

For discrete metrics,

$$N_r(x) = \{x\} \text{ if } r \leq 1, \quad X \text{ if } r > 1$$

strictly greater
than

For $C([0,1]) =$ continuous \mathbb{R} -valued functions,

$$N_r(f) = \text{all } g \text{ such that } |g(x) - f(x)| < r \text{ all } x.$$

OPEN SETS

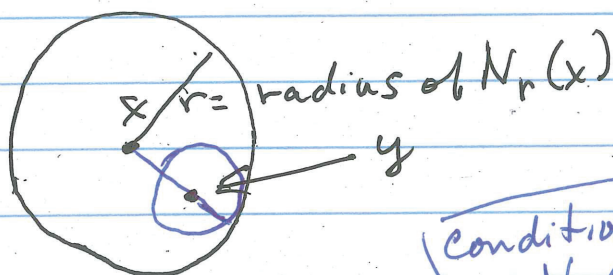
In \mathbb{R}^n , these are the sets needed to study partial derivatives.

Def. (X, d^X) metric space. $U \subseteq X$ is open in X (an open subset of X) \iff for each $u \in U$ there is some $\varepsilon > 0$ (depending on u) so that $N_\varepsilon(u) \subseteq U$.

Sutherland, Prop. 5.31 An open neighborhood of a point $x \in X$ is an open subset of X .

Proof. Figure 5.4 on p. 53 of Sutherland is helpful.

It suggests we take $\varepsilon = r - d(x, y)$ if $y \in N_r(x)$.



condition for $z \in N_\varepsilon(y)$

We want $N_\varepsilon(y) \subseteq N_r(x)$. But $d(z, y) < \varepsilon \implies d(z, x) \leq d(z, y) + d(y, x) < (r - d(x, y)) + d(x, y) = r$. \square
(so $z \in N_r(x)$)

Some open subsets of \mathbb{R}

(a, b) — If $x \in (a, b)$ then

$N_r(x) = (x-r, x+r)$, which is contained
in (a, b) if $r \leq x-a$, ~~$b-x$~~ .

Similarly for $(-\infty, b)$ (need $r \leq \overset{b-x}{\del b-x}$)
 (a, ∞) (need $r \leq x-a$).

A subset which is not open in \mathbb{R}

$A = [0, 1]$ is not open.

If $x = 0$, every set $N_r(x) = (-r, r)$

contains points not in A ; specific examples
are $-\frac{r}{2}, -\frac{r}{3}, \dots$.

More generally the closed half-open intervals

$\left\{ \begin{array}{l} [a, b] \\ [a, b) \\ (a, b] \end{array} \right\}$ are NEVER open in \mathbb{R} .