

Solutions to Exercises 6

5A. Inner products

X1. This amounts to finding solutions to the linear homogeneous system

$$\begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

This system is equivalent to the system with matrix $\begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = 0$, which

has a 1-dim solution space spanned by $(0, -1, 1, 0)$.

X2. Need to solve $\begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$.

This system is equivalent to the one associated to $\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix}$. For the latter, we can let x_3 & x_4 vary arbitrarily, and then x_1 & x_2 are forced.

Basis: $\begin{pmatrix} 1, -2, 1, 0 \\ 2, -3, 0, 1 \end{pmatrix}$

X3.

$b = \frac{1}{4}(e_1 + e_2 + e_3 + e_4)$

$$e_1 - b = \frac{3}{4}e_1 - \frac{1}{4}(e_2 + e_3 + e_4)$$

$$e_2 - b = \frac{3}{4}e_2 - \frac{1}{4}(e_1 + e_3 + e_4)$$

$$\cos \theta = \frac{\langle e_1 - b, e_2 - b \rangle}{|e_1 - b| |e_2 - b|}$$

$$|e_1 - b| = \sqrt{\frac{9}{16} + \frac{1}{16} + \frac{1}{16} + \frac{1}{16}}$$

$$= \sqrt{\frac{3}{4}} = \frac{\sqrt{3}}{2}$$

$$\sim \frac{(e_1 - b)(e_2 - b)}{\frac{3}{4}} = \frac{-\frac{1}{4}}{\frac{3}{4}} = -\frac{1}{3} \quad \text{so}$$

$$\theta \doteq 109.47122 \dots \text{ degrees.}$$

6.B. Orthogonality and dimension

X1 (a) Let $b = (2, 2, 3)$ $b = b_1 + b_2$ where
 $a = (1, 1, 0)$

$$b_1 = \frac{b \cdot a}{a \cdot a} a = \frac{4}{2} (1, 1, 0) = (2, 2, 0)$$

Hence $b_2 = (0, 0, 3)$.

(b) Here $a = (1, 1, 1)$ $b = (1, -1, 1)$ In this case

$$b_1 = \frac{b \cdot a}{a \cdot a} a = \frac{1}{3} a = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right) \text{ and}$$

$$b_2 = \left(+\frac{2}{3}, -\frac{4}{3}, +\frac{2}{3}\right).$$

X2 (a) Call the three vectors v_1, v_2, v_3 .

Then $w_1 = v_1 = (0, 0, 1, 1)$,

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = (0, 1, 1, 0) - \frac{1}{2} (0, 0, 1, 1) \\ = \left(0, 1, \frac{1}{2}, -\frac{1}{2}\right),$$

~~$$w_3 = v_3 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 =$$~~

Since $v_3 = v_1$, the vectors w_1 & w_2 span

(k) In this case

$$w_1 = v_1 = (1, 1, 1, 1), \quad 2$$

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = (-1, 4, 4, 1) - \frac{8}{4} (1, 1, 1, 1) = (-3, 2, 2, -1),$$

$$w_3 = v_3 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 =$$

$$(4, -2, -2, 0) - \frac{0}{4} (1, 1, 1, 1) - \frac{-20}{18} (-3, 2, 2, -1)$$

$$= (4 - \frac{10}{3}, -2 + \frac{20}{9}, -2 + \frac{20}{9}, -\frac{10}{9}) =$$

$$(\frac{2}{3}, \frac{2}{9}, \frac{2}{9}, -\frac{10}{9}), \text{ Note that}$$

$$9w_3 = (6, 2, 2, -10).$$

When one does computations, it is always a good idea to check the results; i.e.,

check that $\left\{ \begin{matrix} \langle w_1, w_2 \rangle \\ \langle w_2, w_3 \rangle \\ \langle w_1, w_3 \rangle \end{matrix} \right\}$ are all zero.