Solutions to problems from Axler, Section 10A

CHAPTER 10

Trace and Determinant

1. Suppose that $T \in \mathcal{L}(V)$ and (v_1, \ldots, v_n) is a basis of V. Prove that $\mathcal{M}(T, (v_1, \ldots, v_n))$ is invertible if and only if T is invertible.

SOLUTION: First suppose that $\mathcal{M}(T)$ is an invertible matrix (because the only basis is sight is (v_1, \ldots, v_n) , we can leave the basis out of the notation). Thus there exists an n-by-n matrix B such that

$$\mathcal{M}(T)B = B\mathcal{M}(T) = I.$$

There exists an operator $S \in \mathcal{L}(V)$ such that $\mathcal{M}(S) = B$ (see 3.19). Thus the equation above becomes

$$\mathcal{M}(T)\mathcal{M}(S) = \mathcal{M}(S)\mathcal{M}(T) = I,$$

which we can rewrite as

$$\mathcal{M}(TS) = \mathcal{M}(ST) = \mathcal{M}(I),$$

which implies that

$$TS = ST = I$$
.

Thus T is invertible, as desired, with inverse S.

To prove the implication in the other direction, suppose now that T is invertible. Thus there exists $S \in \mathcal{L}(V)$ such that

$$TS = ST = I$$
.

This implies that

$$\mathcal{M}(TS) = \mathcal{M}(ST) = \mathcal{M}(I),$$

which implies that

$$\mathcal{M}(T)\mathcal{M}(S) = \mathcal{M}(S)\mathcal{M}(T) = I.$$

Thus $\mathcal{M}(T)$ is invertible, as desired, with inverse $\mathcal{M}(S)$.

2. Prove that if A and B are square matrices of the same size and AB = I, then BA = I.

SOLUTION: Suppose that A and B are n-by-n matrices and AB = I. There exist $S, T \in \mathcal{L}(\mathbb{F}^n)$ such that

$$\mathcal{M}(S) = A$$
 and $\mathcal{M}(T) = B$;

here we are using the standard basis of F^n (the existence of $S, T \in \mathcal{L}(F^n)$ satisfying the equations above follows from 3.19). Because AB = I, we have $\mathcal{M}(S)\mathcal{M}(T) = I$, which implies that $\mathcal{M}(ST) = \mathcal{M}(I)$, which implies that ST = I, which implies that TS = I (by Exercise 23 in Chapter 3). Thus

$$BA = \mathcal{M}(T)\mathcal{M}(S)$$

= $\mathcal{M}(TS)$
= $\mathcal{M}(I)$
= I .

3. Suppose $T \in \mathcal{L}(V)$ has the same matrix with respect to every basis of V. Prove that T is a scalar multiple of the identity operator.

SOLUTION: We begin by proving that (v, Tv) is linearly dependent for every $v \in V$. To do this, fix $v \in V$, and suppose that (v, Tv) is linearly independent. Then (v, Tv) can be extended to a basis $(v, Tv, u_1, \ldots, u_n)$ of V. The first column of the matrix of T with respect to this basis is

Clearly $(2v, Tv, u_1, \ldots, u_n)$ is also a basis of V. The first column of the matrix of T with respect to this basis is

 $\left[\begin{array}{c}0\\2\\0\\\vdots\\0\end{array}\right].$

Thus T has different matrices with respect to the two bases we have considered. This contradiction shows that (v, Tv) is linearly dependent for every $v \in V$. This implies that for every vector in V is an eigenvector of T. This implies that T is a scalar multiple of the identity operator (by Exercise 12 in Chapter 5).

4. Suppose that (u_1, \ldots, u_n) and (v_1, \ldots, v_n) are bases of V. Let $T \in \mathcal{L}(V)$ be the operator such that $Tv_k = u_k$ for $k = 1, \ldots, n$. Prove that

$$\mathcal{M}(T,(v_1,\ldots,v_n))=\mathcal{M}(I,(u_1,\ldots,u_n),(v_1,\ldots,v_n)).$$

SOLUTION: Fix k. Write

$$u_k = a_1 v_1 + \cdots + a_n v_n,$$

where $a_1, \ldots, a_n \in \mathbf{F}$. Because $Tv_k = u_k$, the k^{th} column of the matrix $\mathcal{M}(T, (v_1, \ldots, v_n))$ consists of the numbers a_1, \ldots, a_n . Because $Iu_k = u_k$, the k^{th} column of $\mathcal{M}(I, (u_1, \ldots, u_n), (v_1, \ldots, v_n))$ also consists of the numbers a_1, \ldots, a_n .

Because $\mathcal{M}(T,(v_1,\ldots,v_n))$ and $\mathcal{M}(I,(u_1,\ldots,u_n),(v_1,\ldots,v_n))$ have the same columns, these two matrices must be equal.

5. Prove that if B is a square matrix with complex entries, then there exists an invertible square matrix A with complex entries such that $A^{-1}BA$ is an upper-triangular matrix.

SOLUTION: Suppose B is an n-by-n matrix with complex entries. Let (e_1, \ldots, e_n) denote the standard basis of \mathbb{C}^n . There exists $T \in \mathcal{L}(\mathbb{C}^n)$ such that $\mathcal{M}(T, (e_1, \ldots, e_n)) = B$ (see 3.19).

There is a basis (v_1, \ldots, v_n) of V such that $\mathcal{M}(T, (v_1, \ldots, v_n))$ is an upper-triangular matrix (see 5.13). Let $A = \mathcal{M}((v_1, \ldots, v_n), (e_1, \ldots, e_n))$. Then A is invertible (by 10.2) and

$$A^{-1}BA = A^{-1}\mathcal{M}(T,(e_1,\ldots,e_n))A$$

= $\mathcal{M}(T,(v_1,\ldots,v_n)),$

where the second equality comes from 10.3. Thus $A^{-1}BA$ is an upper-triangular matrix.

6. Give an example of a real vector space V and $T \in \mathcal{L}(V)$ such that

$$trace(T^2) < 0.$$

SOLUTION: Define $T \in \mathcal{L}(\mathbb{R}^2)$ by

$$T(x,y)=(-y,x).$$

Then $T^2 = -I$, so trace $(T^2) = -2$.

7. Suppose V is a real vector space, $T \in \mathcal{L}(V)$, and V has a basis consisting of eigenvectors of T. Prove that $\operatorname{trace}(T^2) \geq 0$.

SOLUTION: Let (v_1, \ldots, v_n) be a basis of V consisting of eigenvectors of T. Thus there exist $\lambda_1, \ldots, \lambda_n \in \mathbb{R}$ such that $Tv_j = \lambda_j v_j$ for each j. Clearly the matrix of T^2 with respect to the basis (v_1, \ldots, v_n) is the diagonal matrix

$$\left[\begin{array}{ccc} \lambda_1^2 & 0 \\ & \ddots & \\ 0 & & \lambda_n^2 \end{array}\right].$$

Thus trace $T^2 = \lambda_1^2 + \cdots + \lambda_n^2 \ge 0$.

8. Suppose V is an inner-product space and $v, w \in \mathcal{L}(V)$. Define $T \in \mathcal{L}(V)$ by $Tu = \langle u, v \rangle w$. Find a formula for trace T.

SOLUTION: First suppose that $v \neq 0$. Extend $(\frac{v}{\|v\|})$ to an orthonormal basis $(\frac{v}{\|v\|}, e_1, \ldots, e_n)$ of V. Note that for each j, we have $Te_j = 0$ (because $\langle e_j, v \rangle = 0$). The trace of T equals the sum of the diagonal entries in the matrix of T with respect to the basis $(\frac{v}{\|v\|}, e_1, \ldots, e_n)$. Thus

trace
$$T = \langle T(\frac{v}{\|v\|}), \frac{v}{\|v\|} \rangle + \langle Te_1, e_1 \rangle + \dots + \langle Te_n, e_n \rangle$$

$$= \langle (\frac{v}{\|v\|}, v) w, \frac{v}{\|v\|} \rangle$$

$$= \langle w, v \rangle.$$

If v = 0, then T = 0 and so trace $T = 0 = \langle w, v \rangle$. Thus we have the formula

$$\operatorname{trace} T = \langle w, v \rangle$$

regardless of whether or not v = 0.

9. Prove that if $P \in \mathcal{L}(V)$ satisfies $P^2 = P$, then trace P is a nonnegative integer.

SOLUTION: Suppose that $T \in \mathcal{L}(V)$ satisfies $P^2 = P$. Let (u_1, \ldots, u_m) be a basis of range P and let (v_1, \ldots, v_n) be a basis of null P. Then

$$(u_1,\ldots,u_m,v_1,\ldots,v_n)$$

is a basis of V (this holds because $V = \operatorname{range} T \oplus \operatorname{null} T$; see Exercise 21 in Chapter 5). For each u_j we have $Pu_j = u_j$ and for each v_k we have $Pv_k = 0$. Thus the matrix of P with respect to the basis above of V is a diagonal matrix whose diagonal contains m 1's followed by n 0's. Thus trace P = m, which is a nonnegative integer, as desired. In fact, we have shown that

$$\operatorname{trace} P = \dim \operatorname{range} P$$
.

10. Prove that if V is an inner-product space and $T \in \mathcal{L}(V)$, then

$$\operatorname{trace} T^* = \overline{\operatorname{trace} T}.$$

SOLUTION: Suppose that V is an inner-product space and $T \in \mathcal{L}(V)$. Let (e_1, \ldots, e_n) be an orthonormal basis of V. The trace of any operator on V equals the sum of the diagonal entries on the matrix of the operator with respect to this basis. Thus

$$\operatorname{trace} T^* = \langle T^* e_1, e_1 \rangle + \dots + \langle T^* e_n, e_n \rangle$$

$$= \langle e_1, Te_1 \rangle + \dots + \langle e_n, Te_n \rangle$$

$$= \overline{\langle Te_1, e_1 \rangle} + \dots + \overline{\langle Te_n, e_n \rangle}$$

$$= \overline{\langle Te_1, e_1 \rangle} + \dots + \overline{\langle Te_n, e_n \rangle}$$

$$= \overline{\operatorname{trace} T}.$$

11. Suppose V is an inner-product space. Prove that if $T \in \mathcal{L}(V)$ is a positive operator and trace T = 0, then T = 0.

SOLUTION: Suppose $T \in \mathcal{L}(V)$ is a positive operator and trace T = 0. There exists an operator $S \in \mathcal{L}(V)$ such that $T = S^*S$ (by 7.27). Let (e_1, \ldots, e_n) be an orthonormal basis of V. Then

$$0 = \operatorname{trace} T$$

$$= \langle Te_1, e_1 \rangle + \dots + \langle Te_n, e_n \rangle$$

$$= \langle S^*Se_1, e_1 \rangle + \dots + \langle S^*Se_n, e_n \rangle$$

$$= ||Se_1||^2 + \dots + ||Se_n||^2.$$

The equation above implies that $Se_j = 0$ for each j. Because S is 0 on a basis of V, we have S = 0. Because $T = S^*S$, this implies that T = 0.

X. Suppose $T \in \mathcal{L}(\mathbb{C}^3)$ is the operator whose matrix is

$$\begin{bmatrix} 51 & -12 & -21 \\ 60 & -40 & -28 \\ 57 & -68 & 1 \end{bmatrix}.$$

Someone tells you (accurately) that -48 and 24 are eigenvalues of T. Without using a computer or writing anything down, find the third eigenvalue of T.

SOLUTION: The sum of the eigenvalues of T equals the sum of the diagonal terms of the matrix above (both quantities equal trace T). The sum of the diagonal terms of the matrix above equals 12. The sum of two of the eigenvalues of T, -48 and 24, equals -24. Because the sum of all three eigenvalues of T must equal 12, the third eigenvalue of T must be 36.

- N. Prove or give a counterexample: if $T \in \mathcal{L}(V)$ and $c \in \mathbb{F}$, then $\operatorname{trace}(cT) = c\operatorname{trace} T$.
- SOLUTION: Suppose $T \in \mathcal{L}(V)$ and $c \in F$. To prove that $\operatorname{trace}(cT) = c\operatorname{trace} T$, consider a basis of V. Then $\operatorname{trace} T$ equals the sum of the diagonal terms of the matrix of T with respect to this basis. The matrix of cT, with respect to the same basis, equals c times the matrix of T. Thus the sum of the diagonal terms of the matrix of cT equals c times the sum of the diagonal terms of the matrix of T. In other words, $\operatorname{trace}(cT) = c\operatorname{trace} T$.
- **M**. Prove or give a counterexample: if $S,T \in \mathcal{L}(V)$, then

16.
$$trace(ST) = (trace S)(trace T)$$
.

SOLUTION: Define $S, T \in \mathcal{L}(\mathbf{F}^2)$ by S(x, y) = T(x, y) = (-y, x). Then with respect to the standard bases the matrix of S (which of course equals the matrix of T) is

$$\left[\begin{array}{cc} 0 & -1 \\ 1 & 0 \end{array}\right].$$

Thus trace $S = \operatorname{trace} T = 0$. However, ST = -I, so trace ST = -2. Thus for this choice of S and T, we have $\operatorname{trace}(ST) \neq (\operatorname{trace} S)(\operatorname{trace} T)$.

Of course there are also many other examples.

- Suppose $T \in \mathcal{L}(V)$. Prove that if $\operatorname{trace}(ST) = 0$ for all $S \in \mathcal{L}(V)$, then T = 0.
- SOLUTION: Suppose that $\operatorname{trace}(ST) = 0$ for all $S \in \mathcal{L}(V)$. Then $\operatorname{trace}(TS) = 0$ for all $S \in \mathcal{L}(V)$ (by 10.12). Suppose that there exists $v \in V$ such that $Tv \neq 0$. Then (Tv) can be extended to a basis (Tv, u_1, \ldots, u_n) of V. Define $S \in \mathcal{L}(V)$ by

$$S(aTv + b_1u_1 + \cdots + b_nu_n) = av.$$

Thus S(Tv) = v and $Su_j = 0$ for each j. Hence (TS)(Tv) = T(S(Tv)) = Tv and $(TS)(u_j) = 0$ for each j. This implies that with respect to the basis (Tv, u_1, \ldots, u_n) , the matrix of TS consists of all 0's except for a 1 in the upper-left corner. Thus trace(TS) = 1. This contradiction shows that our assumption that $Tv \neq 0$ must have been false. Thus Tv = 0 for every $v \in V$, which means that T = 0.

- Suppose V is an inner-product space and $T \in \mathcal{L}(V)$. Prove that if (e_1, \ldots, e_n) is an orthonormal basis of V, then
- 18. $\operatorname{trace}(T^*T) = ||Te_1||^2 + \cdots + ||Te_n||^2.$

Conclude that the right side of the equation above is independent of which orthonormal basis (e_1, \ldots, e_n) is chosen for V.

SOLUTION: Suppose that (e_1, \ldots, e_n) is an orthonormal basis of V. Then

trace
$$T^*T = \langle T^*Te_1, e_1 \rangle + \dots + \langle T^*Te_n, e_n \rangle$$

= $\langle Te_1, Te_1 \rangle + \dots + \langle Te_n, Te_n \rangle$
= $||Te_1||^2 + \dots + ||Te_n||^2$.

Because trace T^*T does not depend upon the choice of a basis of V, the formula above shows that $||Te_1||^2 + \cdots + ||Te_n||^2$ is independent of the orthonormal basis (e_1, \ldots, e_n) .