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## FROM LAGRANGIAN TO HAMILTONIAN DYNAMICS

We want a description of classical mechanics where the action is the integral of some 1-form along a path. This path will lie not

$$X = \text{config. space} \ni \text{position}$$

nor in

$$TX \ni (\text{position, velocity})$$

nor in

$$T^*X = \text{phase space} \ni (\text{position, momentum})$$

but in

$$T^*(X \times \mathbb{R}) = \text{extended phase space} \ni (\text{position, momentum, time, energy})$$

To get there, let's first study the phase space  $T^*X$  and energy (the Hamiltonian). We start with a Lagrangian

$$L: TX \rightarrow \mathbb{R}$$

& get Euler-Lagrange equations:

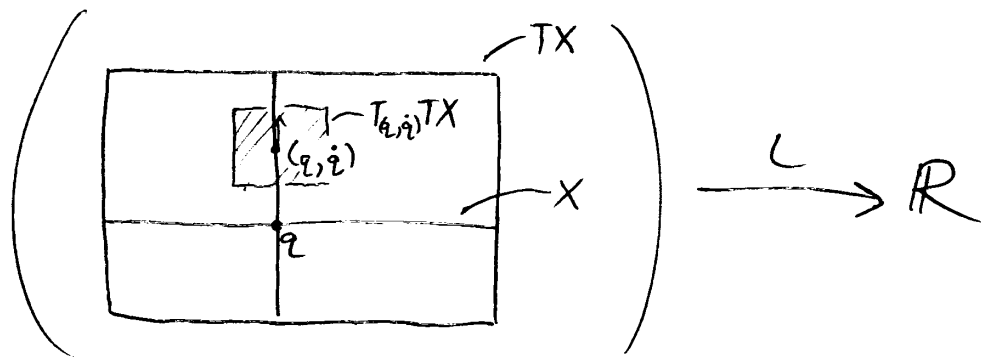
$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}^i} = \frac{\partial L}{\partial q^i}$$

where

$$\frac{\partial L}{\partial \dot{q}^i} = p_i = \text{"momentum"}$$

$$\frac{\partial L}{\partial q^i} = F_i = \text{"force"}.$$

Why is momentum a cotangent vector?



$\frac{\partial L}{\partial \dot{q}_i}$  describes derivative of  $L$  in the "vertical" direction.

$$\{\text{Vertical vectors}\} \subseteq T_{(q, \dot{q})}TX$$

where

$$\{\text{Vertical vectors}\} = \ker d\pi$$

$$\cong T_{(q, \dot{q})}T_q X$$

where  $d\pi : T_{(q, \dot{q})}TX \rightarrow T_q X$  is the differential of the projection  $\pi : TX \rightarrow X$ .

$$(q, \dot{q}) \mapsto q$$

But note for any vector space  $V$ ,  $T_v V \cong V$  in a canonical way so  $T_{(q, \dot{q})}T_q X \cong T_q X$ . So momentum really is the derivative of  $L : TX \rightarrow \mathbb{R}$ , but only in vertical directions. The derivative of  $L$  is the 1-form  $dL$ :

$$dL(q, \dot{q}) : T_{(q, \dot{q})}TX \rightarrow \mathbb{R}$$

so the momentum is this restricted to vertical vectors:

$$\{\text{Vertical vectors}\} \subseteq T_{(q,\dot{q})}TX$$

$$\cong$$

$$T_qX$$

So the momentum is a linear map

$$p: T_qX \longrightarrow \mathbb{R}$$

i.e.  $p \in T_q^*X$  is a cotangent vector.

Now we'll switch from the Lagrangian approach, based on

$$(q, \dot{q}) \in TX$$

to the "Hamiltonian" approach based on

$$(q, p) \in T^*X = \text{"phase space"}$$

We'll do this using the Legendre transform

$$\lambda: TM \longrightarrow T^*M$$

$$(q, \dot{q}) \longmapsto (q, p)$$

where

$$p_i = \frac{\partial L}{\partial \dot{q}^i}$$

(Note  $\lambda$  is defined using  $L$ ). From now on, let's assume

$L$  is strongly regular, meaning that

$$\lambda: TM \longrightarrow T^*M$$

is a diffeomorphism.

Example: A particle moving on a Riemannian manifold  $(X, g)$  has Lagrangian

$$L(q, \dot{q}) = \frac{m}{2} g(\dot{q}, \dot{q}) - V(q)$$

where  $m > 0$  &  $V: X \rightarrow \mathbb{R}$ . Here

$$p_i = \frac{\partial L}{\partial \dot{q}_i} = m g_{ij} \dot{q}^j$$

where  $g_{ij} \dot{q}^j$  is the "coordinate-ridden" expression for

$$g(\dot{q}, -) \in T_q^* X$$

So  $\lambda$  is a diffeo., since  $g$  is nondegenerate: i.e.

$$\dot{q} \mapsto g(\dot{q}, -)$$

is 1-1 and onto. So this  $L$  is strongly regular.

To translate the Euler-Lagrange equations into eqns satisfied by  $q$  &  $p$ , we need the concept of energy.

Thm (conservation of energy) Given any  $L: TX \rightarrow \mathbb{R}$  and  $q: [t_0, t_1] \rightarrow X$  satisfying the E-L eqns, then

$$E(q(t), \dot{q}(t)) \quad (\dot{q}(t) = \frac{d}{dt} q(t))$$

is independent of  $t$ , where  $E: TX \rightarrow \mathbb{R}$  is given by

$$\begin{aligned} E &= p_i \dot{q}^i - L(q, \dot{q}) \\ &= \frac{\partial L}{\partial \dot{q}^i} \dot{q}^i - L(q, \dot{q}) \end{aligned}$$

Proof:  $\frac{d}{dt} E(q(t), \dot{q}(t)) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}^i} \right) \dot{q}^i + \frac{\partial L}{\partial \dot{q}^i} \frac{d}{dt} \dot{q}^i - \frac{\partial L}{\partial q^i} \frac{dq^i}{dt} - \frac{\partial L}{\partial \dot{q}^i} \frac{d}{dt} \dot{q}^i = 0,$

since the E-L eqns. say  $\frac{d}{dt} \frac{\partial L}{\partial \dot{q}^i} = \frac{\partial L}{\partial q^i}$ . ■

Example: For a particle on  $X$  with

$$L = \frac{m}{2} g(\dot{q}, \dot{q}) - V(q)$$

we have

$$\begin{aligned} E &= p_i \dot{q}^i - L \\ &= m g_{ij} \dot{q}^i \dot{q}^j - \frac{m}{2} m g_{ij} \dot{q}^j \dot{q}^i + V(q) \\ &= \frac{m}{2} g(\dot{q}, \dot{q}) + V(q) \end{aligned}$$

So, 'energy' is kinetic energy plus potential energy, just as  $L$  was the difference.

Using our diffeomorphism

$$\lambda: TX \xrightarrow{\sim} T^*X$$

we can define the Hamiltonian  $H := E \circ \lambda^{-1}$ . I.e.

$$H(q, p) = E(q, \dot{q})$$

where  $\lambda(q, \dot{q}) = (q, p)$ .

Now let's figure out "Hamilton's eqns" describing the time evolution of  $(q, p)$ , given that  $(q, \dot{q})$  satisfy the E-L eqns.

$$\begin{array}{c} \text{"} \\ (q(t), p(t)) \end{array}$$

$$\begin{array}{c} \text{"} \\ \lambda(q(t), \frac{dq}{dt}(t)) \end{array}$$

Here's how...

Compute  $dH$  in two ways

1)  $H: T^*X \rightarrow \mathbb{R}$  and  $T^*X$  has local coordinates  $(q^i, p_i)$  coming from the local coordinates  $q^i$  on  $X$ . So we get

$$dH = \frac{\partial H}{\partial q^i} dq^i + \frac{\partial H}{\partial p_i} dp_i$$

2) We can also compute  $dH$  using coordinates  $(q^i, \dot{q}^i)$ . These are local coords. on  $TX$  coming from  $q^i$  on  $X$ , but they may be viewed as local coords. on  $T^*X$

using

$$\lambda: TX \xrightarrow{\sim} T^*X.$$

Here we get

$$\begin{aligned} dH &= d(p_i \dot{q}^i - L(q, \dot{q})) \\ &= dp_i \dot{q}^i + p_i d\dot{q}^i - \frac{\partial L}{\partial q^i} dq^i - \frac{\partial L}{\partial \dot{q}^i} d\dot{q}^i \\ &= dp_i \dot{q}^i - \frac{\partial L}{\partial q^i} dq^i \end{aligned}$$

where we recall  $p_i = \frac{\partial L}{\partial \dot{q}^i}$ . Comparing coefficients thus gives

$$\dot{q}^i = \frac{\partial H}{\partial p_i} \quad \frac{\partial L}{\partial \dot{q}^i} = -\frac{\partial H}{\partial q^i}$$

or, using  $\frac{\partial L}{\partial \dot{q}^i} = \frac{d}{dt} p_i$ ,

$$\boxed{\dot{q}^i = \frac{\partial H}{\partial p_i} \quad \dot{p}_i = -\frac{\partial H}{\partial q^i}}$$

HAMILTON'S  
EQUATIONS