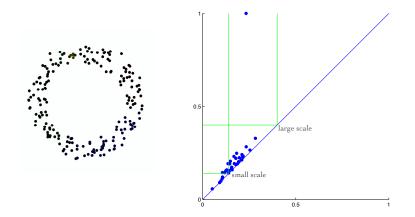
Metrics on Functor Categories & Reeb Graph Operations

Vin de Silva Pomona College

AMS Sectional Meeting, UC Riverside 9–10 November 2019

Edelsbrunner, Letscher, Zomorodian 2000

Persistent homology takes a filtered space $\mathbb{X} = \{X_t \mid t \in \mathbf{R}\}$ and returns a barcode of intervals $[p, q) \subset \mathbf{R}$ or a persistence diagram of points $(p, q) \in \mathbf{R}^2$.



Persistence diagrams

Using commutative algebra (Zomorodian, Carlsson 2003).

- Discretize the *t*-variable to integers: t = 0, 1, 2, ...
- Present X as an increasing sequence:

$$\mathbb{X}$$
: $X_0 \subset X_1 \subset X_2 \subset \ldots$

• Apply a homology functor $H = H(-; \mathbf{k})$ to obtain a **persistence module**:

$$\mathsf{H}(\mathbb{X}): \quad \mathsf{H}(X_0) \to \mathsf{H}(X_1) \to \mathsf{H}(X_2) \to \dots$$

- Observe that H(X) is a graded module over the polynomial ring k[z], where z acts by shifting to the right.
- Decompose this graded module as a direct sum of cyclic submodules.
- Summands $z^{s}\mathbf{k}[z]/(z^{t-s})$ are recorded as intervals [s, t).
- Summands $z^{s}\mathbf{k}[z]$ are recorded as intervals $[s, +\infty)$.

Stability theorem (Cohen-Steiner, Edelsbrunner, Harer 2007)

The map {persistence modules} \rightarrow {diagrams} is 1-Lipschitz.

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Relators

The metrics on the two spaces are defined in terms of 'relators'.

- Two persistence modules may be related by an interleaving.
- Two diagrams may be related by a matching.

Every relator, of each type, has a size associated with it. The metrics are defined by finding the infimum of the size of relators between a given pair of objects. (Compare the geodesic distance in a Riemannian manifold.)

Stability theorem (Cohen-Steiner, Edelsbrunner, Harer 2007)

If two persistence modules admit an $\epsilon\text{-interleaving},$ then their persistence diagrams admit an $\epsilon\text{-matching}.$

Interleaving of Persistence Modules

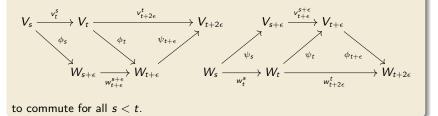
Definition

Let \mathbb{V}, \mathbb{W} be persistence modules. An ϵ -interleaving between \mathbb{V}, \mathbb{W} is a pair (Φ, Ψ) where $\Phi = (\phi_t)$ and $\Psi = (\psi_t)$ are collections of maps

$$\phi_t: V_t \to W_{t+\epsilon} \qquad \qquad \psi_t: W_t \to V_{t+\epsilon}$$

such that [various conditions].

The [various conditions] require the diagrams



Interleaving of Persistence Modules

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Interleavor categories (Chazal, dS, Glisse, Oudot 2016)

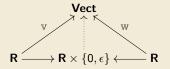
An ϵ -interleaved pair of modules $(\mathbb{V}, \mathbb{W}, \Phi, \Psi)$ is 'the same thing' as a persistence module defined over the set $\mathbf{I} = \mathbf{R} \times \{0, \epsilon\}$ (two copies of the real line) with the partial order

$$(s,a) \leq (t,b) \Leftrightarrow egin{cases} s \leq t & ext{if } a = b \ s + \epsilon \leq t & ext{if } a
eq b \end{cases}$$

 $\mathbf{R} \times \{\mathbf{0}, \epsilon\}:$

Interleavings for classical persistence modules

Two classical persistence modules \mathbb{V}, \mathbb{W} are ϵ -interleaved iff the following functor extension problem has a solution:

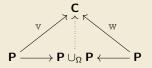


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Interleavings for generalized persistence modules over a poset

Two persistence modules $\mathbb{V}, \mathbb{W} : \mathbf{P} \to \mathbf{C}$ are Ω -interleaved iff the following functor extension problem has a solution:



Here $\mathbf{P} \cup_{\Omega} \mathbf{P}$ has the partial order

$$(s,a) \leq (t,b) \Leftrightarrow egin{cases} s \leq t & ext{if } a = b \ \Omega s \leq t & ext{if } a \neq b \end{cases}$$

where $\Omega : \mathbf{P} \to \mathbf{P}$ is a translation.

Translations (Bubenik, dS, Scott 2015)

Trans_P is the poset of functions $\Omega : \mathbf{P} \to \mathbf{P}$ that are order-preserving and satisfy $x \leq \Omega x$ for all $x \in \mathbf{P}$.

Superlinear Families

A superlinear family is a 1-parameter family of translations of P

 $(\Omega_{\epsilon} \mid \epsilon \in [0,\infty))$

such that

$$\Omega_{\epsilon_1}\Omega_{\epsilon_2} \leq \Omega_{\epsilon_1+\epsilon_2}$$

for all $\epsilon_1, \epsilon_2 \in [0, \infty)$.

Sublinear Projections

A sublinear projection is a map π : Trans_P \rightarrow $[0,\infty]$ such that

```
\pi(\Omega_1\Omega_2) \leq \pi(\Omega_1) + \pi(\Omega_2)
```

for all $\Omega_1, \Omega_2 \in \mathbf{Trans}_{\mathbf{P}}$.

Interleaving Metrics on Functor Categories

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Examples of superlinear famlies

•
$$\mathbf{P} = \mathbf{R}$$
,
 $\Omega_{\epsilon}(t) = t + \epsilon$.

- $\mathbf{P} = \{\text{compact intervals in the real line}\},\ \Omega_{\epsilon}([a, b]) = [a \epsilon, b + \epsilon].$
- $\mathbf{P} = \{ \text{closed subsets of a metric space } X \},\$ $\Omega_{\epsilon}(V) = V^{\epsilon} = \{ x \in X \text{ such that } d(x, V) \leq \epsilon \}.$

Interleaving Metrics on Functor Categories

Superlinear Families

A superlinear family is a 1-parameter family of translations of P

$$(\Omega_{\epsilon} \mid \epsilon \in [0,\infty))$$

such that

$$\Omega_{\epsilon_1}\Omega_{\epsilon_2} \leq \Omega_{\epsilon_1+\epsilon_2}$$

for all $\epsilon_1, \epsilon_2 \in [0, \infty)$.

Interleaving distance (Bubenik, dS, Scott 2015)

Given a superlinear family (Ω_{ϵ}) of translations of P, we define the interleaving distance

 $\mathsf{d}_{\mathsf{i}}(\mathbb{V},\mathbb{W}) = \mathsf{inf}\left(\epsilon \mid \mathbb{V},\mathbb{W} \text{ are } \Omega_{\epsilon} \mathsf{-}\mathsf{interleaved}\right)$

between generalized persistence modules $\mathbb{V},\mathbb{W}:\textbf{P}\rightarrow\textbf{C}.$

Sublinear Projections

A sublinear projection is a map $\pi: \operatorname{Trans}_{\mathsf{P}} \to [0,\infty]$ such that

 $\pi(\Omega_1\Omega_2) \leq \pi(\Omega_1) + \pi(\Omega_2)$

for all $\Omega_1, \Omega_2 \in \mathbf{Trans}_{\mathbf{P}}$.

Interleaving distance (Bubenik, dS, Scott 2015)

Given a sublinear projection family $\pi:\mathbf{Trans}_{\mathbf{P}}\to [0,\infty],$ we define the interleaving distance

 $d_i(\mathbb{V}, \mathbb{W}) = \inf (\pi(\Omega) \mid \mathbb{V}, \mathbb{W} \text{ are } \Omega \text{-interleaved})$

between generalized persistence modules $\mathbb{V}, \mathbb{W} : \mathbf{P} \to \mathbf{C}.$

Interleaving Metrics on Functor Categories

Functoriality

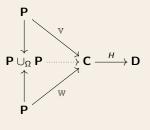
Suppose $\mathbb{V}, \mathbb{W} : \mathbf{P} \to \mathbf{C}$ and $H : \mathbf{C} \to \mathbf{D}$ are functors. Then

 $\mathsf{d}_{\mathsf{i}}(H\mathbb{V},H\mathbb{W}) \leq \mathsf{d}_{\mathsf{i}}(\mathbb{V},\mathbb{W})$

for any superlinear family or sublinear projection.

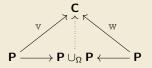
Proof.

An Ω -interleaving of \mathbb{V}, \mathbb{W} gives an Ω -interleaving of $H\mathbb{V}, H\mathbb{W}$:



Interleavings for generalized persistence modules over a poset

Two persistence modules $\mathbb{V}, \mathbb{W} : \mathbf{P} \to \mathbf{C}$ are Ω -interleaved iff the following functor extension problem has a solution:



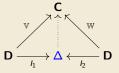
Here $\mathbf{P} \cup_{\Omega} \mathbf{P}$ has the partial order

$$(s,a) \leq (t,b) \Leftrightarrow egin{cases} s \leq t & ext{if } a = b \ \Omega s \leq t & ext{if } a \neq b \end{cases}$$

where $\Omega : \mathbf{P} \to \mathbf{P}$ is a translation.

Interleavings for generalized persistence modules over an arbitrary category

Two persistence modules $\mathbb{V}, \mathbb{W} : \mathbf{D} \to \mathbf{C}$ are Δ -interleaved iff the following functor extension problem has a solution:



Here Δ is a **cospan**. The two functors l_1 , l_2 are full-and-faithful. Every object of Δ is of the form $l_1(d)$ or $l_2(d)$.

Bubenik, dS, Scott

Interleaving and Gromov-Hausdorff distance: arXiv:1707.06288

Example: dynamical system interleavings

Let \boldsymbol{D} be the category defined by the directed graph

Thus **D** has one object and morphisms $\{0, 1, 2, 3, ...\}$.

• Functors $D \rightarrow Top$ are discrete dynamical systems.

Let Δ_n be the category with two objects \bullet_1 and \bullet_2 and morphisms

$$Mor(\bullet_1, \bullet_1) = Mor(\bullet_1, \bullet_1) = \{0, 1, 2, 3, \dots\}$$
$$Mor(\bullet_1, \bullet_2) = Mor(\bullet_2, \bullet_1) = \{n, n+1, n+2, n+3, \dots\}$$

with addition as composition.

• Δ_n -interleavings are shift-equivalences.

Categories with a flow (dS, Munch, Stefanou 2018)

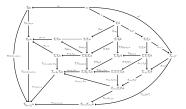
Interleaving distance defined on categories with a coherent $[0,\infty)$ -action.

Examples

- Functor categories $\mathbf{C}^{\mathbf{P}}$, equipped with a superlinear family (Ω_{ϵ}) on \mathbf{P} .
- Poset **S** of subsets of a metric space X; 'thickening' action on **S**:

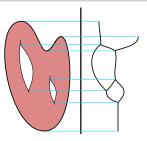
$$A \mapsto A^{\epsilon} = \{x \in X \mid d(x, A) \leq \epsilon\}$$

Interleaving distance = Hausdorff distance.



Reeb graphs

- An **R-space** (X, f) is a topological space X with a map $f : X \to \mathbf{R}$.
- An **R**-space is a **Reeb graph** if each $f^{-1}(t)$ is finite.

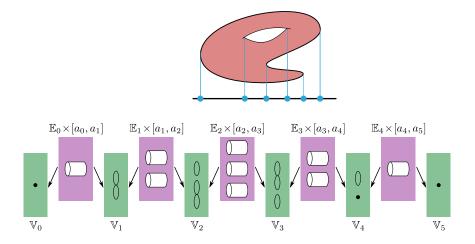


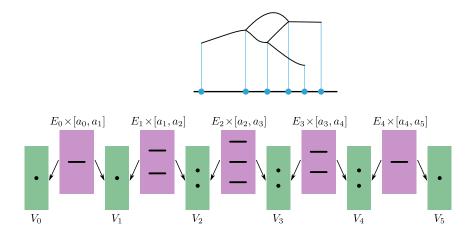
Reeb functor

• The Reeb functor converts a (constructible) R-space into a Reeb graph:

$$(X,f) \longmapsto ((X/\sim),\overline{f})$$

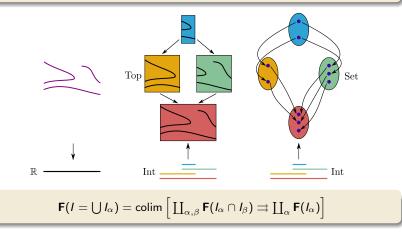
where $x \sim y$ iff x, y are in the same component of the same levelset of f.





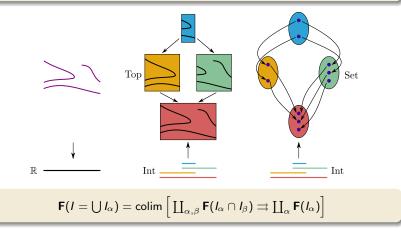
Reeb cosheaves (dS, Munch, Patel 2016)

- Let **Int** denote the poset of open intervals, ⊆.
- A Reeb graph gives rise to a functor F = π₀f⁻¹ : Int → Set that is constructible and satisfies the cosheaf condition for unions of intervals.



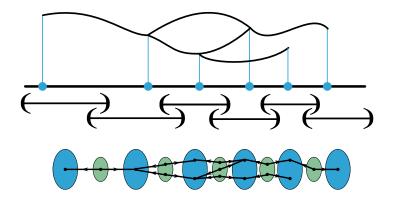
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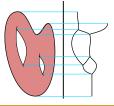
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Reeb functor (two versions)

• The **Reeb functor** converts a (constructible) **R**-space into a Reeb graph:

$$(X, f) \mapsto ((X/\sim), \overline{f})$$

where $x \sim y$ iff x, y are in the same component of the same levelset of f.

or

The Reeb functor converts a constructible R-space into a Reeb cosheaf:

$$\mathbf{F}(I) = \pi_0 f^{-1}(I)$$
$$\mathbf{G}[I \subseteq J] = \pi_0 \left[f^{-1}(I) \subseteq f^{-1}(J) \right]$$

We define a 1-parameter semigroup (Ω_{ϵ}) of functors $Int \rightarrow Int$ by setting

 $\Omega_{\epsilon}(I) = I^{\epsilon} = "\epsilon$ -neighbourhood of I"

Reeb interleaving distance (dS, Munch, Patel 2016)

An ϵ -interleaving between **F**, **G** is given by two families of maps

 $\phi_I: \mathbf{F}(I) \to \mathbf{G}(I^{\epsilon}), \quad \psi_I: \mathbf{G}(I) \to \mathbf{F}(I^{\epsilon})$

which are natural with respect to inclusions $I \subseteq J$, and such that for all I

$$\psi_{I^{\epsilon}} \circ \phi_{I} = \mathbf{F}[I \subseteq I^{2\epsilon}], \quad \phi_{I^{\epsilon}} \circ \psi_{I} = \mathbf{G}[I \subseteq I^{2\epsilon}].$$

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Stability Theorem

If
$$f, g: X \to \mathbf{R}$$
 with $||f - g||_{\infty} \leq \epsilon$ then $d_i(\mathbf{F}, \mathbf{G}) \leq \epsilon$.

Universal Reeb Metric (Bauer, Landi, Mémoli 2018)

The universal metric $d_u(\mathbf{F}, \mathbf{G})$ is the largest that satisfies the stability theorem.

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Cosheaf Smoothing Theorem

If F: Int \rightarrow Set is a (constructible) cosheaf, then so is $F\Omega_{\epsilon}$: Int \rightarrow Set.

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Corollary: Reeb Smoothing

There is a 1-parameter semigroup of 'smoothing' operations on Reeb graphs.



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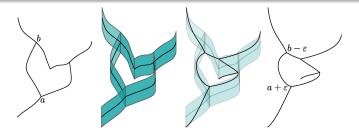
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Cosheaf Smoothing Theorem

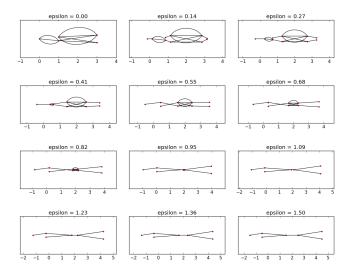
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Corollary: Reeb Smoothing

There is a 1-parameter semigroup of 'smoothing' operations on Reeb graphs.

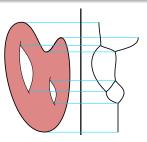


Reeb smoothing algorithm by Dmitriy Smirnov & Song Yu



Reeb graphs

- An **R-space** (X, f) is a topological space X with a map $f : X \to \mathbf{R}$.
- An **R**-space is a **Reeb graph** if X is a graph and each $f^{-1}(t)$ is finite.



Reeb functor

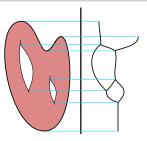
• The Reeb functor converts a (constructible) R-space into a Reeb graph:

$$(X,f) \longmapsto ((X/\sim),\overline{f})$$

where $x \sim y$ iff x, y are in the same component of the same levelset of f.

Reeb spaces

- A **B-space** (X, f) is a topological space X with a map $f : X \to \mathbf{B}$.
- A **B**-space is a **Reeb B**-space if each $f^{-1}(t)$ is finite.



Reeb functor

• The Reeb functor converts a (constructible) B-space into a Reeb B-space:

$$(X,f) \longmapsto ((X/\sim),\overline{f})$$

where $x \sim y$ iff x, y are in the same component of the same fiber of f.

Example: Universal Cover

Let \mathbf{B} be a (locally well-behaved) topological space. Then

$$\mathsf{Path}(\mathbf{B}, b_0) = \big\{\mathsf{paths}\ \gamma: [0,1] \to \mathbf{B} \text{ with } \gamma(0) = b_0\big\}$$

is a $\boldsymbol{B}\text{-space}$ with respect to the evaluation map

$$e: \mathsf{Path}(\mathbf{B}, b_0) \longrightarrow \mathbf{B}; \ \gamma \longmapsto \gamma(1).$$

Then

$$\mathsf{Univ}(\mathbf{B}) = \mathsf{Reeb}\left[\,\mathsf{Path}(\mathbf{B}, b_0), e\right]$$

is the universal cover of \mathbf{B} .

Example: Universal Reeb Metric (Bauer, Landi, Mémoli 2018)

Let X = (X, f) and Y = (Y, g) be Reeb graphs.

• A relator for X, Y is an $(\mathbf{R} \times \mathbf{R})$ -space

$$W \xrightarrow{F} \mathbf{R} \times \mathbf{R}$$

such that

Reeb
$$[W, p_1 \circ F] \cong (X, f),$$

Reeb $[W, p_2 \circ F] \cong (Y, g).$

• The deviation of a relator

$$\operatorname{dev}(W) = \sup_{w \in W} |p_1(F(w)) - p_2(F(w))|$$

measures how far F(W) deviates from the diagonal.

• The universal distance between X, Y is defined

 $d_u(X, Y) = \inf (dev(W) | W \text{ is a relator for } X, Y)$

Let **B** be a topological semigroup with operation \odot .

Reeb **B**-space convolutions

The π_0 -convolution of Reeb spaces

$$X \stackrel{f}{\longrightarrow} \mathbf{B}, \quad Y \stackrel{g}{\longrightarrow} \mathbf{B}$$

is defined to be

$$(X, f) * (Y, g) = \mathsf{Reeb} \left[X imes Y, f \odot g
ight]$$

Reeb graph convolutions

$$(X, f) * (Y, g) = \operatorname{Reeb} [X \times Y, f + g]$$

Reeb graph convolutions

$$(X, f) * (Y, g) = \operatorname{Reeb} [X \times Y, f + g]$$

Examples

• The σ -smoothing of a Reeb graph X = (X, f) is given by the formula

$$X^{\sigma} = X * [-\sigma, \sigma].$$

- The intervals $[-\sigma, \sigma]$, for $\sigma \ge 0$, form a semigroup under *.
- More generally, the convolution of intervals is their Minkowski sum:

$$[m_1 - \sigma_1, m_1 + \sigma_1] * [m_2 - \sigma_2, m_2 + \sigma_2] = [m - \sigma, m + \sigma]$$

where $m = m_1 + m_2$ and $\sigma = \sigma_1 + \sigma_2$.

• The merge-tree and split-tree of X are given by the formulas

$$\mathsf{Merge}(X) = X * [0, +\infty), \quad \mathsf{Split}(X) = X * (-\infty, 0].$$

• Thus X * [-R, R], when $R \gg 0$, combines the merge and split trees of X.

Metric properties of Reeb graph smoothing

Let X, Y be Reeb graphs. Then

$$\mathsf{d}_{\mathsf{i}}(X^{\sigma},Y^{\sigma}) \leq \mathsf{d}_{\mathsf{i}}(X,Y), \quad \mathsf{d}_{\mathsf{u}}(X^{\sigma},Y^{\sigma}) \leq \mathsf{d}_{\mathsf{u}}(X,Y)$$

and

```
\mathsf{d}_{\mathsf{i}}(X,X^{\sigma}) \leq \mathsf{d}_{\mathsf{u}}(X,X^{\sigma}) \leq \sigma
```

for all $\sigma \geq 0$.

Metric properties of Reeb graph smoothing

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and

$$\mathsf{d}_{\mathsf{i}}(X,X^{\sigma}) \leq \mathsf{d}_{\mathsf{u}}(X,X^{\sigma}) \leq \sigma$$

for all $\sigma \geq 0$.

Analogy: Gaussian kernel smoothing

Is there a theory of π_0 signal processing?

Collaborators

Peter Bubenik, Fred Chazal, Marc Glisse, Steve Oudot, Elizabeth Munch, Amit Patel, Jonathan Scott, Dmitriy Smirnov, Anastasios Stefanou, Song Yu

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