# Exercises for Unit I <br> (Topics from linear algebra) 

## I. 0 : Background

Note. There is no corresponding section in the course notes, but as noted at the beginning of Unit I these are a few exercises which involve the prerequisites from linear algebra; most if not all of this material will be used later in the course.

1. Suppose that $\mathbf{V}$ is a vector space and that $\mathbf{x}$ and $\mathbf{y}$ are nonzero vectors in $\mathbf{V}$. Prove that the set $\{\mathbf{x}, \mathbf{y}\}$ is linearly dependent if and only if $\mathbf{x}$ and $\mathbf{y}$ are nonzero multiples of each other.
2. Let $\mathbf{V}$ be a vector space, let $\mathbf{S}=\left\{\mathbf{v}_{\mathbf{1}}, \mathbf{v}_{2}, \ldots, \mathbf{v}_{\boldsymbol{k}}\right\}$ be a set of linearly independent vectors in $\mathbf{V}$, and let $\mathbf{W}$ be the subspace spanned by $\mathbf{S}$. Suppose that $\mathbf{z}$ is a vector in $\mathbf{V}$ which does not lie in $\mathbf{W}$. Prove that the set $\mathbf{S} \cup\{\mathbf{z}\}$ is linearly independent.
3. Let $\mathbf{V}$ be a vector space, let $\mathbf{S}=\left\{\mathbf{v}_{\mathbf{1}}, \mathbf{v}_{\mathbf{2}}, \ldots, \mathbf{v}_{\boldsymbol{k}}\right\}$ be a set of linearly independent vectors in $\mathbf{V}$, and let $\left\{\boldsymbol{c}_{\boldsymbol{1}}, \boldsymbol{c}_{2}, \ldots, \boldsymbol{c}_{\boldsymbol{k}}\right\}$ be a sequence of nonzero scalars. Prove that $\mathbf{S}$ is linearly independent if and only if the set $\left\{c_{1} \mathbf{v}_{1}, c_{2} \mathbf{v}_{2}, \ldots, c_{k} \mathbf{v}_{k}\right\}$ is linearly independent.
4. Let $\mathbf{V}$ and $\mathbf{W}$ be vector spaces, let $\mathbf{T}: \mathbf{V} \rightarrow \mathbf{W}$ be a linear transformation which is invertible, and let $\mathbf{S}=\left\{\mathbf{v}_{\mathbf{1}}, \mathbf{v}_{\mathbf{2}}, \ldots, \mathbf{v}_{\boldsymbol{k}}\right\}$ be a finite subset of vectors in V. Prove that $\mathbf{S}$ is linearly independent if and only if the set $T[S]=\left\{T\left(\mathbf{v}_{\mathbf{1}}\right), T\left(\mathbf{v}_{2}\right), \ldots, T\left(\mathbf{v}_{k}\right)\right\}$ is.

## I. 1 : Dot products

1. Compute the dot product $\mathbf{a} \cdot \mathbf{b}$, where $\mathbf{a}=(\mathbf{3}, 4)$ and $\mathbf{b}=(\mathbf{2}, \mathbf{3})$.
2. Compute the dot product $\mathbf{a} \cdot \mathbf{b}$, where $\mathbf{a}=(\mathbf{2}, \mathbf{- 3}, 4)$ and $\mathbf{b}=(\mathbf{0}, \mathbf{6}, \mathbf{5})$.
3. Compute the dot product $\mathbf{a} \cdot \mathbf{b}$, where $\mathbf{a}=(\mathbf{2}, \mathbf{- 1}, \mathbf{1})$ and $\mathbf{b}=(\mathbf{1}, \mathbf{0}, \mathbf{1})$.
4. Determine whether the vectors $\mathbf{a}=(\mathbf{4}, \mathbf{0})$ and $\mathbf{b}=(\mathbf{1}, \mathbf{1})$ are perpendicular, linearly dependent, or neither.
5. Determine whether the vectors $\mathbf{a}=(2,18)$ and $\mathbf{b}=(9,-1)$ are perpendicular, linearly dependent, or neither.
6. Determine whether the vectors $\mathbf{a}=(\mathbf{2}, \mathbf{- 3}, \mathbf{1})$ and $\mathbf{b}=(\mathbf{- 1}, \mathbf{- 1}, \mathbf{- 1})$ are perpendicular, linearly dependent, or neither.
7. Consider a regular tetrahedron $\mathbf{T}$ (a pyramid with triangular base, where all faces are equilateral triangles) whose vertices are $(\mathbf{0}, \mathbf{0}, \mathbf{0}),(\boldsymbol{k}, \boldsymbol{k}, \mathbf{0}),(\boldsymbol{k}, \mathbf{0}, \boldsymbol{k})$, and $(0, k, k)$ for some positive constant $\boldsymbol{k}$. Find the degree measure of the angle $\angle x z y$, where $z$ is the centroid of $\mathbf{T}$ - whose coordinates are ( $1 / 2 \boldsymbol{k}, 1 / 2 \boldsymbol{k}, 1 / 2 \boldsymbol{k}$ ) - and $\boldsymbol{x}$ and $\boldsymbol{y}$ are any two vertices (the answer will be the same for all choices).
8. Given the vectors $\mathbf{u}=(2,3)$ and $\mathbf{v}=(5,1)$, write $\mathbf{u}=\mathbf{u}_{0}+\mathbf{u}_{1}$, where $\mathbf{u}_{0}$ is a scalar multiple of $\mathbf{v}$ and $\mathbf{u}_{\mathbf{1}}$ is perpendicular to $\mathbf{v}$.
9. Given the vectors $\mathbf{u}=(2,1,2)$ and $\mathbf{v}=(0,3,4)$, write $\mathbf{u}=\mathbf{u}_{0}+\mathbf{u}_{1}$, where $\mathbf{u}_{0}$ is a scalar multiple of $\mathbf{v}$ and $\mathbf{u}_{1}$ is perpendicular to $\mathbf{v}$.
10. Given the vectors $\mathbf{u}=(5,6,2)$ and $\mathbf{v}=(-1,3,4)$, write $\mathbf{u}=\mathbf{u}_{0}+\mathbf{u}_{1}$, where $\mathbf{u}_{0}$ is a scalar multiple of $\mathbf{v}$ and $\mathbf{u}_{1}$ is perpendicular to $\mathbf{v}$.
11. Given the vectors $\mathbf{u}=(\mathbf{1}, \mathbf{1}, \mathbf{1})$ and $\mathbf{v}=(2,1,-3)$, write $\mathbf{u}=\mathbf{u}_{0}+\mathbf{u}_{1}$, where $\mathbf{u}_{0}$ is a scalar multiple of $\mathbf{v}$ and $\mathbf{u}_{1}$ is perpendicular to $\mathbf{v}$.
12. Let $\mathbf{u}, \mathbf{v}$ and $\mathbf{w}$ be vectors in the real inner product space $\mathbb{R}^{n}$ such that $\mathbf{u} \cdot \mathbf{v}$ $=2, \mathbf{v} \cdot \mathbf{w}=-3, \mathbf{u} \cdot \mathbf{w}=5,\|\mathbf{u}\|=1,\|\mathbf{v}\|=2$, and $\|\mathbf{w}\|=7$. Evaluate the following expressions:
(a) $(\mathbf{u}+\mathbf{v}) \cdot(\mathbf{v}+\mathbf{w})$
(b) $(2 v-w) \cdot(3 u+2 w)$
(c) $(u-v-2 w) \cdot(4 u+v)$
(d) $\|\mathbf{u}+\mathbf{v}\|$
(e) $\|2 w-v\|$
(f) $\|u-2 v+4 w\|$
13. Apply the Gram - Schmidt orthogonalization process to the following vectors in $\mathbb{R}^{n}$ with the standard scalar product:
(a) $\mathbf{v}_{1}=(1,1,0), \mathbf{v}_{2}=(0,1,1), \mathbf{v}_{3}=(1,1,1)$
(b) $\mathbf{v}_{1}=(1,0,0,0), \mathbf{v}_{2}=(1,1,0,1), \mathbf{v}_{3}=(1,1,1,0)$, $\mathrm{v}_{4}=(1,1,1,1)$
(c ) $\mathbf{v}_{1}=(1,2,1), \mathbf{v}_{2}=(2,1,0), \mathbf{v}_{3}=(-1,-1,1)$
14. Let $\left\{\mathbf{v}_{\mathbf{1}}, \mathbf{v}_{\mathbf{2}}, \ldots, \mathbf{v}_{\boldsymbol{n}}\right\}$ be an orthonormal basis of the real inner product space $\mathbf{V}$. Show that for every vector $\mathbf{w}$ in $\mathbf{V}$ one has the identity

$$
\|w\|^{2}=\left\langle w, v_{1}\right\rangle^{2}+\left\langle w, v_{2}\right\rangle^{2}+\ldots+\left\langle w, v_{n}\right\rangle^{2} .
$$

15. Let $\mathbf{W}$ be the subspace of $\mathbb{R}^{\mathbf{3}}$ spanned by $(\mathbf{1}, \mathbf{2}, \mathbf{- 1})$.
(a) Find an explicit formula for the orthogonal projection onto $\mathbf{W}$ (with respect to the standard scalar product).
(b) Find the matrix representation of this projection with respect to the standard basis of unit vectors.
16. Suppose that two nonzero vectors $\mathbf{x}$ and $\mathbf{y}$ in the inner product space $\mathbf{V}$ are orthogonal and satisfy $\|\mathbf{x}\|=\|\mathbf{y}\|$. Show that $\mathbf{x}+\mathbf{y}$ and $\mathbf{x}-\mathbf{y}$ are also orthogonal and their lengths are equal.

## I. 2 : Cross products

1. Compute the vector cross product $\mathbf{a} \times \mathbf{b}$, where $\mathbf{a}=(\mathbf{2},-\mathbf{3}, \mathbf{1})$ and $\mathbf{b}=$ (1, - 2, 1).
2. Compute the vector cross product $\mathbf{a} \times \mathbf{b}$, where $\mathbf{a}=(\mathbf{1 2},-\mathbf{3}, \mathbf{0})$ and $\mathbf{b}=$ ( $-2,5,0$ ).
3. Compute the vector cross product $\mathbf{a} \times \mathbf{b}$, where $\mathbf{a}=(\mathbf{1}, \mathbf{1}, \mathbf{1})$ and $\mathbf{b}=$ $(2,1,-1)$.
4. Compute the box product $[\mathbf{a}, \mathbf{b}, \mathbf{c}]$, where $\mathbf{a}=(\mathbf{2}, \mathbf{0}, \mathbf{1}), \mathbf{b}=(\mathbf{0}, \mathbf{3}, \mathbf{0})$ and $\mathbf{c}=(\mathbf{0}, \mathbf{0}, \mathbf{1})$.
5. Compute the triple cross products $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}$ and $\mathbf{a} \times(\mathbf{b} \times \mathbf{c})$ for the vectors in the preceding exercise.
6. Compute the box product $[\mathbf{a}, \mathbf{b}, \mathbf{c}]$, where $\mathbf{a}=(\mathbf{1}, \mathbf{1}, \mathbf{0}), \mathbf{b}=(\mathbf{0}, \mathbf{1}, \mathbf{1})$ and $\mathrm{c}=(1,0,1)$.
7. Compute the triple cross products $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}$ and $\mathbf{a} \times(\mathbf{b} \times \mathbf{c})$ for the vectors in the preceding exercise.
8. Compute the box product $[\mathbf{a}, \mathbf{b}, \mathbf{c}]$, where $\mathbf{a}=(\mathbf{1}, \mathbf{3}, \mathbf{1}), \mathbf{b}=(\mathbf{0}, \mathbf{5}, \mathbf{5})$ and $c=(4,0,4)$.
9. Compute the triple cross products $(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}$ and $\mathbf{a} \times(\mathbf{b} \times \mathbf{c})$ for the vectors in the preceding exercise.
10. Suppose that $\mathbf{a}$ and $\mathbf{b}$ are linearly independent vectors in $\mathbb{R}^{\mathbf{3}}$, and that $\mathbf{c}$ is a nonzero vector which is perpendicular to both $\mathbf{a}$ and $\mathbf{b}$. Show that $\mathbf{c}$ is a scalar multiple of the cross product $\mathbf{a} \times \mathbf{b}$.
11. Suppose that $\mathbf{c}$ is a vector in $\mathbb{R}^{\mathbf{3}}$, and define a mapping $\mathbf{D}$ from $\mathbb{R}^{\mathbf{3}}$ to itself by the formula $\mathbf{D v}=\mathbf{c} \times \mathbf{v}$. Verify that $\mathbf{D}$ is a linear transformation and that it satisfies the Leibniz identity for products: $\mathbf{D}(\mathbf{a} \times \mathbf{b})=\mathbf{D a} \times \mathbf{b}+\mathbf{a} \times \mathrm{Db}$ [ Hint: Use the Jacobi identity.]

## I. 3 : Linear varieties

1. Let $\mathbf{L}$ and $\mathbf{M}$ be the lines in $\mathbb{R}^{\mathbf{3}}$ consisting of all points expressible in the form $\mathrm{p}=\mathbf{a}+\boldsymbol{t} \mathbf{b}$, where

$$
\begin{gathered}
\mathbf{a}=(\mathbf{2}, \mathbf{3}, \mathbf{1}) \text { and } \mathbf{b}=(\mathbf{4}, \mathbf{0}, \mathbf{- 1}) \text { for the line } \mathbf{L} \text {, and } \\
\quad \mathbf{a}=(\mathbf{2}, \mathbf{3}, \mathbf{1}) \text { and } \mathbf{b}=(\mathbf{2}, \mathbf{2}, \mathbf{1}) \text { for the line } \mathbf{M} .
\end{gathered}
$$

Determine whether $\mathbf{L}$ and $\mathbf{M}$ have a common point, and if so then find that point.
2. Let $\mathbf{L}$ and $\mathbf{M}$ be the lines in $\mathbb{R}^{\mathbf{3}}$ consisting of all points expressible in the form $\mathrm{p}=\mathbf{a}+\boldsymbol{t} \mathbf{b}$, where

$$
\begin{aligned}
& \mathbf{a}=(\mathbf{0}, \mathbf{2},-\mathbf{1}) \text { and } \mathbf{b}=(\mathbf{3},-\mathbf{1}, \mathbf{1}) \text { for the line } \mathbf{L} \text {, and } \\
& \mathbf{a}=(\mathbf{1},-\mathbf{2},-\mathbf{3}) \text { and } \mathbf{b}=(\mathbf{4}, \mathbf{1}, \mathbf{3}) \text { for the line } \mathbf{M} .
\end{aligned}
$$

Determine whether $\mathbf{L}$ and $\mathbf{M}$ have a common point, and if so then find that point.
3. Let $\mathbf{L}$ and $\mathbf{M}$ be the lines in $\mathbb{R}^{\mathbf{3}}$ consisting of all points expressible in the form $\mathrm{p}=\mathbf{a}+\boldsymbol{t} \mathbf{b}$, where

$$
\begin{gathered}
\mathbf{a}=(\mathbf{3},-\mathbf{2}, \mathbf{1}) \text { and } \mathbf{b}=(\mathbf{2}, \mathbf{5},-\mathbf{1}) \text { for the line } \mathbf{L} \text {, and } \\
\mathbf{a}=(\mathbf{7}, \mathbf{8}, \mathbf{- 1}) \text { and } \mathbf{b}=(\mathbf{\mathbf { b }}, \mathbf{1}, \mathbf{2}) \text { for the line } \mathbf{M} .
\end{gathered}
$$

Determine whether $\mathbf{L}$ and $\mathbf{M}$ have a common point, and if so then find that point.
4. Find the equation of the plane passing through the points $(\mathbf{0}, \mathbf{0}, \mathbf{0}),(\mathbf{1}, \mathbf{2}, \mathbf{3})$ and (-2, 3, 3).
5. Find the equation of the plane passing through the points $(1,2,3),(\mathbf{3}, 2,1)$ and (-1, -2, 2).
6. Find the equation of the plane which passes through the point $(\mathbf{1}, \mathbf{2}, \mathbf{3})$ and is parallel to the $\boldsymbol{x y}$ - plane.
7. Find the equation of the plane which contains the lines $\mathbf{L}$ and $\mathbf{M}$ given by all points expressible in the form

$$
\begin{aligned}
& (\mathbf{1}, \mathbf{4}, \mathbf{0})+t(-2,1,1) \text { for the line } L \text {, and } \\
& (\mathbf{2}, \mathbf{1}, \mathbf{2})+\boldsymbol{t}(-\mathbf{3}, \mathbf{4},-\mathbf{1}) \text { for the line } \mathbf{M} .
\end{aligned}
$$

8. Find the line determined by the intersections of the two planes whose equations are $5 x-3 y+z=4$ and $x+4 y+7 z=1$.
9. Let $\mathbf{L}$ and $\mathbf{M}$ be lines in $\mathbb{R}^{\mathbf{2}}$ defined respectively by the linear equations $\mathbf{a} \cdot \mathbf{x}$ $=\boldsymbol{b}$ and $\boldsymbol{p} \cdot \mathbf{x}=\boldsymbol{q}$. Show that if $\mathbf{L}$ and $\mathbf{M}$ are parallel (no points in common), then the two vectors a and $\mathbf{p}$ are linearly dependent.
10. Prove that the intersection of two linear varieties is a linear variety.
11. Let $\mathbf{H}$ and $\mathbf{K}$ be hyperplanes in $\mathbb{R}^{\boldsymbol{n}}$, and assume that their intersection is nonempty. Prove that the intersection contains a line if $\boldsymbol{n}$ is at least 3. Furthermore, if $\boldsymbol{n}$ is at least $\mathbf{4}$ and $\mathbf{L}$ is a line in the intersection, prove that the latter also contains a point not on L. [Hint: The intersection is defined as the set of solutions of a system of two linear equations in $\boldsymbol{n}$ unknowns. Look at the set of solutions to the corresponding reduced system of equations.]
12. Let $\mathbf{S}$ and $\mathbf{T}$ be linear varieties in $\mathbb{R}^{\boldsymbol{n}}$ which are defined by the systems of linear equations $\mathbf{a}_{i} \cdot \mathbf{x}=\boldsymbol{b}_{\boldsymbol{i}}$ and $\mathbf{c}_{\boldsymbol{j}} \cdot \mathbf{x}=\boldsymbol{d}_{\boldsymbol{j}}$ respectively. Prove that their union $\mathbf{S} \cup \mathbf{T}$ is the set of all $\mathbf{x}$ such that $\left(\mathbf{a}_{i} \cdot \mathbf{x}-\boldsymbol{b}_{i}\right)\left(\mathbf{c}_{j} \cdot \mathbf{x}-\boldsymbol{d}_{\boldsymbol{j}}\right)=\mathbf{0}$ for all $\boldsymbol{i}$ and $\boldsymbol{j}$. [ Hint: If $\boldsymbol{u} \cdot \boldsymbol{v}=\mathbf{0}$ in $\mathbb{R}$, then either $\boldsymbol{u}=\mathbf{0}$ or else $\boldsymbol{v}=\mathbf{0}$. As usual, there are two inclusions to verify.]
13. Let $\left\{\mathbf{P}_{1}, \mathbf{P}_{2}, \ldots, \mathbf{P}_{n}\right\}$ be a finite set of points in $\mathbb{R}^{\mathbf{3}}$, write each $\mathbf{P}_{\boldsymbol{i}}$ in coordinate form as $\left(\boldsymbol{a}_{\boldsymbol{i}}, \boldsymbol{b}_{\boldsymbol{i}}, \boldsymbol{c}_{\boldsymbol{i}}\right)$, and for each $\boldsymbol{i}$ let $\mathbf{q}_{\boldsymbol{i}}=\left(\boldsymbol{a}_{\boldsymbol{i}}, \boldsymbol{b}_{\boldsymbol{i}}, \boldsymbol{c}_{\boldsymbol{i}}, \mathbf{1}\right)$. Prove that the points $\left\{\mathbf{P}_{\mathbf{1}}, \mathbf{P}_{\mathbf{2}}, \ldots, \mathbf{P}_{\boldsymbol{n}}\right\}$ are coplanar if and only if the vectors $\left\{\mathbf{q}_{1}, \mathbf{q}_{\mathbf{2}}, \ldots, \mathbf{q}_{n}\right\}$ span a proper vector subspace of $\mathbb{R}^{\mathbf{3}}$.

## I. 4 : Barycentric coordinates

1. Let $\mathbf{a}, \mathbf{b}$, and $\mathbf{c}$ be the noncollinear points in $\mathbb{R}^{\mathbf{2}}$ whose coordinates are given by $(-\mathbf{1}, \mathbf{0}),(\mathbf{1}, \mathbf{0})$, and $(\mathbf{0}, \mathbf{1})$ respectively. Find the barycentric coordinates for each of the following points with respect to $\mathbf{a}, \mathbf{b}$, and $\mathbf{c}$.
(a) $(0,0)$
(b) $(1,1)$
(c) $(\operatorname{sqrt}(2), \operatorname{sqrt}(2))$
(d) $(0,5)$
(e) $(2,-1)$
(f) $(-1 / 2,-1 / 3)$
2. Let $\mathbf{V}$ be a vector space over the real numbers. A subset $\left\{\mathbf{v}_{\mathbf{0}}, \mathbf{v}_{\mathbf{1}}, \ldots, \mathbf{v}_{\boldsymbol{n}}\right\}$ of $\mathbf{V}$ is said to be affinely independent if an arbitrary vector $\mathbf{w}$ in $\mathbf{V}$ has at most one expansion as a linear combination $\mathbf{w}=\boldsymbol{a}_{0} \mathbf{v}_{\mathbf{0}}+\boldsymbol{a}_{\mathbf{1}} \mathbf{v}_{\mathbf{1}}+\ldots+\boldsymbol{a}_{\boldsymbol{n}} \mathbf{v}_{\boldsymbol{n}}$ such that $a_{0}+a_{1}+\ldots+a_{n}=1$ (such expressions are often called affine combinations). Prove that the set $\left\{\mathbf{v}_{\mathbf{0}}, \mathbf{v}_{\mathbf{1}}, \ldots, \mathbf{v}_{\boldsymbol{n}}\right\}$ is affinely independent if and only if the set $\left\{\mathbf{v}_{\mathbf{1}}-\mathbf{v}_{\mathbf{0}}, \ldots, \mathbf{v}_{\boldsymbol{n}}-\mathbf{v}_{\mathbf{0}}\right\}$ is linearly independent. Using the symmetry of the indices in the definition of affine independence, explain why the set $\left\{\mathbf{v}_{\mathbf{1}}-\mathbf{v}_{\mathbf{0}}, \ldots, \mathbf{v}_{\boldsymbol{n}}-\mathrm{v}_{\mathbf{0}}\right\}$ is linearly independent if and only if for each $\boldsymbol{j}$ the set of all nonzero vectors of the form $\mathbf{v}_{\boldsymbol{i}}-\mathbf{v}_{\boldsymbol{j}}$ (running over all $\boldsymbol{i}$ such that $\boldsymbol{i} \neq \boldsymbol{j}$ ) is linearly independent.
3. Suppose $\mathbf{a}, \mathbf{b}$ and $\mathbf{d}$ are noncollinear points in $\mathbb{R}^{2}$. Prove that there is a unique point $\mathbf{c}$ distinct from $\mathbf{a}, \mathbf{b}$ and $\mathbf{d}$ such that the lines $\mathbf{a b}$ and $\mathbf{c d}$ are parallel and the lines ad and bc are also parallel, and show that this unique point is given by $\mathbf{b}+\mathbf{d}-\mathbf{a}$. [Hint: If $\mathbf{c}$ is given as above, note that $\mathbf{c}-\mathbf{d}=\mathbf{b}-\mathbf{a}$ and $\mathbf{c}-\mathbf{b}=$ $\mathbf{d} \mathbf{-} \mathbf{a}$, and let $\mathbf{V}$ and $\mathbf{W}$ be the $\mathbf{1}$ - dimensional vector subspaces spanned by $\mathbf{b} \mathbf{- a}$ and $\mathbf{d}-\mathbf{a}$ respectively. Express all four lines in the form $\mathbf{x}+\mathbf{U}$ where $\mathbf{x}$ is one of the four points and $\mathbf{U}$ is one of $\mathbf{V}$ or $\mathbf{W}$. What does the coset property imply if $\mathbf{a b}$ and cd have a point in common or if ad and bc have a point in common?]
Remark, The preceding exercise is closely related to the so - called "parallelogram law" for vector addition and reduces to the latter when $\mathbf{a}=\mathbf{0}$. In the figure below $\mathbf{A}$ and $\mathbf{B}$ correspond to $\mathbf{b}-\mathbf{a}$ and $\mathbf{d}-\mathbf{a}$, so that $\mathbf{A}+\mathbf{B}$ corresponds to $\mathbf{c}-\mathbf{a}$ and $\mathrm{d}=\mathrm{b}+\mathrm{c}-\mathrm{a}$.

(Source: http://mathworld.wolfram.com/ParallelogramLaw.html)
4. Suppose that the points $\mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D}$ form the vertices of a parallelogram in $\mathbb{R}^{\mathbf{2}}$, and let $\mathbf{E}$ be the midpoint of $\mathbf{A}$ and $\mathbf{B}$. Prove that the lines DE and $\mathbf{A C}$ meet in a point $F$ such that
(1) the distance from $\mathbf{A}$ to $\mathbf{F}$ is a third of the distance from $\mathbf{A}$ to $\mathbf{C}$,
(2) the distance from $\mathbf{E}$ to $\mathbf{F}$ is a third of the distance from $\mathbf{E}$ to $\mathbf{D}$. Here is a picture that may be helpful in setting up a purely algebraic proof:

5. Suppose that we are given three noncollinear points $\mathbf{a}, \mathbf{b}, \mathbf{c}$ in $\mathbb{R}^{\mathbf{2}}$, and suppose we are also given three arbitrary points in $\mathbb{R}^{\mathbf{2}}$ with the following expansions in terms of barycentric coordinates:

$$
\begin{aligned}
& \mathrm{p}_{1}=t_{1} \mathrm{a}+u_{1} \mathrm{~b}+v_{1} \mathrm{c} \\
& \mathrm{p}_{2}=t_{2} \mathrm{a}+u_{2} \mathrm{~b}+v_{2} \mathrm{c} \\
& \mathrm{p}_{3}=t_{3} \mathrm{a}+u_{3} \mathrm{~b}+v_{3} \mathrm{c}
\end{aligned}
$$

Show that the points $\mathbf{p}_{\mathbf{1}}, \mathbf{p}_{\mathbf{2}}, \mathbf{p}_{\mathbf{3}}$ are collinear if and only if we have

$$
\left|\begin{array}{lll}
\boldsymbol{t}_{1} & \boldsymbol{u}_{1} & \boldsymbol{v}_{1} \\
\boldsymbol{t}_{2} & \boldsymbol{u}_{2} & \boldsymbol{v}_{2} \\
\boldsymbol{t}_{3} & \boldsymbol{u}_{3} & \boldsymbol{v}_{3}
\end{array}\right|=\mathbf{0}
$$

6. Using the preceding exercise, prove the following result, which is essentially due to Menelaus of Alexandria (c. 70 A. D. - c. 130 A. D.) :
Let $\mathbf{A}, \mathbf{B}, \mathbf{C}$ be noncollinear points, and let $\mathbf{D}, \mathbf{E}, \mathbf{F}$ be points on the lines $\mathbf{A B}, \mathbf{B C}$ and AC respectively. Express these points using barycentric coordinates as affine combinations $\mathrm{D}=t \mathrm{~A}+(\mathbf{1}-\boldsymbol{t}) \mathrm{B}, \mathrm{E}=\boldsymbol{u} \mathrm{B}+(\mathbf{1}-\boldsymbol{u}) \mathrm{C}$, and $\mathrm{F}=v \mathrm{C}+(\mathbf{1}-v) \mathrm{A}$. Then $\mathrm{D}, \mathrm{E}$ and F are collinear if and only if $\boldsymbol{t} \boldsymbol{u} \boldsymbol{v}=-(\mathbf{1}-\boldsymbol{t})(\mathbf{1}-\boldsymbol{u})(\mathbf{1}-\boldsymbol{v})$.

(Source: http://mathworld.wolfram.com/MenelausTheorem.html)
7. In the preceding exercise, suppose that $\mathbf{D}, \mathbf{E}$ and $\mathbf{F}$ are collinear such that $\mathbf{B}$ is halfway between $\mathbf{A}$ and $\mathbf{D}$, while $\mathbf{E}$ is halfway between $\mathbf{B}$ and $\mathbf{C}$. Express the vector $\mathbf{F}$ as a linear combination of $\mathbf{A}$ and $\mathbf{C}$.
8. Using Exercise 5, prove the following result due to G. Ceva (1647-1734):

Let $\mathbf{A}, \mathbf{B}, \mathbf{C}$ be noncollinear points, let $\mathbf{D}, \mathbf{E}, \mathbf{F}$ be points on the lines $\mathbf{B C}, \mathbf{A C}$ and $\mathbf{A B}$ respectively such that $\{\mathbf{D}, \mathbf{E}, \mathbf{F}\}$ and $\{\mathbf{A}, \mathbf{B}, \mathbf{C}\}$ are disjoint, and suppose that the lines $\mathbf{B E}$ and $\mathbf{C F}$ intersect at some point $\mathbf{G}$ which is not equal to $\mathbf{B}$ or $\mathbf{C}$. Express the points $\mathbf{D}, \mathbf{E}, \mathbf{F}$ in terms of barycentric coordinates as $\mathbf{D}=\boldsymbol{t} \mathbf{B}+(\mathbf{1}-\boldsymbol{t}) \mathbf{C}$, $\mathbf{E}=\boldsymbol{u} \mathbf{C}+(\mathbf{1}-\boldsymbol{u}) \mathbf{A}$, and $\mathbf{F}=\boldsymbol{v} \mathbf{A}+(\mathbf{1}-\boldsymbol{v}) \mathbf{B}$. Then the lines $\mathbf{A D}, \mathrm{BE}$ and $\mathbf{C F}$ are concurrent (in other words, the three lines have a point in common) if and only if we have

$$
t u v=(1-t)(1-u)(1-v)
$$


(Source: http://mathworld.wolfram.com/CevasTheorem.html)
[ Hint: The lines AD, BE and CF are concurrent if and only if the points A, D and G are collinear.]
9. In the setting of the preceding exercise, suppose that the three lines AD, BE and CF are concurrent with $\boldsymbol{t}=\mathbf{1} / 2$ and $\boldsymbol{v}=\mathbf{1}-\boldsymbol{u}$. Express the common point $\mathbf{G}$ of these lines as a linear combination of $\mathbf{A}$ and $\mathbf{D}$ with the coefficients expressed in terms of $\boldsymbol{u}$.
10. Let $V$ be a vector space over the real numbers, let $S=\left\{\mathbf{v}_{\mathbf{0}}, \mathrm{v}_{\mathbf{1}}, \ldots, \mathbf{v}_{\boldsymbol{k}}\right\}$ be a subset of $\mathbf{V}$, and let $\mathbf{T}=\left\{\mathbf{w}_{\mathbf{0}}, \mathbf{w}_{\mathbf{1}}, \ldots, \mathbf{w}_{\boldsymbol{m}}\right\}$ be a set of vectors in $\mathbf{V}$ which are affine combinations of the vectors in S. Suppose that $\mathbf{y}$ is a vector in $\mathbf{V}$ which is an affine combination of the vectors in T. Prove that $\mathbf{y}$ is also an affine combination of the vectors in $\mathbf{S}$.
11. Find the barycentric coordinates of the point $(\mathbf{2}, \mathbf{0})$ with respect to the noncollinear points (1, 0), (3, 1), and (3, -1).

