

Solutions to Exercises 6

5A. Inner products

X1. This amounts to finding solutions to the linear homogeneous system

$$\begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

This system is equivalent to the system with matrix $\begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = 0$, which

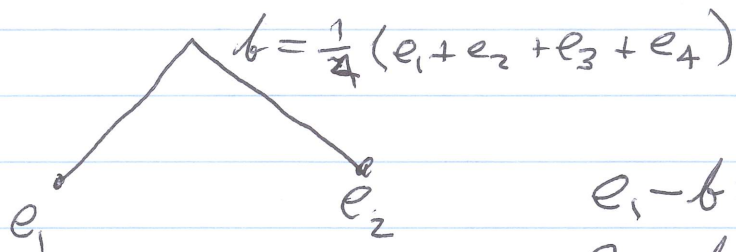
has a 1-dim solution space spanned by $(0, -1, 1, 0)$.

X2. Need to solve $\begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$

This system is equivalent to the one associated to $\begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{pmatrix}$. For the latter, we can let x_3 & x_4 vary arbitrarily, and then x_1 & x_2 are forced.

$$\text{Basis: } \begin{pmatrix} 1, -2, 1, 0 \\ 2, -3, 0, 1 \end{pmatrix}$$

X3.

$$b = \frac{1}{4}(e_1 + e_2 + e_3 + e_4)$$


$$e_1 - b = \frac{3}{4}e_1 - \frac{1}{4}(e_2 + e_3 + e_4)$$

$$e_2 - b = \frac{3}{4}e_2 - \frac{1}{4}(e_1 + e_3 + e_4)$$

$$\cos \theta = \frac{\langle e_1 - b, e_2 - b \rangle}{|e_1 - b| |e_2 - b|}$$

$$|e_1 - b| = \sqrt{\frac{9}{16} + \frac{1}{16} + \frac{1}{16} + \frac{1}{16}}$$

$$= \sqrt{\frac{3}{4}} = \frac{\sqrt{3}}{2}$$

$$= \frac{(e_1 - b) \cdot (e_2 - b)}{\frac{3}{4}} = \frac{-\frac{1}{4}}{\frac{3}{4}} = -\frac{1}{3} \quad \text{so}$$

$$\theta \doteq 109.47122 \dots \text{ degrees.}$$

6.B. Orthogonality and dimension

X1. (a) Let $b = (2, 2, 3)$
 $a = (1, 1, 0)$ $b = b_1 + b_2$ where

$$b_1 = \frac{b \cdot a}{a \cdot a} a = \frac{4}{2} (1, 1, 0) = (2, 2, 0)$$

Hence $b_2 = (0, 0, 3)$.

(b) Here $a = (1, 1, 1)$
 $b = (1, -1, 1)$ In this case

$$b_1 = \frac{b \cdot a}{a \cdot a} a = \frac{1}{3} a = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right) \text{ and}$$

$$b_2 = \left(+\frac{2}{3}, -\frac{4}{3}, +\frac{2}{3}\right).$$

X2. (a) Call the three vectors v_1, v_2, v_3 .

Then $w_1 = v_1 = (0, 0, 1, 1)$,

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = (0, 1, 1, 0) - \frac{1}{2} (0, 0, 1, 1) \\ = (0, 1, \frac{1}{2}, -\frac{1}{2}),$$

~~$$w_3 = v_3 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 =$$~~

Since $v_3 = v_1$, the vectors w_1 & w_2 span

(A) In this case

$$w_1 = v_1 = (1, 1, 1, 1),$$

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = (-1, 4, 4, 1) - \frac{8}{4} (1, 1, 1, 1) \\ = (-3, 2, 2, -1),$$

$$w_3 = v_3 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 =$$

$$(4, -2, -2, 0) - \frac{0}{4} (1, 1, 1, 1) - \frac{-20}{18} (-3, 2, 2, -1)$$

$$= \left(4 - \frac{10}{3}, -2 + \frac{20}{9}, -2 + \frac{20}{9}, -\frac{10}{9} \right) =$$

$$\left(\frac{2}{3}, \frac{2}{9}, \frac{2}{9}, -\frac{10}{9} \right), \text{ Note that}$$

$$9w_3 = (6, 2, 2, -10).$$

When one does computations, it is always a good idea to check the results; i.e.,

check that $\left\{ \begin{array}{l} \langle w_1, w_2 \rangle \\ \langle w_1, w_3 \rangle \\ \langle w_2, w_3 \rangle \end{array} \right\}$ are all zero.

6C. Orthogonal complements, etc.

X1 Prove that $U^\perp \cap W^\perp = (U+W)^\perp$.
(correcting misprint)

① Show $U^\perp \cap W^\perp \subseteq (U+W)^\perp$. Let
 $x \in U^\perp \cap W^\perp$. Then $\langle x, u \rangle = 0 = \langle x, w \rangle$ for
 all $u \in U$ & $w \in W$. If $y \in U+W$, write
 $y = u + w$ with $u \in U, w \in W$. Then $\langle x, y \rangle =$
 $\langle x, u + w \rangle = \langle x, u \rangle + \langle x, w \rangle = 0 + 0 = 0$. Hence
 $x \in (U+W)^\perp$.

② Reverse inclusion: Since $U, W \subseteq U+W$
 we have $(U+W)^\perp \subseteq U^\perp, W^\perp$, which means
 $(U+W)^\perp \subseteq U^\perp \cap W^\perp$.

X2 We know that $E^2 = E$. Therefore
 if $T = (I - 2E)$, then $T^2 = (I - 2E)^2 =$
 $I - 2(2E) + 2E^2 = I - 4E + 4E = I$.

Also $x \in W \Rightarrow Ex = x \Rightarrow Tx = (I - 2E)x$
 $= x - 2Ex = x - 2x = -x$. Hence x is
 an eigen vector for T with eigenvalue -1 .

X3 First find an orthogonal basis for W if $v_1 + v_2$ are given as in the problem.

Then $w_1 = v_1 = (1, 1, 0)$ and

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 = (0, 1, 1) - \frac{1}{2}(1, 1, 0) \\ = \left(\frac{1}{2}, -\frac{1}{2}, 1\right).$$

So an ^{orthogonal} basis for W is given by $(1, 1, 0)$ and

$$(1, -1, 2) = x_2.$$

It follows that

$$E e_j = e_j - \frac{\langle e_j, x_1 \rangle}{\langle x_1, x_1 \rangle} x_1 - \frac{\langle e_j, x_2 \rangle}{\langle x_2, x_2 \rangle} x_2$$

Now substitute e_1, e_2, e_3 for e_j .

$$E e_1 = (1, 0, 0) - \frac{1}{2}(1, 1, 0) - \frac{1}{6}(1, -1, 2) = \\ \left(\frac{1}{3}, -\frac{1}{3}, -\frac{1}{3}\right) ~~\left(\frac{1}{3}, -\frac{1}{3}, -\frac{1}{3}\right)~~$$

$$E e_2 = (0, 1, 0) - \frac{1}{2}(1, 1, 0) - \frac{(-1)}{6}(1, -1, 2) = \\ \left(-\frac{1}{3}, \frac{2}{3}, \frac{1}{3}\right) ~~\left(-\frac{1}{3}, \frac{2}{3}, \frac{1}{3}\right)~~$$

Finally,

$$E e_3 = (0, 0, 1) - \frac{0}{2} (1, 1, 0) - \frac{2}{6} (1, -1, 2) = \left(-\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right).$$

So the matrix of E is given by

$$\begin{pmatrix} \frac{1}{3} & -\frac{1}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{2}{3} & \frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}$$

One way to partially check this is to compute E^2 and see if it equals E . If not, there is a mistake in the solution.

Also, it turns out that $E = {}^T E$ (transpose) must hold.