

10 Apr 2007

Smooth Spaces & Smooth Categories

Last time we posed a question: what's a "smooth functor"

$$S: C \rightarrow \mathbb{R} \quad ?$$

For this we need C to be a "smooth category", which we succeeded in defining given a category C^∞ of "smooth spaces" & "smooth maps." More generally, given a category K we can define a category (say C) in K to consist of

- $Ob(C) \in K$
- $Mar(C) \in K$
- $s, t: Mar(C) \rightarrow Ob(C)$ (i.e. $s, t \in \text{hom}_K(Mar(C), Ob(C))$)
- $i: Ob(C) \rightarrow Mar(C)$
- $\circ: Mar(C) \times_s Mar(C) \rightarrow Mar(C)$

satisfying the usual category theory axioms.

This trick — taking a definition & replacing sets and functions by objects and morphisms of K — is called internalization (in K). The result is often called an internal category (in K) or simply a category in K .

This works best if K has pullbacks, so we can write " $\text{Mar}(C) \times_{\text{Mar}(C)} \text{Mar}(C)$ " and know it's defined.

The category $K = \text{Set}$ has pullbacks:

$$\begin{array}{ccc} X & \xrightarrow{f, g} & Y \\ \downarrow & \lrcorner & \downarrow f \\ Y & \xrightarrow{g} & Z \end{array}$$

where in this case

$$X \times_{f, g} Y = \{(x, y) \in X \times Y : f(x) = g(y)\}$$

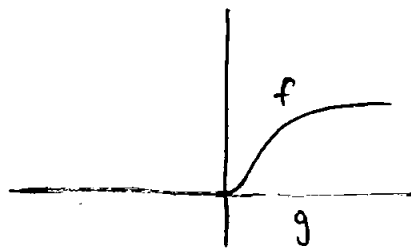
The category Diff of smooth manifolds & smooth maps doesn't have pullbacks. For a rough idea why, consider

$$\begin{array}{ccc} \{(x, y) : f(x) = g(y)\} & \longrightarrow & \mathbb{R} \\ \downarrow & & \downarrow f \\ \mathbb{R} & \xrightarrow{g} & \mathbb{R} \end{array}$$

where

$$f(x) = \begin{cases} e^{-1/x} & x > 0 \\ 0 & x \leq 0 \end{cases}$$

$$g(x) = 0$$

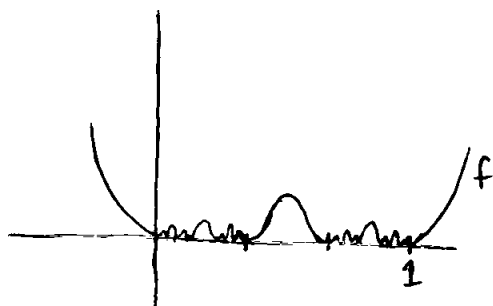


Here $\{(x, y) : f(x) = g(y)\} = \{(x, y) \text{ s.t. } x \leq 0\}$ is a manifold with boundary — not a smooth manifold.

A more sophisticated example

$f(x) = 0$ only on
the Cantor set

$g(x) = 0$



So, let's introduce a bigger category of smooth spaces that does have pullbacks, following Grothendieck's dictum:

"A nice category with some bad objects is better than a bad category with only nice objects."

He used this to invent "schemes", generalizing "algebraic varieties", revolutionizing algebraic geometry. Let's do the same for differential geometry.

So, what's a smooth space? Following Chen's ideas:

Def: A convex set is a convex subset of \mathbb{R}^n

e.g. \mathbb{R}^n , a half-space, a quarter-space, etc.

Def: A function $f: C \rightarrow C'$ between convex sets is smooth if it has continuous n th derivatives $\forall n \geq 0$, defined in the usual way.

Def: A smooth space is a set X equipped with, for each convex set C , a set of plots

$$\varphi: C \rightarrow X$$

(which we think of as 'smooth'), s.t.

1) Given a plot $\varphi: C \rightarrow X$ & a smooth map $f: C' \rightarrow C$ between convex sets, $\varphi \circ f: C' \rightarrow X$ is a plot.

2) Given inclusions $i_\alpha: C_\alpha \rightarrow C$ such that $\{C_\alpha\}$ ^{is an open} cover of C , given $\varphi: C \rightarrow X$, then $\varphi \circ i_\alpha: C_\alpha \rightarrow X$ are plots $\forall \alpha$
 $\Rightarrow \varphi: C \rightarrow X$ is a plot.

3) Every map from a point (in \mathbb{R}^n) to X is a plot.

Def: Given smooth spaces X & Y a function $f: X \rightarrow Y$ is a smooth map if for every plot $\varphi: C \rightarrow X$, $f \circ \varphi: C \rightarrow Y$ is a plot in Y .

Examples:

- 1) Any convex set C becomes a smooth space where the plots $\varphi: C' \rightarrow C$ are just the smooth maps (as defined earlier).
- 2) Any set X has a discrete smooth structure such that the plots $\varphi: C \rightarrow X$ are just the constant functions.
- 3) Any set X has an indiscrete smooth structure where every function $\varphi: C \rightarrow X$ is a plot.
- 4) Any smooth manifold X becomes a smooth space where $\varphi: C \rightarrow X$ is a plot iff φ is smooth in the usual sense of smooth manifolds. If X, Y are manifolds, $f: X \rightarrow Y$ is smooth according to our new definition iff it's smooth in the usual sense.
- 5) The product $X \times Y$ of smooth spaces becomes a smooth space where a function $\varphi: C \rightarrow X \times Y$ is a plot iff $C \xrightarrow{\varphi} X \times Y \xrightarrow{p_1} X$ & $C \xrightarrow{\varphi} X \times Y \xrightarrow{p_2} Y$ are plots.

In fact our category C^∞ of smooth spaces & smooth maps has products, given as above.

6) The disjoint union $X+Y$ of smooth spaces becomes a smooth space where a function $\varphi: C \rightarrow X+Y$ is a plot iff either

$$\begin{array}{ccc} & \nearrow \varphi_1 & X \\ C & \xrightarrow{\varphi} & X+Y \\ & & \downarrow i_1 \end{array}$$

commutes for some plot $\varphi_1: C \rightarrow X$ or

$$\begin{array}{ccc} & \nearrow \varphi_2 & Y \\ C & \xrightarrow{\varphi} & X+Y \\ & & \downarrow i_2 \end{array}$$

commutes for some plot $\varphi_2: C \rightarrow Y$.

In fact, C^∞ has coproducts.

7) Any subset $Y \subseteq X$ of a smooth space X becomes a smooth space, where a plot $\varphi: C \rightarrow Y$ is any function s.t.

$$C \xrightarrow{\varphi} Y \hookrightarrow X$$

is a plot in X . So, e.g. the Cantor set is a smooth space.

HW — Show that C^∞ has pullbacks.