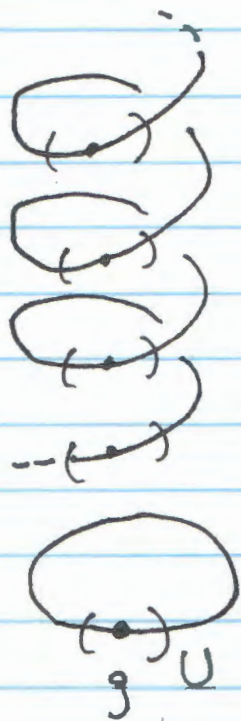


Universal Covers

A homomorphism of Lie groups $f: H \rightarrow G$ is a cover if every $g \in G$ has an open neighborhood U such that $f^{-1}(U)$ is a disjoint union of open sets U_α such that

$$f|_{U_\alpha} : U_\alpha \rightarrow U$$

is a homeomorphism (& thus a diffeomorphism).



$$\begin{array}{c} \mathbb{R} \\ \downarrow f \\ U(1) \cong SO(2) \cong S^1 \end{array} \quad f(x) = e^{ix}$$

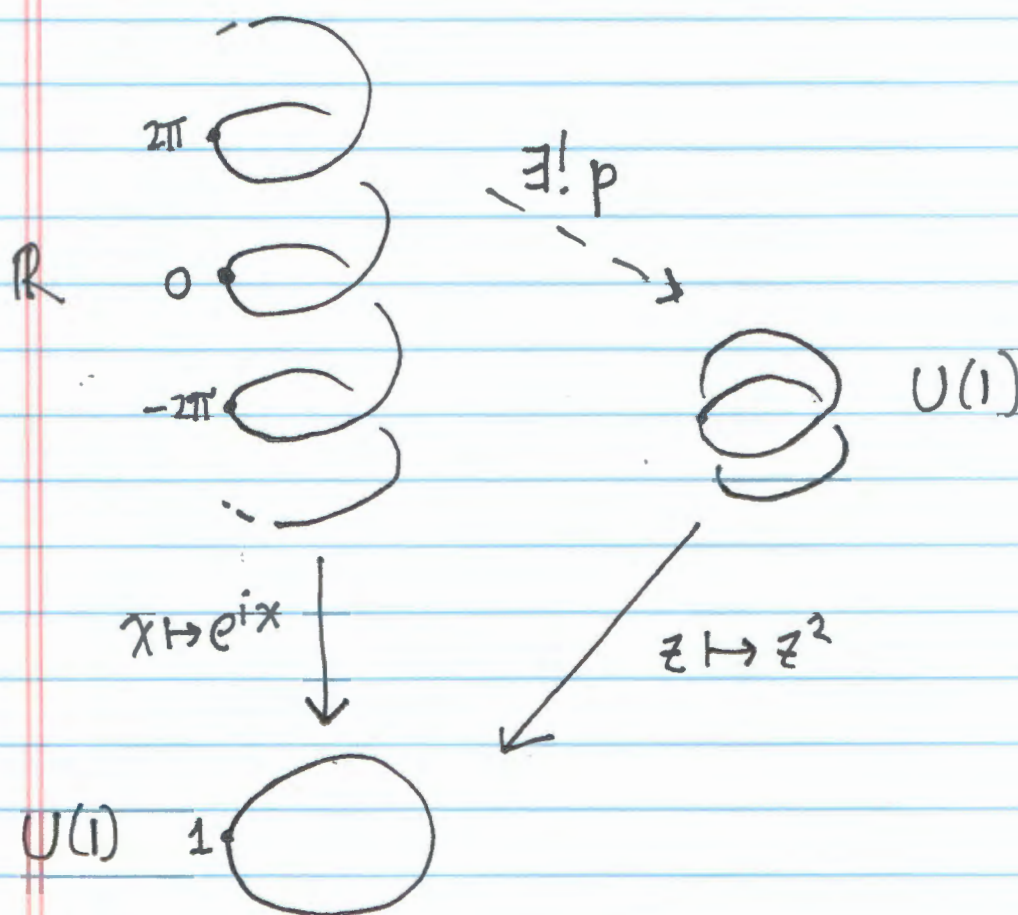
Theorem - Every connected Lie group G has a universal cover $\pi: \tilde{G} \rightarrow G$:
 a cover such that for any cover $p: H \rightarrow G$
 there exists a unique Lie group homomorphism
 $p: \tilde{G} \rightarrow H$ such that this diagram commutes:

$$\begin{array}{ccc} \tilde{G} & \xrightarrow{\exists! p} & H \\ \pi \downarrow & & \swarrow f \\ G & & \end{array}$$

In fact p is a cover.

Theorem - A cover $p: H \rightarrow G$ is universal
 iff H is simply connected: it's connected
 & every loop in H is contractible.

Theorem - The kernel of $\pi: \tilde{G} \rightarrow G$
 is isomorphic to the fundamental group of G , $\pi_1(G)$.



$\mathbb{R}$ is the universal cover of $U(1)$, so $\exists! p: \mathbb{R} \rightarrow U(1)$ such that the triangle commutes:

$$e^{ix} = p(x)^2 \quad \forall x \in \mathbb{R}$$

What is p ?

Note the kernel of
 $\mathbb{R} \rightarrow U(1)$
 $x \mapsto e^{ix}$

is $2\pi\mathbb{Z}$, isomorphic to $\pi_1(U(1)) \cong \mathbb{Z}$.

$SO(2) \cong U(1)$, so we've just seen

$$\widetilde{SO(2)} \cong \mathbb{R} \quad \& \quad \pi_1(SO(2)) \cong \mathbb{Z}.$$

Next we'll see

$$\widetilde{SO(3)} \cong SU(2) \quad \& \quad \pi_1(SO(3)) \cong \mathbb{Z}_2.$$

Some harder facts:

$$\widetilde{SO(4)} \cong SU(2) \times SU(2) \quad \& \quad \pi_1(SO(4)) \cong \mathbb{Z}_2$$

$$\widetilde{SO(5)} \cong Sp(2) \quad \& \quad \pi_1(SO(5)) \cong \mathbb{Z}_2$$

$$\widetilde{SO(6)} \cong SU(4) \quad \& \quad \pi_1(SO(6)) \cong \mathbb{Z}_2$$

No higher $\widetilde{SO(n)}$'s have cute descriptions like this, but we define the spin groups

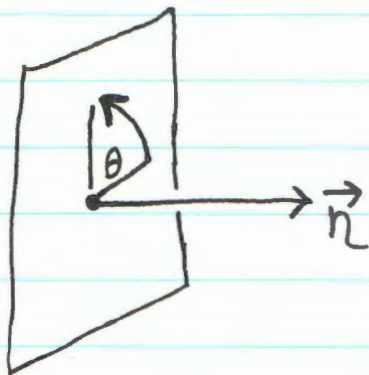
$$\text{Spin}(n) = \widetilde{SO(n)} \quad (n \geq 2)$$

& we have

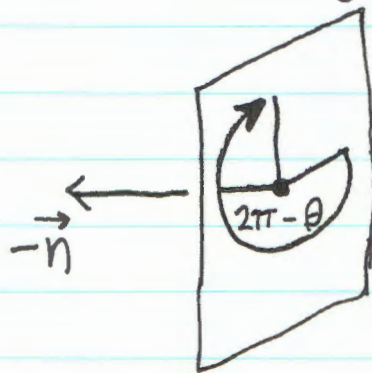
$$\pi_1(SO(n)) \cong \mathbb{Z}_2 \quad (n \geq 2)$$

so $\pi: \text{Spin}(n) \rightarrow SO(n)$ is a 2-1 Lie group homomorphism.

The topology of $SO(3)$



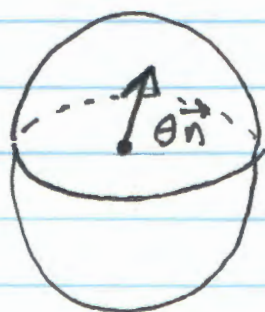
Every rotation $g \in SO(3)$ fixes a unit vector $\vec{n} \in \mathbb{R}^3$ and rotates the plane orthogonal to $\vec{n}$ counterclockwise by some angle θ . But it also fixes $-\vec{n}$ and rotates counterclockwise by $-\theta$ about $-\vec{n}$, or counterclockwise by $2\pi - \theta$:



So any rotation $g \in SO(3)$ is rotation counterclockwise about some unit vector $\vec{n}$ by an angle $0 \leq \theta \leq \pi$, and this $\vec{n}$ is unique unless:

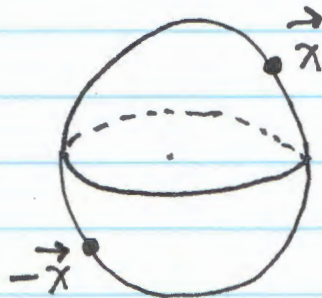
- 1) $\theta = 0$: then every $\vec{n}$ gives the same rotation, namely $g = 1 \in SO(3)$
- 2) $\theta = \pi$: then $\vec{n}$ & $-\vec{n}$ give the same rotation.

So, we can describe $g \in SO(3)$ by a point $\theta \vec{n}$ in the ball of radius π , where the points $\pi \vec{n}$ & $-\pi \vec{n}$ are identified.



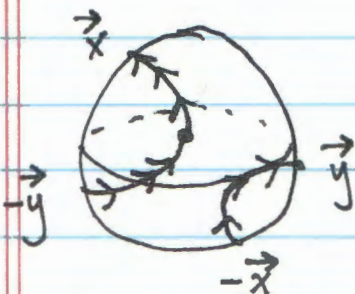
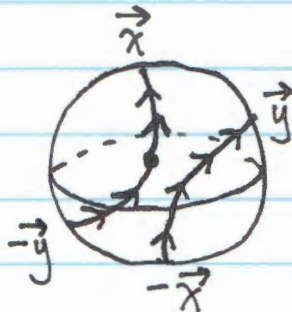
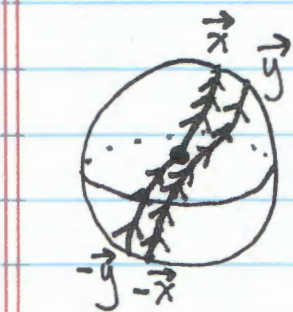
$$0 \leq \theta \leq \pi$$

SO_3 , $SO(3)$ is homeomorphic to a
3d ball, B^3 , with opposite points on its
boundary identified:



rotating π counterclockwise
around $\vec{x}$ = rotating π
counterclockwise around $-\vec{x}$

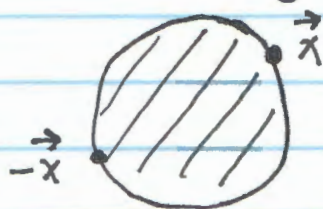
This space is called RP^3 , real projective
3-space. It has $\pi_1(RP^3) \cong \mathbb{Z}_2$:



The loop in $SO(3)$
where we rotate two
full turns ($4\pi = 720^\circ$)
about an axis is
contractible!

We can think of $\mathbb{R}P^n$ in two ways:

- 1) It's the ball B^n with opposite points on its boundary S^{n-1} identified:



$n=2$

- 2) It's the sphere S^n with opposite points identified:



$n=2$

The second way makes it easier to prove that $\mathbb{R}P^n$ is a smooth n -dimensional manifold with a cover:

$$\begin{array}{c} S^n \\ \pi \downarrow \\ \mathbb{R}P^n \end{array}$$

with π being 2-1. When $n=3$ we get

$$\begin{array}{ccc} S^3 & \cong & SU(2) \\ \pi \downarrow & \text{diffeo.} & \\ \mathbb{R}P^3 & \cong & SO(3) \\ & \text{diffeo.} & \end{array}$$

This suggests:

Theorem - There is a 2-1 Lie group homomorphism $\pi: SU(2) \rightarrow SO(3)$ making $SU(2)$ into a universal cover of $SO(3)$.

Proof - Write

$$\mathbb{H} = \underset{\substack{\text{scalars} \\ a_0}}{\mathbb{R}} \oplus \underset{\substack{\text{vectors} \\ a_1 i + a_2 j + a_3 k = \vec{a}}}{\mathbb{R}^3}$$

In a lemma we'll show that if

$$g \in \{x \in \mathbb{H} : |x| = 1\} = Sp(1) \cong SU(2)$$

and $\vec{v} \in \mathbb{R}^3 \subseteq \mathbb{H}$ then $g \vec{v} g^{-1} \in \mathbb{R}^3$.

$$\text{Moreover } |g \vec{v} g^{-1}| = |g| |\vec{v}| |g^{-1}| = |\vec{v}|$$

so the map

$$\vec{v} \mapsto g \vec{v} g^{-1}$$

preserves lengths.

$$\rho(g) : \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$$\vec{v} \mapsto g \vec{v} g^{-1}$$

preserves lengths and it's linear so

$$\rho(g) \in O(3).$$

$$\rho : Sp(1) \rightarrow O(3)$$

is a group homomorphism:

$$\begin{aligned} \rho(gh)(\vec{v}) &= gh \vec{v} (gh)^{-1} \\ &= gh \vec{v} h^{-1} g^{-1} \\ &= \rho(g) \rho(h) \vec{v} \quad \forall g, h \in Sp(1) \end{aligned}$$

ρ is smooth so it's a Lie group homomorphism. $Sp(1) \stackrel{\text{diffeo}}{\cong} S^3$ is

connected so ρ maps $Sp(1)$ into one

connected component of $O(3) \stackrel{\text{diffeo}}{\cong} SO(3) \sqcup SO(3)$,

the component containing $\rho(1) = 1$.

So,

$$\rho: Sp(1) \rightarrow SO(3)$$

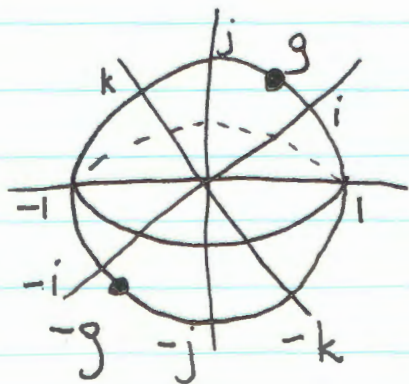
is a Lie group homomorphism. It's
at least 2-1 since $g \in Sp(1) \Rightarrow$
 $-g \in Sp(1)$ and

$$\rho(-g)\vec{v} = -g\vec{v}(-g)^{-1} = g\vec{v}g^{-1} = \rho(g)\vec{v}$$

With more work one can show ρ is 2-1,
onto, and a cover. It's just our friend

$$\pi: S^3 \rightarrow \mathbb{RP}^3$$

in disguise! Since S^3 is simply
connected ρ is a universal cover.



$g, -g \in Sp(1)$
map to same element
of $SO(3)$

In short,

$$\begin{array}{c} \rho: \text{Sp}(1) \rightarrow \text{SO}(3) \\ \parallel \\ \text{SU}(2) \end{array}$$

is a universal cover as desired. 

Lemma - If $g \in \text{Sp}(1)$ & $\vec{v} \in \mathbb{R}^3 \subseteq \mathbb{H}$
then $g\vec{v}g^{-1} \in \mathbb{R}^3 \subseteq \mathbb{H}$.

Proof - A quaternion $a \in \mathbb{H}$ has $a \in \mathbb{R}^3$
iff it's "imaginary": $a^* = -a$. So we
have $\vec{v}^* = -\vec{v}$ and want to show $(g\vec{v}g^{-1})^* =$
 $-(g\vec{v}g^{-1})^*$. Since $|g| = 1$ we have
 $g^{-1} = g^*$, and in general $(ab)^* = b^*a^*$ &
 $a^{**} = a$, so

$$(g\vec{v}g^{-1})^* = (g\vec{v}g^*)^* = g^{**}\vec{v}^*g^* = -g\vec{v}g^{-1}.$$

