb{R}^2).$$

*Proof.* For fixed  $t \in [0, T]$ , let  $I(x) := \int_0^t (f * \psi)(s, x) ds$ . Note that  $I$  is in  $(L^\infty(\mathbb{R}^2))^2$ . Then for any  $\varphi \in \mathcal{S}(\mathbb{R}^2)$  we can apply the Tonelli-Fubini theorem to give,

$$\begin{aligned} (\operatorname{div} I, \varphi) &= -(I, \nabla \varphi) = - \int_0^t \int_{\mathbb{R}^2} (f * \psi)(s, x) \cdot \nabla \varphi(x) dx ds \\ &= - \int_0^t \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} f(s, x - y) \psi(s, y) \cdot \nabla \varphi(x) dy dx ds \\ &= - \int_0^t \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} f(s, x - y) \cdot \nabla \varphi(x) \psi(s, y) dx dy ds \\ &= \int_0^t \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} (\operatorname{div} f)(s, x - y) \varphi(x) \psi(s, y) dx dy ds \\ &= \int_0^t (\operatorname{div} f(s) * \tilde{\varphi}, \tilde{\psi}(s)) ds = 0. \end{aligned} \quad \square$$

Here,  $\tilde{\varphi}$  and  $\tilde{\psi}$  are reflected versions of  $\varphi$  and  $\psi$ , namely  $\tilde{\varphi}(x) = \varphi(-x)$  and  $\tilde{\psi}(y) = \psi(-y)$ .

**3.1. Continuity in space.** We turn now, in Proposition 3.2, to showing that mild solutions gain some Hölder regularity immediately after time zero.

**Proposition 3.2.** *Suppose that  $(\theta, u)$  is a mild solution to (SQG) on  $[0, T]$ . If  $\alpha > 1/2$  then for all  $t \in (0, T]$  and  $0 < \gamma < 2\alpha - 1$ ,  $(\theta(t, \cdot), u(t, \cdot)) \in (C^\gamma(\mathbb{R}^2))^3$ .*

We first establish a series of lemmas.

**Lemma 3.3.** *Let  $f \in L^1(\mathbb{R}^2) \cap C^\gamma(\mathbb{R}^2)$  for some  $\gamma \in (0, 1)$  and  $g \in L^\infty(\mathbb{R}^2)$ . Then*

$$\|f * g\|_{C^\gamma} \leq \|f\|_{\tilde{C}^\gamma} \|g\|_{L^\infty},$$

where

$$\|f\|_{\tilde{C}^\gamma} := \sup_{x \neq y} \int_{\mathbb{R}^2} \frac{|f(x - z) - f(y - z)|}{|x - y|^\gamma} dz.$$

*Proof.* Let  $x, y \in \mathbb{R}^2$ . Then

$$\frac{|f * g(x) - f * g(y)|}{|x - y|^\gamma} = \left| \int_{\mathbb{R}^2} \frac{f(x - z) - f(y - z)}{|x - y|^\gamma} g(z) dz \right| \leq \|f\|_{\tilde{C}^\gamma} \|g\|_{L^\infty}. \quad \square$$



Applying Lemma 3.3 to obtain Proposition 3.2 comes down to showing that  $g_\alpha(t)$  and p.v.  $K * \nabla g_\alpha(t)$  have a  $\tilde{C}^\gamma$  seminorm that scales sufficiently well in time.

**Lemma 3.4.** *Let  $F \in \tilde{C}^\gamma$ ,  $\gamma \in (0, 1)$ , and for any  $r > 0$  define  $F_r(\cdot) = r^{2a} F(r^a \cdot)$  for some fixed  $a > 0$ . Then  $F_r \in \tilde{C}^\gamma$  with*

$$\|F_r\|_{\tilde{C}^\gamma} \leq r^{a\gamma} \|F\|_{\tilde{C}^\gamma}.$$

*Proof.* For any distinct  $x, y \in \mathbb{R}^2$ ,

$$\begin{aligned} \int_{\mathbb{R}^2} \frac{|F_r(x-z) - F_r(y-z)|}{|x-y|^\gamma} dz &= r^{2a} \int_{\mathbb{R}^2} \frac{|F(r^a(x-z)) - F(r^a(y-z))|}{|r^a x - r^a y|^\gamma} r^{a\gamma} dz \\ &= r^{2a+a\gamma} r^{-2a} \int_{\mathbb{R}^2} \frac{|F(r^a x - w) - F(r^a y - w)|}{|r^a x - r^a y|^\gamma} dw \leq r^{a\gamma} \|F\|_{\tilde{C}^\gamma}. \end{aligned} \quad \square$$

**Lemma 3.5.** *If  $f \in W^{1,1}(\mathbb{R}^2)$  then for all  $\gamma \in (0, 1)$ , we have  $f \in \tilde{C}^\gamma$  with  $\|f\|_{\tilde{C}^\gamma} \leq 2 \|f\|_{W^{1,1}}$ .*

*Proof.* Assume first that  $|x-y| \leq 1$  with  $x \neq y$ , and let  $h = (y-x)/|x-y|$ . Then

$$\begin{aligned} \int_{\mathbb{R}^2} \frac{|f(x-z) - f(y-z)|}{|x-y|^\gamma} dz &\leq \int_{\mathbb{R}^2} \frac{|f(x-z) - f(y-z)|}{|x-y|} dz \\ &= \frac{1}{|x-y|} \int_{\mathbb{R}^2} \left| \int_0^{|x-y|} \nabla f(x+sh-z) \cdot h ds \right| dz \\ &\leq \frac{1}{|x-y|} \int_0^{|x-y|} \int_{\mathbb{R}^2} |\nabla f(x+sh-z)| dz ds \\ &= \frac{1}{|x-y|} \int_0^{|x-y|} \|\nabla f\|_{L^1} ds = \|\nabla f\|_{L^1}, \end{aligned}$$

where we used the translation invariance of the  $L^1$  norm. If  $|x-y| > 1$  then

$$\int_{\mathbb{R}^2} \frac{|f(x-z) - f(y-z)|}{|x-y|^\gamma} dz \leq \int_{\mathbb{R}^2} |f(x-z) - f(y-z)| dz \leq 2 \|f\|_{L^1},$$

which completes the proof.  $\square$

**Corollary 3.6.** *Each of  $g_\alpha(1)$ ,  $\nabla g_\alpha(1)$ , and p.v.  $K * \nabla g_\alpha(1)$  have finite  $\tilde{C}^\gamma$  norm.*

*Proof.* For  $g_\alpha(1)$ ,  $\nabla g_\alpha(1)$ , apply Lemma 3.5 to Lemma 2.8.

We know that p.v.  $K * \nabla g_\alpha(1) \in L^1$  by Lemma 2.9. To bound its derivatives, let  $\varphi \in C_c^\infty(\mathbb{R}^2)$  take values in  $[0, 1]$  with  $\varphi \equiv 1$  on  $B_1(0)$  and supported on  $B_2(0)$ . Then, much as in (2.27) of Lemma 2.15 (and see Remark 2.16), for  $j = 1, 2$  setting  $k = 3 - j$ ,

$$\begin{aligned} \partial_j(\text{p.v. } K * \nabla g_\alpha(1)) &= |\psi * \partial_k \nabla g_\alpha(1)| = |(\varphi\psi) * \partial_k \nabla g_\alpha(1) + ((1-\varphi)\psi) * \partial_k \nabla g_\alpha(1)| \\ &= |(\varphi\psi) * \partial_k \nabla g_\alpha(1) + (\partial_k(1-\varphi)\psi) * \nabla g_\alpha(1)|, \end{aligned}$$

so

$$\|\partial_j(\text{p.v. } K * \nabla g_\alpha(1))\|_{L^1} \leq \|\varphi\psi\|_{L^1} \|\partial_k \nabla g_\alpha(1)\|_{L^1} + \|\partial_k((1-\varphi)\psi)\|_{L^1} \|\nabla g_\alpha(1)\|_{L^1},$$

which is finite by Lemma 2.8. Hence, we can apply Lemma 3.5 again to give that p.v.  $K * \nabla g_\alpha(1)$  has a finite  $\tilde{C}^\gamma$  norm.  $\square$

**Lemma 3.7.** *For any  $t > 0$ ,*

$$\begin{aligned} \|g_\alpha(t)\|_{\tilde{C}^\gamma} &\leq Ct^{-\frac{\gamma}{2\alpha}}, \\ \|\nabla g_\alpha(t)\|_{\tilde{C}^\gamma} &\leq Ct^{-\frac{1+\gamma}{2\alpha}}, \\ \|\text{p. v. } K * \nabla g_\alpha(t)\|_{\tilde{C}^\gamma} &\leq Ct^{-\frac{1+\gamma}{2\alpha}}. \end{aligned}$$

*Proof.* The bounds on  $\|g_\alpha(t)\|_{\tilde{C}^\gamma}$  and  $\|\nabla g_\alpha(t)\|_{\tilde{C}^\gamma}$  follow from applying Lemma 3.4 and Corollary 3.6 with the scaling given by (2.6). The bound on  $\|\text{p. v. } K * \nabla g_\alpha(t)\|_{\tilde{C}^\gamma}$  follows from applying Lemma 3.4 and Corollary 3.6 with the scaling given by (2.13), noting the additional factor in that equation of  $t^{-\frac{1}{2\alpha}}$ .  $\square$

**Proof of Proposition 3.2.** Applying Lemmas 3.3 and 3.7 to (1.3), we have

$$\|\theta(t)\|_{C^\gamma} \leq Ct^{-\frac{\gamma}{2\alpha}} \|\theta_0\|_{L^\infty} + C \int_0^t (t-s)^{-\frac{1+\gamma}{2\alpha}} \|(\theta u)(s)\|_{L^\infty} ds,$$

which is finite since  $\gamma \in (0, 2\alpha - 1)$ . The bound on  $u(t)$  is obtained the same way.  $\square$

**3.2. Continuity in time.** With the above result, we can now establish the regularity in time of the mild solution.

**Proposition 3.8.** *Suppose that  $(\theta, u)$  is a mild solution to (SQG) on  $[0, T]$ . Then we have the following:*

- (1) *If  $\dot{\Delta}_j u_0 = (\dot{\Delta}_j K) * \theta_0$  for all  $j \in \mathbb{Z}$ , then  $\dot{\Delta}_j u(t) = (\dot{\Delta}_j K) * \theta(t)$  for all  $t \in [0, T]$  and all  $j \in \mathbb{Z}$ .*
- (2) *Let  $\alpha > 1/2$ , then  $(\theta, u)$  belongs to  $(C((0, T]; L^\infty(\mathbb{R}^2)))^3$ .*
- (3) *We have,  $\theta(t, x) \rightarrow \theta_0(x)$  and  $u(t, x) \rightarrow u_0(x)$  a.e.  $x \in \mathbb{R}^2$  as  $t \rightarrow 0$ .*
- (4) *If  $\text{div } u_0 = 0$  then  $\text{div } u = 0$  on  $[0, T] \times \mathbb{R}^2$ .*

*Proof. (1):* Suppose that  $\dot{\Delta}_j u_0 = (\dot{\Delta}_j K) * \theta_0$ . Applying  $(\dot{\Delta}_j K) *$  to both sides of the expression for  $\theta(t, x)$  in (1.3), we have

$$\begin{aligned} (\dot{\Delta}_j K) * \theta(t, x) &= (\dot{\Delta}_j K) * (G_\alpha(t)\theta_0)(x) - (\dot{\Delta}_j K) * \int_0^t (\nabla G_\alpha(t-s) \cdot (\theta u)(s))(x) ds \\ &= (g_\alpha(t) * (\dot{\Delta}_j K) * \theta_0)(x) - \int_0^t (\dot{\Delta}_j K) * (\nabla g_\alpha(t-s) * (\theta u)(s))(x) ds \\ &= G_\alpha(t)(\dot{\Delta}_j u_0)(x) - \int_0^t \dot{\Delta}_j ((K * \nabla g_\alpha(t-s)) * (\theta u)(s))(x) ds \\ &= \dot{\Delta}_j (G_\alpha(t)u_0)(x) - \dot{\Delta}_j \int_0^t (K * \nabla g_\alpha(t-s)) * (\theta u)(s) ds \\ &= \dot{\Delta}_j u(t, x). \end{aligned}$$

Here, we used that  $\dot{\Delta}_j K \in \mathcal{S}(\mathbb{R}^2)$  by Lemma 2.6 to move  $\dot{\Delta}_j K$  inside the integral and to commute  $\dot{\Delta}_j K$  with the convolution at time zero. We brought  $\dot{\Delta}_j = \varphi_j *$  outside the integral similarly. Finally, we used that

$$(\dot{\Delta}_j K) * \nabla g_\alpha(t-s) * (\theta u)(s) = \dot{\Delta}_j ((K * \nabla g_\alpha(t-s)) * (\theta u)(s)),$$

as the Fourier transforms of the two expressions coincide.

**(2):** We first aim to bound the size of  $u(b, x) - u(a, x)$  uniformly in  $x$  for  $a, b > 0$ . We can write

$$\begin{aligned} \|u(b, x) - u(a, x)\|_{L_x^\infty} &\leq \|(G_\alpha(b) - G_\alpha(a))u_0\|_{L_x^\infty} \\ &\quad + \left\| \int_0^b K * \nabla G_\alpha(b-s) \cdot (\theta u)(s, x) ds - \int_0^a K * \nabla G_\alpha(a-s) \cdot (\theta u)(s, x) ds \right\|_{L_x^\infty} \\ &\leq \|(G_\alpha(b) - G_\alpha(a))u_0(x)\|_{L_x^\infty} + \left\| \int_a^b K * \nabla G_\alpha(b-s) \cdot (\theta u)(s, x) ds \right\|_{L_x^\infty} \\ &\quad + \left\| \int_0^a (K * \nabla G_\alpha(b-s) - K * \nabla G_\alpha(a-s)) \cdot (\theta u)(s, x) ds \right\|_{L_x^\infty}. \end{aligned} \quad (3.1)$$

For the second term on the right hand side of (3.1), applying Young's inequality and Lemma 2.9 for  $k = 1$  gives the bound,

$$\begin{aligned} \left\| \int_a^b K * \nabla G_\alpha(b-s) \cdot (\theta u)(s, x) ds \right\|_{L_x^\infty} &\leq C \int_a^b (b-s)^{-\frac{1}{2\alpha}} \|(\theta u)(s, x)\|_{L_x^\infty} ds \\ &\leq \frac{2\alpha}{2\alpha-1} C \|\theta\|_{L_{t,x}^\infty} \|u\|_{L_{t,x}^\infty} (b-a)^{1-\frac{1}{2\alpha}}. \end{aligned} \quad (3.2)$$

Moreover, applying Young's inequality to the third term on the right hand side of (3.1), we have

$$\begin{aligned} &\left\| \int_0^a (K * \nabla G_\alpha(b-s) - K * \nabla G_\alpha(a-s)) \cdot (\theta u)(s, x) ds \right\|_{L_x^\infty} \\ &\leq \|\theta\|_{L_{t,x}^\infty} \|u\|_{L_{t,x}^\infty} \int_0^a \|K * \nabla g_\alpha(b-s) - K * \nabla g_\alpha(a-s)\|_{L_x^1} ds. \end{aligned} \quad (3.3)$$

For the above integral term, by the Fundamental Theorem of Calculus and Lemma 2.14, we can write

$$\begin{aligned} \int_0^a \|K * \nabla g_\alpha(b-s) - K * \nabla g_\alpha(a-s)\|_{L_x^1} ds &= \int_0^a \left\| \int_{a-s}^{b-s} \frac{\partial}{\partial \rho} K * \nabla g_\alpha(\rho) d\rho \right\|_{L_x^1} ds \\ &\leq \int_0^a \int_{a-s}^{b-s} \left\| \frac{\partial}{\partial \rho} K * \nabla g_\alpha(\rho) \right\|_{L_x^1} d\rho ds \leq \nu \int_0^a \int_{a-s}^{b-s} \|K * \Lambda^{2\alpha} \nabla g_\alpha(\rho)\|_{L_x^1} d\rho ds. \end{aligned} \quad (3.4)$$

Subsequently, by Lemma 2.12, one has

$$\|K * \Lambda^{2\alpha} \nabla g_\alpha(\rho)\|_{L_x^1} \leq C \rho^{-(1+\frac{1}{2\alpha})}. \quad (3.5)$$

Substituting (3.5) into (3.4) and integrating, one finds that,

$$\int_0^a \|K * \nabla g_\alpha(b-s) - K * \nabla g_\alpha(a-s)\|_{L_x^1} ds \lesssim \frac{4\alpha^2}{2\alpha-1} \left[ (b-a)^{1-\frac{1}{2\alpha}} + b^{1-\frac{1}{2\alpha}} - a^{1-\frac{1}{2\alpha}} \right]. \quad (3.6)$$

To estimate the first term on the right hand side of (3.1), we note that by Lemmas 3.3 and 3.7,  $G_\alpha(a)u_0$  belongs to  $C^\gamma$  for all  $\gamma > 0$  and is therefore uniformly continuous. We can then apply an approximation to the identity argument to conclude that, as  $b-a \rightarrow 0$ ,

$$\|G_\alpha(b)u_0 - G_\alpha(a)u_0\|_{L_x^\infty} = \|G_\alpha(b-a)G_\alpha(a)u_0 - G_\alpha(a)u_0\|_{L_x^\infty} \rightarrow 0. \quad (3.7)$$

Gathering (3.1), (5.16), (3.3), (3.6), and (3.7) and taking the limit of (3.1) as  $a \rightarrow b$ , the continuity of  $u$  is proved.

For  $\theta$ , we proceed with a series of estimates analogous to those of  $u$  to obtain the following:

$$\begin{aligned} \|\theta(b, x) - \theta(a, x)\|_{L_x^\infty} &\leq \|(G_\alpha(b) - G_\alpha(a))\theta_0\|_{L_x^\infty} \\ &\quad + C\|\theta\|_{L_{t,x}^\infty}\|u\|_{L_{t,x}^\infty} \left[ (b-a)^{1-\frac{1}{2\alpha}} + b^{1-\frac{1}{2\alpha}} - a^{1-\frac{1}{2\alpha}} \right]. \end{aligned}$$

Taking the limit as  $a \rightarrow b$ , the desired continuity of  $\theta$  is achieved.

**(3):** The proof is similar to that of (2), but with  $b = 0$ . Indeed, the proofs of (2) and (3) differ only in that the first term on the right side of (3.1), given by

$$\|u_0 - G_\alpha(a)u_0\|_{L^\infty} = \|u_0 - g_\alpha(a) * u_0\|_{L^\infty},$$

need not vanish as  $a \rightarrow 0$ , since  $u_0$  is not necessarily uniformly continuous. Rather, in this case, we use that  $(g_\alpha(t, \cdot)_{t>0})$  is an approximation to the identity to conclude that  $g_\alpha(a) * u_0(x) \rightarrow u_0(x)$  at every Lebesgue point of  $u_0$  (see Theorem 8.15 of [12]) and hence a.e.. From this, (3) follows.

**(4):** We apply Lemma 3.1 on  $[0, T]$  with  $f = K * \nabla g_\alpha$  and  $\psi = (\theta u)$ . The choice of  $f$  satisfies the hypotheses of the lemma, as for all  $t \in [0, T]$ ,  $\operatorname{div} f(t) = 0$  in  $\mathcal{S}'(\mathbb{R}^2)$  and  $f(t) \in L^1(\mathbb{R}^2)$  by Lemma 2.9. Thus,

$$\begin{aligned} \operatorname{div} u(t, x) &= \operatorname{div}(g_\alpha(t) * u_0(x)) - \operatorname{div} \int_0^t ((K * \nabla g_\alpha(t-s)) * (\theta u)(s))(x) ds \\ &= g_\alpha(t) * \operatorname{div} u_0(x). \end{aligned}$$

Therefore,  $\operatorname{div} u(t) = 0$  for all  $t \in [0, T]$  if  $\operatorname{div} u_0 = 0$ .  $\square$

**3.3. Preservation of the constitutive law.** Having shown the time and spatial regularity of  $(\theta, u)$ , we are now in a position to prove that (1) If  $(\theta_0, u_0)$  satisfy the constitutive law (6.3)<sub>2</sub> in the form  $u_0 = \text{p.v. } K * \theta_0$  uniformly then  $u(t) = \text{p.v. } K * \theta(t)$  for  $t > 0$ ; (2) With sufficient regularity of the initial conditions, a solution to the mild formulation satisfies (SQG) pointwise. We prove (1) in this subsection, (2) in the next.

**Proposition 3.9.** *Suppose that  $(\theta, u)$  is a mild solution to (SQG) on  $[0, T]$  for which  $(\theta, u) \in L^\infty([0, T] \times \mathbb{R}^2)^3$ . If  $u_0 = \text{p.v. } K * \theta_0$ , converging uniformly over annuli, as in (2.8), then (SQG)<sub>2</sub> holds.*

*Proof.* We show that (SQG)<sub>2</sub> is satisfied componentwise. Pick  $j = 1, 2$ , and convolve the solution  $\theta$  with  $\text{p.v. } K^j$ ,

$$\begin{aligned} (\text{p.v. } K^j * \theta)(t, x) &= \left( \text{p.v. } K^j * \left( G_\alpha(t)\theta(0, \cdot) - \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, \cdot) ds \right) \right)(x) \\ &= (\text{p.v. } K^j * (G_\alpha(t)\theta(0, \cdot)))(x) - \left( \text{p.v. } K^j * \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, \cdot) ds \right)(x). \end{aligned} \tag{3.8}$$

As for the second term, because  $K(x-y) \in L^\infty(A_{r,R}(x))$  and  $\nabla G_\alpha(t-s) \cdot (\theta u)(s, \cdot) \in L^1(\mathbb{R}^2)$ , we can invoke the Fubini-Tonelli theorem to give

$$\begin{aligned}
& \left( \text{p. v. } K * \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds \right)(x) \\
&= \lim_{r,R} \int_{A_{r,R}(x)} \int_0^t K(x-y) (\nabla G_\alpha(t-s) \cdot (\theta u)(s, y)) ds dy \\
&= \lim_{r,R} \int_0^t \int_{A_{r,R}(x)} K(x-y) (\nabla G_\alpha(t-s) \cdot (\theta u)(s, y)) dy ds \quad (3.9) \\
&= \lim_{r,R} \int_0^t (\mathbb{1}_{A_{r,R}(0)} K) * [\nabla g_\alpha(t-s) * (\theta u)](s, x) ds \\
&= \lim_{r,R} \int_0^t \left[ (\mathbb{1}_{A_{r,R}(0)} K) * \nabla g_\alpha(t-s) \right] * (\theta u)(s, x) ds.
\end{aligned}$$

Because the integrand was the convolution of two  $L^1$  functions and an  $L^\infty$  function, we were able to use the associativity of the convolutions. By Lemma 2.18,

$$\begin{aligned}
& \left| \left[ (\mathbb{1}_{A_{r,R}(0)} K) * \nabla g_\alpha(t-s) \right] * (\theta u)(s, x) \right| \\
&\leq \left\| (\mathbb{1}_{A_{r,R}(0)} K) * \nabla g_\alpha(t-s) \right\|_{L^1(\mathbb{R}^2)} \|(\theta u)(s)\|_{L^\infty(\mathbb{R}^2)} \\
&\leq C \|\theta u\|_{L^\infty((0,T) \times \mathbb{R}^2)} (t-s)^{-1/(2\alpha)},
\end{aligned}$$

which is in  $L^1((0, t))$ . Hence, we can apply the dominated convergence theorem to give,

$$\begin{aligned}
& \left( \text{p. v. } K * \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds \right)(x) \\
&= \int_0^t \lim_{r,R} \left[ (\mathbb{1}_{A_{r,R}(0)} K) * \nabla g_\alpha(t-s) \right] * (\theta u)(s, x) ds \\
&= \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta u)(s, x) ds.
\end{aligned}$$

Similarly, with the equality  $K * \theta(0, x) = u(0, x)$ , by applying Lemma 2.5, we have

$$\text{p. v. } K * (G_\alpha(t)\theta(0, x)) = G_\alpha(t)(\text{p. v. } K * \theta(0, x)) = G_\alpha(t)u(0, x). \quad (3.10)$$

Using (3.10) in (3.8), we obtain

$$\text{p. v. } (K * \theta)(t, x) = G_\alpha(t)u(0, x) - \int_0^t K * \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds = u(t, x).$$

From this, we conclude that  $(\textcolor{red}{SQG})_2$  holds for all  $t \in [0, T]$ ; that is,  $u = \text{p. v. } K * \theta$  in  $[0, T] \times \mathbb{R}^2$ . □

**3.4. Classical  $(\textcolor{red}{SQG})$  for smooth initial data.** Having shown that  $(\textcolor{red}{SQG})_2$  holds for mild solutions, we now show that sufficiently smooth mild solutions also satisfy  $(\textcolor{red}{SQG})_1$ . In the following proposition  $f(x) = \lceil x \rceil$  denotes the ceiling function.

**Proposition 3.10.** *Suppose that  $(\theta, u)$  is a mild solution to (SQG) on  $[0, T]$  for which  $(\theta, u) \in (L^\infty([0, T]; C_b^{[2\alpha]}(\mathbb{R}^2)))^3$  and  $u_0 = \text{p.v. } K * \theta_0$ . Then  $\theta$  and  $u$  are once differentiable in time and  $(\text{SQG})_1$  holds in the classical sense for a.e  $x \in \mathbb{R}^2$ .*

*Proof.* To avoid the singularity at  $G_\alpha(0)$  and  $\nabla G_\alpha(0)$ , we first use the Dominated Convergence Theorem to rewrite the mild formulation as

$$\begin{aligned} \theta(t, x) &= G_\alpha(t)\theta(0, x) - \int_0^t \nabla G_\alpha(t-s) \cdot (u\theta)(s, x) ds \\ &= G_\alpha(t)\theta(0, x) - \lim_{\varepsilon \rightarrow 0} \int_0^{t-\varepsilon} \nabla G_\alpha(t-s) \cdot (u\theta)(s, x) ds. \end{aligned}$$

Taking a time derivative of our expression for  $\theta$  above, we make use of  $g_\alpha(t)$  as the fundamental solution of the fractional heat equation given by (2.3) and write

$$\frac{\partial}{\partial t} \theta(t, x) = -\nu \Lambda^{2\alpha} G_\alpha(t)\theta(0, x) - \frac{\partial}{\partial t} \lim_{\varepsilon \rightarrow 0} \int_0^{t-\varepsilon} \nabla G_\alpha(t-s) \cdot (u\theta)(s, x) ds. \quad (3.11)$$

We wish to show that the derivative and limit can be swapped. Equivalently (see Theorem 7.17 of [21]), fix  $t$ , let  $(\varepsilon_n)_{n=1}^\infty$  be any sequence such that  $\varepsilon_n \rightarrow 0$  as  $n \rightarrow \infty$ , and define the functions

$$f_n(t, x) := \int_0^{t-\varepsilon_n} \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds,$$

and

$$f(t, x) := \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds = \lim_{n \rightarrow \infty} f_n(t, x).$$

We will show that for each  $x \in \mathbb{R}^2$ ,

- (1)  $f_n(t, x)$  converges uniformly to  $f$  in time and
- (2)  $\partial_t f_n(t, x)$  converges uniformly in time.

From this, we will conclude that  $\partial_t f$  exists and

$$\lim_{n \rightarrow \infty} \frac{\partial}{\partial t} f_n(t, x) = \frac{\partial}{\partial t} f(t, x).$$

For (1): Uniform convergence in time follows by invoking Lemma 2.9 and Young's inequality. For each  $x \in \mathbb{R}^2$ , write

$$\begin{aligned} \|f(t, x) - f_n(t, x)\|_{L_t^\infty} &= \left\| \int_{t-\varepsilon_n}^t \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds \right\|_{L_t^\infty} \\ &\leq \left\| \int_{t-\varepsilon_n}^t C(t-s)^{-\frac{1}{2\alpha}} \|(\theta u)(s, x)\|_{L_x^\infty} ds \right\|_{L_t^\infty} \leq \frac{2\alpha}{2\alpha-1} C \|u\|_{L_{t,x}^\infty} \|\theta\|_{L_{t,x}^\infty} \varepsilon_n^{1-\frac{1}{2\alpha}}. \end{aligned}$$

For (2): We note that for each  $n$ ,  $\partial_t f_n$  exists using the Leibniz integral rule,

$$\begin{aligned} \frac{\partial}{\partial t} f_n(t, x) &= \frac{\partial}{\partial t} \int_0^{t-\varepsilon_n} \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds \\ &= (\nabla G_\alpha(\varepsilon_n) \cdot (\theta u))(t-\varepsilon_n, x) + \int_0^{t-\varepsilon_n} \frac{\partial}{\partial t} \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds. \end{aligned} \quad (3.12)$$

To justify the use of Leibniz rule above, we note that  $\|\frac{\partial}{\partial t} \nabla g_\alpha(t-s, x)\|_{L_x^1}$  is continuous in  $s$  on  $[0, t - \varepsilon_n]$ , and  $\|\theta u(s, x)\|_{L_x^\infty}$  is bounded on  $[0, t - \varepsilon_n]$  by assumption. Thus, an application of Young's inequality implies that the expression

$$\frac{\partial}{\partial t} [\nabla G_\alpha(t-s) \cdot (u\theta)(s, x)]$$

exists and is absolutely integrable in  $s$  on  $[0, t - \varepsilon_n]$ .

Now we show that  $(\partial_t f_n)_{n=1}^\infty$  is Cauchy in  $L_t^\infty$ . First note that by integration by parts and an application of (2.3),

$$\frac{\partial}{\partial t} [\nabla G_\alpha(t-s) \cdot (u\theta)(s, x)] = \frac{\partial}{\partial t} G_\alpha(t-s) \operatorname{div}(u\theta)(s, x) = \Lambda G_\alpha(t-s) \Lambda^{2\alpha-1} \operatorname{div}(u\theta)(s, x).$$

Substituting this equality into (3.12) gives

$$\begin{aligned} \frac{\partial}{\partial t} f_n(t, x) &= \frac{\partial}{\partial t} \int_0^{t-\varepsilon_n} \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds \\ &= (\nabla G_\alpha(\varepsilon_n) \cdot (\theta u))(t - \varepsilon_n, x) + \int_0^{t-\varepsilon_n} \Lambda G_\alpha(t-s) \Lambda^{2\alpha-1} \operatorname{div}(u\theta)(s, x) ds. \end{aligned} \quad (3.13)$$

Thus, we have for  $n > m > 0$  and for each  $x \in \mathbb{R}^2$ ,

$$\begin{aligned} \|\partial_t f_n(x) - \partial_t f_m(x)\|_{L_t^\infty} &\leq \|(\nabla G_\alpha(\varepsilon_n) - \nabla G_\alpha(\varepsilon_m)) \cdot (\theta u)(t - \varepsilon_n, x)\|_{L_t^\infty} \\ &\quad + \|\nabla G_\alpha(\varepsilon_m) \cdot ((\theta u)(t - \varepsilon_n, x) - (\theta u)(t - \varepsilon_m, x))\|_{L_t^\infty} \\ &\quad + \nu \left\| \int_{t-\varepsilon_m}^{t-\varepsilon_n} \Lambda G_\alpha(t-s) \Lambda^{2\alpha-1} \operatorname{div}((u\theta)(s, x)) ds \right\|_{L_t^\infty}. \end{aligned} \quad (3.14)$$

For the first term of (3.14), we use the Fundamental Theorem of Calculus and the fractional heat kernel property (2.3) to write

$$\begin{aligned} \|(\nabla G_\alpha(\varepsilon_n) - \nabla G_\alpha(\varepsilon_m)) \cdot (\theta u)(t - \varepsilon_n, x)\|_{L_t^\infty} &= \left\| \int_{\varepsilon_n}^{\varepsilon_m} \frac{\partial}{\partial \rho} \nabla G_\alpha(\rho) \cdot (\theta u)(t - \varepsilon_n, x) d\rho \right\|_{L_t^\infty} \\ &\leq \nu \left\| \int_{\varepsilon_n}^{\varepsilon_m} \nabla G_\alpha(\rho) \cdot \Lambda^{2\alpha}(u\theta)(t - \varepsilon_n, x) d\rho \right\|_{L_t^\infty} \\ &\leq \nu \left\| \int_{\varepsilon_n}^{\varepsilon_m} \|\nabla G_\alpha(\rho) \cdot \Lambda^{2\alpha}(u\theta)(t - \varepsilon_n, x)\|_{L_x^\infty} d\rho \right\|_{L_t^\infty}. \end{aligned}$$

Applying Young's inequality and Lemma 2.9, and integrating with respect to  $\rho$ , yields

$$\begin{aligned} &\left\| \int_{\varepsilon_m}^{\varepsilon_n} \|\nabla G_\alpha(\rho) \cdot \Lambda^{2\alpha}(u\theta)(t - \varepsilon_n, x)\|_{L_x^\infty} d\rho \right\|_{L_t^\infty} \\ &\leq \frac{2\alpha}{2\alpha-1} C \|\Lambda^{2\alpha}(u\theta)\|_{L_{t,x}^\infty} \left( \varepsilon_m^{1-\frac{1}{2\alpha}} - \varepsilon_n^{1-\frac{1}{2\alpha}} \right). \end{aligned} \quad (3.15)$$



We expand the second term of (3.14) by using integration by parts, Young's convolution inequality, and the divergence-free condition on  $u = \nabla^\perp \Lambda \theta$ , which follows from Proposition 3.9. We write

$$\begin{aligned}
& \sup_{t \in [0, T]} |\nabla G_\alpha(\varepsilon_n) \cdot ((\theta u)(t - \varepsilon_n, x) - (\theta u)(t - \varepsilon_m, x))| \\
&= \sup_{t \in [0, T]} |G_\alpha(\varepsilon_n) \operatorname{div}((\theta u)(t - \varepsilon_n, x) - (\theta u)(t - \varepsilon_m, x))| \\
&\leq \sup_{t \in [0, T]} \|g_\alpha(\varepsilon_n, x)\|_{L_x^1} \|u \cdot \nabla \theta(t - \varepsilon_n, x) - u \cdot \nabla \theta(t - \varepsilon_m, x)\|_{L_x^\infty} \\
&= \sup_{t \in [0, T]} \|(u \cdot \nabla \theta)(t - \varepsilon_n, x) - (u \cdot \nabla \theta)(t - \varepsilon_m, x)\|_{L_x^\infty}.
\end{aligned} \tag{3.16}$$

The above term vanishes as a consequence of the continuity in time of  $u$  from Proposition 3.8(2) and the continuity in time of  $\nabla \theta$  from Lemma 5.1 below. Turning to the third term in (3.14), we apply Lemma 2.9 and invoke the  $C_b^{[2\alpha]}$  regularity of  $(\theta, u)$ , to write

$$\begin{aligned}
& \left\| \int_{t-\varepsilon_m}^{t-\varepsilon_n} \Lambda G_\alpha(t-s) \Lambda^{2\alpha-1} \operatorname{div}((u\theta)(s, x)) ds \right\|_{L_t^\infty} \\
&\leq \int_{t-\varepsilon_m}^{t-\varepsilon_n} C(t-s)^{-\frac{1}{2\alpha}} \|\Lambda^{2\alpha-1} \operatorname{div}((u\theta)(s, x))\|_{L_x^\infty} ds \\
&\leq \frac{2\alpha}{2\alpha-1} C \|\Lambda^{2\alpha-1} \operatorname{div}(u\theta)\|_{L_{t,x}^\infty} \left( \varepsilon_m^{1-\frac{1}{2\alpha}} - \varepsilon_n^{1-\frac{1}{2\alpha}} \right).
\end{aligned} \tag{3.17}$$

Combined, (3.15), (3.16), and (3.17) imply that  $\partial_t f_n$  is Cauchy in  $L_t^\infty$ . In addition,  $\partial_t f$  exists and  $\partial_t f_n \rightarrow \partial_t f$  as  $n \rightarrow \infty$ . We utilize this convergence and (3.13) to rewrite (3.11) as

$$\begin{aligned}
\frac{\partial}{\partial t} \theta(t, x) &= \frac{\partial}{\partial t} [G_\alpha(t) * \theta(0, \cdot)](x) - \lim_{n \rightarrow \infty} \frac{\partial}{\partial t} f_n(t, x) \\
&= \frac{\partial}{\partial t} [G_\alpha(t) * \theta(0, \cdot)](x) - \lim_{n \rightarrow \infty} \left[ \nabla G_\alpha(\varepsilon_n) \cdot (\theta u)(t - \varepsilon_n, x) \right. \\
&\quad \left. - \nu \int_0^{t-\varepsilon_n} \Lambda G_\alpha(t-s) \Lambda^{2\alpha-1} \operatorname{div}(u\theta)(s, x) ds \right].
\end{aligned} \tag{3.18}$$

For the first term on the right-hand side of (3.18), we apply (2.3), and for the second term, we use integration by parts. Finally, for the third term, we apply the Dominated Convergence Theorem, noting that by a calculation similar to that in (3.17),  $\Lambda G_\alpha(t-\cdot) \Lambda^{2\alpha-1} \operatorname{div}(u\theta)(\cdot, x)$  belongs to  $L^1([0, t])$  for each  $x$ . We conclude that

$$\begin{aligned}
\frac{\partial}{\partial t} \theta &= -\nu \Lambda^{2\alpha} G_\alpha(t) \theta(0, \cdot) - \lim_{n \rightarrow \infty} [G_\alpha(\varepsilon_n) \operatorname{div}(\theta u)(t - \varepsilon_n, \cdot)] \\
&\quad + \nu \int_0^t \Lambda^{2\alpha} \nabla G_\alpha(t-s) \cdot (\theta u)(s, \cdot) ds.
\end{aligned} \tag{3.19}$$

For the second term of (3.19), write it as

$$\begin{aligned}
& G_\alpha(\varepsilon_n) \operatorname{div}(\theta u)(t - \varepsilon_n, \cdot) \\
&= G_\alpha(\varepsilon_n) (\operatorname{div}(\theta u)(t - \varepsilon_n, \cdot) - \operatorname{div}(\theta u)(t, \cdot)) + G_\alpha(\varepsilon_n) \operatorname{div}(\theta u)(t, \cdot)
\end{aligned} \tag{3.20}$$

Applying the divergence free condition on  $u$ , the first term of (3.20) vanishes as a consequence of the continuity in time of  $\nabla\theta$  from Lemma 5.1 and the continuity in time of  $u$  from Proposition 3.8(2).

For the second term of (3.20), we apply Theorem 8.15 of [12] to assert the a.e. convergence of  $G_\alpha(\varepsilon_n) \operatorname{div}(\theta u)(t, x)$  to  $\operatorname{div}(\theta u)(t, x)$ . Hence,

$$\lim_{n \rightarrow \infty} G_\alpha(\varepsilon_n) \operatorname{div}(\theta u) = \operatorname{div}(\theta u) = u \cdot \nabla \theta, \quad (3.21)$$

where we used the divergence free condition on  $u$  to get the second equality above. Notice that for the third term of (3.19), we can interchange the order of time integration and  $\Lambda^{2\alpha}$  as a consequence of the Leibniz integral rule, as both

$$\nabla G_\alpha(t-s) \cdot (\theta u) \text{ and } \Lambda^{2\alpha} \nabla G_\alpha(t-s) \cdot (u\theta)$$

are integrable in time by Lemma 2.9 and Lemma 2.12, respectively. Indeed, for  $\Lambda^{2\alpha} \nabla G_\alpha(t-s) \cdot (u\theta)$ , we apply  $\Lambda^{2\alpha}$  to the product  $\theta u$  and use the boundedness of the derivatives of  $\theta u$  to reach the conclusion. Thus, we have

$$\nu \int_0^t \Lambda^{2\alpha} \nabla G_\alpha(t-s) \cdot (u\theta)(s, x) ds = \nu \Lambda^{2\alpha} \int_0^t \nabla G_\alpha(t-s) \cdot (u\theta)(s, x) ds. \quad (3.22)$$

Collecting terms (3.21) and (3.22), we can rewrite (3.19) using the definition of  $\theta$  in (1.3)<sub>1</sub> and deduce

$$\begin{aligned} \frac{\partial}{\partial t} \theta(t, x) &= -\nu \Lambda^{2\alpha} G_\alpha(t) \theta(0, x) - (u \cdot \nabla \theta)(t, x) + \nu \Lambda^{2\alpha} \int_0^t \nabla G_\alpha(t-s) \cdot (u\theta)(s, x) ds \\ &= -\nu \Lambda^{2\alpha} \theta(t, x) - (u \cdot \nabla \theta)(t, x). \end{aligned}$$

Hence, we see that (SSQG)<sub>1</sub> is satisfied. From here, we can estimate the size of  $\frac{\partial}{\partial t} \theta$  by

$$\left\| \frac{\partial}{\partial t} \theta \right\|_{L_x^\infty} \leq \nu \|\Lambda^{2\alpha} \theta\|_{L_x^\infty} + \|u\|_{L_x^\infty} \|\nabla \theta\|_{L_x^\infty} < \infty. \quad (3.23)$$

Thereby, we conclude that  $(\theta, u)$  is a classical solution.  $\square$

**3.5. Solutions to (SSQG).** Reusing the first parts of the argument of Proposition 3.10, by modifying the assumption on the initial data, we can show mild solutions of (SSQG) also satisfy the equation pointwise.

**Proposition 3.11.** *Suppose that  $(\theta, u) \in L^\infty([0, T]; C_b^2(\mathbb{R}^2)) \times (L^\infty([0, T]; C_b^2(\mathbb{R}^2)))^2$  and satisfy (1.1) with  $\dot{\Delta}_j u_0 = (\dot{\Delta}_j K) * \theta_0$  for all  $j \in \mathbb{Z}$  and  $\operatorname{div} u_0 = 0$ . Then  $(\theta, u)$  are once differentiable in time and satisfy (SSQG).*

*Proof.* By Proposition 3.8 (4) one has  $\operatorname{div} u = 0$ , Therefore, the argument in Proposition 3.10 proceeds identically up to line (3.19). More specifically, we have that  $\theta$  is differentiable in time. For any sequence  $(\varepsilon_n)_{n=1}^\infty$  with  $\varepsilon_n \rightarrow 0$ , the time derivative of  $\theta$  is given by:

$$\begin{aligned} \frac{\partial}{\partial t} \theta &= -\nu \Lambda^{2\alpha} G_\alpha(t) \theta(0, x) - \lim_{n \rightarrow \infty} G_\alpha(\varepsilon_n) \operatorname{div}(\theta u) \\ &\quad + \nu \int_0^t \Lambda^{2\alpha} \nabla G_\alpha(t-s) \cdot (u\theta) ds. \end{aligned} \quad (3.24)$$

For the first term of (3.24), we can successively apply part (4) and Theorem 8.15 of [12],

$$\lim_{n \rightarrow \infty} G_\alpha(\varepsilon_n) \operatorname{div}(\theta u) = \lim_{n \rightarrow \infty} G_\alpha(\varepsilon_n) (u \cdot \nabla \theta) = u \cdot \nabla \theta. \quad (3.25)$$

Substituting (3.22) and (3.25) into (3.24) yields the desired result for  $\theta$ ,

$$\frac{\partial}{\partial t}\theta = -\nu\Lambda^{2\alpha}\theta - u \cdot \nabla\theta.$$

We invoke the same estimate as in the previous proposition for  $\frac{\partial}{\partial t}\theta$ ,

$$\left\| \frac{\partial}{\partial t}\theta \right\|_{L_x^\infty} \leq \nu\|\Lambda^{2\alpha}\theta\|_{L_x^\infty} + \|u\|_{L_x^\infty}\|\nabla\theta\|_{L_x^\infty} < \infty, \quad (3.26)$$

by the hypotheses. The constitutive law  $(SSQG)_2$  is recovered directly from Proposition 3.8 (1).  $\square$

#### 4. EXISTENCE OF A FINITE TIME MILD SOLUTION

In this section, we prove Theorem 1.2. We let  $\tau > 0$ , choosing a precise value of  $\tau$  later. For  $p \in L^\infty([0, \tau] \times \mathbb{R}^2)$  and  $\omega \in (L^\infty([0, \tau] \times \mathbb{R}^2))^2$ , we define the two maps,

$$\begin{aligned} T_\omega p(t, \cdot) &:= G_\alpha(t)\theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot (p\omega)(s) ds, \\ U_p \omega(t, \cdot) &:= G_\alpha(t)u_0 - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (p\omega) ds. \end{aligned} \quad (4.1)$$

Our proof of existence will follow an iterative scheme, setting

$$\theta^1(t, x) := \theta_0(x), \quad u^1(t, x) := u_0(x) \text{ for all } t \geq 0, \quad (4.2)$$

while for  $n \geq 1$ ,

$$\begin{aligned} \theta^{n+1}(t, x) &:= T_{u^n} \theta^{n+1}(t, x) = G_\alpha(t)\theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot (u^n \theta^{n+1})(s) ds, \\ u^{n+1}(t, x) &:= U_{\theta^{n+1}} u^n(t, x) = G_\alpha(t)u_0 - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (u^n \theta^{n+1})(s) ds. \end{aligned} \quad (4.3)$$

We iterate over  $n = 0, 1, \dots$  as follows:

- (1) Setting  $\omega = u^n$ , we use the Banach contraction mapping theorem to obtain  $\theta^{n+1}$  as the fixed point of the operator  $T_\omega$ . This fixed point exists on a time interval  $\tau > 0$  that depends on the initial data, but is independent of  $n$ .
- (2) For a fixed  $p = \theta^{n+1}$ , we set  $u^{n+1} = U_p u^n$ .

We then prove the convergence of the sequences  $(\theta^n)$  and  $(u^n)$  to  $\theta$  and  $u$ , respectively, and we show that  $(\theta, u)$  is a mild solution as in Definition 1.1 up to time  $\tau$ .

We begin with estimates on the integrals appearing in  $T$  and  $U$ .

From the definition of  $G_\alpha(t)$  and Lemma 2.9 for  $k = 1$ ,

$$\begin{aligned} \left\| \int_0^t \nabla G_\alpha(t-s) \cdot (p\omega) ds \right\|_{L_x^\infty} &\leq \int_0^t \|\nabla g_\alpha(t-s, y) * \cdot (p\omega)\|_{L_x^\infty} ds \\ &\leq C \int_0^t (t-s)^{-\frac{1}{2\alpha}} \|p\omega\|_{L_x^\infty} ds \leq C \int_0^t (t-s)^{-\frac{1}{2\alpha}} \|p\|_{L_x^\infty} \|\omega\|_{L_x^\infty} ds. \end{aligned}$$

Integrating the above in time and applying the  $L_t^\infty \equiv L^\infty([0, \tau])$  norm to both sides of the resulting inequality gives

$$\left\| \int_0^t \nabla G_\alpha(t-s) \cdot (p\omega) ds \right\|_{L_{t,x}^\infty} \leq \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|p\|_{L_{t,x}^\infty} \|\omega\|_{L_{t,x}^\infty}. \quad (4.4)$$

Again, using Lemma 2.9 for  $k = 1$ ,

$$\begin{aligned} \left\| \int_0^t K * \nabla G_\alpha(t-s) \cdot (p\omega)(s) ds \right\|_{L_x^\infty} &\leq \int_0^t \|(K * \nabla G_\alpha(t-s)) \cdot (p\omega)(s)\|_{L_x^\infty} ds \\ &\leq \int_0^t C(t-s)^{-\frac{1}{2\alpha}} \|p\|_{L_x^\infty} \|\omega\|_{L_x^\infty} ds. \end{aligned}$$

As before, integrating in time and applying the  $L_t^\infty$  norm to both sides gives

$$\left\| \int_0^t K * \nabla G_\alpha(t-s) \cdot (p\omega) ds \right\|_{L_{t,x}^\infty} \leq \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|p\|_{L_{t,x}^\infty} \|\omega\|_{L_{t,x}^\infty}. \quad (4.5)$$

Now, we choose  $\tau > 0$  to satisfy the following size condition,

$$\frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} (\|\theta_0\|_{L_x^\infty} + \|u_0\|_{L_x^\infty}) \leq \frac{1}{8}. \quad (4.6)$$

**Convergence of Approximating Sequence.** We begin the iterative process by realizing  $\theta^2$  as the fixed point of  $T_{u_1}$  using the Banach contraction mapping theorem (Step 1). From there we can quickly obtain  $u^2$  and then for illustrative purposes, we proceed by generating  $\theta^3$  with a similar argument, as the fixed point of  $T_{u_2}$  (Step 2). Finally, we consider the general case of  $\theta^{n+1}$  as the fixed point of  $T_{u^n}$  (Step 3).

**Step 1 (Fixed point of  $T_{u_1}$ ):** Set  $R = 2\|\theta_0\|_{L_x^\infty}$  and define  $B_R$  as the ball of radius  $R$  centered at the origin in  $L^\infty([0, \tau] \times \mathbb{R}^2)$ . Let  $p$  and  $\bar{p}$  be two elements of  $B_R$ . Then, using estimate (4.4) and the equality  $\|u^1\|_{L_{t,x}^\infty} = \|u_0\|_{L_x^\infty}$  from (4.2), we have

$$\begin{aligned} \|T_{u^1}p - T_{u^1}\bar{p}\|_{L_{t,x}^\infty} &= \left\| \int_0^t \nabla G_\alpha(t-s) \cdot (u^1(p - \bar{p})) ds \right\|_{L_{t,x}^\infty} \\ &\leq \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|u^1\|_{L_{t,x}^\infty} \|p - \bar{p}\|_{L_{t,x}^\infty} = \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|u_0\|_{L_x^\infty} \|p - \bar{p}\|_{L_{t,x}^\infty}. \end{aligned}$$

Invoking the size condition on  $\tau$  in (4.6), we conclude that

$$\|T_{u^1}p - T_{u^1}\bar{p}\|_{L_{t,x}^\infty} \leq \frac{1}{8} \|p - \bar{p}\|_{L_{t,x}^\infty}. \quad (4.7)$$

To see that  $T_{u^1}$  maps  $B_R$  into  $B_R$ , select  $p \in B_R$ . Applying the estimate (4.7) and Young's inequality, we write

$$\begin{aligned} \|T_{u^1}p\|_{L_{t,x}^\infty} &\leq \|T_{u^1}p - T_{u^1}0\|_{L_{t,x}^\infty} + \|T_{u^1}0\|_{L_{t,x}^\infty} \leq \frac{1}{8} \|p - 0\|_{L_{t,x}^\infty} + \|G_\alpha(t)\theta_0\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{8} \|p\|_{L_{t,x}^\infty} + \sup_{t \in (0, \tau]} \|g_\alpha(t)\|_{L_x^1} \|\theta_0\|_{L_x^\infty} \leq \frac{1}{4} \|\theta_0\|_{L_x^\infty} + \|\theta_0\|_{L_x^\infty} = \frac{5}{4} \|\theta_0\|_{L_x^\infty} \leq R. \end{aligned} \quad (4.8)$$

It follows that  $T_{u^1}$  is a strict contraction from  $B_R$  into  $B_R$ . Thus, there exists a fixed point of  $T_{u^1}$ , call it  $\theta^{1+1} = \theta^2$ .

To proceed, we establish the existence of  $u^2 := U_{\theta^2} u^1$  by proving the boundedness of  $U_{\theta^2}$ . By (4.3)<sub>2</sub> and (4.5),

$$\begin{aligned} \|u^2(t)\|_{L_{t,x}^\infty} &= \left\| G_\alpha(t)u_0(x) - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta^2 u^1)(s) ds \right\|_{L_{t,x}^\infty} \\ &\leq \|G_\alpha(t)u_0(x)\|_{L_{t,x}^\infty} + \left\| \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta^2 u^1)(s) ds \right\|_{L_{t,x}^\infty} \\ &\leq \|u_0\|_{L_x^\infty} + \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|\theta^2\|_{L_{t,x}^\infty} \|u^1\|_{L_{t,x}^\infty}. \end{aligned}$$

We then substitute in the estimate  $\|\theta^2\|_{L_{t,x}^\infty} \leq \frac{5}{4}\|\theta_0\|_{L_x^\infty}$  from (4.8) and apply our condition on  $\tau$  in (4.6). This gives

$$\begin{aligned} \|u^2(t)\|_{L_{t,x}^\infty} &\leq \|u_0\|_{L_x^\infty} + \frac{5}{4} \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|\theta_0\|_{L_{t,x}^\infty} \|u_0\|_{L_x^\infty} \\ &\leq \|u_0\|_{L_x^\infty} + \frac{5}{32} \|u_0\|_{L_x^\infty} \leq 2\|u_0\|_{L_x^\infty} = R. \end{aligned} \quad (4.9)$$

With the boundedness of  $u^2 \in (L^\infty([0, \tau] \times \mathbb{R}^2))^2$ , we continue by showing the existence of the fixed point of  $T_{u^2}$ .

**Step 2 (Fixed point of  $T_{u^2}$ ):** For  $p \in L^\infty([0, \tau] \times \mathbb{R}^2)$ , consider

$$T_{u^2} p(t, x) = G_\alpha(t)\theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot (pu^2)(s) ds. \quad (4.10)$$

Using an argument similar to the work in Step 1, we find that for  $p$  and  $\bar{p}$  in  $B_R$ ,

$$\|T_{u^2} p - T_{u^2} \bar{p}\|_{L_{t,x}^\infty} \leq \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|p - \bar{p}\|_{L_{t,x}^\infty} \|u^2\|_{L_{t,x}^\infty}. \quad (4.11)$$

Substituting (4.9) into (4.11) yields

$$\|T_{u^2} p - T_{u^2} \bar{p}\|_{L_{t,x}^\infty} \leq 2 \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|p - \bar{p}\|_{L_{t,x}^\infty} \|u_0\|_{L_x^\infty}.$$

Again, applying the size condition on  $\tau$  in (4.6), we conclude that

$$\|T_{u^2} p - T_{u^2} \bar{p}\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|p - \bar{p}\|_{L_{t,x}^\infty}. \quad (4.12)$$

As before, we now show  $T_{u^2}$  maps  $B_R$  into  $B_R$ . Let  $f \in B_R$  and utilize (4.12) and Young's inequality to write

$$\begin{aligned} \|T_{u^2} f\|_{L_{t,x}^\infty} &\leq \|T_{u^2} f - T_{u^2} 0\|_{L_{t,x}^\infty} + \|T_{u^2} 0\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|f - 0\|_{L_{t,x}^\infty} + \|G_\alpha(t)\theta_0\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{4} \|f\|_{L_{t,x}^\infty} + \sup_{t \in [0, \tau]} \|g_\alpha(t)\|_{L_x^1} \|\theta_0\|_{L_x^\infty} \leq R. \end{aligned}$$

Thus  $T_{u^2}$  has a fixed point, call it  $\theta^{2+1} = \theta^3$ .

**Step 3 (General case):** For the inductive step, fix  $n \in \mathbb{N}$  and suppose  $\|\theta^m\|_{L_{t,x}^\infty} \leq 2\|\theta_0\|_{L_x^\infty}$  for every  $m \leq n$ . We compute  $\theta^{n+1}$  by showing the existence of a fixed point of the map defined on  $B_R$  given by

$$T_{u^n} p = G_\alpha(t)\theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot (pu^n)(s) ds. \quad (4.13)$$

The dependence of  $T_{u^n}$  on  $u^n$  prompts us to first estimate the size of  $u^m$ . To that effect, observe that for  $m \leq n$ ,

$$\begin{aligned} \|u^m\|_{L_{t,x}^\infty} &= \left\| G_\alpha(t)u_0 - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta^m u^{m-1})(s) ds \right\|_{L_{t,x}^\infty} \\ &\leq \|G_\alpha(t)u_0\|_{L_{t,x}^\infty} + \left\| \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta^m u^{m-1})(s) ds \right\|_{L_{t,x}^\infty} \\ &\leq \|u_0\|_{L_x^\infty} + \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|\theta^m\|_{L_{t,x}^\infty} \|u^{m-1}\|_{L_{t,x}^\infty}, \end{aligned}$$

where we have used our estimate on the integral of  $K * \nabla G$  from (4.5) in the second inequality. We can then apply the induction hypothesis  $\|\theta^m\|_{L_{t,x}^\infty} \leq 2\|\theta_0\|_{L_x^\infty}$  coupled with the size condition on  $\tau$  in (4.6) to conclude that

$$\begin{aligned} \|u^m\|_{L_{t,x}^\infty} &\leq \|u_0\|_{L_x^\infty} + \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|\theta^m\|_{L_{t,x}^\infty} \|u^{m-1}\|_{L_{t,x}^\infty} \\ &\leq \|u_0\|_{L_x^\infty} + 2\frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|\theta_0\|_{L_x^\infty} \|u^{m-1}\|_{L_{t,x}^\infty} \\ &\leq \|u_0\|_{L_x^\infty} + \frac{1}{4} \|u^{m-1}\|_{L_{t,x}^\infty}. \end{aligned} \tag{4.14}$$

Thus, for each  $m \leq n$ ,

$$\begin{aligned} \|u^m\|_{L_{t,x}^\infty} &\leq \|u_0\|_{L_x^\infty} + \frac{1}{4} \|u^{m-1}\|_{L_{t,x}^\infty} \\ &\leq \|u_0\|_{L_x^\infty} + \frac{1}{4} \left( \|u_0\|_{L_x^\infty} + \frac{1}{4} \|u^{m-2}\|_{L_{t,x}^\infty} \right) \\ &\leq \|u_0\|_{L_x^\infty} + \frac{1}{4} \left( \|u_0\|_{L_x^\infty} + \frac{1}{4} \left( \|u_0\|_{L_x^\infty} + \frac{1}{4} \|u^{m-3}\|_{L_{t,x}^\infty} \right) \right) \\ &= \left( 1 + \frac{1}{4} + \left( \frac{1}{4} \right)^2 \right) \|u_0\|_{L_x^\infty} + \left( \frac{1}{4} \right)^3 \|u^{m-3}\|_{L_{t,x}^\infty}. \end{aligned}$$

Continuing in this way, we find that for every  $m \leq n$ ,

$$\begin{aligned} \|u^m\|_{L_{t,x}^\infty} &\leq \sum_{k=0}^{m-2} \left( \frac{1}{4} \right)^k \|u^0\|_{L_x^\infty} + \left( \frac{1}{4} \right)^{m-1} \|u^1\|_{L_{t,x}^\infty} \\ &= \sum_{k=0}^{m-1} \left( \frac{1}{4} \right)^k \|u^1\|_{L_{t,x}^\infty} \leq \frac{4}{3} \|u^1\|_{L_{t,x}^\infty} = \frac{4}{3} \|u_0\|_{L_x^\infty} \leq 2\|u_0\|_{L_x^\infty}. \end{aligned} \tag{4.15}$$

We now show that  $T_{u^n}$  is a contraction map. Suppose  $p, \bar{p} \in B_R$ . Invoking the integral estimate in (4.4), the estimate on  $u^n$  in (4.15), and the condition on  $\tau$  in (4.6) successively,

$$\begin{aligned} \|T_{u^n}p - T_{u^n}\bar{p}\|_{L_{t,x}^\infty} &= \left\| \int_0^t \nabla G_\alpha(t-s) \cdot ((p - \bar{p})u^n) ds \right\|_{L_{t,x}^\infty} \\ &\leq \frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|p - \bar{p}\|_{L_{t,x}^\infty} \|u^n\|_{L_{t,x}^\infty} \leq 2\frac{2\alpha}{2\alpha-1} C\tau^{1-\frac{1}{2\alpha}} \|p - \bar{p}\|_{L_{t,x}^\infty} \|u_0\|_{L_x^\infty} \\ &\leq \frac{1}{4} \|p - \bar{p}\|_{L_{t,x}^\infty}. \end{aligned}$$

Moreover, observe that  $T_{u^n}p \in B_R$  whenever  $p \in B_R$ , as

$$\begin{aligned} \|T_{u^n}p\|_{L_{t,x}^\infty} &\leq \|T_{u^n}p - T_{u^n}0\|_{L_{t,x}^\infty} + \|T_{u^n}0\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{4}\|p\|_{L_{t,x}^\infty} + \|\theta_0\|_\infty \leq 2\|\theta_0\|_{L_x^\infty} = R. \end{aligned} \quad (4.16)$$

Thus,  $T_{u^n}$  has a fixed point  $\theta^{n+1}$  and we conclude by induction that

$$\|\theta^n\|_{L_{t,x}^\infty} \leq 2\|\theta_0\|_{L_x^\infty} \quad (4.17)$$

and

$$\|u^n\|_{L_{t,x}^\infty} \leq 2\|u_0\|_{L_x^\infty} \quad (4.18)$$

for all  $n > 1$ .

**Passing to the limit.** We show that the sequences  $\{\theta^n\}$  and  $\{u^n\}$  are Cauchy. Indeed, we have

$$\begin{aligned} \theta^{n+1} - \theta^n &= \int_0^t \nabla G_\alpha(t-s) \cdot (\theta^n u^{n-1} - \theta^{n+1} u^n) ds \\ &= \int_0^t \nabla G_\alpha(t-s) \cdot \theta^n (u^{n-1} - u^n) ds + \int_0^t \nabla G_\alpha(t-s) \cdot (\theta^n - \theta^{n+1}) u^n ds, \\ u^{n+1} - u^n &= \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta^n u^{n-1} - \theta^{n+1} u^n) ds \\ &= \int_0^t (K * \nabla G_\alpha(t-s)) \cdot \theta^n (u^{n-1} - u^n) ds \\ &\quad + \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta^n - \theta^{n+1}) u^n ds. \end{aligned}$$

Using the integral bounds in (4.4) and (4.5), one has the estimate,

$$\begin{aligned} &\|\theta^{n+1} - \theta^n\|_{L_{t,x}^\infty} + \|u^{n+1} - u^n\|_{L_{t,x}^\infty} \\ &\leq 2(\|u_0\|_{L^\infty} + \|\theta_0\|_{L^\infty}) C \frac{2\alpha}{2\alpha-1} \tau^{1-\frac{1}{2\alpha}} \left( \|\theta^{n+1} - \theta^n\|_{L_{t,x}^\infty} + \|u^n - u^{n-1}\|_{L_{t,x}^\infty} \right). \end{aligned}$$

By invoking the size condition on  $\tau$  in (4.6), we can write

$$\|\theta^{n+1} - \theta^n\|_{L_{t,x}^\infty} + \|u^{n+1} - u^n\|_{L_{t,x}^\infty} \leq \frac{1}{4} \left( \|\theta^{n+1} - \theta^n\|_{L_{t,x}^\infty} + \|u^n - u^{n-1}\|_{L_{t,x}^\infty} \right). \quad (4.19)$$

Thus

$$\|u^{n+1} - u^n\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|u^n - u^{n-1}\|_{L_{t,x}^\infty},$$

from which it follows that  $\{u^n\}$  is Cauchy and converges to  $u$  in  $L^\infty((0, \tau) \times \mathbb{R}^2)$ .

It also follows from (4.19) that

$$\frac{3}{4} \|\theta^{n+1} - \theta^n\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|u^n - u^{n-1}\|_{L_{t,x}^\infty},$$

so  $\{\theta^n\}$  is Cauchy and converges to  $\theta$  in  $L^\infty((0, \tau) \times \mathbb{R}^2)$ .

Finally, the above observations imply that

$$\|\theta\|_{L_{t,x}^\infty} \leq 2\|\theta_0\|_{L_x^\infty} \quad (4.20)$$

and

$$\|u\|_{L_{t,x}^\infty} \leq 2\|u_0\|_{L_x^\infty}. \quad (4.21)$$



**The limit  $(u, \theta)$  is a mild solution.** We have

$$\begin{aligned} u(t, x) - G_\alpha(t)u_0(x) + \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (u\theta)(s, x) ds \\ = u(t, x) - u^{n+1}(t, x) + \int_0^t (K * \nabla G_\alpha(t-s)) \cdot ((u\theta)(s) - (u^n\theta^{n+1})(s, x)) ds. \end{aligned}$$

Because  $u_n \rightarrow u$  and  $\theta_n \rightarrow \theta$  in  $L^\infty((0, \tau) \times \mathbb{R}^2)$  and are bounded in that same space, we have,

$$|((u\theta)(s) - (u^n\theta^{n+1})(s, x))| \leq C \left( \|u - u^n\|_{L_{t,x}^\infty} + \|\theta - \theta^{n+1}\|_{L_{t,x}^\infty} \right) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

It follows that

$$u(t, x) - G_\alpha(t)u_0(x) + \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (u\theta)(s, x) ds = 0.$$

With the parallel argument for  $\theta$ , we see that  $(u, \theta)$  is a mild solution to (SQG) as in Definition 1.1.

**Uniqueness.** For uniqueness, suppose  $(\theta, u)$  and  $(\tilde{\theta}, \tilde{u})$  are two mild solutions as in (1.1). We can then write

$$\begin{aligned} \|\theta - \tilde{\theta}\|_{L_{t,x}^\infty} + \|u - \tilde{u}\|_{L_{t,x}^\infty} \\ = \left\| \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u - \tilde{\theta} \tilde{u}) ds \right\|_{L_{t,x}^\infty} + \left\| \int_0^t K * \nabla G_\alpha(t-s) \cdot (\theta u - \tilde{\theta} \tilde{u}) ds \right\|_{L_{t,x}^\infty} \\ \leq \frac{4\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|\theta u - \tilde{\theta} \tilde{u}\|_{L_{t,x}^\infty} = \frac{4\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|\theta u - \tilde{\theta} u + \tilde{\theta} u - \tilde{\theta} \tilde{u}\|_{L_{t,x}^\infty} \\ \leq \frac{4\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \left( \|u\|_{L_{t,x}^\infty} \|\theta - \tilde{\theta}\|_{L_{t,x}^\infty} + \|\tilde{\theta}\|_{L_{t,x}^\infty} \|u - \tilde{u}\|_{L_{t,x}^\infty} \right). \end{aligned} \tag{4.22}$$

We apply the uniform bounds on  $\tilde{\theta}$  in (4.20) and  $u$  in (4.21), and the constraint on  $\tau$  in (4.6). We conclude that

$$\begin{aligned} \|\theta - \tilde{\theta}\|_{L_{t,x}^\infty} + \|u - \tilde{u}\|_{L_{t,x}^\infty} \\ \leq \frac{8\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \left( \|u_0\|_{L_{t,x}^\infty} \|\theta - \tilde{\theta}\|_{L_{t,x}^\infty} + \|\theta_0\|_{L_{t,x}^\infty} \|u - \tilde{u}\|_{L_{t,x}^\infty} \right) \\ \leq \frac{1}{2} \left( \|\theta - \tilde{\theta}\|_{L_{t,x}^\infty} + \|u - \tilde{u}\|_{L_{t,x}^\infty} \right). \end{aligned} \tag{4.23}$$

Thus,  $\theta = \tilde{\theta}$  and  $u = \tilde{u}$ . We conclude that  $(\theta, u)$  is the unique mild solution on  $[0, \tau]$ . With a simple application of Proposition 3.9, for all  $t \in [0, T]$ , we have  $u(t) = \text{p.v. } K * \theta(t)$ . Lastly, the stated continuity properties are a consequence of Proposition 3.8.

## 5. SPATIAL REGULARITY OF THE SOLUTION

In this section we establish the spatial regularity of short-time solutions as is stated in Theorem 1.3. Going forward, we set  $D^\gamma = \frac{\partial^{\gamma_1}}{\partial x^1} \frac{\partial^{\gamma_2}}{\partial x^2}$  for  $\gamma \in \mathbb{N}^2$ , and we let  $D$  denote the partial derivative with respect to either  $x_1$  or  $x_2$ .

**Proof of Theorem 1.3.** The argument is similar to that in [28]. We will manipulate (1.3) formally by taking spatial derivatives to obtain a map in terms of the derivatives of  $u$  and  $\theta$ . We can then apply a Banach fixed point argument to produce a solution. Our argument will use induction on the number of derivatives of  $u$  and  $\theta$ .

**5.1. Existence of first derivatives of  $\theta$  and  $u$ .** We start by noting that if  $D\theta$  and  $Du$  exist, then they must satisfy

$$\begin{aligned} D\theta &= G_\alpha(t)D\theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot ((D\theta)u + \theta Du) ds, \\ Du &= G_\alpha(t)Du_0 - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot ((D\theta)u + \theta Du) ds. \end{aligned} \quad (5.1)$$

Our strategy is to show that the operator defined by the right hand side of (5.1) has a fixed point. By uniqueness, the fixed point will correspond to our derivatives  $D\theta$  and  $Du$ . To show that (5.1) has a fixed point, we apply an argument similar to that used to show (1.3) has a fixed point.

Let  $\theta_0 \in C_b^1(\mathbb{R}^2)$  and  $u_0 \in (C_b^1(\mathbb{R}^2))^2$ . We will show that the sequence  $(\theta_x^n, u_x^n)$  generated by

$$\begin{aligned} \theta_x^1(t, x) &= D\theta_0(x), \\ u_x^1(t, x) &= Du_0(x), \end{aligned} \quad (5.2)$$

and

$$\begin{aligned} \theta_x^{n+1}(t, x) &= G_\alpha(t)D\theta_0(x) - \int_0^t \nabla G_\alpha(t-s) \cdot (\theta u_x^n + \theta_x^{n+1}u)(s) ds, \\ u_x^{n+1}(t, x) &= G_\alpha(t)Du_0(x) - \int_0^t K * \nabla G_\alpha(t-s) \cdot (\theta u_x^n + \theta_x^{n+1}u)(s) ds \end{aligned} \quad (5.3)$$

converges to the desired fixed point  $(D\theta, Du)$ . (That is, we will find that the sequence  $\theta_x^n$  converges to a limit as  $n \rightarrow \infty$ . We have previously shown that  $\theta$  exists, and we will call this limit  $\theta_x$ . However, that will leave a step still to establish, which is to show that this  $\theta_x$  is actually the derivative of our  $\theta$  with respect to  $x$ . And, of course, we establish the corresponding results for  $u$  as well.) We first construct solutions  $\theta_x$  and  $u_x$  on  $[0, \tau]$  with initial data  $(\theta_0, u_0)$ , where  $\tau$  is the same as in (4.6), satisfying

$$\frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} (\|u_0\|_{L_x^\infty} + \|\theta_0\|_{L_x^\infty}) \leq 1/8. \quad (5.4)$$

Set  $R = 2 \max\{\|\theta_0\|_{C_b^1}, \|u_0\|_{C_b^1}\}$  and  $B_R = \{f \in L^\infty([0, \tau] \times \mathbb{R}^2) : \|f\|_{L_{t,x}^\infty} \leq R\}$ . We will use an inductive argument to posit the existence and boundedness of the sequence  $(\theta_x^n, u_x^n)$ . For the base case, it is obvious that  $\|\theta_x^1\|_{L_{t,x}^\infty} \leq R$  and  $\|u_x^1\|_{L_{t,x}^\infty} \leq R$ . For the inductive step, suppose that for all  $0 < t < \tau$ ,  $\theta_x^n$  and  $u_x^n$  satisfy (5.3) with the bounds

$$\|\theta_x^n\|_{L_{t,x}^\infty} \leq R \text{ and } \|u_x^n\|_{L_{t,x}^\infty} \leq R. \quad (5.5)$$

We aim to show the existence of  $\theta_x^{n+1}$  and  $u_x^{n+1}$  satisfying (5.3). Using a Banach fixed point argument, assign the maps

$$T'_\omega p = DG_\alpha(t)\theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot (\theta\omega + pu) ds,$$

and

$$U'_p \omega = DG_\alpha(t)u_0 - \int_0^t K * \nabla G_\alpha(t-s) \cdot (\theta \omega + pu) ds,$$

and let  $p, \bar{p} \in B_R$ . We apply our uniform bound on  $u$  in (4.21) and the size condition on  $\tau$  in (5.4) to yield

$$\begin{aligned} \|T'_{u_x^n}(p - \bar{p})\|_{L_{t,x}^\infty} &= \left\| \int_0^t \nabla G_\alpha(t-s) \cdot (u(p - \bar{p})) ds \right\|_{L_{t,x}^\infty} \\ &\leq 2 \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|u_0\|_{L_x^\infty} \|p - \bar{p}\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|p - \bar{p}\|_{L_{t,x}^\infty}. \end{aligned} \quad (5.6)$$

To see that  $T'_{u_x^n}$  maps  $B_R$  into  $B_R$ , we use (5.6), the integral estimate (4.4), and the boundedness of  $\theta_0$  in  $C_b^1$  to write

$$\begin{aligned} \|T'_{u_x^n} f\|_{L_{t,x}^\infty} &\leq \|T'_{u_x^n} f - T'_{u_x^n} 0\|_{L_{t,x}^\infty} + \|T'_{u_x^n} 0\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{4} \|p\|_{L_{t,x}^\infty} + \left\| G_\alpha(t) D\theta_0 - \int_0^t \nabla G_\alpha(t-s) (u_x^n \theta) ds \right\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{4} \|p\|_{L_{t,x}^\infty} + \|G_\alpha(t) D\theta_0\|_{L_{t,x}^\infty} + \left\| \int_0^t \nabla G_\alpha(t-s) (u_x^n \theta) ds \right\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{4} \|p\|_{L_{t,x}^\infty} + \|\theta_0\|_{C_b^1} + \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|u_x^n\|_{L_{t,x}^\infty} \|\theta\|_{L_{t,x}^\infty}. \end{aligned}$$

The uniform bound on  $\theta$  in (4.20) and (5.4) gives

$$\begin{aligned} \|T'_{u_x^n} f\|_{L_{t,x}^\infty} &\leq \frac{1}{4} \|f\|_{L_{t,x}^\infty} + \|\theta_0\|_{C_b^1} + 2 \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \|u_x^n\|_{L_{t,x}^\infty} \|\theta_0\|_{L_{t,x}^\infty} \\ &\leq \frac{1}{4} \|f\|_{L_{t,x}^\infty} + \|\theta_0\|_{C_b^1} + \frac{1}{4} \|u_x^n\|_{L_{t,x}^\infty}. \end{aligned}$$

By our induction hypothesis (5.5),

$$\|T'_{u_x^n} f\|_{L_{t,x}^\infty} \leq \frac{1}{4} R + \|\theta_0\|_{C_b^1} + \frac{1}{4} R \leq R. \quad (5.7)$$

We therefore have shown the existence of  $\theta_x^{n+1}$  satisfying (5.3)<sub>1</sub> and (5.5). We apply a similar argument on  $U'_{\theta_x^{n+1}}$  to yield the existence of  $u_x^{n+1}$  satisfying (5.3)<sub>2</sub>. Note also that, thanks to the integral estimate in (4.5), the condition on  $\tau$  given by (5.4), the uniform bounds on  $\theta$  and  $u$  given by (4.20) and (4.21) respectively, and our induction hypothesis in (5.5), we derive the following inequalities.

$$\begin{aligned} \|u_x^{n+1}\|_{L_{t,x}^\infty} &= \left\| G_\alpha(t) Du_0(x) - \int_0^t K * \nabla G_\alpha(t-s) \cdot (u_x^n \theta + \theta u_x^{n+1})(s) ds \right\|_{L_{t,x}^\infty} \\ &\leq \|G_\alpha(t) Du_0(x)\|_{L_{t,x}^\infty} + \left\| \int_0^t K * \nabla G_\alpha(t-s) \cdot (u_x^n \theta + \theta u_x^{n+1})(s) ds \right\|_{L_{t,x}^\infty} \\ &\leq \|u_0\|_{C_b^1} + \frac{2\alpha}{2\alpha-1} C \tau^{1-\frac{1}{2\alpha}} \left( \|u_x^n\|_{L_{t,x}^\infty} \|\theta\|_{L_{t,x}^\infty} + \|u\|_{L_{t,x}^\infty} \|\theta_x^{n+1}\|_{L_{t,x}^\infty} \right) \\ &\leq \|u_0\|_{C_b^1} + \frac{1}{4} \|u_x^n\|_{L_{t,x}^\infty} + \frac{1}{4} \|\theta_x^{n+1}\|_{L_{t,x}^\infty} \leq R. \end{aligned} \quad (5.8)$$

Hence, we can generate the sequences  $\{\theta_x^n\}$  and  $\{u_x^n\}$ , which by construction possess weak- $\star$  limits  $\theta_x$  and  $u_x$ , respectively, in  $L_{t,x}^\infty$ .

To finalize the proof of the existence of  $D\theta$  and  $Du$ , we show that  $\theta_x$  and  $u_x$  satisfy (5.1). To this end, note that by an argument identical to that leading to (4.19), we have

$$\|\theta_x^{n+1} - \theta_x^n\|_{L_{t,x}^\infty} + \|u_x^{n+1} - u_x^n\|_{L_{t,x}^\infty} \leq \frac{1}{4}(\|\theta_x^{n+1} - \theta_x^n\|_{L_{t,x}^\infty} + \|u_x^n - u_x^{n-1}\|_{L_{t,x}^\infty}), \quad (5.9)$$

from which we conclude, as in Section 4, that

$$\|u_x^{n+1} - u_x^n\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|u_x^n - u_x^{n-1}\|_{L_{t,x}^\infty}.$$

Thus,  $\{u_x^n\}$  is Cauchy and converges to  $u_x$  in  $L^\infty((0, \tau) \times \mathbb{R}^2)$ .

It also follows from (5.9) that

$$\frac{3}{4} \|\theta_x^{n+1} - \theta_x^n\|_{L_{t,x}^\infty} \leq \frac{1}{4} \|u_x^n - u_x^{n-1}\|_{L_{t,x}^\infty},$$

so  $\{\theta_x^n\}$  is Cauchy and converges to  $\theta_x$  in  $L^\infty((0, \tau) \times \mathbb{R}^2)$ .

Let  $Du$  satisfy  $Du = U'_{\theta_x} Du$ , and let  $D\theta$  satisfy  $T'_{Du} D\theta = D\theta$ . We omit the proof of the existence of  $Du$  and  $D\theta$ , but their existence and the bounds

$$\|D\theta\|_{L_{t,x}^\infty} \leq R \text{ and } \|Du\|_{L_{t,x}^\infty} \leq R, \quad (5.10)$$

are readily checked with an analogous argument given by the previous considerations in (5.6), (5.7) and (5.8).

To see that  $\theta_x = D\theta$ , we show that  $\theta_x$  also satisfies  $T'_{Du} \theta_x = \theta_x$ . We write

$$\begin{aligned} \theta_x - DG(t)\theta_0 + \int_0^t \nabla G_\alpha(t-s) \cdot (\theta_x u + \theta u_x) ds \\ = \theta_x - \theta_x^n + \int_0^t \nabla G_\alpha(t-s) \cdot ((\theta_x u + \theta u_x) - (\theta_x^n u + \theta u_x^{n-1})) ds. \end{aligned}$$

As  $u_x^n \rightarrow u_x$  and  $\theta_x^n \rightarrow \theta_x$  in  $L^\infty((0, T) \times \mathbb{R}^2)$  and are bounded in that same space, we have,

$$|(\theta_x u + \theta u_x) - (\theta_x^n u + \theta u_x^{n-1})| \leq C \left( \|\theta_x - \theta_x^n\|_{L_{t,x}^\infty} + \|u_x - u_x^{n-1}\|_{L_{t,x}^\infty} \right) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

It follows that

$$\theta_x(t, x) - DG_\alpha(t)\theta_0(x) + \int_0^t (K * \nabla G_\alpha(t-s)) \cdot (\theta_x u + \theta u_x)(s, x) ds = 0,$$

and we have  $T'_{Du} \theta_x = \theta_x$ .

A similar argument shows that  $U'_{D\theta} u_x = u_x$ .

We conclude by the uniqueness of the fixed point in the Banach contraction mapping theorem that  $\theta_x = D\theta$  and  $u_x = Du$ . Thus the first order derivatives of  $u$  and  $\theta$  exist and satisfy (5.1).

**5.2. Existence of higher derivatives of  $\theta$  and  $u$ .** To establish existence of higher derivatives, we once more use induction. Fix  $k \in \mathbb{N}$  and set  $R = 2 \max\{\|\theta_0\|_{C_b^k}, \|u_0\|_{C_b^k}\}$ . The base case is shown in the previous section. For the inductive step, suppose that  $D^\beta \theta$  and  $D^\beta u$  exist for all  $\beta \in \mathbb{N}^2$  satisfying  $|\beta| < k$  with the bound

$$\|\theta\|_{C_b^{k-1}} \leq R \text{ and } \|u\|_{C_b^{k-1}} \leq R.$$

Our objective is to show the existence of  $D^\gamma \theta$  and  $D^\gamma u$  for  $\gamma \in \mathbb{N}^2$  with  $|\gamma| = k$ . First note that if such derivatives were to exist, then, by the Leibniz rule, they would satisfy

$$D^\gamma \theta = G_\alpha(t) D^\gamma \theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot \left[ \sum_{0 \leq \beta \leq \gamma} \binom{\gamma}{\beta} D^\beta \theta D^{\gamma-\beta} u \right] ds, \quad (5.11)$$

and

$$D^\gamma u = G_\alpha(t) D^\gamma u_0 - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot \left[ \sum_{0 \leq \beta \leq \gamma} \binom{\gamma}{\beta} D^\beta \theta D^{\gamma-\beta} u \right] ds. \quad (5.12)$$

As in the previous subsection, we construct sequences  $\{u_\gamma^n\}$  and  $\{\theta_\gamma^n\}$  via an iterative scheme and show that the sequences converge to  $D^\gamma u$  and  $D^\gamma \theta$ , respectively. First let

$$\theta_\gamma^1(t, x) \equiv D^\gamma \theta_0(x) \text{ and } u_\gamma^1(t, x) \equiv D^\gamma u_0,$$

and, using a similar iterative scheme as in (5.3), set

$$\theta_\gamma^{n+1} = G_\alpha(t) D^\gamma \theta_0 - \int_0^t \nabla G_\alpha(t-s) \cdot \left[ \theta_\gamma^{n+1} u + \theta u_\gamma^n + \sum_{0 < \beta < \gamma} \binom{\gamma}{\beta} D^\beta \theta D^{\gamma-\beta} u \right] ds,$$

and

$$u_\gamma^{n+1} = G_\alpha(t) D^\gamma u_0 - \int_0^t (K * \nabla G_\alpha(t-s)) \cdot \left[ \theta_\gamma^{n+1} u + \theta u_\gamma^n + \sum_{0 < \beta < \gamma} \binom{\gamma}{\beta} D^\beta \theta D^{\gamma-\beta} u \right] ds. \quad (5.13)$$

The argument that  $\{\theta_\gamma^n\}$  converges uniformly to  $D^\gamma \theta$  and that  $\{u_\gamma^n\}$  converges uniformly to  $D^\gamma u$  is virtually identical to the analogous argument for the first derivatives of  $\theta$  and  $u$  as given in Subsection 5.1, so we omit the details. Remarkably, the higher derivatives satisfy that following bounds.

$$\|D^\gamma \theta\|_{L_{t,x}^\infty} \leq R \text{ and } \|D^\gamma u\|_{L_{t,x}^\infty} \leq R. \quad (5.14)$$

This completes the proof of Theorem 1.3.  $\square$

We can also show that the first spatial derivatives of  $\theta$  are continuous in time. The proof follows as a direct variation of Proposition 3.8.

**Lemma 5.1.** *Let  $\alpha > \frac{1}{2}$  and select  $\theta_0 \in C_b^1(\mathbb{R}^2)$ ,  $u_0 \in C_b^1(\mathbb{R}^2)^2$  satisfying  $u_0 = \text{p.v. } K * \theta_0$ . Let  $(\theta, u)$  be the mild solution given by Theorem 1.2 which exists up to time  $T$ . For all  $t < T$ , we have  $\partial_{x_i} \theta(t, x)$  is continuous in  $t$  for all  $t > 0$  for  $i = 1, 2$ .*

*Proof.* We first aim to bound the size of  $\partial_{x_i}\theta(b, x) - \partial_{x_i}\theta(a, x)$  uniformly in  $x$  for  $a, b > 0$ . We can write

$$\begin{aligned} \|\partial_{x_i}\theta(b, x) - \partial_{x_i}\theta(a, x)\|_{L_x^\infty} &\leq \|(G_\alpha(b) - G_\alpha(a)) \partial_{x_i}\theta_0\|_{L_x^\infty} \\ &+ \left\| \int_0^b \nabla G_\alpha(b-s) \cdot (\partial_{x_i}\theta u + \theta \partial_{x_i}u)(s, x) ds - \int_0^a \nabla G_\alpha(a-s) \cdot (\partial_{x_i}\theta u + \theta \partial_{x_i}u)(s, x) ds \right\|_{L_x^\infty} \\ &\leq \|(G_\alpha(b) - G_\alpha(a)) \partial_{x_i}\theta_0(x)\|_{L_x^\infty} + \left\| \int_a^b \nabla G_\alpha(b-s) \cdot (\partial_{x_i}\theta u + \theta \partial_{x_i}u)(s, x) ds \right\|_{L_x^\infty} \\ &\quad + \left\| \int_0^a (\nabla G_\alpha(b-s) - \nabla G_\alpha(a-s)) \cdot (\partial_{x_i}\theta u + \theta \partial_{x_i}u) ds \right\|_{L_x^\infty}. \end{aligned} \quad (5.15)$$

For the second term on the right hand side of (5.15), applying Young's inequality and Lemma 2.9 for  $k = 1$  gives the bound,

$$\begin{aligned} \left\| \int_a^b \nabla G_\alpha(b-s) \cdot (\partial_{x_i}\theta u + \theta \partial_{x_i}u)(s, x) ds \right\|_{L_x^\infty} &\leq C \int_a^b (b-s)^{-\frac{1}{2\alpha}} \|(\partial_{x_i}\theta u + \theta \partial_{x_i}u)(s)\|_{L_x^\infty} ds \\ &\leq \frac{2\alpha}{2\alpha-1} C \|\partial_{x_i}\theta u + \theta \partial_{x_i}u\|_{L_{t,x}^\infty} (b-a)^{1-\frac{1}{2\alpha}}. \end{aligned} \quad (5.16)$$

Observe that  $\|\partial_{x_i}\theta u + \theta \partial_{x_i}u\|_{L_{t,x}^\infty}$  is bounded as a consequence of Theorem 1.3. Moreover, applying Young's inequality to the third term on the right hand side of (5.15), we have

$$\begin{aligned} &\left\| \int_0^a (\nabla G_\alpha(b-s) - \nabla G_\alpha(a-s)) \cdot (\partial_{x_i}\theta u + \theta \partial_{x_i}u)(s, x) ds \right\|_{L_x^\infty} \\ &\leq \|\partial_{x_i}\theta u + \theta \partial_{x_i}u\|_{L_{t,x}^\infty} \int_0^a \|\nabla g_\alpha(b-s) - \nabla g_\alpha(a-s)\|_{L_x^1} ds. \end{aligned}$$

The argument then follows similarly to that after line (3.3).  $\square$

Lastly, we conclude with a proof of Theorem 1.6.

## 6. EXTENDING THE SOLUTION

**6.1. Improved bounds on  $(\theta, u)$ .** Having established the short time existence and regularity of  $(\theta, u)$ , we now extend the solution to all  $t \in [0, \infty)$ . In order to achieve an extension, we must establish the appropriate  $L^\infty$  bounds for  $(\theta, u)$ ; in particular, the current bounds  $\|\theta\|_{L_{t,x}^\infty} \leq 2\|\theta_0\|_{L_x^\infty}$  and  $\|u\|_{L_{t,x}^\infty} \leq 2\|u_0\|_{L_x^\infty}$  only allow us to extend the solution up to some finite time.

To begin, we restate a convolution-type Grönwall inequality from [27].

**Lemma 6.1** (Volterra-Grönwall Inequality (Theorem 3.2 of [27])). *Suppose  $v(t) \in L^\infty([0, T])$  with  $v(t) \geq 0$  for all  $t \in [0, T]$ , and let  $a \geq 0, b > 0$ , and  $0 < \gamma < 1$  be constants. If  $v(t)$  satisfies the inequality*

$$v(t) \leq a + b \int_0^t (t-s)^{-\gamma} v(s) ds \text{ for a.e } t \in [0, T],$$

then

$$v(t) \leq \frac{a}{1-\gamma} \exp \left( \frac{b}{1-\gamma} \left( \frac{\gamma}{bB_0} \right)^{-\frac{\gamma}{1-\gamma}} t \right) \text{ for a.e } t \in [0, T].$$

Here  $B_0 = B(1-\gamma, 1)$  where  $B(x, y)$  is the Beta function.

From here, we are able to improve the  $L^\infty$  bound on  $u$ .

**Proposition 6.2.** *Let  $T > 0$ . Suppose  $(\theta, u)$  is a mild solution to (SQG) on  $[0, T]$  with initial data  $(\theta_0, u_0) \in L^\infty(\mathbb{R}^2)$ . Then  $u$  satisfies the bound:*

$$\|u(t)\|_{L_x^\infty} \leq \mu \|u_0\|_{L_x^\infty} \exp \left( C_\alpha \|\theta(t)\|_{L_x^\infty}^\mu t \right),$$

where

$$\mu = \frac{2\alpha}{2\alpha-1}, \quad B_0 = B(\mu^{-1}, 1), \quad \text{and} \quad C_\alpha = \frac{2\alpha}{2\alpha-1} C(2\alpha B_0)^{\frac{1}{2\alpha-1}}. \quad (6.1)$$

*Proof.* Applying the  $L^\infty$  norm to (1.3)<sub>2</sub> and using the fact that  $G_\alpha$  is a probability measure, we obtain,

$$\|u(t)\|_{L_x^\infty} \leq \|u_0\|_{L_x^\infty} + \left\| \int_0^t K * \nabla G_\alpha(t-s) \cdot (\theta u)(s, x) ds \right\|_{L_x^\infty}. \quad (6.2)$$

Next, bringing the  $L^\infty$  norm inside the integral, invoking Young's convolution inequality, and applying the bound on  $K * \nabla G_\alpha(t)$  in Lemma 2.9 yields

$$\begin{aligned} \|u(t)\|_{L_x^\infty} &\leq \|u_0\|_{L_x^\infty} + \int_0^t C(t-s)^{-\frac{1}{2\alpha}} \|\theta u\|_{L_x^\infty} ds \\ &\leq \|u_0\|_{L_x^\infty} + \|\theta\|_{L^\infty([0,t];\mathbb{R}^2)} \int_0^t C(t-s)^{-\frac{1}{2\alpha}} \|u\|_{L_x^\infty} ds. \end{aligned}$$

To reach the conclusion, we employ Lemma 6.1 with

$$a = \|u_0\|_{L_x^\infty}, \quad b = C\|\theta\|_{L^\infty([0,t];\mathbb{R}^2)}, \quad \text{and} \quad \gamma = \frac{1}{2\alpha}$$

to produce the desired inequality,

$$\|u(t)\|_{L_x^\infty} \leq \frac{2\alpha}{2\alpha-1} \|u_0\|_{L_x^\infty} \exp \left( \frac{2\alpha}{2\alpha-1} C\|\theta\|_{L^\infty([0,t];\mathbb{R}^2)} (2\alpha B_0 \|\theta\|_{L^\infty([0,t];\mathbb{R}^2)})^{\frac{1}{2\alpha-1}} t \right).$$

□

We now establish a maximum principle for a solution  $\theta$  of (SQG) with sufficient regularity.

**Proposition 6.3.** *Let  $\alpha \in (\frac{1}{2}, 1]$ . Suppose that  $(\theta, u) \in (L^\infty([0, T]; C_b^2(\mathbb{R}^2)))^3$  is a mild solution to (SQG) on  $[0, T]$  for some  $T$  with initial data  $(\theta_0, u_0)$ . Then  $\theta$  obeys the maximum principle*

$$\|\theta\|_{L^\infty([0,T] \times \mathbb{R}^2)} \leq \|\theta_0\|_{L_x^\infty}.$$

*Proof.* With the hypotheses of the proposition, by Proposition 3.10,  $(\theta, u)$  is a  $C^2$ -solution to

$$\partial_t \theta + u \cdot \nabla \theta = -\nu \Lambda^{2\alpha} \theta \quad (6.3)$$

on  $[0, T] \times \mathbb{R}^2$ .

Let  $\phi$  be a smooth, compactly supported bump function, with  $\phi$  identically one on  $B_1(0)$  and  $\text{supp } \phi$  contained in  $B_2(0)$ . For each  $R > 0$  and  $x \in \mathbb{R}^2$ , set  $\phi_R(x) = \phi(x/R)$ .



We multiply (6.3) by  $\phi_R$ , which gives

$$\frac{\partial}{\partial t}(\phi_R \theta) + \phi_R u \cdot \nabla \theta = -\nu \phi_R \Lambda^{2\alpha} \theta. \quad (6.4)$$

Using the product rule, we have

$$u \cdot \nabla(\phi_R \theta) = \theta u \cdot \nabla \phi_R + \phi_R u \cdot \nabla \theta.$$

Making the above substitution and adding and subtracting  $\nu \Lambda^{2\alpha}(\phi_R \theta)$ , one has

$$\begin{aligned} \frac{\partial}{\partial t}(\phi_R \theta) + u \cdot \nabla(\phi_R \theta) &= \theta u \cdot \nabla \phi_R - \nu \phi_R \Lambda^{2\alpha} \theta + \nu \Lambda^{2\alpha}(\phi_R \theta) - \nu \Lambda^{2\alpha}(\phi_R \theta) \\ &= -\nu \Lambda^{2\alpha}(\phi_R \theta) + I + II, \end{aligned} \quad (6.5)$$

where

$$I = u \theta \cdot \nabla \phi_R$$

and

$$II = \nu [\Lambda^{2\alpha}, \phi_R] \theta.$$

Now, for  $p \geq 2$ , multiply (6.5) by  $p|\phi_R \theta|^{p-2} \phi_R \theta$  and integrate over  $\mathbb{R}^2$ . This gives

$$\begin{aligned} \int_{\mathbb{R}^2} p|\phi_R \theta|^{p-2} \phi_R \theta \frac{\partial}{\partial t}(\phi_R \theta) dx &= - \int_{\mathbb{R}^2} p|\phi_R \theta|^{p-2} \phi_R \theta u \cdot \nabla(\phi_R \theta) dx \\ &\quad - \int_{\mathbb{R}^2} \nu p|\phi_R \theta|^{p-2} \phi_R \theta \Lambda^{2\alpha}(\phi_R \theta) dx + \int_{\mathbb{R}^2} p|\phi_R \theta|^{p-2} \phi_R \theta (I + II) dx. \end{aligned}$$

Using a weak derivative formulation, we apply the identity  $\frac{d}{dt}|z(t)|^p = p|z(t)|^{p-2} z(t) \frac{dz}{dt}$  and the Liebniz integral rule to conclude that

$$\int_{\mathbb{R}^2} p|\phi_R \theta|^{p-2} \phi_R \theta \frac{\partial}{\partial t}(\phi_R \theta) dx = \int_{\mathbb{R}^2} \frac{\partial}{\partial t} |\phi_R \theta|^p dx = \frac{d}{dt} \int_{\mathbb{R}^2} |\phi_R \theta|^p dx.$$

Therefore, we have

$$\begin{aligned} \frac{d}{dt} \|\phi_R \theta\|_{L^p}^p &= -p \int_{\mathbb{R}^2} |\phi_R \theta|^{p-2} \phi_R \theta u \cdot \nabla(\phi_R \theta) dx \\ &\quad - \nu p \int_{\mathbb{R}^2} |\phi_R \theta|^{p-2} \phi_R \theta \Lambda^{2\alpha}(\phi_R \theta) dx + p \int_{\mathbb{R}^2} |\phi_R \theta|^{p-2} \phi_R \theta (I + II) dx. \end{aligned} \quad (6.6)$$

With the divergence free condition on  $u_0$ , by Lemma 3.1,  $u$  is divergence free for all time, so we can recast the first term on the right hand side of (6.6) as

$$\begin{aligned} p \int_{\mathbb{R}^2} |\phi_R \theta|^{p-2} \phi_R \theta u \cdot \nabla(\phi_R \theta) dx &= \int_{\mathbb{R}^2} u \cdot \nabla(\phi_R \theta)^p dx \\ &= - \int_{\mathbb{R}^2} (\phi_R \theta)^p \operatorname{div} u dx = 0. \end{aligned} \quad (6.7)$$

Moreover, by Lemma 2.5 of [10],

$$-p\nu \int_{\mathbb{R}^2} |\phi_R \theta|^{p-2} (\phi_R \theta) \Lambda^{2\alpha}(\phi_R \theta) dx \leq 0.$$

Thus,

$$p \|\phi_R \theta\|_{L_x^p}^{p-1} \frac{d}{dt} \|\phi_R \theta\|_{L_x^p} \leq p \int_{\mathbb{R}^2} |\phi_R \theta|^{p-2} \phi_R \theta (I + II) dx. \quad (6.8)$$

We divide both sides of (6.8) by  $p\|\phi_R\theta\|_{L_x^p}^{p-1}$ . We conclude that

$$\begin{aligned} \frac{d}{dt}\|\phi_R\theta\|_{L_x^p} &\leq p \left( \frac{1}{p\|\phi_R\theta\|_{L_x^p}^{p-1}} \right) \int_{\mathbb{R}^2} |\phi_R\theta|^{p-2} \phi_R\theta(I + II) dx \\ &\leq \|I + II\|_{L_x^\infty} \frac{\|\phi_R\theta\|_{L_x^{p-1}}^{p-1}}{\|\phi_R\theta\|_{L_x^p}^{p-1}} = \|I + II\|_{L_x^\infty} \left( \frac{\|\phi_R\theta\|_{L_x^{p-1}}}{\|\phi_R\theta\|_{L_x^p}} \right)^{p-1}. \end{aligned} \quad (6.9)$$

We now bound the second term in the product. By the generalized Hölder inequality and the compactness of the support of  $\phi$ ,

$$\|\phi_R\theta\|_{L_x^{p-1}} = \|\phi_{2R}\phi_R\theta\|_{L_x^{p-1}} \leq \|\phi_{2R}\|_{L_x^{p(p-1)}} \|\phi_R\theta\|_{L_x^p} \leq (2\pi R^2)^{\frac{1}{p(p-1)}} \|\phi_R\theta\|_{L_x^p}.$$

This implies

$$\left( \frac{\|\phi_R\theta\|_{L_x^{p-1}}}{\|\phi_R\theta\|_{L_x^p}} \right)^{p-1} \leq (2\pi R^2)^{\frac{1}{p}}.$$

Substituting the above bound into (6.9), we find that for any  $p \in [1, \infty)$  and any fixed  $R < \infty$ ,

$$\frac{d}{dt}\|\phi_R\theta\|_{L_x^p} \leq (2\pi R^2)^{\frac{1}{p}} \|I(s) + II(s)\|_{L_x^\infty}.$$

Integrating the above expression over time, we get

$$\|\phi_R\theta(t)\|_{L_x^p} \leq \|\phi_R\theta_0\|_{L_x^p} + (2\pi R^2)^{\frac{2}{p}} \int_0^t \|I(s) + II(s)\|_{L_x^\infty} ds.$$

We take the limit as  $p \rightarrow \infty$  to produce the bound

$$\|\phi_R\theta(t)\|_{L_x^\infty} \leq \|\phi_R\theta_0\|_{L_x^\infty} + \int_0^t \|I(s) + II(s)\|_{L_x^\infty} ds. \quad (6.10)$$

We claim that  $\|I(t) + II(t)\|_{L_x^\infty} < \infty$  for all  $t$  and moreover,

$$\lim_{R \rightarrow \infty} \|I(t) + II(t)\|_{L_x^\infty} = 0.$$

Clearly we have

$$\|I\|_{L_x^\infty} \leq \frac{1}{R} \|(\theta u)(s, x)\|_{L_x^\infty} \|\nabla \phi\|_{L_x^\infty}. \quad (6.11)$$

We now estimate the commutator term  $II$ . We consider two cases separately:  $\alpha \in (1/2, 1)$  and  $\alpha = 1$ . First assume  $\alpha \in (1/2, 1)$ . We expand the fractional Laplacian using the singular integral definition (2.2), since  $\theta \in C_b^2(\mathbb{R}^2)$ . We then simplify the commutator as follows:

$$\begin{aligned} [\Lambda^{2\alpha}, \phi_R]\theta(x) &= \phi_R(x) \int_{\mathbb{R}^2} \frac{\theta(x) - \theta(y)}{|x - y|^{2+2\alpha}} dy - \int_{\mathbb{R}^2} \frac{\phi_R(x)\theta(x) - \phi_R(y)\theta(y)}{|x - y|^{2+2\alpha}} dy \\ &= \int_{\mathbb{R}^2} \frac{\phi_R(y)\theta(y) - \phi_R(x)\theta(x)}{|x - y|^{2+2\alpha}} dy. \end{aligned}$$

We now split up the above integral into two parts,

$$[\Lambda^{2\alpha}, \phi_R]\theta(x) = III + IV,$$

where

$$\begin{aligned} III &= \int_{\mathbb{R}^2} \phi(x-y) \frac{\phi_R(y)\theta(y) - \phi_R(x)\theta(y)}{|x-y|^{2+2\alpha}} dy, \\ IV &= \int_{\mathbb{R}^2} (1-\phi)(x-y) \frac{\phi_R(y)\theta(y) - \phi_R(x)\theta(y)}{|x-y|^{2+2\alpha}} dy. \end{aligned}$$

We estimate  $III$  and  $IV$  separately. Starting with  $III$ , write

$$\begin{aligned} III &= \int_{\mathbb{R}^2} \phi(x-y) \frac{\phi_R(y)\theta(y) - \phi_R(x)\theta(y)}{|x-y|^{2+2\alpha}} dy \\ &= \int_{\mathbb{R}^2} \phi(x-y) \frac{(\phi_R(y) - \phi_R(x))(\theta(y) - \theta(x)) + \phi_R(y)\theta(x) - \phi_R(x)\theta(x)}{|x-y|^{2+2\alpha}} dy \\ &= \int_{\mathbb{R}^2} \phi(x-y) \frac{(\phi_R(y) - \phi_R(x))(\theta(y) - \theta(x))}{|x-y|^{2+2\alpha}} dy + \theta(x) \int_{\mathbb{R}^2} \phi(x-y) \frac{(\phi_R(y) - \phi_R(x))}{|x-y|^{2+2\alpha}} dy. \end{aligned}$$

We invoke the Lipschitz bounds on  $\phi_R$  and  $\theta$ , as well as the singular integral definition of  $\Lambda^{2\alpha}$ , and find that

$$\begin{aligned} III &\leq \|\nabla\phi_R\|_{L_x^\infty} \|\nabla\theta\|_{L_x^\infty} \int_{\mathbb{R}^2} \frac{\phi(x-y)}{|x-y|^{2\alpha}} + \left| \theta(x) \int_{\mathbb{R}^2} \phi(x-y) \frac{(\phi_R(y) - \phi_R(x))}{|x-y|^{2+2\alpha}} dy \right| \\ &\leq C \|\nabla\phi_R\|_{L_x^\infty} \|\nabla\theta\|_{L_x^\infty} + |\theta(x) \Lambda^{2\alpha}\phi_R(x)| \\ &\quad + \left| \theta(x) \int_{\mathbb{R}^2} (1-\phi)(x-y) \frac{(\phi_R(y) - \phi_R(x))}{|x-y|^{2+2\alpha}} dy \right| \\ &\leq C \|\nabla\phi_R\|_{L_x^\infty} \|\nabla\theta\|_{L_x^\infty} + \|\theta\|_{L_x^\infty} \|\Lambda^{2\alpha}\phi_R\|_{L_x^\infty} + C \|\theta\|_{L_x^\infty} \|\nabla\phi_R\|_{L_x^\infty}. \end{aligned} \tag{6.12}$$

Moving on to  $IV$ , we use the Lipschitz bound of  $\phi_R$  to write

$$\begin{aligned} IV &\leq \int_{\mathbb{R}^2} (1-\phi)(x-y) \frac{(\phi_R(y) - \phi_R(x))}{|x-y|^{2+2\alpha}} |\theta(y)| dy \\ &\leq \|\theta\|_{L_x^\infty} \|\nabla\phi_R\|_{L_x^\infty} \int_{\mathbb{R}^2} \frac{(1-\phi)(x-y)}{|x-y|^{1+2\alpha}} dy \leq C \|\theta\|_{L_x^\infty} \|\nabla\phi_R\|_{L_x^\infty}. \end{aligned} \tag{6.13}$$

Combining (6.12) and (6.13), we conclude that

$$\|[\Lambda^{2\alpha}, \phi_R]\theta(x)\|_{L_x^\infty} = \|III + IV\|_{L_x^\infty} \leq \tilde{C} \|\theta\|_{C_b^1} (\|\nabla\phi_R\|_{L_x^\infty} + \|\Lambda^{2\alpha}\phi_R\|_{L_x^\infty}).$$

It remains to show that as  $R \rightarrow \infty$ , the above quantities vanish in the limit. Clearly we have

$$\|\nabla\phi_R\|_{L_x^\infty} \leq \frac{1}{R} \left\| (\nabla\phi) \left( \frac{x}{R} \right) \right\|_{L_x^\infty} = \frac{1}{R} \|\nabla\phi\|_{L_x^\infty}. \tag{6.14}$$

Lastly, we have to prove  $\|\Lambda^{2\alpha}\phi_R\|_{L_x^\infty} \rightarrow 0$  as  $R$  approaches infinity. To see why this is the case, write

$$\begin{aligned} \Lambda^{2\alpha}\phi_R(x) &= \int_{\mathbb{R}^2} \frac{\phi_R(y) - \phi_R(x)}{|x-y|^{2+2\alpha}} dy = \frac{1}{R^{2+2\alpha}} \int_{\mathbb{R}^2} \frac{\phi(y/R) - \phi(x/R)}{|(x/R) - (y/R)|^{2+2\alpha}} dy \\ &= \frac{1}{R^{2\alpha}} \int_{\mathbb{R}^2} \frac{\phi(z) - \phi(x/R)}{|(x/R) - z|^{2+2\alpha}} dz = \frac{1}{R^{2\alpha}} (\Lambda^{2\alpha}\phi)(x/R). \end{aligned} \tag{6.15}$$

Therefore,

$$\|\Lambda^{2\alpha}\phi_R\|_{L_x^\infty} = \frac{1}{R^{2\alpha}} \|(\Lambda^{2\alpha}\phi)(\cdot/R)\|_{L_x^\infty} = \frac{1}{R^{2\alpha}} \|\Lambda^{2\alpha}\phi\|_{L_x^\infty}. \tag{6.16}$$

Gathering (6.14) and (6.16), we obtain the following commutator estimate:

$$\|[\Lambda^{2\alpha}, \phi_R]\theta(x)\|_{L_x^\infty} \leq \tilde{C}\|\theta\|_{C_{b,x}^1} \left( \frac{1}{R}\|\nabla\phi\|_{L_x^\infty} + \frac{1}{R^{2\alpha}}\|\Lambda^{2\alpha}\phi\|_{L_x^\infty} \right). \quad (6.17)$$

Substituting (6.17) and the estimate for  $I$  in (6.11) into the  $L^\infty$  bound for the cutoff of  $\theta$  in (6.10), we conclude that

$$\begin{aligned} \|\phi_R\theta(t)\|_{L_x^\infty} &\leq \|\phi_R\theta_0\|_{L_x^\infty} + \int_0^t \left( \frac{1}{R}\|(u\theta)(s)\|_{L_x^\infty}\|\nabla\phi\|_{L_x^\infty} \right. \\ &\quad \left. + \tilde{C}\nu\|\theta(s)\|_{C_{b,x}^1} \left( \frac{1}{R}\|\nabla\phi\|_{L_x^\infty} + \frac{1}{R^{2\alpha}}\|\Lambda^{2\alpha}\phi\|_{L_x^\infty} \right) \right) ds. \end{aligned}$$

Thus, given our hypotheses, which imply  $\theta \in C_{b,t,x}^1$ , we can rewrite the above expression as

$$\begin{aligned} \|\phi_R\theta(t)\|_{L_x^\infty} &\leq \|\phi_R\theta_0\|_{L_x^\infty} + t \left( \frac{1}{R}\|\theta u\|_{L_{t,x}^\infty}\|\nabla\phi\|_{L_x^\infty} \right. \\ &\quad \left. + \tilde{C}\|\theta\|_{C_{b,t,x}^1} \left( \frac{1}{R}\|\nabla\phi\|_{L_x^\infty} + \frac{1}{R^{2\alpha}}\|\Lambda^{2\alpha}\phi\|_{L_x^\infty} \right) \right). \end{aligned} \quad (6.18)$$

Taking the limit  $R \rightarrow \infty$  and invoking the weak- $\star$  convergence of  $\phi_R\theta \rightarrow \theta$  and the uniform boundedness principle yields the desired conclusion,

$$\|\theta(t)\|_{L_x^\infty} \leq \|\theta_0\|_{L_x^\infty}, \quad (6.19)$$

for all  $t \in [0, \tau)$ , when  $\alpha \in (1/2, 1)$ .

Now suppose that  $\alpha = 1$ . We again fix  $R > 0$  and multiply (6.3) by the radial function  $\phi_R$ , which gives

$$\frac{\partial}{\partial t}(\phi_R\theta) + \phi_R u \cdot \nabla\theta = \nu\phi_R\Delta\theta.$$

We expand the Laplacian term as

$$\phi_R\Delta\theta = \Delta(\phi_R\theta) - \theta\Delta\phi_R - 2\nabla\theta \cdot \nabla\phi_R.$$

Proceeding as before, we multiply by  $p|\phi_R\theta|^{p-2}\phi_R\theta$  and integrate over  $\mathbb{R}^2$ , leading to

$$\frac{d}{dt}\|\phi_R\theta\|_{L^p}^p \leq p \int_{\mathbb{R}^2} |\phi_R\theta|^{p-2} \phi_R\theta(I + II') dx,$$

where

$$II' = -\nu\theta\Delta\phi_R - 2\nu\nabla\theta \cdot \nabla\phi_R.$$

For the new term, we have

$$\begin{aligned} \|II'\|_{L^\infty} &\leq \nu\|\Delta\phi_R\|_{L^\infty}\|\theta\|_{L^\infty} + 2\nu\|\nabla\phi_R\|_{L^\infty}\|\nabla\theta\|_{L^\infty} \\ &\leq \frac{\tilde{C}'\nu}{R^2}\|\theta\|_{L^\infty} + \frac{\tilde{C}'\nu}{R}\|\nabla\theta\|_{L^\infty}, \end{aligned} \quad (6.20)$$

Repeating the argument up to (6.10), we get

$$\|\phi_R\theta(t)\|_{L_x^\infty} \leq \|\phi_R\theta_0\|_{L_x^\infty} + \int_0^t \|I(s) + II'(s)\|_{L_x^\infty} ds.$$

By repeating an analogous argument as above, we arrive at the same conclusion. That is, for  $\alpha = 1$ ,

$$\|\theta(t)\|_{L_x^\infty} \leq \|\theta_0\|_{L_x^\infty} \quad (6.21)$$

for all  $t \in [0, T]$ .  $\square$

**6.2. Extending the Solution.** In this section we prove Theorems 1.4 and 1.5.

**Proof of Theorem 1.4.** By Theorem 1.2, we can produce a short time solution  $(\theta, u)$  on  $[0, \tau]$  for some  $\tau > 0$ . By Theorem 1.3,  $(\theta(t), u(t)) \in (C_b^2(\mathbb{R}^2))^3$  for all  $t \in [0, \tau]$ . This implies that  $(\theta, u)$  is a classical solution to (SQG) on  $[0, \tau]$  by Proposition 3.9 and Proposition 3.10. Moreover, from the construction of the solution, we have  $\|\theta(t)\|_{L_x^\infty} \leq 2\|\theta_0\|_{L_x^\infty}$  and  $\|u(t)\|_{L_x^\infty} \leq 2\|u_0\|_{L_x^\infty}$ . In fact, we have better bounds for the solution:

$$\begin{aligned} \text{(i) By Proposition 6.3, } & \|\theta(t)\|_{L_x^\infty} \leq \|\theta_0\|_{L_x^\infty}, \quad \forall t \in [0, \tau]. \\ \text{(ii) By Proposition 6.2, } & \|u(t)\|_{L_x^\infty} \leq \frac{2\alpha}{2\alpha-1} \|u_0\|_{L_x^\infty} \exp(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu t), \quad \forall t \in [0, \tau], \end{aligned} \quad (6.22)$$

where

$$\mu = \frac{2\alpha}{2\alpha-1} \quad \text{and} \quad C_\alpha = \frac{2\alpha}{2\alpha-1} C(2\alpha B_0)^{\frac{1}{2\alpha-1}}.$$

Let  $\tau_1 = \tau$ . Inductively, we will create a sequence  $\{\tau_n\}_{n=1}^\infty$  of finite times for which we can extend the solution. To do so, for each additional extension time  $\tau_n$ , we verify that the conditions (6.22) hold.

For each integer  $k \geq 1$ , define

$$S_k := \sum_{j=1}^k \tau_j.$$

Suppose that we have constructed the solution up to time  $S_{n-1}$  and that (6.22) holds for all  $t \in [0, S_{n-1}]$ . Then, define  $\tau_n$  as in (4.6) by

$$\frac{2\alpha}{2\alpha-1} C \tau_n^{1-\frac{1}{2\alpha}} \left( \|\theta_0\|_{L_x^\infty} + \frac{2\alpha}{2\alpha-1} \|u_0\|_{L_x^\infty} \exp\left(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu S_{n-1}\right) \right) \leq \frac{1}{8}. \quad (6.23)$$

For this  $\tau_n$ , setting  $S_n := S_{n-1} + \tau_n$ , we use Theorem 1.2 to generate a mild solution to (SQG) on  $[S_{n-1}, S_n]$  whose initial data is given by  $(\theta(S_{n-1}, x), u(S_{n-1}, x))$ . With Theorem 1.3, the extended solution satisfies  $(\theta, u) \in (L^\infty([0, S_n]; C_b^2(\mathbb{R}^2)))^3$ . Moreover, on the interval  $[0, S_n]$ , we have the a priori bounds on  $\theta$  and  $u$  given by

$$\begin{aligned} \|\theta\|_{L^\infty([0, S_n] \times \mathbb{R}^2)} & \leq \max \left\{ \|\theta\|_{L^\infty([S_{n-1}, S_n] \times \mathbb{R}^2)}, \|\theta\|_{L^\infty([0, S_{n-1}] \times \mathbb{R}^2)} \right\} \\ & \leq \max \left\{ 2\|\theta(S_{n-1}, \cdot)\|_{L_x^\infty}, \|\theta_0\|_{L_x^\infty} \right\} \leq 2\|\theta_0\|_{L_x^\infty}, \end{aligned}$$

and similarly,

$$\begin{aligned} \|u\|_{L^\infty([0, S_n] \times \mathbb{R}^2)} & \leq \max \left\{ \|u\|_{L^\infty([S_{n-1}, S_n] \times \mathbb{R}^2)}, \|u\|_{L^\infty([0, S_{n-1}] \times \mathbb{R}^2)} \right\} \\ & \leq \max \left\{ 2\|u(S_{n-1}, \cdot)\|_{L_x^\infty}, \frac{2\alpha}{2\alpha-1} \|u_0\|_{L_x^\infty} \exp(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu t) \right\} \\ & \leq \frac{4\alpha}{2\alpha-1} \|u_0\|_{L_x^\infty} \exp(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu t). \end{aligned}$$

Thus, we improve these estimates to match our induction hypothesis.

- (1) We now have that a classical solution exists on  $[0, S_n]$ . Thus, with Proposition 6.3, we deduce  $\|\theta(t)\|_{L_x^\infty} \leq \|\theta_0\|_{L_x^\infty}$  for all  $t \in [0, S_n]$ .

- (2) By Proposition 6.2,  $\|u(t)\|_{L_x^\infty} \lesssim \|u_0\|_{L_x^\infty} \exp(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu t)$  for some exponent  $\mu > 0$  and all  $t \in [0, S_n]$ .

Lastly, we verify that this extension process will cover all time  $t \in [0, \infty)$ . Rearranging (6.23) and solving for  $\tau_n$  gives

$$\tau_n \leq \left[ \frac{1}{8} \frac{2\alpha - 1}{2\alpha} \frac{1}{C} \frac{1}{\|\theta_0\|_{L_x^\infty} + \frac{2\alpha}{2\alpha - 1} \|u_0\|_{L_x^\infty} \exp\left(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu S_{n-1}\right)} \right]^{\frac{2\alpha}{2\alpha - 1}}.$$

For large  $S_{n-1}$  the exponential term dominates so that

$$\tau_n \gtrsim \exp(-\lambda S_{n-1}),$$

for some  $\lambda > 0$ . It is clear that  $S_n$  satisfies the discrete recurrence,

$$S_n = S_{n-1} + \tau_n \quad \text{with} \quad \tau_n \gtrsim \exp(-\lambda S_{n-1}).$$

For that reason, consider the continuous ODE analogue:

$$\frac{dS}{dn} = \exp(-\lambda S), \quad S(0) = S_0.$$

Hence,

$$S(n) = \frac{1}{\lambda} \ln(\lambda n + \exp(\lambda S_0)).$$

Since  $\ln(\lambda n + \exp(\lambda S_0)) \rightarrow \infty$  as  $n \rightarrow \infty$ , we conclude that  $S(n) \rightarrow \infty$ . By a discrete-continuous comparison argument, it follows that

$$\sum_{n=1}^{\infty} \tau_n = \lim_{n \rightarrow \infty} S_n = \infty.$$

Therefore, we conclude that the solution can be extended for arbitrary time. Moreover, for any  $T > 0$ , we have the bounds,

- (1)  $\|\theta\|_{L^\infty([0, T] \times \mathbb{R}^2)} \leq \|\theta_0\|_{L^\infty(\mathbb{R}^2)}$  and
- (2)  $\|u\|_{L^\infty([0, T] \times \mathbb{R}^2)} \leq \|u_0\|_{L_x^\infty} \exp\left(C_\alpha \|\theta_0\|_{L_x^\infty}^\mu T\right).$

We conclude from Theorem 1.3 that if  $(\theta_0, u_0) \in C_b^k(\mathbb{R}^2)$ , then the higher derivatives of  $(\theta, u)$  also exist on the interval  $[0, \tau_n]$  for  $n$  arbitrarily large. Moreover, we have the simple estimate  $\|\nabla^k \theta\|_{L^\infty([0, \tau_n] \times \mathbb{R}^2)} \leq 2^n \|\nabla^k \theta_0\|_{L_x^\infty}$  and  $\|\nabla^k u\|_{L^\infty([0, \tau_n] \times \mathbb{R}^2)} \leq 2^n \|\nabla u_0\|_{L_x^\infty}$ .  $\square$

Having extended the  $C^k$  solution for  $k \geq 2$  to be global in time, we now use this result to extend solutions whose initial data is in  $L^\infty(\mathbb{R}^2)$ . We present the proof of Theorem 1.5

**Proof of Theorem 1.5.** For the mild solutions  $(\theta, u)$ , if  $(\theta_0, u_0)$  are not  $C^\gamma$  continuous for some  $\gamma$ , set  $(\theta_0, u_0) := (\theta(t), u(t))$  for some arbitrarily small  $t \in [0, T]$ . As a consequence of Proposition 3.2, we can assume that there exists  $\gamma > 0$  such that  $u_0$  and  $\theta_0$  belong to  $C^\gamma(\mathbb{R}^2)$ . Let  $\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}$  be a smooth bump function and consider  $\varphi_n(x) := n^2 \varphi(nx)$ . Consider the sequence  $\theta_0^n := \varphi_n * \theta_0$ . Clearly,  $\theta_0^n \in L^\infty(\mathbb{R}^2)$  and moreover  $u_0^n := \text{p. v. } K * \theta_0^n$  exists and is an element of  $L^\infty(\mathbb{R}^2)$  as

$$\|\text{p. v. } K * (\varphi_n * \theta)\|_\infty \leq \|\varphi_n\|_{L^1} \|\text{p. v. } K * \theta\|_{L^\infty}.$$

Because of the convolution, we have that  $(\theta_0^n, u_0^n)$  is sufficiently regular that Theorem 1.4 applies. We can therefore let  $(\theta^n, u^n)$  be the classical solution on  $[0, T]$  with initial data  $(\theta_0^n, u_0^n)$ . We show that  $\{(\theta^n, u^n)\}_{n=1}^\infty$  is Cauchy in  $L_{t,x}^\infty$ . For  $n > m \geq 0$ ,

$$\|\theta^n - \theta^m\|_{L_x^\infty} \leq \|G_\alpha(t)(\theta_0^n - \theta_0^m)\|_{L_x^\infty} + \int_0^t \|\nabla G_\alpha(t-s) \cdot ((\theta^n u^n - \theta^m u^m)(s, x))\|_{L_x^\infty} ds$$

and similarly for  $u$ ,

$$\|u^n - u^m\|_{L_x^\infty} \leq \|G_\alpha(t)(u_0^n - u_0^m)\|_{L_x^\infty} + \int_0^t \|(K * \nabla G_\alpha(t-s)) \cdot ((\theta^n u^n - \theta^m u^m)(s, x))\|_{L_x^\infty} ds.$$

Adding the above lines together we invoke the boundedness of  $G_\alpha(t)$ ,

$$\begin{aligned} \|\theta^n - \theta^m\|_{L_x^\infty} + \|u^n - u^m\|_{L_x^\infty} &\leq \|\theta_0^n - \theta_0^m\|_{L_{t,x}^\infty} + \|u_0^n - u_0^m\|_{L_{t,x}^\infty} \\ &\quad + \int_0^t \|\nabla G_\alpha(t-s) \cdot ((\theta^n u^n - \theta^m u^m)(s, x))\|_{L_x^\infty} ds \\ &\quad + \int_0^t \|K * \nabla G_\alpha(t-s) \cdot ((\theta^n u^n - \theta^m u^m)(s, x))\|_{L_x^\infty} ds. \end{aligned}$$

Now apply the kernel estimates of Lemma 2.9,

$$\begin{aligned} \|\theta^n - \theta^m\|_{L_x^\infty} + \|u^n - u^m\|_{L_x^\infty} &\leq \|\theta_0^n - \theta_0^m\|_{L_{t,x}^\infty} + \|u_0^n - u_0^m\|_{L_{t,x}^\infty} \\ &\quad + 2C \int_0^t (t-s)^{-\frac{1}{2\alpha}} \|\theta^n u^n - \theta^m u^m\|_{L_x^\infty} ds. \end{aligned}$$

Further, by adding and subtracting  $\theta^n u^m$ , one can derive the bound

$$\begin{aligned} \|\theta^n - \theta^m\|_{L_x^\infty} + \|u^n - u^m\|_{L_x^\infty} &\leq \|\theta_0^n - \theta_0^m\|_{L_{t,x}^\infty} + \|u_0^n - u_0^m\|_{L_{t,x}^\infty} \\ &\quad + 2C \left( \|\theta^n\|_{L_{t,x}^\infty} + \|u^m\|_{L_{t,x}^\infty} \right) \int_0^t (t-s)^{-\frac{1}{2\alpha}} \left( \|\theta^n - \theta^m\|_{L_x^\infty} + \|u^n - u^m\|_{L_x^\infty} \right) ds. \end{aligned} \quad (6.24)$$

Thus, by Volterra-Grönwall inequality as in Lemma 6.1, one has

$$\begin{aligned} &\|\theta^n - \theta^m\|_{L_x^\infty} + \|u^n - u^m\|_{L_x^\infty} \\ &\leq \mu \left( \|\theta_0^n - \theta_0^m\|_{L_{t,x}^\infty} + \|u_0^n - u_0^m\|_{L_{t,x}^\infty} \right) \exp \left( C_\alpha \left( 2C \left( \|\theta^n\|_{L_{t,x}^\infty} + \|u^m\|_{L_{t,x}^\infty} \right)^\mu \right) t \right), \end{aligned}$$

where  $\mu$  and  $C_\alpha$  are given by (6.1). Next, invoking the  $C^\gamma$  continuity of the initial data, by an approximation to the identity argument (see Lemma 8.14 of [12]) we have,

$$\theta_0^\varepsilon \rightarrow \theta_0 \text{ and } u_0^\varepsilon \rightarrow u_0 \text{ as } \varepsilon \rightarrow 0.$$

For fixed  $T$ , one can conclude  $\{(\theta^n, u^n)\}_{n=1}^\infty$  forms a Cauchy sequence.

Since the sequence converges uniformly and each element of the sequence satisfies a mild formulation, it is clear that the limit  $(\theta, u)$  will also satisfy the mild solution definition. Therefore, for arbitrary  $T > 0$ , there exists a mild solution  $(\theta, u)$  to (SQG) on  $[0, T]$  with initial data  $(\theta_0, u_0) \in (L^\infty(\mathbb{R}^2))^3$ , and with  $\|\theta\|_{L_{t,x}^\infty} \leq \|\theta_0\|_{L_x^\infty}$ .  $\square$

Finally, we show Theorem 1.6.

**Proof of Theorem 1.6.** The first conclusion holds from Theorem 1.2. The second conclusion follows from Theorem 1.3. The global existence of solutions follows from Theorem 1.4. The fact that  $C^2$  solutions to (SSQG) satisfy the equation in a classical sense follows from Proposition 3.11.  $\square$

## APPENDIX A.

We conclude by showing the equivalence of the definitions of  $\Lambda$  and  $\Lambda_I$  on  $C_b^2(\mathbb{R}^2)$ .

**Lemma A.1.** *Suppose that  $f \in C_b^2(\mathbb{R}^2)$ , then for  $\alpha \in (1/2, 1)$ ,*

$$\Lambda^{2\alpha} f \equiv \Lambda_I^{2\alpha} f.$$

*Proof.* As a consequence of Lemma 3.10 of [14] or Lemma 1 Section V of [25], it suffices to show that  $\Lambda_I^{2\alpha} f$  is well defined as  $\text{Dom}(\Lambda_I^{2\alpha}; L^\infty(\mathbb{R}^2)) \subset \text{Dom}(\Lambda^{2\alpha}; L^\infty(\mathbb{R}^2))$ . To that end, we first break the integral into two pieces,

$$\Lambda_I^{2\alpha} f = \lim_{r \rightarrow 0^+} \int_{r < |h| < 1} \underbrace{\frac{f(x+h) - f(x)}{|h|^{2+2\alpha}} dh}_{=: I(x)} + \underbrace{\int_{|h| > 1} \frac{f(x+h) - f(x)}{|h|^{2+2\alpha}} dh}_{=: II(x)}.$$

We first work with  $I(x)$  by using the differentiability of  $f$ . Rewrite  $I(x)$  as

$$I(x) = \lim_{r \rightarrow 0^+} \frac{1}{2} \int_{r < |h| < 1} \frac{f(x+h) - 2f(x) + f(x-h)}{|h|^{2+2\alpha}} dh.$$

Since  $f \in C_b^2(\mathbb{R}^2)$ , by the Mean Value Theorem there exists some  $\xi$  on the line segment from  $x$  to  $x+h$  such that

$$f(x+h) - f(x) = \nabla f(x+\xi h) \cdot h.$$

Similarly, there exists some  $\zeta$  on the segment from  $x-h$  to  $x$  such that

$$f(x) - f(x-h) = \nabla f(x-\zeta h) \cdot h.$$

Subtracting the second equality from the first, we obtain

$$f(x+h) - 2f(x) + f(x-h) = \nabla f(x+\xi h) \cdot h - \nabla f(x-\zeta h) \cdot h.$$

Now, we apply the Mean Value Theorem once more to the difference  $\nabla f(x+\xi h) - \nabla f(x-\zeta h)$ . Since  $f \in C_b^2(\mathbb{R}^2)$  implies that  $\nabla f$  is Lipschitz, there exists some point  $\eta$  (lying on the line segment connecting  $x+\xi h$  and  $x-\zeta h$ ) such that

$$\nabla f(x+\xi h) - \nabla f(x-\zeta h) = D^2 f(\eta) [(x+\xi h) - (x-\zeta h)] = D^2 f(\eta) [(\xi+\zeta)h].$$

Noting that  $\xi, \zeta \in [0, 1]$  so that  $\xi + \zeta \leq 2$ , we deduce

$$|f(x+h) - 2f(x) + f(x-h)| \leq \|D^2 f\|_{L^\infty} (\xi + \zeta) |h|^2 \leq 2 \|D^2 f\|_{L^\infty} |h|^2.$$

Thus, for every  $x \in \mathbb{R}^2$  and  $h \neq 0$  we have

$$\frac{|f(x+h) - 2f(x) + f(x-h)|}{|h|^{2+2\alpha}} \leq 2 \|D^2 f\|_{L^\infty} \frac{|h|^2}{|h|^{2+2\alpha}} = 2 \|D^2 f\|_{L^\infty} \frac{1}{|h|^{2\alpha}}.$$

Thus, since  $\alpha \in (1/2, 1)$ ,

$$|I(x)| \leq 2 \|D^2 f\|_{L^\infty} \int_{|h| \leq 1} \frac{dh}{|h|^{2\alpha}} < \infty.$$

Turning to estimate  $II$ , we have

$$\begin{aligned} |II(x)| &\leq \int_{|h| > 1} \frac{|f(x+h) - f(x)|}{|h|^{2+2\alpha}} \leq \int_{|h| > 1} \frac{|f(x+h) - f(x)|}{|h|^{2+2\alpha}} \\ &\leq \|f\|_{L^\infty} \int_{|h| > 1} \frac{1}{|h|^{2+2\alpha}} dh < \infty. \end{aligned}$$



Hence, the principal-value integral

$$I(x) = \frac{1}{2} \lim_{r \rightarrow 0^+} \int_{|h| > r} \frac{f(x+h) - 2f(x) + f(x-h)}{|h|^{2+2\alpha}} dh$$

converges absolutely for each  $x \in \mathbb{R}^2$ , and so the singular integral definition of the fractional Laplacian is well defined for  $f \in C_b^2(\mathbb{R}^2)$ . □

#### ACKNOWLEDGMENTS

DMA is grateful to the National Science Foundation for support through grant DMS-2307638. EC is grateful to the Simons Foundation for support through grant 429578.

#### REFERENCES

- [1] H. Abidi and T. Hmidi. On the global well-posedness of the critical quasi-geostrophic equation. *SIAM J. Math. Anal.*, 40(1):167–185, 2008. [2](#)
- [2] D.M. Ambrose, E. Cozzi, D. Erickson, and J.P. Kelliher. Existence of solutions to fluid equations in Hölder and uniformly local Sobolev spaces. *J. Differential Equations*, 364:107–151, 2023. [4](#), [5](#)
- [3] D.M. Ambrose, J.P. Kelliher, M.C. Lopes Filho, and H.J. Nussenzweig Lopes. Serfati solutions to the 2D Euler equations on exterior domains. *J. Differential Equations*, 259(9):4509–4560, 2015. [4](#)
- [4] H. Bahouri, J.-Y. Chemin, and R. Danchin. *Fourier analysis and nonlinear partial differential equations*, volume 343 of *Grundlehren der mathematischen Wissenschaften*. Springer, Heidelberg, 2011. [7](#)
- [5] K. Bogdan, T. Grzywny, and M. Ryznar. Heat kernel estimates for the fractional Laplacian with Dirichlet conditions. *Ann. Probab.*, 38(5):1901–1923, 2010. [9](#)
- [6] D. Chae and J. Lee. Global well-posedness in the super-critical dissipative quasi-geostrophic equations. *Comm. Math. Phys.*, 233(2):297–311, 2003. [2](#)
- [7] Q. Chen, C. Miao, and Z. Zhang. A new Bernstein’s inequality and the 2D dissipative quasi-geostrophic equation. *Comm. Math. Phys.*, 271(3):821–838, 2007. [2](#)
- [8] P. Constantin, A.J. Majda, and E.G. Tabak. Singular front formation in a model for quasigeostrophic flow. *Phys. Fluids*, 6(1):9–11, 1994. [2](#)
- [9] P. Constantin and J. Wu. Behavior of solutions of 2D quasi-geostrophic equations. *SIAM J. Math. Anal.*, 30(5):937–948, 1999. [2](#)
- [10] A. Córdoba and D. Córdoba. A maximum principle applied to quasi-geostrophic equations. *Comm. Math. Phys.*, 249(3):511–528, 2004. [37](#)
- [11] H. Dong and D. Li. On the 2D critical and supercritical dissipative quasi-geostrophic equation in Besov spaces. *J. Differential Equations*, 248(11):2684–2702, 2010. [2](#)
- [12] G.B. Folland. *Real analysis: Modern techniques and their applications*. Pure and Applied Mathematics. John Wiley & Sons, Inc., New York, second edition, 1999. [19](#), [24](#), [43](#)
- [13] A. Kiselev, F. Nazarov, and A. Volberg. Global well-posedness for the critical 2D dissipative quasi-geostrophic equation. *Invent. Math.*, 167(3):445–453, 2007. [2](#)
- [14] M. Kwaśnicki. Ten equivalent definitions of the fractional Laplace operator. *Fract. Calc. Appl. Anal.*, 20(1):7–51, 2017. [44](#)
- [15] O. Lazar. Global existence for the critical dissipative surface quasi-geostrophic equation. *Comm. Math. Phys.*, 322(1):73–93, 2013. [2](#)
- [16] O. Lazar. Global and local existence for the dissipative critical SQG equation with small oscillations. *J. Math. Fluid Mech.*, 17(3):533–549, 2015. [2](#)
- [17] F. Marchand. Existence and regularity of weak solutions to the quasi-geostrophic equations in the spaces  $L^p$  or  $\dot{H}^{-1/2}$ . *Comm. Math. Phys.*, 277(1):45–67, 2008. [3](#)
- [18] F. Marchand and P.G. Lemarié-Rieusset. Solutions auto-similaires non radiales pour l’équation quasi-geostrophique dissipative critique. *C. R. Math. Acad. Sci. Paris*, 341(9):535–538, 2005. [3](#)
- [19] R. May and E. Zahrouni. Global existence of solutions for subcritical quasi-geostrophic equations. *Commun. Pure Appl. Anal.*, 7(5):1179–1191, 2008. [2](#)
- [20] S.G. Resnick. *Dynamical problems in non-linear advective partial differential equations*. ProQuest LLC, Ann Arbor, MI, 1995. Thesis (Ph.D.)—The University of Chicago. [2](#)

- [21] W. Rudin. *Principles of mathematical analysis*. International Series in Pure and Applied Mathematics. McGraw-Hill Book Co., New York-Auckland-Düsseldorf, third edition, 1976. [21](#)
- [22] Y. Sawano. Homogeneous Besov spaces. *Kyoto J. Math.*, 60(1):1–43, 2020. [7](#)
- [23] M. Schonbek and T. Schonbek. Moments and lower bounds in the far-field of solutions to quasi-geostrophic flows. *Discrete Contin. Dyn. Syst.*, 13(5):1277–1304, 2005. [9](#)
- [24] P. Serfati. Solutions  $C^\infty$  en temps,  $n$ -log Lipschitz bornées en espace et équation d'Euler. *C. R. Acad. Sci. Paris Sér. I Math.*, 320(5):555–558, 1995. [4](#)
- [25] E.M. Stein. *Singular integrals and differentiability properties of functions*, volume No. 30 of *Princeton Mathematical Series*. Princeton University Press, Princeton, NJ, 1970. [9](#), [44](#)
- [26] J.P. Ward, K.N. Chaudhury, and M. Unser. Decay properties of Riesz transforms and steerable wavelets. *SIAM J. Imaging Sci.*, 6(2):984–998, 2013. [8](#), [9](#), [14](#)
- [27] J.R.L. Webb. Weakly singular Gronwall inequalities and applications to fractional differential equations. *J. Math. Anal. Appl.*, 471(1-2):692–711, 2019. [35](#)
- [28] J. Wu. Dissipative quasi-geostrophic equations with  $L^p$  data. *Electron. J. Differential Equations*, pages No. 56, 13, 2001. [2](#), [31](#)

DEPARTMENT OF MATHEMATICS, DREXEL UNIVERSITY  
 Email address: [dma68@drexel.edu](mailto:dma68@drexel.edu)

DEPARTMENT OF MATHEMATICS, UNIVERSITY OF CALIFORNIA, RIVERSIDE  
 Email address: [ryan.aschoff@email.ucr.edu](mailto:ryan.aschoff@email.ucr.edu)

DEPARTMENT OF MATHEMATICS, OREGON STATE UNIVERSITY  
 Email address: [cozzie@math.oregonstate.edu](mailto:cozzie@math.oregonstate.edu)

DEPARTMENT OF MATHEMATICS, UNIVERSITY OF CALIFORNIA, RIVERSIDE  
 Email address: [kelliher@math.ucr.edu](mailto:kelliher@math.ucr.edu)