

Black-boxing open reaction networks

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Black-boxing

We saw that there is a functor

$$\blacksquare: \text{RxNet} \rightarrow \text{Dynam},$$

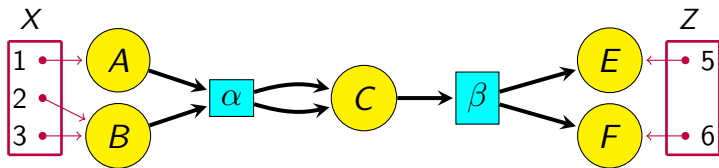
the gray-boxing functor, sending an open reaction network to the open dynamical system generated by mass-action kinetics.

Here,

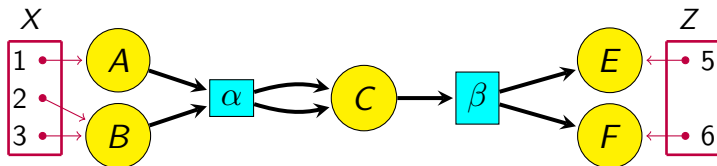
- RxNet is the category of open reaction networks and
- Dynam is the category of open dynamical systems.

I'll describe a functor $\blacksquare: \text{Dynam} \rightarrow \text{Rel}$ sending an open dynamical system to the space of possible *steady state* inflows and outflows.

Black boxing



Black boxing



$$v_A = -r(\alpha)AB$$

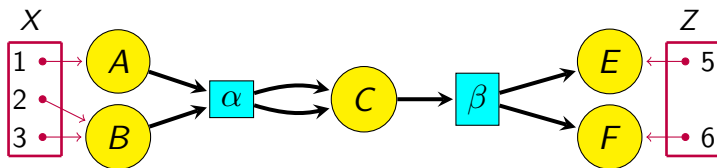
$$v_B = -r(\alpha)AB$$

$$v_C = 2r(\alpha)AB - r(\beta)C$$

$$v_E = r(\beta)C$$

$$v_F = r(\beta)C$$

Black boxing



$$\frac{dA}{dt} = -r(\alpha)AB + I_1$$

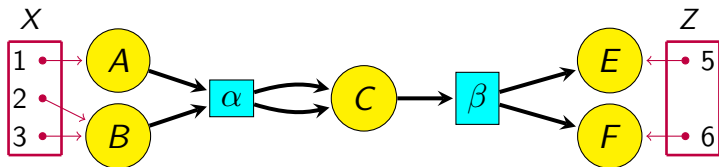
$$\frac{dB}{dt} = -r(\alpha)AB + I_2 + I_3$$

$$\frac{dC}{dt} = 2r(\alpha)AB - r(\beta)C$$

$$\frac{dE}{dt} = r(\beta)C - O_5$$

$$\frac{dF}{dt} = r(\beta)C - O_6$$

Black-boxing



$$0 = -r(\alpha)AB + I_1$$

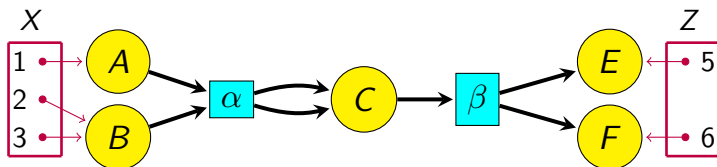
$$0 = -r(\alpha)AB + I_2 + I_3$$

$$0 = 2r(\alpha)AB - r(\beta)C$$

$$0 = r(\beta)C - O_5$$

$$0 = r(\beta)C - O_6$$

Black-boxing



$$I_1 = r(\alpha)AB$$

$$I_2 + I_3 = r(\alpha)AB$$

$$2r(\alpha)AB = r(\beta)C$$

$$O_5 = r(\beta)C$$

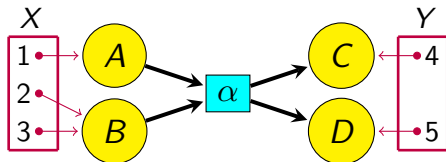
$$O_6 = r(\beta)C.$$

Open reaction networks

Theorem (Baez, BP.)

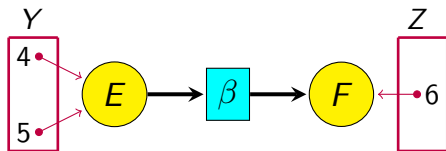
There is a category RxNet whose objects are finite sets and whose morphisms correspond to open reaction networks.

$$R: X \rightarrow Y$$



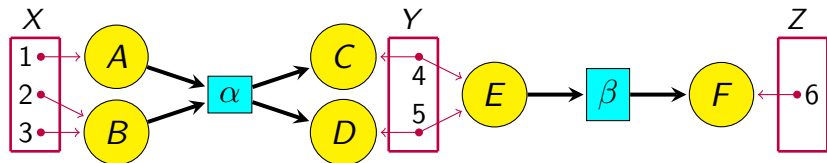
Composition of open reaction networks

Given another open reaction network $R': Y \rightarrow Z$



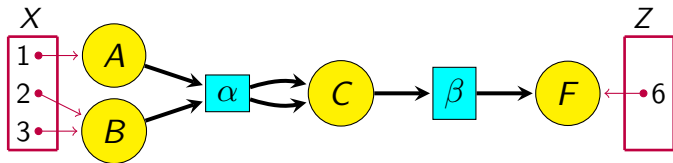
Composition of open reaction networks

To compose $R: X \rightarrow Y$ and $R': Y \rightarrow Z$ we first combine them



Composition of open reaction networks

Then, we identify any species which are in the image of the same point in Y

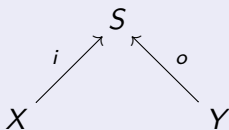


This gives a new open reaction network $RR' : X \rightarrow Z$.

A category of open dynamical systems

Definition

An **open dynamical system** $D: X \rightarrow Y$ on S consists of a cospan of finite sets



together with a polynomial vector field v on \mathbb{R}^S .

Theorem (Baez, P.)

There is a category Dynam where objects are finite sets and morphisms are isomorphism classes of open dynamical systems.

The gray-boxing functor

Theorem (Baez, P.)

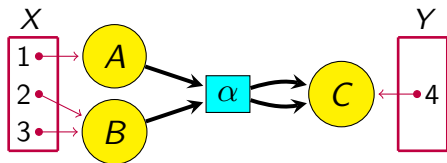
There is a functor $\blacksquare: \text{RxNet} \rightarrow \text{Dynam}$ sending an open reaction network to its corresponding open dynamical system generated by the rate equation.

For open reaction networks $R: X \rightarrow Y$ and $R': Y \rightarrow Z$, the gray-boxing functor satisfies

$$\blacksquare(RR') = \blacksquare(R) \blacksquare(R').$$

The gray-boxing functor

■ $(R: X \rightarrow Y)$



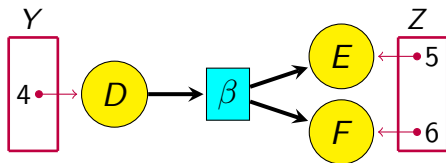
$$v_A = -r(\alpha)A(t)B(t)$$

$$v_B = -r(\alpha)A(t)B(t)$$

$$v_C = 2r(\alpha)A(t)B(t)$$

The gray-boxing functor

■ $(R': Y \rightarrow Z)$



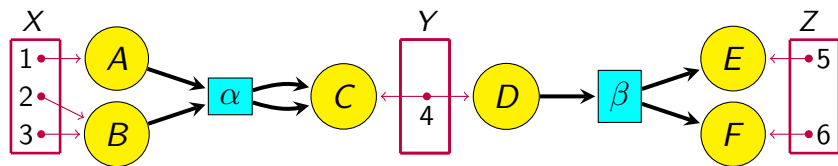
$$v_D = -r(\beta)D(t)$$

$$v_E = r(\beta)D(t)$$

$$v_F = r(\beta)D(t)$$

Composition in Dynam

■ $(R: X \rightarrow Y)$ ■ $(R': Y \rightarrow Z)$



$$v_A = -r(\alpha)AB$$

$$v_B = -r(\alpha)AB$$

$$v_C = 2r(\alpha)AB$$

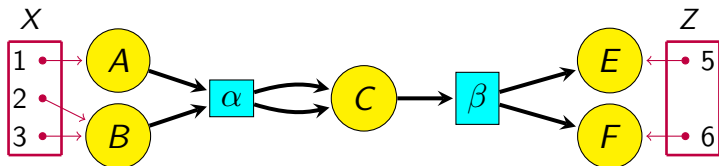
$$v_D = -r(\beta)D$$

$$v_E = r(\beta)D$$

$$v_F = r(\beta)D$$

Composition in Dynam

■ $(R: X \rightarrow Y)$ ■ $(R': Y \rightarrow Z)$



$$v_A = -r(\alpha)AB$$

$$v_B = -r(\alpha)AB$$

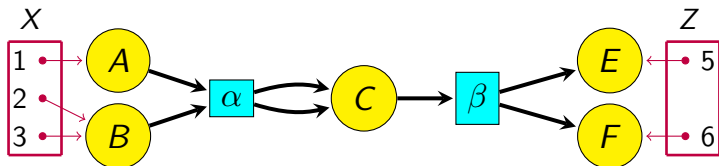
$$v_C + v_D = 2r(\alpha)AB - r(\beta)D \text{ and } C = D$$

$$v_E = r(\beta)D$$

$$v_F = r(\beta)D$$

The gray-boxing functor

■ $(RR': X \rightarrow Z)$



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$$v_B = -r(\alpha)AB$$

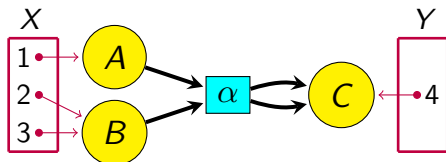
$$v_C = 2r(\alpha)AB - r(\beta)C$$

$$v_E = r(\beta)C$$

$$v_F = r(\beta)C$$

The open rate equation

Let $I: \mathbb{R} \rightarrow \mathbb{R}^X$ and $O: \mathbb{R} \rightarrow \mathbb{R}^Y$ be arbitrary smooth functions of time specifying the **inflows** and **outflows**.



$$\frac{dA(t)}{dt} = -r(\alpha)A(t)B(t) + I_1(t)$$

$$\frac{dB(t)}{dt} = -r(\alpha)A(t)B(t) + I_2(t) + I_3(t)$$

$$\frac{dC(t)}{dt} = 2r(\alpha)A(t)B(t) - O_4(t)$$

The open rate equation

Given an open dynamical system together with specified inflows $I \in \mathbb{R}^X$ and outflows $O \in \mathbb{R}^X$, we define the pushforward $i_*: \mathbb{R}^X \rightarrow \mathbb{R}^S$ by

$$i_*(I)_\sigma = \sum_{\{x:i(x)=\sigma\}} I_x$$

and define $o_*: \mathbb{R}^Y \rightarrow \mathbb{R}^S$ by

$$o_*(O)_\sigma = \sum_{\{y:o(y)=\sigma\}} O_y.$$

We can then write down the **open rate equation** as

$$\frac{dc(t)}{dt} = v(c(t)) + i_*(I(t)) - o_*(O(t)).$$

Steady states

A **steady state** solution of the open rate equation is a concentration vector $c \in \mathbb{R}^S$ such that

$$\frac{dc}{dt} = 0.$$

From the open rate equation

$$\frac{dc}{dt} = v(c) + i_*(I) - o_*(O)$$

we see that this implies

$$v(c) = o_*(O) - i_*(I).$$

This imposes relations among the steady state concentrations and flows along the boundary.

Rel

A relation $L: U \rightsquigarrow V$ is a subspace $L \subseteq U \oplus V$.

There is a category \mathbf{Rel} where an object is real vector space and a morphism is a relation between real vector spaces.

Given relations $L: U \rightsquigarrow V$ and $L': V \rightsquigarrow W$, their composite $LL': U \rightsquigarrow W$ is given by

$$LL' = \{(u, w) : \exists v \in V \text{ with } (u, v) \in L \text{ and } (v, w) \in L'\}.$$

Composition in \mathbf{Rel} requires that the subspaces agree on their overlap.

Composition in Rel

Given the relation $L: \mathbb{R} \rightsquigarrow \mathbb{R}^2$

$$L = \{ (w, x, y) \mid w = y^2 \}$$

and the relation $L': \mathbb{R}^2 \rightsquigarrow \mathbb{R}$

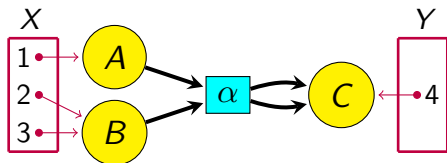
$$L' = \{ (x', y', z) \mid y' = z \},$$

their composite $LL': \mathbb{R} \rightsquigarrow \mathbb{R}$ is

$$LL' = \{ (w, z) \mid w = z^2 \}.$$

Steady state behavior

We characterize the steady state behavior of an open reaction network in terms of the relation imposed between inputs and outputs.



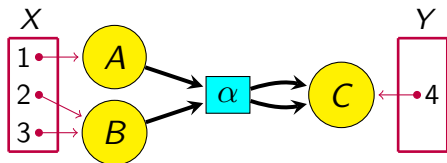
$$\frac{dA(t)}{dt} = -r(\alpha)A(t)B(t) + I_1(t)$$

$$\frac{dB(t)}{dt} = -r(\alpha)A(t)B(t) + I_2(t) + I_3(t)$$

$$\frac{dC(t)}{dt} = 2r(\alpha)A(t)B(t) - O_4(t)$$

Steady state behavior

$$c_X = (c_1, c_2, c_3) \in \mathbb{R}^X, \quad l_X = (l_1, l_2, l_3) \in \mathbb{R}^X$$
$$c_Y = c_4 \in \mathbb{R}^Y, \quad O_Y = O_4 \in \mathbb{R}^Y$$



$$(c_X, l_X, c_Y, O_Y) \subseteq \mathbb{R}^X \oplus \mathbb{R}^X \oplus \mathbb{R}^Y \oplus \mathbb{R}^Y$$

such that

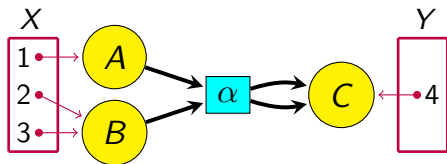
$$l_1 = r(\alpha)AB$$

$$l_2 + l_3 = r(\alpha)AB$$

$$O_4 = 2r(\alpha)AB$$

Steady state behavior

$$c_X = (c_1, c_2, c_3) \in \mathbb{R}^X, \quad l_X = (l_1, l_2, l_3) \in \mathbb{R}^X$$
$$c_Y = c_4 \in \mathbb{R}^Y, \quad O_Y = O_4 \in \mathbb{R}^Y$$



$$(c_1, c_2, c_3, l_1, l_2, l_3, c_4, O_4) \subseteq \mathbb{R}^X \oplus \mathbb{R}^X \oplus \mathbb{R}^Y \oplus \mathbb{R}^Y$$

such that

$$l_1 = r(\alpha)AB$$

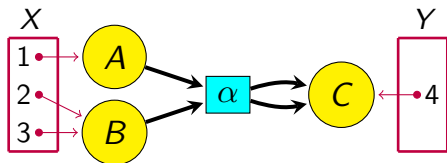
$$l_2 + l_3 = r(\alpha)AB$$

$$O_4 = 2r(\alpha)AB$$

Steady state behavior

$$c_X = (c_1, c_2, c_3) \in \mathbb{R}^X, \quad l_X = (l_1, l_2, l_3) \in \mathbb{R}^X$$

$$c_Y = c_4 \in \mathbb{R}^Y, \quad O_Y = O_4 \in \mathbb{R}^Y$$



$$(c_1, c_2, c_3, l_1, l_2, l_3, c_4, O_4)$$

=

$$(A, B, B, r(\alpha)AB, l_2, r(\alpha)AB - l_2, C, 2r(\alpha)AB)$$

The black-box functor

Theorem (Baez, P.)

There is a functor

$$\blacksquare: \text{Dynam} \rightarrow \text{Rel}$$

sending an open dynamical system to the relation characterizing its steady state boundary concentrations and flows.

The black-box functor

Theorem (Baez, P.)

There is a functor

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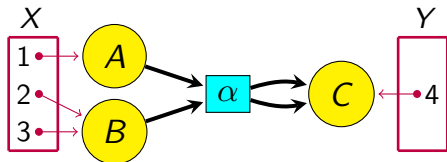
Composing the gray-boxing and black-boxing functors gives a functor

$$\text{RxNet} \xrightarrow{\blacksquare} \text{Dynam} \xrightarrow{\blacksquare} \text{Rel}$$

sending an open reaction network to the subspace of possible steady state boundary concentrations and flows.

Black-boxing

■ $(R: X \rightarrow Y)$



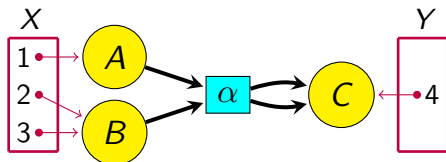
$$\frac{dA(t)}{dt} = -r(\alpha)A(t)B(t) + I_1(t)$$

$$\frac{dB(t)}{dt} = -r(\alpha)A(t)B(t) + I_2(t) + I_3(t)$$

$$\frac{dC(t)}{dt} = 2r(\alpha)A(t)B(t) - O_4(t)$$

Black-boxing

$$\blacksquare(\blacksquare(R)): \mathbb{R}^X \oplus \mathbb{R}^X \rightsquigarrow \mathbb{R}^Y \oplus \mathbb{R}^Y$$



$$(c_X, l_X, c_Y, O_Y)$$

such that

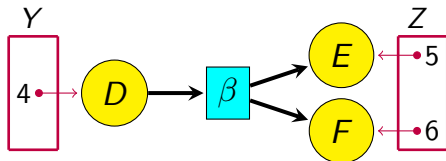
$$l_1 = r(\alpha)AB$$

$$l_2 + l_3 = r(\alpha)AB$$

$$O_4 = 2r(\alpha)AB$$

The 'gray-boxing' functor

■ $(R': Y \rightarrow Z)$



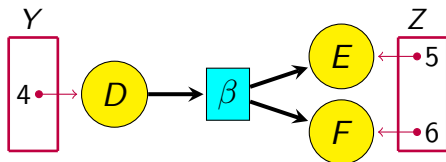
$$\frac{dD(t)}{dt} = -r(\beta)D(t) + I_4(t)$$

$$\frac{dE(t)}{dt} = r(\beta)D(t) - O_5(t)$$

$$\frac{dF(t)}{dt} = r(\beta)D(t) - O_6(t)$$

Black-boxing

$$\blacksquare(\blacksquare(R')): \mathbb{R}^Y \oplus \mathbb{R}^Y \rightsquigarrow \mathbb{R}^Z \oplus \mathbb{R}^Z$$



$$(c_Y, l_Y, c_Z, O_Z)$$

$$l_4 = r(\beta)D$$

$$O_5 = r(\beta)D$$

$$O_6 = r(\beta)D$$

Composing relations

$$\blacksquare(\blacksquare(R))\blacksquare(\blacksquare(R'))$$

$$(c_X, l_X, c_Y, O_Y)(c_Y, l_Y, c_Z, O_Z)$$

$$\begin{array}{ll} l_1 = r(\alpha)AB & l_4 = r(\beta)D \\ l_2 + l_3 = r(\alpha)AB & O_5 = r(\beta)D \\ O_4 = 2r(\alpha)AB & O_6 = r(\beta)D \end{array}$$

Composing relations

$$\blacksquare(\blacksquare(R))\blacksquare(\blacksquare(R'))$$

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$$C = D$$

$$O_4 = l_4$$

Composing relations

$$\blacksquare(\blacksquare(R))\blacksquare(\blacksquare(R'))$$

$$(c_X, l_X, c_Y, O_Y)(c_Y, l_Y, c_Z, O_Z)$$

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$$C = D$$

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Composing relations

$$\blacksquare(\blacksquare(R))\blacksquare(\blacksquare(R')): \mathbb{R}^X \oplus \mathbb{R}^X \rightsquigarrow \mathbb{R}^Z \oplus \mathbb{R}^Z$$

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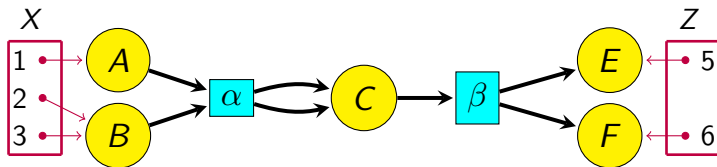
$$2r(\alpha)AB = r(\beta)C$$

$$O_5 = r(\beta)C$$

$$O_6 = r(\beta)C.$$

Black-boxing

■ $(RR' : X \rightarrow Y)$



$$\frac{dA}{dt} = -r(\alpha)AB + I_1$$

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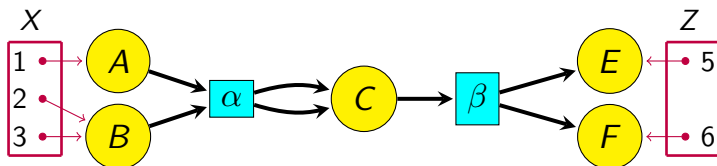
$$\frac{dC}{dt} = 2r(\alpha)AB - r(\beta)C$$

$$\frac{dE}{dt} = r(\beta)C - O_5$$

$$\frac{dF}{dt} = r(\beta)C - O_6$$

Black-boxing

$$\blacksquare(\blacksquare(RR')): \mathbb{R}^X \oplus \mathbb{R}^X \rightsquigarrow \mathbb{R}^Z \oplus \mathbb{R}^Z$$



$$I_1 = r(\alpha)AB$$

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$$2r(\alpha)AB = r(\beta)C$$

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$$O_6 = r(\beta)C.$$

Summary

The fact that black-boxing is accomplished via a functor means that one can compute the steady state behavior of a composite open reaction network by composing the semialgebraic relations characterizing the steady state behaviors of its constituent systems:

$$\blacksquare(\blacksquare(R)) \blacksquare(\blacksquare(R')) = \blacksquare(\blacksquare(R)\blacksquare(R')) = \blacksquare(\blacksquare(RR'))$$

This provides a compositional approach to studying both the dynamical and steady state behaviors of open reaction networks.

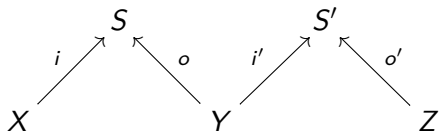
Thank you!

For more:

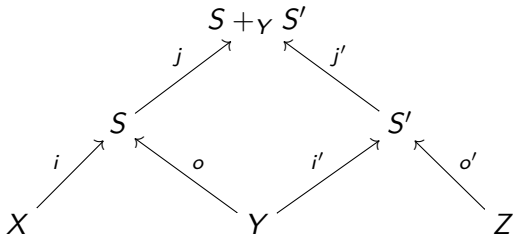
- John C. Baez and Blake S. Pollard, [A compositional framework for reaction networks](#), submitted.
- John C. Baez, Brendan Fong and Blake S. Pollard, [A compositional framework for Markov processes](#), *Journal of Mathematical Physics*.
- Blake S. Pollard, [Open Markov processes: A compositional perspective on non-equilibrium steady states in biology](#), *Entropy*.
- Blake S. Pollard, [A Second Law for open Markov processes](#), *Open Systems and Information Dynamics*.

Composition in Dynam

Given open dynamical systems $D: X \rightarrow Y$ on S and $D': Y \rightarrow Z$ on S'



with vector fields $v: \mathbb{R}^S \rightarrow \mathbb{R}^S$ and $v': \mathbb{R}^{S'} \rightarrow \mathbb{R}^{S'}$ to get an open dynamical system $DD': X \rightarrow Z$ on $S +_{\gamma} S'$



we need to cook up a vector field $v'': \mathbb{R}^{S +_{\gamma} S'} \rightarrow \mathbb{R}^{S +_{\gamma} S'}$.

Composition in Dynam

To get a vector field $v'' : \mathbb{R}^{S+\gamma S'} \rightarrow \mathbb{R}^{S+\gamma S'}$, first take the inclusion map

$$[j, j'] : S + S' \rightarrow S + \gamma S'$$

and define two maps, $[j, j']_* : \mathbb{R}^{S+S'} \rightarrow \mathbb{R}^{S+\gamma S'}$ as

$$[j, j']_*(v + v')_\sigma = \sum_{\{\sigma' \mid [j, j'](\sigma') = \sigma\}} (v + v')_{\sigma'},$$

and $[j, j']^* : \mathbb{R}^{S+\gamma S'} \rightarrow \mathbb{R}^{S+S'}$ as

$$[j, j']^*(c'') = c'' \circ [j, j']$$

with $c'' \in \mathbb{R}^{S+\gamma S'}$. We can then define our vector field via the expression

$$v''(c'') = [j, j']_*(v + v')[j, j']^*(c'').$$

Semialgebraic relations

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Given semialgebraic relations $A: U \rightsquigarrow V$ and $B: V \rightsquigarrow W$, their composite $AB: U \rightsquigarrow W$ is given by

$$AB = \{(u, w) : \exists v \in V \text{ with } (u, v) \in A \text{ and } (v, w) \in B\}.$$