# SOLUTIONS TO EXERCISES FOR 

## MATHEMATICS 205A — Part 7

Fall 2014

## VII. Topological deformations and approximations

## VII. 0 : Categories and functors

Additional exercises

1. (a) Follow the hint and prove the contrapositives.

Not a monomorphism $\Rightarrow$ not $1-1$. If $f$ is not a monomorphism, then there exist mappings $g, h: C \rightarrow A$ such that $g \neq h$ but $f \circ g=f \circ h$. Now $g \neq h$ means that there is some $x \in C$ such that $g(x) \neq h(x)$, and by hypothesis we have $f(g(x))=f \circ g(x)=f \circ h(x)=f(h(x))$, so that $f$ sends both $g(x)$ and $h(x)$ to the same element of $B$. But this means that $f$ is not $1-1$.■

Not an epimorphism $\Rightarrow$ not onto. If $f$ is not an epimorphism, then there exist mappings $u, v: B \rightarrow D$ such that $u \neq v$ but $u^{\circ} f=v^{\circ} f$. The functional identity translates to the identity $u(f(a))=v(f(a))$ for all $a \in A$, and therefore we have $u|f[A]=v| f[A]$. On the other hand, $u \neq v$ implies that $u(b) \neq v(b)$ for some $b \in B$, and by the previous sentence we know that $b$ cannot belong to $f[A]$. Therefore $f[A]$ is a proper subset of $B$, which means that $f$ is not onto.■
(b) Suppose that $f[A]$ is dense in $B$ and $u^{\circ} f=u^{\circ} g$, where $u, v: B \rightarrow D$. Then $u$ and $v$ are equal on the dense subset $f[A]$. Since $D$ is Hausdorff, the set $E$ of all points $b$ such that $u(b)=v(b)$ is closed. We know that $E$ contains the dense subset $f[A]$, so we must have $E=B . ■$

Note. The Wikipedia article http://en.wikipedia.org/wiki/Epimorphism gives extensive information on the relationship between epimorphisms and surjective mappings for many standard examples of categories. Frequently, but not always, these notions are equivalent.
(c) Suppose we are given $f_{1}: A \rightarrow B$ and $f_{2}: B \rightarrow C$.

Assume both maps are monomorphisms. Let $g$ and $h$ be morphisms into $A$ such that $\left(f_{2} \circ f_{1}\right) \circ g=\left(f_{2} \circ f_{1}\right)^{\circ} h$. By associativity of composition and the monomorphism hypothesis on $f_{2}$, we have $f_{1}{ }^{\circ} g=f_{1}{ }^{\circ} h$; but now the monomorphism hypothesis on $f_{1}$ implies that $g=h . ■$

Assume both maps are epimorphisms. Let $u$ and $v$ be morphisms from $C$ such that $u^{\circ}\left(f_{2} \circ f_{1}\right)=v^{\circ}\left(f_{2} \circ f_{1}\right)$. By associativity of composition and the epimorphism hypothesis on $f_{1}$, we have $u^{\circ} f_{2}=v{ }^{\circ} f_{2}$; but now the epimorphism hypothesis on $f_{2}$ implies that $u=v . ■$
(d) Suppose that $f$ and $g$ are morphisms $W \rightarrow X$ such that $r \circ f=f \circ g$, and let $q$ be such that $q^{\circ} r=\operatorname{id}_{X}$. Then we have

$$
f=\operatorname{id}_{X}{ }^{\circ} f=q^{\circ} r^{\circ} f=q^{\circ} r^{\circ} g=\operatorname{id}_{X}{ }^{\circ} g=g
$$

which means that $r$ is a monomorphism.
(e) Suppose that $u$ and $v$ are morphisms $B \rightarrow D$ such that $u^{\circ} p=v^{\circ} p$. Then we have

$$
u=u^{\circ} \mathrm{id}_{B}=u^{\circ} p^{\circ} s=v^{\circ} p^{\circ} s=v^{\circ} \mathrm{id}_{B}=v
$$

which means that $p$ is a epimorphism.
Note. In the category of sets, the Axiom of Choice implies that every monomorphism is a retract and every epimorphism is a retraction, but for other categories this fails. For example, in the category of abelian groups the monomorphism $\mathbb{Z}_{2} \rightarrow \mathbb{Z}_{4}$ is not a retract and the epimorphism $\mathbb{Z}_{4} \rightarrow \mathbb{Z}_{2}$ is not a retraction. [PROOF: In the first case, if there was a homomorphism $q: \mathbb{Z}_{4} \rightarrow \mathbb{Z}_{2}$ such that $q \mid \mathbb{Z}_{2}$ was the identity, then the fact that the image of $\mathbb{Z}_{2}$ is $2 \mathbb{Z}_{4}$ implies that $q \mid 2 \mathbb{Z}_{4}$ is nonzero, and this cannot happen since $2 \mathbb{Z}_{2}=0$. In the second case, if one could find a suitable homomorphism $s$ then the image of $s$ would be contained in $2 \mathbb{Z}_{4}$ and once again this would yield the contradictory conclusion $p^{\circ} s=0$.]
2. We shall first dispose of the converse. Assume $f$ is an isomorphism, and let $g: B \rightarrow A$ be its inverse. Then by associativity of composition we know that $\operatorname{Mor}(f, \cdots){ }^{\circ} \operatorname{Mor}(g, \cdots)$ sends a morphism $h: A \rightarrow X$ to $h \circ g \circ f=h \circ \operatorname{id}_{A}=h$, so that $\operatorname{Mor}(f, \cdots) \circ \operatorname{Mor}(g, \cdots)$ is the identity on $\operatorname{Mor}(A, X)$. Similarly, by associativity of composition we know that $\operatorname{Mor}(g, \cdots){ }^{\circ} \operatorname{Mor}(f, \cdots)$ sends a morphism $k: B \rightarrow X$ to $h^{\circ} f^{\circ} g=k \circ \operatorname{id}_{B}=k$, so that $\operatorname{Mor}(g, \cdots)^{\circ} \operatorname{Mor}(f, \cdots)$ is the identity on $\operatorname{Mor}(B, X)$.

We shall now prove the exercise itself. Assume that $\operatorname{Mor}(f, \cdots)$ is an isomorphism from $\operatorname{Mor}(B, X)$ to $\operatorname{Mor}(A, X)$ for all $X$. If we let $X=A$ this means that there is a unique $p: B \rightarrow A$ such that $p \circ f=\operatorname{id}_{A}$. To prove the result we want, it suffices to show that $f \circ p=\operatorname{id}_{B}$. Since $\operatorname{Mor}(f, \cdots)$ is $1-1$, it will suffice to prove that $\left(f^{\circ} p\right)^{\circ} f=\operatorname{id}_{B}{ }^{\circ} f=f$; but this follows immediately from $p^{\circ} f=\mathrm{id}_{A}$.■
3. (a) For the empty set, the unique map is the one whose graph is the empty subset of $\emptyset \times A=\emptyset$ (this function is often called the empty map). For the one point set, the unique map is the one whose graph is the entire set $A \times\{$ point $\}$ (in other words, the only possible constant map into the set).
(b) Since a linear transformation always sends a zero vector to a zero vector, there is only one possibility for the map if the vector space consists only of the zero vector, so a zero space is an initial object. On the other hand, for a linear transformation into a zero space there is only possible value for the transformaton at a point; namely, the zero vector. Therefore a zero space is also a terminal object.
(c) We shall first consider initial objects. Since there is an identity map from an initial object $\mathcal{O}$ to itself and by hypothesis there is only one self-map of $\mathcal{O}$, it follows that a map from $\mathcal{O}$ to itself must be the identity. Suppose now that $\mathcal{O}$ and $\mathcal{O}^{\prime}$ are initial objects. Then there are unique maps $a: \mathcal{O} \rightarrow \mathcal{O}^{\prime}$ and $b: \mathcal{O}^{\prime} \rightarrow \mathcal{O}$. By the uniqueness of self-maps for initial objects, it follows that $b{ }^{\circ} a$ is the identity for $\mathcal{O}$ and $a^{\circ} b$ is the identity for $\mathcal{O}^{\prime}$. Therefore $a$ and $b$ are both isomorphisms.

We next consider terminal objects. Since there is an identity map from a terminal object $\mathcal{T}$ to itself and by hypothesis there is only one self-map of $\mathcal{T}$, it follows that a map from $\mathcal{T}$ to itself must be the identity. Suppose now that $\mathcal{T}$ and $\mathcal{T}^{\prime}$ are terminal objects. Then there are unique maps $a: \mathcal{T} \rightarrow \mathcal{T}^{\prime}$ and $b: \mathcal{T}^{\prime} \rightarrow \mathcal{T}$. By the uniqueness of self-maps for terminal objects, it follows that $b^{\circ} a$ is the identity for $\mathcal{T}$ and $a^{\circ} b$ is the identity for $\mathcal{T}^{\prime}$. Therefore $a$ and $b$ are both isomorphisms. -
4. If $Z$ is a null object and $A$ is an arbitrary object, then there are unique maps $A \rightarrow Z$ and $Z \rightarrow A$, so for each null object we obtain a unique composite morphism $A \rightarrow A$. We need to show that if $W$ is any other null object, then the composites $A \rightarrow Z \rightarrow A$ and $A \rightarrow W \rightarrow A$ are equal. For the sake of definiteness, let $t_{Z}: A \rightarrow Z$ and $j_{Z}: Z \rightarrow A$ be the unique maps from and to the null object $Z$, and similarly for $W$. Now let $a: W \rightarrow Z$ and $b: Z \rightarrow W$ be the unique maps between
the two null objects; then $a^{\circ} b$ and $b^{\circ} a$ must be identity maps by uniqueness, and consequently $a$ and $b$ are isomorphisms which are inverse to each other. Therefore we have

$$
j_{W}{ }^{\circ} t_{W}=j_{W}{ }^{\circ} \mathrm{id}_{W}{ }^{\circ} t_{W}=j_{W}{ }^{\circ} b^{\circ} a^{\circ} t_{W}
$$

and since $a^{\circ} t_{W}=t_{Z}$ and $j_{W}{ }^{\circ} b=j_{Z}$ by uniqueness, it follows that $j_{W}{ }^{\circ} t_{W}=j_{Z}{ }^{\circ} t_{Z}$, and hence the composite does not depend upon a the choice of a specific null object.
4. Suppose that $r: X \rightarrow Y$ is a retract and $s: Y \rightarrow X$ is a map such that $q^{\circ} r=\operatorname{id}_{X}$. If $F$ is a covariant functor defined on the category under consideration then we have

$$
\operatorname{id}_{F(X)}=F\left(\mathrm{id}_{X}\right)=F\left(q^{\circ} r\right)=F(q)^{\circ} F(r)
$$

and consequently $F(r)$ is also a retract. Similarly, if $p: A \rightarrow B$ is a retraction and $p^{\circ} s=\operatorname{id}_{B}$, then we have

$$
\operatorname{id}_{F(B)}=F\left(\mathrm{id}_{B}\right)=F\left(p^{\circ} s\right)=F(p)^{\circ} F(s)
$$

and consequently $F(p)$ is also a retraction.
If $G$ is a contravariant functor the conclusions are more complicated; namely, if $r$ is a retract then $G(r)$ is a retraction, and if $p$ is a retraction then $G(p)$ is a retract. The derivations are nearly the same as the preceding ones, but at the last step one must reverse the orders of composition.■
5. In fact, $f$ is a retract, for there is a unique morphism $c: X \rightarrow E$ because $E$ is terminal, and as noted before the morphism $c^{\circ} f: E \rightarrow E$ must be the identity if $E$ is terminal.
6. This is basically a translation of fundamental statements about matrix multiplication into the language of category theory. A morphism $A: n \rightarrow m$ is merely an $m \times n$ matrix over the integers, the identity matrix is the identity morphism, and composition is matrix multiplication. The composition rules for identities and associativity are then merely restatements of the corresponding properties of matrix multiplication.■
7. Let $f: X \rightarrow Y$ be a morphism, and suppose that $f$ has a quasi-inverse $g: Y \rightarrow X$; we claim there is some $h: Y \rightarrow X$ such that $f$ is a quasi-inverse to $h$. The natural first candidate is $h=g$, but this does not lead anywhere so we need to find another choice for $h$. The correct choice is $g \circ f^{\circ} g$, and the string of equations

$$
(g f g) f(g f g)=(g f g)(f g f) g=(g f g) f g=g(f g f) g=g f g
$$

shows that $f$ is a quasi-inverse to $g \circ f \circ g$ (the composition operators were omitted in the display to make the equations easier to follow).

Note. Usually morphisms in a category do not have quasi-inverses, but in the category of sets the Axiom of Choice is essentially equivalent to the existence of quasi-inverses.

## VII.1: Homotopic mappings

Problems from Munkres, § 51, p. 330
2. On the unit interval $I=[0,1]$ the identity map is homotopic to a constant map by convexity. Therefore we have the following:
(a) If $f: X \rightarrow I$ is continuous, then $f=\operatorname{id}_{I}{ }^{\circ} f$ is homotopic to $C_{0}{ }^{\circ} f$, where $C_{0}$ is the constant function whose value everywhere is zero. Since $C_{0}{ }^{\circ} f=C_{0}$, it follows that $f$ is homotopic to the map which sends everything to zero.
(b) If $f: I \rightarrow Y$ is continuous, then $f=f{ }^{\circ} \mathrm{id}_{I}$ is homotopic to $f{ }^{\circ} C_{0}$, which is the constant map with value $f(0)$ everywhere. Since $Y$ is arcwise connected, one can use a curve joining $f(0)$ to an arbitrary point $y_{0} \in Y$, and hence all constant maps are homotopic to each other. Combining these, we see that every continuous mapping $I \rightarrow Y$ is homotopic to the constant map with value $y_{0}$. •
3. (a) More generally, if $K \subset \mathbb{R}^{n}$, then the straight line homotopy $H(x, t)=(1-t) x+t x_{0}$ is a homotopy from the identity on $K$ to the constant map whose value everywhere is $x_{0}$.-
(b) If $H: X \times[0,1] \rightarrow X$ is the homotopy from the identity to the constant map with value $x_{0}$, then $H \mid\{x\} \times[0,1]$ is a curve joining $x$ to $x_{0}$, and therefore every point in $X$ lies in the arc component of $x_{0}$.•
(c) This is essentially the same argument as in $2(a)$ with $I$ replaced by an arbitrary contractible space.
(d) This is essentially the same argument as in 2(b) with $I$ replaced by an arbitrary contractible space.

Problem from Munkres, § 52, p. 334

1. (a) If $A \subset \mathbb{R}^{2}$ is the union of the $x$ - and $y$-axes, then $A$ is star convex with $a_{0}$ taken to be the origin because $x \in A$ and $0<t<1$ implies $t x \in A$. However, $A$ is not convex because $(1,0)$ and $(0,1)$ are in $A$ but $\left(\frac{1}{2}, \frac{1}{2}\right)=\frac{1}{2}(1,0)+\frac{1}{2}(0,1)$ does not lie in $A$.-
(b) [Not included because the concept of simple connectedness has not yet been introduced. However, another exercise has a stronger result; namely, a star convex set is contractible.]

## Additional exercises

1. The set of continuous maps $P \rightarrow X$ is in 1-1 correspondence with the points of $X$ such that $f: P \rightarrow X$ corresponds to $f\left(p_{0}\right) \in X$. Two such continuous mappings are homotopic if and only if their values $f_{0}\left(p_{0}\right)$ and $f_{1}\left(p_{0}\right)$ can be joined by a continuous curve in $X$. Therefore one obtains a 1-1 correspondence between $[I, X]$ and the set of arc components of $X$ by sending $f$ to the arc component of $f\left(p_{0}\right)$.-
2. The idea is to follow the hint and prove that two of maps from $X$ to $Y$ are always homotopic. As noted in the hint, if $Y$ has the indiscrete topology and $W$ is an arbitrary topological space, then every map of sets from $W$ to $Y$ is continuous. In particular, if $V \subset W$ and $g: V \rightarrow Y$ is continuous, then there is an extension of $g$ to a map of sets from $W$ to $Y$, and this extension is automoatically continuous. In particular, this is true if $W=X \times[0,1]$ and $V=X \times\{0,1\}$, proving that if $f_{0}$ and $f_{1}$ are continuous mappings from $X$ to the indiscrete space $Y$, then one can always construct a homotopy from $f_{0}$ to $f_{1}$. .
3. Since a continuous map takes connected sets to connected sets and the connected components of a discrete space are the one point subsets, it follows that every continuous map $X \rightarrow Y$ is a constant map and, in addition, every homotopy between two continuous maps is also constant. Therefore, if we take the 1-1 correspondence between points of $Y$ and constant maps from $X$ to $Y$, we obtain a map $Y \rightarrow[X, Y]$ which is both $1-1$ and onto.
4. (i) Star convexity implies that the image of the straight line homotopy $H(x, t)=(1-t) a_{0}+t x$ is contained in $A$, so it follows that the identity on $A$ is homotopic to the constant map whose value is $a_{0} \cdot \square$
(ii) Follow the hint. First of all, if $K$ and $L$ are convex and $p \in K \cap L$, then $K \cup L$ is star convex with respect to $p$ because $x \in K \cup L$ implies $x \in K$ or $x \in L$, and in either case the line segment defined by $(1-t) p+t x$ will be contained in $K \cup L$. In the example, $K$ and $L$ are convex subsets of $\mathbb{R}^{2}$, and one can check that $(7 / 4,3 / 4)$ and $(3 / 4,7 / 4)$ are in $A=K \cup L$. However, their midpoint is $(5 / 4,5 / 4)$, and this point is not in $A$

## VII.2 : Some examples

## Additional exercises

1. Let $x \in U$, and choose $\delta>0$ such that $N_{\delta}(x)$ is contained in $U$. Since $\mathbb{Q}^{n}$ is dense in $\mathbb{R}^{n}$, it follows that there is some point $y \in N_{\delta}(x) \cap \mathbb{Q}^{n}$. Now $N_{\delta}(x)$ is arcwise connected and hence is contained in the arc component of $x$, so we have shown that this arc component contains a point in $\mathbb{Q}^{n}$. It follows that we can define a $1-1$ map from the arc components of $U$ to $\mathbb{Q}^{n}$ by choosing some point in $\mathbb{Q}^{n}$ for each arc component. Since $\mathbb{Q}^{n}$ is countable, this means the set of arc components must also be countable.
2. Let $H: X \times[0,1] \rightarrow Y$ be the homotopy from $f_{0}$ to $f_{1}$, and consider the image $B$ of $A \times[0,1]$ where $A$ is an arcwise connected subset of $X$. Since $A \times[0,1]$ is arcwise connected, it follows that $B$ is arcwise connected and hence is contained in an arc component of $Y$. The conclusion of the exercise now follows because both $f_{0}[A]$ and $f_{1}[A]$ are contained in $B$..

## VII. 3 : Homotopy classes of mappings

Problem from Munkres, § 58, pp. 366-367
6. The first thing to notice is that the arcwise connectedness of $X$ implies that all constant maps into $X$ are homotopic, and consequently if the identity on $X$ is homotopic to a constant map, it is also homotopic to a constant map whose value lies in the subspace $A$. Now let $i: A \rightarrow X$ be a retract, with $r: X \rightarrow A$ such that $r{ }^{\circ} i=\operatorname{id}_{A}$, and let $H: X \times[0,1] \rightarrow X$ be a homotopy from the identity to a constant map whose value lies in $A$. Then the composite

$$
h^{\prime}(a, t)=r^{\circ} H(a, t)
$$

is a homotopy from the identity on $A$ to a constant map.

Problems from Hatcher, pp. 18-20
4. Let $j: A \rightarrow X$ be the inclusion map, and let $g: X \rightarrow A$ be the map $g(x)=f_{1}(x)$, which exists because the image of $f_{1}$ is contained in $A$. By construction we then know that $j{ }^{\circ} g=f_{1}$ is homotopic to $f_{0}$, which is the identity on $X$. To prove that $g^{\circ} j$ is homotopic to the identity on $A$, proceed as follows: Since each map $f_{t}$ maps $A$ into itself, it follows that $f_{t}$ induces a homotopy
$H: A \times[0,1] \rightarrow A$ such that $H(a, t)=f_{t}(a)$ for all $a$ and $t$. It then follows that $H$ defines a homotopy from the identity on $A$ to $f_{1} \mid A=j{ }^{\circ} g$. .
10. We shall first prove the statement in the first sentence. If $X$ is contractible, then the identity map on $X$ is homotopic to a constant, so if $f: X \rightarrow Y$ is arbitrary then $f=f \circ \mathrm{id}_{X}$ is homotopic to $f{ }^{\circ} C_{0}$ for some constant map $C_{0}$; since the latter composite is also a constant map, this shows that $f$ must be nullhomotopic. Conversely, the hypothesis $[X, Y]=\{$ point $\}$ for all $Y$ specializes to the case $Y=X$ and the statement that the homotopy class of the identity map in $[X, X]$ must be equal to the homotopy class of the constant map.
12. If $f: X \rightarrow Y$ is a homotopy equivalence and $P$ is a one point set, then $f_{*}:[P, X] \rightarrow[P, Y]$ must be an isomorphism; since $[P, Z]$ is the set of arc components of $Z$ by a previous exercise, it follows that $f$ induces a $1-1$ correspondence between the arc components of $X$ and the arc components of $Y$.

The proof of the corresponding statement for connected components is also elementary but slightly different. We can express things formally as follows: If $g: A \rightarrow B$ is a continuous map, then for each connected component $C$ of $A$ we know that the connected set $g[A]$ must lie in a connected component of $B$, and therefore if $\operatorname{ConnComp}(E)$ denotes the set of connected components of a space $E$, then the continuous mapping $g$ induces a map of sets

$$
\operatorname{ConnComp}(g): \operatorname{ConnComp}(A) \longrightarrow \operatorname{ConnComp}(B)
$$

and it is an elementary exercise to verify that this defines a covariant functor on the category of topological spaces and continuous maps. Furthermore, since arcwise connected sets are connected, a variant on Additional Exercise VII.2.2 implies that if $g_{0}$ and $g_{1}$ are homotopic maps from $A$ to $B$, then the induced maps of connected components satisfy the homotopy invariance property

$$
\operatorname{ConnComp}\left(g_{0}\right)=\operatorname{ConnComp}\left(g_{1}\right) .
$$

Combining these observations, we see that if $f$ is a homotopy equivalence from $X$ to $Y$ then the map ConnComp $(f)$ will be an isomorphism.

To prove the statement in the final sentence, observe that we have the following commutative diagram, in which we identify $[P, Z]$ with the arc components of a space $Z$ and the horizontal maps send an arc component of a space $Z$ to the connected component which contains it.


If $f$ is a homotopy equivalence, then the results in the first two paragraphs imply that $f_{*}$ and $\operatorname{ConnComp}(f)$ are isomorphisms. Therefore if either of the maps $\alpha_{X}$ or $\alpha_{Y}$ is an isomorphism, then so is the other.-

## Additional exercises

1. The key point to observe is that $f$ and $g$ are homotopy inverses to $f^{-1}$ and $g^{-1}$ respectively. Therefore it follows that $\operatorname{id}_{X}=f^{-1} \circ f \simeq f^{-1} \circ g$, yielding a relationship chain

$$
g^{-1}=\operatorname{id}_{X} \circ g^{-1}=f^{-1} \circ g^{\circ} g^{-1}=f-1 \circ \mathrm{id}_{X}=f^{-1}
$$

which shows that $f^{-1} \simeq g^{-1}$.
2. (i) Follow the hints. For the first part, suppose that $i$ is a retract. If $r: X \rightarrow A$ is such that $r^{\circ} i=\operatorname{id}_{A}$, then by functoriality $r_{*}{ }^{\circ} i_{*}=\left(i=\operatorname{id}_{A}\right)_{*}$, and since the latter is the identity on $[A, Y]$ it follows that $r_{*}$ is a retract, and consequently $r_{*}$ is $1-1$. For the second part, let $Y=A=\{0,1\} \subset[0,1]=X$ as in the hints. Since $A$ is a discrete space, every self-map of $A$ is continuous, and no two self-maps are homotopic (use a previous exercise), so the set $[A, A]$ contains exactly four elements. On the other hand, since $X$ is contractible the set $[A, X]$ contains exactly one element by a previous exercise. Therefore the map $[A, A] \rightarrow[X, A]$ cannot be 1-1.
(ii) In this case we have $i^{*}$ or $r^{*}=\left(i=\operatorname{id}_{A}\right)^{*}$, and since the latter is the identity on $[Z, A]$ it follows that $i^{*}$ is a retraction, and consequently $i^{*}$ is onto. To show that $i^{*}$ need not be onto, take $Z=A$ and $X$ as in the first part of the exercise. Then $[A, X]$ consists of one point and $[A, A]$ consists of four points, and therefore $i^{*}:[A, X] \rightarrow[A, A]$ is not onto for this example.■
3. (i) In the setting of this exercise, a map $f: Z \rightarrow X \times Y$ is totally determined by $p \circ f$ and $q \circ f$; two maps are equal if and only if their coordinate projections are equal, and if we are given $Z \rightarrow X$ and $Z \rightarrow Y$ then this pair arises as the coordinate projections of a continuous map $Z \rightarrow X \times Y$. Similarly, if $H$ is a homotopy from $f$ to $f^{\prime}$, then $p^{\circ} H$ and $q^{\circ} H$ define homotopies of their respective coordinate projections, and if we have homotopies of the coordinate projections then they arise as the coordinate projections of some homotopy $Z \times[0,1] \rightarrow Y$. These observations combine to prove that coordinate projections define an isomorphism $\theta_{Z}$.

To prove the naturality property of $\theta_{Z}$ (i.e., the commuative diagram), note that if $g: W \rightarrow Z$ is continuous, then the coordiante projections of $f \circ g$ are merely $p^{\circ} f \circ g$ and $q \circ f \circ g$ respectively. $\quad$.
(ii) Given homotopy classes $u, v, w \in[Y, X]$, choose representative continuous functions $r, s, t$ respectively, and let $C_{1}$ denote the constant map $Y \rightarrow X$ whose value is always 1 . The associative law on homotopy classes $u \cdot(v \cdot w)=(u \cdot v) \cdot W$ follows directly from the associativity identity

$$
[r \cdot(s \cdot t)](y)=r(y) s(y) t(y)=[(r \cdot s) \cdot t](y)
$$

which comes from the associativity of $m$ and holds for all $y \in Y$. Similarly, $u \cdot\left[C_{1}\right]=u=\left[C_{1}\right] \cdot u$ follows from $r(y) \cdot 1=r(y)=1 \cdot r(y)$. Finally, an inverse to the homotopy class of $u$ is given by the function $q(y)=r(y)^{-1}$, for we have $q \cdot r=C_{1}=r \cdot q$ by the same reasoning as above.

If $h: Y \rightarrow Z$ is continuous, then $h^{*}$ sends $u, v, w$ to classes represented by $r^{\circ} h, s^{\circ} h$ and $t^{\circ} h$. Therefore $h^{*}(u \cdot v)$ is represented by $(r \cdot s)^{\circ} h$, which is equal to $\left(r^{\circ} h\right) \cdot\left(s^{\circ} h\right)$. Since the latter represents $h^{*}(u) \cdot h^{*}(v)$, it follows that $h^{*}$ defines a group homomorphism with respect to the group structure on $[Y, X]$.

Note. If $X=S^{1}$, then this group structure is abelian because $S^{1}$ is abelian, and the resulting abelian group - often called the Bruschlinsky group - is used in the file polishcircle.pdf.
4. (a) The straight line homotopy $H_{t}$ from $\operatorname{id}_{A}$ to the constant map with value $a_{0}$ is a basepoint preserving homotopy. Therefore if $f:\left(A, a_{0}\right) \rightarrow\left(X, x_{0}\right)$ is a basepoint preserving map, then $f \circ{ }^{\circ} H_{t}$ is a basepoint preserving homotopy from $f$ to the basepoint preserving constant map.
(b) Let $H_{t}$ be as in part (a), and suppose we are given a basepoint preserving map $g:\left(X, x_{0}\right) \rightarrow$ $\left(A, a_{0}\right)$. Then $H_{t}{ }^{\circ} g$ is a basepoint preserving homotopy from $f$ to the basepoint preserving constant map.■

Note. In contrast to some previous exercises, there was no need to assume $X$ was arcwise connected in $(a)$ because a basepoint preserving map will always send the arcwise connected space $A$ into the arc component of the basepoint in $X$.
5. (i) As suggested in the hint, let $g$ be a homotopy inverse to $f$. Then the associated maps of homotopy classes $(f \circ g)_{*}=f_{*}{ }^{\circ} g_{*},(g \circ f)_{*}=g_{*}{ }^{\circ} f_{*},\left(f^{\circ} g\right)^{*}=g^{*} \circ f^{*}$, and $\left(g^{\circ} f\right)^{*}=f^{*} \circ g^{*}$ are all identity maps because $f^{\circ} g$ and $g \circ f$ are homotopic to identity maps. It follows that $g_{*}$ is an inverse to $f_{*}$ and $g^{*}$ is an inverse to $f^{*}$.
(ii) This was already done in Exercise 12 on page 19 of Hatcher, for which the solution was given above.■
6. The Cantor set $X$ is given as the intersection of closed subsets $X_{n}$, where each $X_{n}$ is a finite union of pairwise disjoint intervals, each of which has length $3^{-n}$. If $u, v \in X$ lie in the same arc component, then for each $n$ they must lie on one of these intervals and hence the distance between them is at most $3^{-n}$, so that $|u-v|<3^{-n}$ for all $n$. But this can happen only if $u=v$. Therefore the arc components of $X$ are one point sets, and there are countably many of them. If $X$ were homotopy equivalent to an open subset of some $\mathbb{R}^{n}$, then by an earlier exercise the open set and $X$ would have to contain only countably many components. Consequently, there is no homotopy equivalence from $X$ to an open subset of some $\mathbb{R}^{n}$.

## VII. 4 : Homotopy types

Problem from Munkres, § 58, pp. 366-367

1. Note that "deformation retract" in Munkres means "strong deformation retract" in the sense of this course. We now proceed to the proof of the exercise.

Let $i: A \rightarrow B$ and $j: B \rightarrow X$ be the inclusions, and let $p: B \rightarrow A$ and $q: X \rightarrow B$ be the maps given by the deformation retract data. Then $\left(p^{\circ} q\right)^{\circ}\left(j^{\circ} i\right)=p^{\circ}\left(q^{\circ} j\right)^{\circ} i=p^{\circ} \mathrm{id}_{B}{ }^{\circ} i=\mathrm{id}_{A}$, so it only remains to show that $\left(j^{\circ} i\right)^{\circ}\left(p^{\circ} q\right)$ is homotopic to the identity relative to $A$. We know that $i^{\circ} p$ is homotopic to the identity relative to $A$, and since $p q \mid A$ is the identity it follows that $\left(j^{\circ} i\right){ }^{\circ}\left(p^{\circ} q\right)\left(j^{\circ}\left(i^{\circ} p\right){ }^{\circ} q\right)$ is homotopic to $\left(j^{\circ} \mathrm{id}_{A}{ }^{\circ} q\right)=j^{\circ} q$ relative to $A$. Since the right hand side is homotopic to the $\mathrm{id}_{X}$ relative to $B$ and $A \subset B$, it follows that $\left(j{ }^{\circ} i\right)^{\circ}\left(p^{\circ} q\right)$ is homotopic to the identity relative to $A$. This means that $A$ is a strong deformation retract of $X$.

Problems from Hatcher, pp. 18-20
5. Let $H: X \times[0,1] \rightarrow X$ be a homotopy from the identity to the constant map $C_{x}$, and let $W$ be the open set $H^{-1}[W]$. This open subset contains $\{x\} \times[0,1]$, so by Wallace's Theorem there is an open neighborhood $V$ of $x$ such that $V \times[0,1] \subset W$. It follows that $H \mid V \times[0,1]$ defines a homotopy into $U$ from the inclusion $V \subset U$ to the constant map $C_{x}$ on $V$.
13. To simplify the notation, we shall denote the deformation retract data by $H: X \times[0,1] \rightarrow X$ and $K: X \times[0,1] \rightarrow X$ respectively. It will also be convenient to denote the boundary of $[0,1] \times[0,1]$ in $\mathbb{R}^{2}$ (the four edge segments) by $\Gamma$.

By the definition of deformation retract data, the homotopies $H$ and $K$ satisfy the following conditions:
(1) If $a \in A$, then $H(a, t)=K(a, t)=a$ for all $t \in[0,1]$.
(2) We have $H(x, 0)=K(x, 0)=x$ for all $x \in X$.
(3) We have $H(x, 1) \in A$ and $K(x, 1) \in A$ for all $x \in X$.

The goal of the exercise is to construct a homotopy from $H$ to $K$; in other words, we want a map $L: X \times[0,1] \times[0,1] \rightarrow X$ with the following additional properties:
(4) We have $L(X, 0, t)=H(x, t)$ and $L(X, 1, t)=K(x, t)$ for all $x \in X$ and $t \in[0,1]$.
(5) If $a \in A$, then $L(a, s, t)=a$ for all $s, t \in[0,1]$.
(6) We have $L(x, s, 1) \in A$ for all $x \in X$ and $s \in[0,1]$.
(7) We have $L(x, s, 0)=x$ for all $x \in X$ and $s \in[0,1]$.

If $L$ exists, then we can view the maps $L_{s}=L \mid X \times\{s\} \times[0,1]$ as a 1-parameter family of deformation retract data starting with $H$ and ending with $K$.

The first step in constructing $L$ is to define $D: X \times[0,1] \times[0,1] \rightarrow X$ by the formula

$$
D(x, s, t)=H(K(x, s), t) .
$$

The hypotheses on $H$ and $K$ imply that $D$ has the following properties:
(8) We have $D(X, s, 0)=K(x, s)$ and $D(X, 0, t)=H(x, t)$ for all $x \in X$ and $s, t \in[0,1]$.
(9) If $a \in A$, then $L(a, t, s)=K(a, t, s)=a$ for all $s, t \in[0,1]$.
(A) We have $L(x, s, t) \in A$ and for all $x \in X$ if either $s=1$ or $t=1$.
(B) We have $D(x, 0,0)=x$ for all $x \in X$.

Evidently the behavior of $D \mid X \times \Gamma$ does not fit the requirements for $L$ that we have listed, but the properties of this restriction suggest that we can realize the requirements for $L$ if we compose $D$ with $\operatorname{id}_{X} \times \theta$, where $\theta:[0,1] \times[0,1] \rightarrow[0,1] \times[0,1]$ is a continuous map with the following behavior on $\Gamma$ :
(C) The bottom edge $[0,1] \times\{0\}$ is collapsed to $(0,0)$.
(D) The left edge $\{0\} \times[0,1]$ is mapped to itself by the identity.
(E) The top edge $[0,1] \times\{1\}$ maps to the union of the top and right edges $[0,1] \times\{1\} \cup\{1\} \times[0,1]$ such that $\left[0, \frac{1}{2}\right] \times\{1\}$ maps to the top edge such that $(t, 1)$ is sent to $(2 t, 1)$ and $\left[\frac{1}{2}, 1\right] \times\{1\}$ maps to the right edge such that $(t, 1)$ is sent to $(1,2-2 t)$.
(F) The right edge $\{1\} \times[0,1]$ maps to the bottom edge $[0,1] \times\{0\}$ such that $(1, t)$ is sent to $(t, 0)$.
The drawing in math205Aexercises7a.pdf illustrates the behavior we want on $\Gamma$, and a suitable function $\theta$ is constructed in that document. One can then use the definitions to verify that the function $L(x ; s, t)=D(x ; \theta(s, t))$ has all the desired properties.

## Additional exercises

1. In words, the subset $A$ consists of the bottom edge and the side edges of the rectangle $X$. As usual, we shall follow the approach in the hint; there is a drawing for this exercise in math205Aexercises7a.pdf.

The retraction $r:[-1,1] \times[0,1] \rightarrow[-1,1] \times\{0\} \cup\{-1,1\} \times[0,1]$ is defined by a radial projection with center $(\mathbf{0}, 2) \in[-1,1] \times \mathbb{R}$. As indicated by the drawing, the formula for $r$ depends upon whether $2|x|+t \geq 2$ or $2|x|+t \leq 2$. Specifically, if $2|x|+t \geq 2$ then

$$
r(x, t)=\frac{1}{|x|}(x, 2|x|+t-2)
$$

while if $2|x|+t \leq 2$ then we have

$$
r(x, t)=\frac{1}{2}((2-t) x, 0)
$$

and these are consistent when $2|x|+t=2$ then both formulas yield the value $|x|^{-1}(x, 0)$. Elementary but slightly tedious calculation then implies that $r(x, t)$ always lies in $[-1,1] \times[0,1]$, and likewise that $r$ is the identity on $[-1,1] \times\{0\} \cup\{-1,1\} \times[0,1]$. The homotopy from inclusion ${ }^{\circ} r$ to the identity is then the straight line homotopy

$$
H(x, t ; s)=(1-s) \cdot r(x, t)+s \cdot(x, t)
$$

and this completes the proof of the exercise.
2. Follow the hint: Let $X^{\prime} \subset X \times[0,1]$ be the subset $X \times\{0\} \cup A \times[0,1]$, and let $A^{\prime}=A \times\{1\}$.

If $h: X \rightarrow X^{\prime}$ is the composite $X \cong X \times\{0\} \subset X^{\prime}$, let $\rho: X^{\prime} \rightarrow X$ maps $X \times\{0\}$ to $X$ by projection onto the first coordinate and maps $A \times[0,1]$ to $A$ similarly. Then Exercise 4 implies that $X \times\{0\}$ is a deformation retract of $X^{\prime}$ and hence $h$ is a homotopy equivalence. Take the mapping $h_{0}$ to be the slice embedding $A \cong A \times\{1\}$. A homotopy from $h \mid A$ to $j^{\circ} h_{0}$ is given by $K(a, t)=(a, t)$. Finally, we need to find an open neighborhood $U$ of $A^{\prime}$ in $X^{\prime}$ such that $A^{\prime}$ is a strong deformation retract of $U$, and this can be done by taking $U=A \times(0,1]$. Since $A^{\prime}=A \times\{1\}$ it follows that $A^{\prime}$ is a strong deformation retract of $U$, so the only thing remaining is to prove that $U$ is open in $X^{\prime}$. We can see this most easily by viewing everything as a subspace of $X \times[0,1]$; in particular, since $V=X \times(0,1]$ is open in $X \times[0,1]$ and $X^{\prime} \cap V=A \times(0,1]=U$, it follows that $U$ is open in $X^{\prime}$.
3. For each $\alpha$ we have mappings $g_{\alpha}: Y_{\alpha} \rightarrow X_{\alpha}$ such that $g_{\alpha}{ }^{\circ} f_{\alpha}$ is homotopic to the identity on $X_{\alpha}$ and $f_{\alpha}{ }^{\circ} g_{\alpha}$ is homotopic to the identity on $Y_{\alpha}$; denote these homotopies by $H_{\alpha}$ and $K_{\alpha}$ respectively.

We claim that $\prod_{\alpha} g_{\alpha}$ is a homotopy inverse to $\prod_{\alpha} f_{\alpha}$, and this requires the construction of homotopies

$$
\Phi:\left(\prod_{\alpha \in A} X_{\alpha}\right) \times[0,1] \longrightarrow \prod_{\alpha \in A} X_{\alpha}, \quad \Psi:\left(\prod_{\alpha \in A} Y_{\alpha}\right) \times[0,1] \longrightarrow \prod_{\alpha \in A} Y_{\alpha}
$$

such that the composites

$$
\begin{aligned}
& \prod_{\alpha \in A} g_{\alpha}{ }^{\circ} f_{\alpha}=\left(\prod_{\alpha \in A} g_{\alpha}\right) \circ\left(\prod_{\alpha \in A} f_{\alpha}\right) \\
& \prod_{\alpha \in A} f_{\alpha} \circ g_{\alpha}=\left(\prod_{\alpha \in A} f_{\alpha}\right) \circ\left(\prod_{\alpha \in A} g_{\alpha}\right)
\end{aligned}
$$

are respectively homoptopic to the identity maps on $\prod_{\alpha \in A} X_{\alpha}$ and $\prod_{\alpha \in A} Y_{\alpha}$.
As usual, it suffices to define the coordinate projections of $\Phi$ and $\Psi$ for each $\gamma \in A$, and we do so by the formulas

$$
\pi_{\gamma}{ }^{\circ} \Phi=H_{\gamma} \circ\left(\pi_{\gamma} \times \mathrm{if}_{[0,1]}\right), \quad \pi_{\gamma}{ }^{\circ} \Psi=K_{\gamma} \circ\left(\pi_{\gamma} \times \mathrm{if}_{[0,1]}\right) .
$$

It follows immediately that these maps define homotopies from

$$
\left(\prod_{\alpha \in A} g_{\alpha}\right) \circ\left(\prod_{\alpha \in A} f_{\alpha}\right) \quad \text { and } \quad\left(\prod_{\alpha \in A} f_{\alpha}\right) \circ\left(\prod_{\alpha \in A} g_{\alpha}\right)
$$

to the identity mappings..
4. (i) Let $r: F \rightarrow B$ and $h: F \times[0,1] \rightarrow F$ be the deformation retraction data which exist because $B$ is a strong deformation retract of $F$. Extend $r$ to $r^{\prime}: X \rightarrow A$ by letting $r^{\prime} \mid A$ be the identity, and extend $h$ to $H: X \times[0,1] \rightarrow X$ by letting $H \mid A \times[0,1]$ be projection onto the first factor. If these maps are continuous, then they for deformation retract data for $A \subset X$. But the continuity of these extensions follows because $F \cap A=B$, and the restriction of $r$ to $B$ is the identity, and the restrictions of $h$ to $B \times[0,1]$ is projection onto the first factor.■
(ii) For $i=1,2$ let $r_{i}$ and $H^{(i)}$ be deformation retract data for $C \subset F_{i}$. Then the restrictions of these data to $X$ and $X \times[0,1]$ are the identity and projection onto the first factor respectively, so we can assemble $r_{1}$ and $r_{2}$ into a continuous mapping $r: X \rightarrow C$, and likewise we can assemble $H^{(1)}$ and $H^{(2)}$ into a continuous mapping $H: X \times[0,1] \rightarrow X$. The properties of the deformation retract data for $C \subset F_{i}$ imply that $r$ and $H$ are deformation retract data for $C \subset X . ■$

## Drawing for Hatcher, Exercise 13, page 19

This drawing is meant to motivate and clarify a crucial step in our solution for the cited exercise. We need to find a continuous mapping from the solid square $[\mathbf{0}, \mathbf{1}] \times[\mathbf{0}, \mathbf{1}]$ to itself with the following behavior on the edges:
(1) The bottom edge (in gold) is collapsed to the corner point $(\mathbf{0}, \mathbf{0})$.
(2) The left edge (in blue) is mapped to itself.
(3) The top edge (in red) maps to the union of the top and right edges.
(4) The right edge (in green) maps to the bottom edge.

The drawing and discussion below suggest one way of constructing such a function.


It is convenient to break the mapping into a twofold composite, where the first step is to stretch the square $[\mathbf{0}, \mathbf{1}] \times[\mathbf{0}, \mathbf{1}]$ to the rectangle $[\mathbf{0}, \mathbf{2}] \times[\mathbf{0}, \mathbf{1}]$ in the obvious fashion. The second step is to collapse the rectangle back into the square, such that the (pink) triangle with vertices $(\mathbf{0}, \mathbf{0}),(\mathbf{0}, \mathbf{1})$, and $(\mathbf{1}, \mathbf{1})$ is mapped to itself by the identity, the (yellow) triangle with vertices $(\mathbf{1}, \mathbf{1}),(\mathbf{2}, \mathbf{1})$, and $(\mathbf{2}, \mathbf{0})$ is mapped to the congruent triangle with vertices $(\mathbf{1}, \mathbf{1}),(\mathbf{1}, \mathbf{0})$, and $(\mathbf{0}, \mathbf{0})$ such that $(\mathbf{1}, \mathbf{1})$ corresponds to itself, $(\mathbf{2}, \mathbf{1})$ corresponds to $(\mathbf{1}, \mathbf{0})$, and $(\mathbf{2}, \mathbf{0})$ corresponds to ( $\mathbf{0}, \mathbf{0}$ ); also, the (striped gray) triangle with vertices $(\mathbf{0}, \mathbf{0}),(\mathbf{1}, \mathbf{1})$, and $(\mathbf{2}, \mathbf{0})$ is collapsed along horizontal lines onto the closed segment joining the first two vertices. Explicit formulas defining this mapping are given as follows; to simplify the notation we shall refer to the triangles by their colors (we have already defined them formally):
(1) On the pink triangle, which consists of the points $(u, v)$ in the rectangle such that $\boldsymbol{u} \leq \boldsymbol{v}$, the map sends $(\boldsymbol{u}, \boldsymbol{v})$ to itself.
(2) On the striped gray triangle, which consists of the points $(u, v)$ in the rectangle such that $v \leq u \leq 2-v$, the map sends $(u, v)$ to $(v, v)$.
(3) On the yellow triangle, which consists of the points $(u, v)$ in the rectangle such that $\mathbf{2 - v} \leq \boldsymbol{u}$, the map sends $(\boldsymbol{u}, \boldsymbol{v})$ to $(\boldsymbol{v}, \mathbf{2 - u})$.
The first two formulas are easy to derive, and the third can be done using linear algebra in various ways. For example, this can be done by finding the unique affine transformation of the coordinate plane which takes the points $(\mathbf{1}, \mathbf{1}),(\mathbf{2}, \mathbf{1})$, and $(\mathbf{2}, \mathbf{0})$ to the points $(\mathbf{1}, \mathbf{1}),(\mathbf{1}, \mathbf{0})$, and $(\mathbf{0}, \mathbf{0})$ respectively, or one can derive the formula by observing that the map on the yellow triangle is a clockwise rotation through $\mathbf{9 0}$ degrees which is centered at (1,1). Either way, the formula for the mapping turns out to be the one which is given in the third case. One can check directly that these definitions yield the same values for points on more than one triangle, so the formulas yield a well defined function.

## Drawing to accompany Additional Exercise VII.4.1

Here is a picture of the retraction described in the hint:


In this illustration, the retraction from $[-\mathbf{1 , 1}] \times[\mathbf{0 , 1}]$ to $[-\mathbf{1 , 1}] \times\{\mathbf{0}\} \cup\{-\mathbf{1 , 1}\} \times[\mathbf{0 , 1}]$ (the blue line segments) sends the points marked in black into the points marked in red on the corresponding lines. The explicit definition of the retraction has two cases, depending upon whether or not the original point lie in the pink colored region or the green colored region(s).

A similar argument shows that $\mathrm{D}^{\boldsymbol{n}} \times[\mathbf{0 , 1}] \cup \mathbf{S}^{\boldsymbol{n - 1}} \times[\mathbf{0 , 1}]$ is a retract of $\mathrm{D}^{n} \times[\mathbf{0 , 1}]$ for all positive integers $\boldsymbol{n}$. For example, one can obtain the case $\boldsymbol{n}=\mathbf{2}$ from the $\mathbf{1}$ - dimensional case by taking solids and surfaces of revolution about the $t$ - axis, and likewise in higher dimensions one can view the drawing as a planar cross section of the general construction.

# SOLUTIONS TO EXERCISES FOR 

## MATHEMATICS 205A — Part 8

Fall 2014

## VIII. The fundamental group

## VIII. 1 : Definitions and basic properties

Problems from Munkres, § 52, pp. 334-335
2. We shall start by translating the conclusion into the notation in the course notes. Given a curve $\theta$, Munkres' notation $\widehat{\theta}$ refers to the curve we call $-\theta$; for a curve defined on $[0,1]$ we have $-\theta(t)=\theta(1-t)$. So in our terminology the identity to be verified is

$$
-(\alpha+\beta)=(-\beta)+(-\alpha)
$$

Recall that $\{\alpha+\beta\}(t)=\alpha(2 t)$ if $t \leq \frac{1}{2}$ and $\{\alpha+\beta\}(t)=\beta(2 t-1)$ if $t \leq \frac{1}{2}$. Therefore $-\{\alpha+\beta\}(t)=$ $\{\alpha+\beta\}(1-t)$ is given by
(a) $\alpha(2(1-t))=\alpha(2-2 t)$ if $(1-t) \leq \frac{1}{2}$ or equivalently if $t \geq \frac{1}{2}$,
(b) $\beta(2(1-t)-1)=\beta(1-2 t)$ if $(1-t) \geq \frac{1}{2}$ or equivalently if $t \leq \frac{1}{2}$.

Similarly, we see that $\{(-\beta)+(-\alpha)\}(t)$ is given by
(c) $-\beta(2 t)=\beta(1-2 t)$ if $t \leq \frac{1}{2}$,
(d) $-\alpha(2 t-1)=\alpha(1-(2 t-1))=\alpha(2-2 t)$ if $t \geq \frac{1}{2}$.

Therefore we have shown that for each $t \in[0,1]$ the values of $-(\alpha+\beta)$ and $(-\beta)+(-\alpha)$ at $t$ are the same, and hence the two curves are equal. $\quad$
4. Let $i: A \rightarrow X$ denote the inclusion map. Since the fundamental group construction defines a covariant functor, we have $r_{*}{ }^{\circ} i_{*}=\mathrm{id}_{\pi_{1}(A)}$. Therefore if $u \in \pi_{1}\left(A, a_{0}\right)$ we have $u=r_{*}\left(i_{*}(u)\right)$ and therefore $u$ lies in the image of $r_{*}$, which means that $r_{*}$ is surjective.■
7. (a) In order to prove functional identities, one needs to show that the values of both sides of the equation at every point $s$ in the domain are the same. We apply this to verify the associativity, neutral element and inverse identities in $\Omega(G, 1)$ :

Associativity. For all $s$ we have

$$
\{(f \otimes g) \otimes h\}(s)=(f(s) \cdot g(s)) \cdot h(s)=f(s) \cdot(g(s) \cdot h(s))=\{f \otimes(g \otimes h)\}(s)
$$

Neutral element. If $C_{1}(t)=1$ for all $t$, then for all $s$ we have

$$
\left\{f \otimes C_{1}\right\}(s)=f(s) \cdot 1=f(s), \quad\left\{C_{1} \otimes f\right\}(s)=1 \cdot f(s)=f(s)
$$

Inverses. If $g(t)=f(t)^{-1}$ for all $t$, then for all $s$ we have

$$
\{f \otimes g\}(s)=f(s) \cdot g(s)=1=C_{1}(s), \quad\{g \otimes f\}(s)=g(s) \cdot f(s)=1=C_{1}(s) .
$$

(b) The crucial point to verify is that if $f_{0}$ and $g_{0}$ are endpoint preserving homotopic to $f_{1}$ and $g_{1}$ respectively, then $f_{0} \otimes g_{0}$ is endpoint preserving homotopic to $f_{1} \otimes g_{1}$. If we know this, then we can define a binary operation on $\pi_{1}(G, 1)$ by noting that there is a well defined binary operation on the latter with $[f] \otimes[g]=[f \otimes g]$. The associativity, neutral element and inverse identities will then follow from the corresponding identities derived in $(a)$.

To prove the statement in the preceding paragraph, note that if $H$ and $K$ are endpoint preserving homotopies from $f_{0}$ and $g_{0}$ to $f_{1}$ and $g_{1}$ respectively, then $H \otimes K$ is endpoint preserving homotopy from $f_{0} \otimes g_{0}$ to $f_{1} \otimes g_{1}$.
(c) Follow the hint. Direct computation yields the identity

$$
f+g=\left(f+C_{1}\right) \otimes\left(C_{1}+g\right)
$$

from which we find that $[f] \cdot[g]=\left[f+C_{1}\right] \otimes\left[C_{1}+g\right]=[f] \otimes[g]$. .
(d) For each value of $s$ either $\left\{f+C_{1}\right\}(s)$ or $\left\{C_{1}+g\right\}(s)$ is equal to 1 , so these two curves commute with respect to the " $\otimes$ " operation. Once again applying the reasoning in (c), we find that $[f] \otimes[g]=[g] \otimes[f]$ for all $[f]$ and $[g]$. The main conclusion of $(c)$ now implies that $[f[\cdot[g]=$ $[f] \otimes[g]=[g] \otimes[f]=[g] \cdot[f] .$.

Problems from Hatcher, pp. 38-40
10. This is very similar to parts of the preceding exercise. Let $i_{X}:\left(X, x_{0}\right) \rightarrow\left(X \times Y,\left(x_{0}, y_{0}\right)\right)$ be the slice inclusion sending $x$ to $\left(x, y_{0}\right)$, and let $i_{Y}:\left(Y, y_{0}\right) \rightarrow\left(X \times Y,\left(x_{0}, y_{0}\right)\right)$ be the slice inclusion sending $y$ to $\left(x_{0}, y\right)$. The goal is to construct a homotopy from $\left(i_{X}{ }^{\circ} f\right)+\left(i_{Y}{ }^{\circ} g\right)$ to $\left(i_{Y}{ }^{\circ} g\right)+\left(i_{X}{ }^{\circ} f\right)$. As is always the case with mappings into products, it is enough to construct the homotopies for the coordinate projections of these maps onto $\left(X, x_{0}\right)$ and ( $Y, y_{0}$ ). In other words, we only need to construct homotopies

$$
\begin{aligned}
& p_{X}{ }^{\circ}\left(\left(i_{X} \circ f\right)+\left(i_{Y}{ }^{\circ} g\right)\right) \text { to } p_{X}{ }^{\circ}\left(\left(i_{Y}{ }^{\circ} g\right)+\left(i_{X} \circ f\right)\right) \\
& p_{Y}{ }^{\circ}\left(\left(i_{X} \circ f\right)+\left(i_{Y}{ }^{\circ} g\right)\right) \text { to } p_{Y}{ }^{\circ}\left(\left(i_{Y}{ }^{\circ} g\right)+\left(i_{X} \circ f\right)\right)
\end{aligned}
$$

(where $p_{X}$ and $p_{Y}$ are coordinate projections), and we shall explain how these may be found using homotopies we have already constructed (for our puposes, this is "explicit" enough).

Since $p_{X}{ }^{\circ} i_{X}=\operatorname{id}{ }_{X}, p_{Y}{ }^{\circ} i_{Y}=\operatorname{id}_{Y}, p_{X}{ }^{\circ} i_{Y}=\operatorname{constant}\left(x_{0}\right)$ and $p_{Y}{ }^{\circ} i_{X}=\operatorname{constant}\left(y_{0}\right)$, we can translate the display to conclude that we only need to construct homotopies from $f+\operatorname{constant}\left(x_{0}\right)$ to constant $\left(x_{0}\right)+f$ and from $g+\operatorname{constant}\left(y_{0}\right)$ to constant $\left(y_{0}\right)+g$. This can be done by splicing together the standard homotopies from $h+$ constant to $h$ and from $h$ to constant $+h$ for $h=f$ or $g . \quad$
13. As stated, the problem has an almost trivial solution which require NO HYPOTHESES on the map of fundamental groups or the arcwise connectedness of $A$. Here is the solution: Given any curve $\gamma:[0,1] \rightarrow X$ with endpoints in $A$, the homotopy $h_{s}(t)=\gamma(s t)$ defines a homotopy from the constant curve with value $\gamma(0) \in A$ to the original curve $\gamma$. Presumably the author intended the following, which we shall prove below: ... iff every path in $X$ with endpoints in $A$ is endpoint preserving homotopic to a curve in $A$.
$(\Longrightarrow)$ Suppose that $i_{*}: \pi_{1}\left(A, x_{0}\right) \rightarrow \pi_{1}\left(X, x_{0}\right)$ is onto, and let $a_{0}, a_{1} i n A$. Since $A$ is arcwise connected, there are continuous curves $\alpha_{0}$ and $\alpha_{1}$ joining $x_{0}$ to $a_{0}$ and $a_{1}$ respectively.

We claim that every curve $\gamma:[0,1] \rightarrow X$ such that $\gamma(i)=a_{i}$ for $i=0,1$ is endpoint preserving homotopic to a curve of the form $\left(-\alpha_{0}+\beta\right)+\alpha_{1}$, where $\beta$ is a basepoint preserving closed curve in $X$. In fact, if we set $\beta$ equal to $\left(\alpha_{0}+\gamma\right)+\left(-\alpha_{1}\right)$, then we have the identities

$$
[\gamma]=\left[C\left(a_{0}\right)+\gamma+C\left(a_{1}\right)\right]=\left[\left(-\alpha_{0}\right)+\alpha_{0}+\gamma+\left(-\alpha_{1}\right)+\alpha_{1}\right]=\left[\left(-\alpha_{0}+\beta\right)+\alpha_{1}\right]
$$

when we adopt the convention in the course notes that endpoint preserving homotopy classes of iterated concatenations do not depend upon where parentheses are inserted. The hypothesis in this part of the problem is that $\beta$ is endpoint preserving homotopic to a curve $\theta$ whose image lies in $A$, and therefore $[\gamma]=\left[\left(-\alpha_{0}\right)+\beta+\alpha_{1}\right]$ is equal to

$$
\left(-\alpha_{0}+\theta\right)+\alpha_{1}
$$

, where the image of the representative curve $\left(-\alpha_{0}+\theta\right)+\alpha_{1}$ is contained in $A$.
$(\Longrightarrow)$ This follows immediately, for if $\gamma$ is a closed curve in $X$ which is endpoint (hence basepoint) preserving homotopic to a curve $\theta$ whose image is in $A$, then $[\gamma]=i_{*}([\theta])$.

## Additional exercises

1. Parts of this exercise are similar to parts of Exercise 52.7 in Munkres, for which a solution is given above.
(i) The first statement to prove is that the map sending $(\alpha, \beta)$ to $\alpha+\beta$ is continuous. We can do this by showing that $\mathbf{d}\left(\alpha^{\prime}+\beta^{\prime}, \alpha+\beta\right)<\varepsilon$ if $\mathbf{d}\left(\alpha^{\prime}, \alpha\right)<\varepsilon$ and $\mathbf{d}\left(\beta^{\prime}, \beta\right)<\varepsilon$. In fact, the maximum distance between the points $\left\{\alpha^{\prime}+\beta^{\prime}\right\}(s)$ and $\{\alpha+\beta\}(s)$ is the greater of $(a)$ the maximum distance between the points $\left\{\alpha^{\prime}\right\}(s)$ and $\{\alpha\}(s),(b)$ the maximum distance between the points $\left\{\beta^{\prime}\right\}(s)$ and $\{\beta\}(s)$.

We now turn to the homotopy assertions, and we shall use the notation of Proposition VIII.1.3. Let $H_{R}:[0,1] \times[0,1] \rightarrow[0,1]$ be the straight line homotopy from the identity to $h_{R}$, and let $H_{L}$ : $[0,1] \times[0,1] \rightarrow[0,1]$ be the straight line homotopy from the identity to $h_{L}$. Define corresponding maps $K_{R}, K_{L}: \Omega(X, x) \times[0,1] \rightarrow \Omega(X, x)$ by $\left\{K_{R}(\gamma, t)\right\}(s)=\gamma^{\circ} H_{R}(s, t)$ and $\left\{K_{L}(\gamma, t)\right\}(s)=$ $\gamma^{\circ} H_{L}(s, t)$. The definitions then imply that $K_{L}(\gamma, 0)=\gamma^{\circ} h_{L}=C_{x}+\gamma$ and $K_{L}(\gamma, 1)=\gamma$, and similarly we know that $K_{R}(\gamma, 0)=\gamma^{\circ} h_{R}=\gamma+C_{x}$ and $K_{R}(\gamma, 1)=\gamma$. If $\gamma^{\prime}$ is another element of $\Omega\left(X, x_{0}\right)$, then by construction the distance between $K_{R}(\gamma, t)$ and $K_{R}\left(\gamma^{\prime}, t\right)$ is equal to the distance between $\gamma$ and $\gamma^{\prime}$, and likewise for $K_{R}(\gamma, t)$ and $K_{R}\left(\gamma^{\prime}, t\right)$. These imply that $K_{L}$ and $K_{R}$ are continuous and hence yield homotopies of the types described in the statement of the exercise.
(ii) Follow the hint and imitate the reasoning in Munkres, Exercise 52.7. The results of $(i)$ show that $(Y, e)=\left(\Omega(X, x), C_{x}\right)$ is an $H$-space as defined following the statement of this exercise. We shall prove more generally that $\pi_{1}((Y, e)$ is abelian using the approach for the exercise in Munkres. Let $m: Y \times Y \rightarrow Y$ denote the continuous binary operation, and define a binary operation " $\otimes$ " on $\pi_{1}(Y, e)$ sending $([f],[g])$ to the class of the composite $f \otimes g(s)=m(f(s), g(s))$. We shall often denote the right hand side by $f(s) \cdot g(s)$ for the sake of simplicity, but when we do so we have to remember that this construction does not necessarily satisfy associativity or neutral element identities; all we know is that $f$ is basepoint preservingly homotopic to both $f \cdot C_{e}$ and $C_{e} \cdot f$. The latter suffice to yield two weaker identities

$$
[f+g]=\left[f+C_{1}\right] \otimes\left[C_{1}+g\right], \quad[f+g]=\left[C_{1}+g\right] \otimes\left[f+C_{1}\right]
$$

and since the right hand sides are equal to $[f] \otimes[g]$ and $[g] \otimes[f]$ respectively, it follows that the " $\otimes$ operation agrees with the usual group operation on the fundamental group, and both operations are abelian.■
(iii) If $\varepsilon>0$, then there is some $\delta>0$ such that $\mathbf{d}\left(x, x^{\prime}\right)<\delta$ implies $\mathbf{d}\left(f(x), f\left(x^{\prime}\right)\right)<\varepsilon$. It follows that if $\alpha$ and $\beta$ are curves such that $\mathbf{d}(\alpha, \beta)<\delta$, then $\mathbf{d}(f \circ \alpha, f \circ \beta)<\varepsilon$ (because the distance between two curves is the maximum distance between their values at points of the domain).
(iv) The second part follows from the first because continuous mappings from one compact metric space to another are always uniformly continuous, so everything reduces to proving the first assertion in the conclusion. For $n \geq 2$, define $\pi_{n}(X)=\pi_{1}\left(\Omega^{n-1}(X, x)\right.$, basepoint) as in the statement of the exercise. By (ii) we know this is an abelian group. By (iii) and induction we know that a basepoint preserving uniformly continuous mapping $f$ induces a map with the same properties, say $\Omega^{n-1}(f)$, from $\Omega^{n-1}(X, x)$ to $\Omega^{n-1}(Y, y)$, and this construction is functorial because it is given by composition of functions. Define $f_{*}: \pi_{n}(X, x) \rightarrow \pi_{n}(Y, y)$ to be the homomorphism of fundamental groups induced by $\Omega^{n-1}(f)$.

Note. Hatcher and most other books covering homotopy theory define $\pi_{n}$ differently, but eventually one almost always finds a proof that their construction(s) is/are equivalent to the one given here.
2. We claim that basepoint preserving maps from $\left(S^{0}, 1\right)$ to $(X, x)$ are the same as maps from $\{-1\}$ to $X$ and basepoint preserving homotopies are the same as homotopies of such mappings $\{-1\} \rightarrow X$. The first part is true because the basepoint of $S^{0}$ must go to the basepoint of $X$, but there are no constraints on where the second point can go. To see the statement on homotopies, note that the restriction of a homotopy to $\{1\} \times[0,1]$ must be constant but the restriction to $\{-1\} \times[0,1]$ can be an arbitrary continuous mapping from $[0,1]$ into $X .$.

## VIII. 2 : An important special case

Problems from Munkres, § 58, pp. 366-367
2. (a) Infinite cyclic.
(c) Infinite cyclic.
(d) Infinite cyclic.
(f) Infinite cyclic.
(g) Infinite cyclic.
(h) Trivial.
(i) Infinite cyclic.
(j) Infinite cyclic.
9. (a) This was not included because our definition does not involve any choices of an initial point on the circle.
(b) As in the statement of the exercise, let $\omega(t)=\exp 2 \pi i t$, and let $t_{0} \in \mathbb{R}$ be such that $p\left(t_{0}\right)=h^{\circ} \omega(0)$, where $p: \mathbb{R} \rightarrow S^{1}$ is the usual map $p(t)=\exp 2 \pi i t$. Let $\alpha$ be the unique path lifting of $h^{\circ} \omega$ starting at $t_{0}$. Then $\operatorname{deg}(h)$ is the unique integer $d(h)$ such that $\alpha(1)=t_{0}+d(h)$.

Now let $H: S^{1} \times[0,1] \rightarrow S^{1}$ be a homotopy from $h$ to $k$, and let $L:[0,1] \times[0,1] \rightarrow \mathbb{R}$ be the unique lifting of $H$ such that $L(0,0)=t_{0}$ and $p^{\circ} L(s, t)=H(p(s), t)$. By the uniqueness of path lifings we know that $\alpha(s)=L(s, 0)$ and the curve $L(s, 1)$ is a lifting $\beta$ of $k$. Furthermore, since $L(1, t)$ and $L(0, t)$ are both liftings of the curve $H \mid\{1\} \times[0,1]$. it follows that there is some integer $\Delta$ such that $L(1, t)=L(0, t)+\Delta$ for all $t$. In particular, we have $L(1,1)=L(0,1)+\Delta$ and $L(1,0)=L(0,0)+\Delta$. Now $L(s, 0)=\alpha(s)$ by the uniqueness of path liftings, and therefore $\Delta=\operatorname{deg}(h)$. On the other hand, $L(s, 1)$ is a lifting of $k(s)=H(s, 1)$, and therefore it also follows that $\Delta=\operatorname{deg}(k)$. In words, we have shown that (freely) homotopic maps from $S^{1}$ to itself have the same degree.■
(c) This one is probably easier to prove using the functoriality properties of the fundamental group. The proof of the main theorem in this section immediately yields the following result:

CLAIM. If $f$ is a basepoint preserving continuous mappings from $S^{1}$ to itself (with say $f(1)=1$ ), then the self-homomorphism $f_{*}$ on $\pi_{1}\left(S^{1}, 1\right) \cong \mathbb{Z}$ is multiplication by deg $(f)$.

Proof of the claim. Since the class $[\omega]$ generates $\pi_{1}\left(S^{1}, 1\right)$, it is enough to prove that $f_{*}([\omega])=\operatorname{deg}(f) \cdot[\omega]$, and we can do this using the Path Lifting Property because the image $\partial(f)$ of $f_{*}([\omega])=[f \circ \omega]$ in $\mathbb{Z}$ is given by taking a lifting $\theta$ of $f \circ \omega$ starting at $0 \in \mathbb{R}$ and setting $\partial(f)$ equal to $\theta(1)$. This coincides with the definition of degree for the mapping $f .$.
Before proceeding, we note that the claim yields the conclusion of the exercise if $h$ and $k$ are basepoint preserving, for in that case we have

$$
\begin{aligned}
&\left.\operatorname{deg}\left(h^{\circ} k\right) \cdot[\omega]\right)=\left(h^{\circ} k\right)_{*}([\omega])=\left(h_{*}^{\circ} k_{*}\right)([\omega])=h_{*}(\operatorname{deg}(k) \cdot[\omega])= \\
& \operatorname{deg}(k) \cdot h_{*}([\omega])=\operatorname{deg}(k) \cdot \operatorname{deg}(h) \cdot[\omega]
\end{aligned}
$$

and since $[\omega] \in \pi_{1}\left(S_{1}, 1\right) \cong \mathbb{Z}$ has infinite order it follows that $\operatorname{deg}\left(h^{\circ} k\right)=\operatorname{deg}(h) \cdot \operatorname{deg}(k)$.
In order to apply the preceding discussion to $h$ and $k$, we have to replace them with (freely) homotopic mappings which ARE basepoint preserving. The easiest way to do this is to choose $a$ and $b$ such that $p(a)=h(1)$ and $p(b)=k(1)$ and define homotopies by $H(z, t)=h(z) \cdot p(t a)^{-1}$ and $K(z, t)=k(z) \cdot p(t b)^{-1}$; it then follows that $H_{0}=h$ and $H_{1}$ is basepoint preserving, and similarly $K_{0}=k$ and $K_{1}$ is basepoint preserving. Applying (ii) and recalling that $H_{1}{ }^{\circ} K_{1}$ is homotopic to $h^{\circ} k$, we find that

$$
\operatorname{deg}\left(h^{\circ} k\right)=\operatorname{deg}\left(H_{1}{ }^{\circ} K_{1}\right)=\operatorname{deg}\left(H_{1}\right) \cdot \operatorname{deg}\left(H_{1}\right)=\operatorname{deg}(h) \cdot \operatorname{deg}(k)
$$

which is what we wanted to prove.■
Note. The tools developed in 205B yield a simpler proof which generalizes to a notion of degree for continuous self maps of $S^{n}$ when $n \geq 2$.
(d) The unique lifting $\alpha$ of a constant map $f$ is a constant map, so $\alpha(1)=\alpha(0)$ implies that the degree is zero. - For the identity, we know that $\omega$ is a unique lift, and here the degree is $\omega(1)-\omega(0)=1$. - For $z^{n}$ where $n$ is an integer, we know that a unique lifting is given by $\omega_{n}(t)=n t$, and in this case $\omega_{n}(1)-\omega_{n}(0)=n$ is the degree; this applies to each of the final two cases in the exercise.
(e) Suppose that $h$ and $k$ have the same degree, and let $H_{1}$ and $K_{1}$ be basepoint preserving maps which are freely homotopic to $h$ and $k$ respectively. Since $h \simeq H_{1}$ and $k \simeq K_{1}$, it suffices to show that if $h$ and $k$ have the same degree (so by $(i)$ the same is true for $H_{1}$ and $K_{1}$ ), then $H_{1}$ and $K_{1}$ are homotopic. But the latter follows directly from the proof of the main result, for if the
degrees are equal then $\partial\left(H_{1}\right)=\partial\left(K_{1}\right)$, and hence the unique liftings of $H_{1}$ and $K_{1}$ starting at 0 are endpoint preserving homotopic. We can then compose this homotopy with $p$ to obtain a homotopy from $H_{1}$ to $K_{1}$, and since homotopy of maps is an equivalence relation it will follow that $h \simeq k$.

## Problems from Hatcher, pp. 38-40

3. $\quad(\Longrightarrow)$ Suppose that $X$ is arcwise connected and $\pi_{1}\left(X, x_{0}\right)$ is abelian. If $\alpha$ and $\beta$ are two continuous curves joining $x_{0}$ to $x_{1} \in X$, we want to prove that $\alpha^{*}=\beta^{*}$. - The desired conclusion is equivalent to proving that $(\alpha+(-\beta))^{*}$ induces the identity on $\pi_{1}\left(X, x_{0}\right)$ for all $\alpha$ and $\beta$, and if we make the substitution $\gamma=\alpha+(-\beta)$ this translates into proving that for each closed curve $\gamma$ which starts and ends at $x_{0}$ the automorphism $\gamma^{*}$ - which we have shown is given by $\gamma^{*}(u)=[\gamma]^{-1} u[\gamma]$ - is the identity. This identity holds if and only if $\pi_{1}\left(X, x_{0}\right)$ is abelian, so $\alpha^{*}=\beta^{*}$ in this case.
$(\Longrightarrow)$ Suppose now that we have $\alpha^{*}=\beta^{*}$ for all paths $\alpha$ and $\beta$ from $x_{0}$ to $x_{1}$. By the same reasoning as in the first part, it follows that $\gamma^{*}(u)=[\gamma]^{-1} u[\gamma]$ is the identity for all closed curves $\gamma$ and $u \in \pi_{1}\left(X, x_{0}\right)$. In other words, we have $u=v^{-1} u v$ for all $u$ and $v$ in the fundamental group. But this is true if and only if $\pi_{1}\left(X, x_{0}\right)$ is abelian.
4. If $A \subset X$ and a retraction $r: X \rightarrow A$ exists, then the induced map in fundamental groups $\pi_{1}(A) \rightarrow \pi_{1}(X)$ is $1-1$ and the induced map $r_{*}$ in fundamental groups is onto, so it suffices to prove that either $\pi_{1}(A) \rightarrow \pi_{1}(X)$ is not $1-1$ or $\pi_{1}(A)$ is not isomorphic to a homomorphic image of $\pi_{1}(X)$.
(a) If $X=\mathbb{R}^{3}$ and $A \cong S^{1}$ then $\pi_{1}(X)$ is trivial but $\pi_{1}(A) \cong \mathbb{Z}$. Since a nontrivial group cannot be isomorphic to a homeomorphic image of a trivial group, there cannot be a retraction.■
(b) This is a little informal, in part because the inclusion $A \rightarrow X$ is only described by means of an unannotated drawing, but it can be justified if one describes the inclusion $A \subset X$ explicitly; this turns out to be possible, but at this stage it would take several paragraphs to explain everything in full detail. In this case both $\pi_{1}(A)$ and $\pi_{1}(X)$ are infinite cyclic, and if $B \subset X=S^{1} \times D^{2}$ is equal to $S^{1} \times\{\mathbf{0}\}$, then the inclusion of $A \cong S^{1}$ in $X$ is homotopic to the map $S^{1} \rightarrow B \cong S^{1}$ given by something like $p^{\circ} f(t)$, where $f:[0,1] \rightarrow \mathbb{R}$ is the closed curve given by $f(t)=(1+h) \sin t$ for some small $h>0$. By convexity $f$ is homotopic to a constant curve in $\mathbb{R}$, so $p^{\circ} f$ is homotopic to a constant curve in $B$, and hence the mapping $A \rightarrow B$ is null homotopic. But this means that the composite $\pi_{1}(A) \rightarrow \pi_{1}(B) \cong \pi_{1}(X)$ is trivial. Since $\pi_{1}(A)$ and $\pi_{1}(X)$ are infinite cyclic, this means that the map $\pi_{1}(A) \rightarrow \pi_{1}(X)$ is not $1-1$, and we have noted that in such cases a retraction cannot exist. $\quad$
5. The assignment modifies the question to ask for infinitely many homotopy classes of retractions for the slice inclusion $j_{1}: S^{1} \rightarrow S^{1} \times S^{1}$ sending $z$ to $(z, 1)$. At the end of the exercise we shall explain how one can extract a solution to the exercise as it is stated in Hatcher.

Given an integer $n$, let $r_{n}: S^{1} \times S^{1} \rightarrow S^{1}$ be the map sending $(z, w)$ to $z w^{n}$. It follows that for each $n$ we have $r_{n}{ }^{\circ} j_{1}=\mathrm{id}$. To prove that $r_{n}$ and $r_{m}$ are not homotopic if $m \neq n$, let $j_{2}: S^{1} \rightarrow S^{1} \times S^{1}$ be the other slice inclusion $j_{2}(z)=(1, z)$. Then the degree of $r_{n}{ }^{\circ} j_{2}$ is equal to $n$, and therefore the homotopy classes of the mappings $r_{n}$ and $r_{m}$ are distinct if $m \neq n$.■

Solution for the problem as stated in Hatcher. In this case $S^{1} \vee S^{1}$ is identified with the subspace

$$
S^{1} \times\{1\} \cup\{1\} \times S^{1} \subset S^{1} \times S^{1}
$$

and the slice inclusions $j_{1}, j_{2}$ factor through maps $i_{1}, i_{2}$ from $S^{1}$ to $S^{1} \vee S^{1}$. Therefore if $r_{n}^{\prime}=$ $r_{n} \mid S^{1} \vee S^{1}$ we have $r_{n}^{\prime}{ }^{\circ} i_{1}=\mathrm{id}$ and $\operatorname{deg}\left(r_{n}^{\prime}{ }^{\circ} i_{2}\right)=n . ■$

## Additional exercises

0. This was done already as a step in the solution to Munkres, Exercise 58.9 (q.v.)..
1. Follow the hint. Given continuous mappings $f, g: S^{1} \rightarrow S^{1}$, with product $h(z)$, let $\alpha, \beta$ : $[0,1] \rightarrow \mathbb{R}$ be liftings and let $\gamma$ be their algebraic sum (if we write this symbolically, it will conflict with the use of " + " for concatenation); as suggested by the hint, the curve $\gamma$ is a lifting of $h$. By definition the degree of $h$ is equal to $\gamma(1)-\gamma(0)$, and the latter is equal to

$$
\alpha(1)+\beta(1)-\alpha(0)-\beta(0)=(\alpha(1)-\alpha(0))+(\beta(1)-\beta(0))=\operatorname{deg}(f)+\operatorname{deg}(g)
$$

which is what we wanted to prove.
2. (i) It is probably best to start by describing $\Pi(X)$ more explicitly. Its objects are the points of $X$, and a morphism from $x_{0}$ to $x_{1}$ is an endpoint preserving homotopy class of curves from $x_{0}$ to $x_{1}$. The identity morphism for $x$ is just the homotopy class of the constant curve at $x$, and if $\alpha$ and $\beta$ are curves joining $x_{0}$ to $x_{1}$ and $x_{1}$ to $x_{2}$ respectively, then the formal composite $[\beta] \circ[\alpha]$ is merely $[\alpha+\beta]$ (note the order reversal!). The morphisms from $x$ to itself then correspond to elements of $\pi_{1}(X, x)$ (with reversed multiplication!), and $[\alpha]^{-1}=[-\alpha]$ by the results of Sections VIII1 and VIII.2.

Functoriality can now be seen fairly easily. On objects, each point $x \in X$ goes to $f(x) \in Y$, and the homotopy class of a curve $\alpha$ joining $x_{0}$ to $x_{1}$ goes to the homotopy class $f_{*}([\alpha])$ of $f^{\circ} \alpha$. The results of this and the previous section imply that this does not depend on which $\alpha$ we choose to represent an endpoint preserving homotopy class. Since $f^{\circ} \alpha$ is constant if $\alpha$ is constant, it follows that the identity morphism for $x$ is sent to the identity morphism for $f(x)$, and the chain of identities

$$
[f \circ \beta][f \circ \alpha]=[f \circ(\alpha+\beta)]=f_{*}([\alpha+\beta])=f_{*}([\beta][\alpha])
$$

shows that the construction preserves composition of morphisms.■
3. Before starting, we recall the construction of $J_{k}: \pi_{1}\left(T^{k}, \mathbf{1}\right) \rightarrow \mathbb{Z}^{k}:$ Let $p_{k}: \mathbb{R}^{k} \rightarrow T^{k}$ be the Cartesian $k^{\text {th }}$ power map $p \times \cdots \times p$ ( $k$ factors) from $\mathbb{R}^{k}$ to $T^{k}$. Let $\mathbf{1} \in T^{k}$ be the point whose coordinates are all equal to the unit element of $S^{1}$.

If $\gamma$ is a basepoint preserving closed curve in $T^{k}$ which starts and ends at 1 , the we can apply the Path Lifting and Covering Homotopy Properties to each coordinatefunction of $\gamma$; this yields a unique lifting of $\gamma$ to a curve $\Gamma:[0,1] \rightarrow \mathbb{R}^{k}$ such that $\Gamma(0)=\mathbf{0}$, and $\Gamma(1) \in \mathbb{Z}^{n}$ because $p^{\circ} \Gamma(1)=\mathbf{1}$. As in the proof of the main result, $\Gamma(1)$ only depends upon the basepoint preserving homotopy class of $\gamma$, and hence the map $\gamma \rightarrow \Gamma(1)$ defines a map $J_{k}: \pi_{1}\left(T^{k}, \mathbf{1}\right) \rightarrow \mathbb{Z}^{k}$; the argument proving the main result of this section also shows that $J_{k}$ is a group isomorphism. The inverse map is given by sending $\left(d_{1}, \cdots, d_{k}\right)$ to the homotopy class of the curve $\left(p\left(d_{1} t\right), \cdots, p\left(d_{k} t\right)\right.$ ), where $p: \mathbb{R} \rightarrow S^{1}$ is the usual map.
(i) If $(a, b) \in \mathbb{Z}^{2}$, then $m_{*}{ }^{\circ} J_{2}^{-1}$ sends $(a, b)$ to the curve $p(a t) \cdot p(b t)=p((a+b) t)$, and $J_{1}^{-1}$ takes the latter curve to $a+b \in \mathbb{Z}^{2}$.
(ii) Suppose that $f$ is given as in the exercise. For each $j$ between 1 and $k$ let $s_{j}: S^{1} \rightarrow T^{k}$ denote the slice inclusion onto the $j^{\text {th }}$ slice (all coordinates are 1 except possibly the $j^{\text {th }}$ one). Then the images of the homomorphisms $s_{j *}$ generate $p i_{1}\left(T^{k}, \mathbf{1}\right)$, so it is enough to compute the degree of each map $f^{\circ} s_{j}$. The latter is the map sending $z$ to $z^{c_{j}}$, and therefore the degree is equal to $c_{j}$. This immediately yields the conclusion of part (ii).■
4. (i) Since we are mapping into a product, it is enough to prove this for projection onto the factors, and we have already done this in the second part of the preceding exercise.
(ii) If $\Phi_{A}$ is a homeomorphism, or even homotopic to a homeomorphism, then the induced homomorphism $\Phi_{A *}$ of $\pi_{1}\left(T^{k}, \mathbf{1}\right) \cong \mathbb{Z}^{k}$, which corresponds to left multiplication by $A$ on $\mathbb{Z}^{k}$, must be an automorphism, and therefore $\operatorname{det} A$ must be equal to $\pm 1$. Conversely, if $\operatorname{det} A= \pm 1$ and $B=A^{-1}$, then by Cramer's Rule $B$ has integral entries and hence we can construct $\Phi_{B}$. The definitions of the maps imply that $\Phi_{A B}=\Phi_{A}{ }^{\circ} \Phi_{B}$ and similarly if $B$ and $A$ are reversed; furthermore, if $A$ is the identity matrix $I$ then it follows that $\Phi_{I}$ is the identity mapping. These observations combine to imply that $\Phi_{B}$ is inverse to $\Phi_{A}$.-
(iii) The first part follows because an arbitrary self-homomorphism (endomorphism) of the group $\pi_{1}\left(T^{k}, \mathbf{1}\right) \cong \mathbb{Z}^{k}$ is given by some $k \times k$ matrix $A$ with integral entries, and we have shown that $\Phi_{A *}$ corresponds to left multiplication by $A$. The second part follows because if this matrix $A$ is $1-1$ and onto then $\Phi_{A}$ is a basepoint preserving homeomorphism from $T^{k}$ to itself.

## VIII. 3 : Covering spaces

## Problems from Munkres, § 53, p. 341

For these exercises, we do NOT assume the Default Hypothesis.

1. If $p$ is given as in the exercise, then for each $x \in X$ the whole space $X$ is an evenly covered open neighborhood of $x$ in $X$.
2. We know that $p *-1[U]$ is homeomorphic to $U \times F$ for some discrete space $F$. Since $U$ is connected, this means that the sheets $U \times\{y\}$ are the connected components of $U \times F$, and under the homeomorphism they correspond to the connected components of $p *-1[U]$..
3. Let $z \in Z$, and let $U$ be an open neighborhood of $z \in Z$ which is evenly covered; specifically, let $r^{-1}[U]$ be the union of the pairwise disjoint open subsets $U_{1}, \cdots, U_{n}$ such that $r$ maps each $U_{j}$ homeomorphically onto $U$, and let $y_{j} \in U_{j}$ be the unique point such that $r\left(y_{j}\right)=z$. Since $q$ is a covering space projection, for each $j$ there is an open neighborhood $V_{j}$ of $y_{j}$ in $Y$ which is evenly covered. Intersecting $V_{j}$ with $U_{j}$ if necessary, we might as well assume that $V_{j} \subset U$ (an open subset of an openly covered open set is also evenly covered!). Let $W=\cap_{j} r\left[V_{j}\right]$. Then by construction $z=r\left(y_{j}\right)$ (for each $j$ ) lies in $W$, and this set is open in $Z$ because $r$ is an open mapping. Furthermore, $W$ is evenly covered by the union of the pairwise disjoint subsets $W_{j}$. Now let $W_{j}=r^{-1}[W] \cap V_{j}$, so that $y_{j} \in W_{j}$ and $W_{j}$ is also evenly covered. Therefore, for all $j$ the inverse image $q^{-1}\left[W_{j}\right]$ is homeomorphic to $W_{j} \times F_{j}$, where $F_{j}$ is discrete, such that the restriction of $q$ to $q^{-1}\left[W_{j}\right]$ corresponds to projection onto $W_{j}$.

For each $j$ let $r_{j}: W_{j} \rightarrow W$ denote the homeomorphism determined by $r$. Since $p=r{ }^{\circ} q$, it follows that

$$
\begin{gathered}
p^{-1}[W]=q^{-1}\left[r^{-1}[W]\right]=q^{-1}\left[\bigcup_{j} W_{j}\right] \cong \\
\coprod_{j} W_{j} \times F_{j} \cong W \times\left(\coprod_{j} F_{j}\right)
\end{gathered}
$$

where we use the homeomorphisms $W_{j} \cong W$ at the last step. This implies that the open neighborhood $W$ of $z$ is evenly covered with respect to $p$, and the latter means that $p$ is also a covering space projection.■
6. (a) Let $p: X \rightarrow Y$ be a covering space projection. This part of the exercise involves proving that if $Y$ has a stated topological property, then so does $X$. There are several distinct properties, and we shall verify the assertions about them separately. Note that the priorities on the parts of this exercise vary depending upon the specific property.

Hausdorff. Let $x_{1} \neq x_{2}$ in $X$. There are two cases depending upon whether or not $p\left(x_{1}\right)=$ $p\left(x_{2}\right)$. If $p\left(x_{1}\right) \neq p\left(x_{2}\right)$, then since $Y$ is Hausdorff there are disjoint open neighborhoods $U_{1}$ and $U_{2}$ of $p\left(x_{1}\right)$ and $p\left(x_{2}\right)$ in $Y$, and their inverse images $p^{-1}\left[U_{1}\right]$ and $p^{-1}\left[U_{2}\right]$ are disjoint open neighborhoods of $x_{1}$ and $x_{2}$ in $X$. On the other hand, if $p\left(x_{1}\right)=p\left(x_{2}\right)$, let $W$ be an evenly covered open neighborhood of this point. Then $p^{-1}[W]$ is an open set homeomorphic to a disjoint union of copies of $W$. Since $x_{1} \neq x_{2}$, one of these copies contains $x_{1}$ and another contains $x_{2}$, and these two copies of $W$ in $X$ are disjoint open neighborhoods of the two points.

Regular. Let $x \in X$. It suffices to prove the regularity condition for a set of open neighborhoods $\mathcal{V}$ of $x$ such that every open neighborhood of $X$ contains a subneighborhood in $\mathcal{V}$, for if $x \in W$ open and $x \in V \subset W$ with $V \in \mathcal{V}$, then $x \in U \subset \bar{U} \subset V$ implies the same inclusions with $W$ replacing $V$.

In view of the preceding discussion, let $x \in V$, where $V$ is an open neighborhood of $x$ such that $p[V]=W$ is evenly covered and $V$ is one of the sheets. Since $Y$ is regular, there is an open neighborhood $U$ of $p(x)$ such that $p(x) \in U \subset \bar{U} \subset W$. Let $U_{1}=p^{-1}[U] \cap V$ be the sheet over $U$ which is contained in $V$. If we can prove that the closure $\overline{U_{1}}$ of $U_{1}$ in $X$ is contained in $V$, then the defining condition for regularity will hold at the point $x$, and since $x$ was chosen arbitrarily this will imply that $X$ is regular.

It will suffice to prove that $p^{-1}[\bar{U}] \cap V$, which contains $U_{1}$, is closed in $X$ because we would then have $\overline{U_{1}} \subset p^{-1}[\bar{U}] \cap V \subset V$. By construction and continuity we know that $p^{-1}[\bar{U}]$ is closed in $X$ and it is contained in the evenly covered open subset $p^{-1}[W]$. If $V^{*}$ denotes the union of all sheets in $p^{-1}[W]$ except $X$, then $V^{*}$ is open and hence $X-V^{*}$ is closed in $X$; with this notation we can rewrite the inclusion in the preceding sentence in the form $p^{-1}[\bar{U}] \subset V \cup V^{*}$, and it follows that

$$
p^{-1}[\bar{U}] \cap V=p^{-1}[\bar{U}] \cap\left(X-V^{*}\right)
$$

and since the right hand side is an intersection of two closed subsets of $X$, it follows that the left hand side is also a closed subset of $X$, which is what we needed to complete the proof.

Completely regular. By the preceding discussion we know that $X$ is regular, and as in the preceding discussion it suffices to prove that if $V$ is an open neighborhood of $x$ such that $p[V]=W$ is evenly covered and $V$ is one of the sheets. Let $U$ be an open subneighborhood such that $x \in U \subset \bar{U} \subset \underline{V}$, so that $U^{\prime}=p[U]$ and $V^{\prime}=p[V]$ are open neighborhoods of $p(x)$ such that $p(x) \in U^{\prime} \subset \overline{U^{\prime}} \subset V^{\prime}$. Since a subspace of a completely regular space is regular, there is a continuous function $g: V^{\prime} \rightarrow[0,1]$ such that $g(p(x))=0$ and $g=1$ on $V^{\prime}-U^{\prime}$; the composite $g{ }^{\circ} p$ satisfies similar properties: The value of $g^{\circ} p$ at $x$ is zero and $g^{\circ} p=1$ on $V-U$. If we define a new function $f$ : Xto[0, 1] such that $f\left|\bar{U}=g^{\circ} p\right| \bar{U}$ and $f \mid X-U=0$, then these functions agree on the overlapping closed subset $\bar{U}-U$, and therefore $f$ defines a continuous function on $X$ which is 1 at x and 0 off $U$.

Locally compact Hausdorff. We already know that $X$ is Hausdorff, so it is only necessary to show that every $x \in X$ has some open neighborhood whose closure is compact. As before, let $V$ be an open neighborhood of $x$ such that $p[V]=W$ is evenly covered and $V$ is one of the sheets. Since $Y$ is locally compact, it follows that there is some open neighborhood $U$ of $p(x)$ such that $\bar{U} \subset V$ and $\bar{U}$ is compact. Let $U_{1}=p^{-1}[U] \cap V$ be the sheet over $U$ which is contained in $V$,
and let $F=p^{-1}[\bar{U}] \cap V$. Since $p \mid V$ is a homeomorphism onto an open subset, it follows that $F$ is homeomorphic to $\bar{U}$ and hence is compact. Therefore we have found an open neighborhood $U_{1}$ of $x$ and a compact subset $F \subset X$ such that $x \in U_{1} \subset F \subset V$. Since $X$ is compact we know that $F$ is closed in $X$, and therefore it follows that $\overline{U_{1}}$ is also compact. As before, we started with an arbitrary $x \in X$, so the argument implies that $X$ is locally compact near every point and hence is a locally compact (Hausdorff) space.
(b) We shall first prove this when $Y$ is Hausdorff (in which case $X$ is also Hausdorff by part (a).

Let $p: X \rightarrow Y$ be a covering space projection such that $Y$ is compact and there are only finitely many sheets at each point of $Y$. We shall prove that $X$ is a union of finitely many compact subsets. Let $y \in Y$, and let $V_{y}$ be an open neighborhood of $y$ which is evenly covered. Since a locally compact Hausdorff space is regular, there is some subneighborhood $W_{y}$ of $V_{y}$ such that $\overline{W_{y}} \subset V_{y}$ (and $\overline{W_{y}}$ is compact). The family $\mathcal{W}$ of all sets $W_{y}$ is an open covering of $Y$, so there is a finite subcovering $\left\{W_{y_{1}}, \cdots, W_{y_{k}}\right\}$. Since the covering has finitely many sheets, each of the sets $p^{-1}\left[\overline{W_{y_{j}}}\right]$ is also compact, and since these form a finite closed covering of $X$ it follows that $X$ is also compact.

Here is a proof when $Y$ is not necessarily Hausdorff.
Let $\mathcal{U}$ be an open covering of $X$. For each $y \in Y$, let $V_{y}$ be an evenly covered open subset, and let $V_{y, 1}, \cdots V_{y, k(y)}$ denote the sheets over $V_{y}$ (we know there are only finitely many). If $x_{j} \in V_{y, j}$ is the unique point such that $p\left(x_{j}\right)=y$, then there is an open subneighborhood $\Omega_{y, j}$ of $x_{j}$ which is contained in some open set $U_{\alpha}$ in the open covering $\mathcal{U}$. Since $p$ is an open mapping, the set $W_{y}=\cap_{j} p\left[\Omega_{y, j}\right]$ is an evenly covered open neighborhood of $y$ which is contained in $V_{y}$. If $W_{y, j}=p^{-1}\left[W_{y}\right] \cap V_{y, j}$, then $p$ maps this set homeomorphically onto the open neighborhood $W_{y}$.

Since $Y$ is compact, the open covering $\mathcal{W}$ of $Y$ by the open subsets $W_{y}$ has a finite subcovering consisting of sets $W_{z}$, where $z$ lies in some finite subset $Z \subset Y$. The sheets of the inverse images $p^{-1}\left[W_{z}\right]$ then form an open covering of $X$ such that each set in this open covering is contained in some $U_{\alpha}$ which belongs to $\mathcal{U}$. Therefore if for each $W_{z, j}$ we choose some $U_{\alpha(z, j)}$ such that $W_{z, j} \subset U_{\alpha(z, j)}$, then the open sets $U_{\alpha(z, j)}$ form a finite subcovering of $\mathcal{U} . ■$

Problem from Hatcher, pp. 79-82
2. Assume that we are given covering space projections $p_{1}: E_{1} \rightarrow B_{1}$ and $p_{2}: E_{2} \rightarrow B_{2}$; we need to prove that $p_{1} \times p_{2}$ is also a covering space projection.

Let $\left(x_{1}, x_{2}\right) \in B_{1} \times B_{2}$. Then the hypotheses imply that for $i=1,2$ there is an evenly covered open neighborhood $U_{i}$ of $X_{i}$; i.e., there are discrete spaces $A_{i}$ and $B_{i}$ together with homeomorphisms $h_{i}: p_{i}^{-1}\left[U_{i}\right] \rightarrow U_{i} \times A_{i}$ such that $\operatorname{proj}\left(U_{i}\right)^{\circ} h_{i}$ is the restriction of $p_{i}$ to $p_{i}^{-1}\left[U_{i}\right]$. We claim that $U_{1} \times U_{2}$ is an evenly covered neighborhood of $\left(x_{1}, x_{2}\right)$ in $B_{1} \times B_{2}$. This is true because the homeomorphism
$H:\left(p_{1} \times p_{2}\right)^{-1}\left[U_{1} \times U_{2}\right]=p_{1}^{-1}\left[U_{1}\right] \times p_{2}^{-1}\left[U_{2}\right] \longrightarrow U_{1} \times A_{1} \times U_{2} \times A_{2} \cong\left(U_{1} \times U_{2}\right) \times\left(A_{1} \times A_{2}\right)$
(where the last map switches the second and third factors) is such that $\operatorname{proj}\left(U_{1} \times U_{2}\right)^{\circ} H$ is the restriction of $p_{1} \times p_{2}$ to $\left(p_{1} \times p_{2}\right)^{-1}\left[U_{1} \times U_{2}\right]$.

## Additional exercises

1. (i) Let $U$ be an open subset of $B$, and consider the following commutative diagram, which is derived from the exercise by considering various restriction mappings:


Let $y \in Y$, set $x$ equal to $\varphi^{-1}(y)$, and let $U$ be an evenly covered open neighborhood of $x$, so that there is a homeomorphism $h: p^{-1}[U] \rightarrow U \times A$ satisfying the defining identity. Then the composite

$$
h^{\prime}=\left(\varphi_{U} \times \mathrm{id}\right)^{\circ} h^{\circ} \Phi_{U}^{1}
$$

is a homeomorphism from $f^{-1}[\varphi[U]]$ to $\varphi[U] \times A$ such that $f_{\varphi[U]}$ is $h^{\prime}$ followed by coordinate projection onto $\varphi[U]$. Therefore $\varphi[U]$ is an evenly covered open neighborhood of $y .-$
(ii) Let $x \in X$, and choose $U_{\alpha}$ in $\mathcal{U}$ such that $x \in U_{\alpha}$. Since $q_{\alpha}$ is a covering space projection, we know that there is some open neighborhood $V \subset U_{\alpha}$ of $x$ such that $V$ is evenly covered by $q_{\alpha}$, and since $q_{\alpha}$ has the same values as $p$ at all points (but a different domain and codomain) it follows that $V$ is also evenly covered by $p$.
2. Given $x \in X$ we can find open neighborhoods $U_{1}$ and $U_{2}$ of $x$ which are evenly covered by $p_{1}$ and $p_{2}$, and by local connectedness there is a connected subneighborhood $U \subset U_{1} \cap U_{2}$; it follows that $U$ is evenly covered with respect to both $p_{1}$ and $p_{2}$. If $\mathcal{U}=\left\{U_{\gamma} \mid \gamma \in \Gamma\right\}$ is an open covering of $E_{2}$ by open subsets which are connected and evenly covered by $p_{1}$ and $p_{2}$, then by part (ii) of Exercise 1 it will suffice to show that the restricted maps

$$
p_{1}^{-1}\left[U_{\gamma}\right]=p^{-1}\left[p_{2}^{-1}\left[U_{\gamma}\right]\right] \longrightarrow p_{2}^{-1}\left[U_{\gamma}\right]
$$

determined by $p$ are all covering space projections.
If $U$ is connected and evenly covered by $p_{1}$ and $p_{2}$, let Let $h_{1}: p_{1}^{-1}[U] \rightarrow U \times A$ and $h_{2}$ : $p_{2}^{-1}[U] \rightarrow U \times B$ be homeomorphisms (where $A$ and $B$ are discrete spaces) such that proj( $U$ ) ${ }^{\circ} h_{i}$ is the restriction of $p_{i}$, and let $q: U \times A \rightarrow U \times B$ be the map unique continuous mapping from $p_{1}^{-1}[U]=p^{-1}\left[p_{2}^{-1}[U]\right]$ to $p_{2}^{-1}[U]$ such that $p\left(h_{1}^{-1}(u, a)\right)=h_{2}^{-1}(q(u, a))$. By continuity, for each $a \in A$ the map $q$ sends the connected subset $U \times\{a\} \subset U \times A$ into some connected component $U \times\{b(a)\} \subset U \times B$, and $q$ is onto because $p$ is onto. Since the composites

$$
U \times\{a\} \longrightarrow p_{1}^{-1}[U] \longrightarrow U, \quad U \times\{b\} \longrightarrow p_{2}^{-1}[U] \longrightarrow U
$$

are homeomorphisms, it follows that $q$ must map $U \times\{a\}$ homeomorphically onto $U \times\{b(a)\}$; denote the corresponding homeomorphism from $U$ to itself by $q_{a}$. If we compose $h$ with the union of the homeomorphisms $\varphi=\cup_{a} q_{a}: U \times A \rightarrow U \times A$ and replace $h$ with the composite $\varphi^{\circ} h$, then we obtain a new map $q^{\prime}$ analogous to $q$ but satisfying the condition that $q$ maps $U \times\{a\}$ to $U \times\{b(a)\}$ to the identity; note that $q^{\prime}$ is onto because $q$ is onto. It follows that $q^{\prime}$ is a covering space projection, and by part ( $i$ ) of Exercise 1 it also follows that the map

$$
p_{1}^{-1}[U]=p^{-1}\left[p_{2}^{-1}[U]\right] \longrightarrow p_{2}^{-1}[U]
$$

determined by $p$ is also a covering space projection.
If we apply the reasoning of the preceding paragraph to the open covering of $E_{2}$ by the sets $p_{2}^{-1}\left[U_{\gamma}\right]$, where $U_{\gamma}$ belongs to the previously described open covering $\mathcal{U}$, we see that each of the maps

$$
p_{1}^{-1}\left[U_{\gamma}\right]=p^{-1}\left[p_{2}^{-1}\left[U_{\gamma}\right]\right] \longrightarrow p_{2}^{-1}\left[U_{\gamma}\right]
$$

is a covering space projection, and as noted above this suffices to prove that $p$ itself is a covering space projection.

Note. Here is an example where $p$ is not onto: Let $X$ be an arbitrary nonempty space. Take $p: X \rightarrow X \amalg X$ to be inclusion into the first summand, and take $p_{2}: X \amalg X \rightarrow X$ to be the map which is the identity on each summand. There is a variation of this exercise in which one replaces the surjectivity hypothesis on $p$ by an assumption that $E_{2}$ is connected; the relationship with Exercise 2 is that if $E_{2}$ is connected then one can prove that $p$ is onto.
3. (i) Let $y \in Y$, let $U$ be an evenly covered open neighborhood of $f(x)$, and let $V$ be an open neighborhood of $x$ such that $f[V] \subset U$. We claim that $V$ is evenly covered in $Y \times_{X} E$. The definitions imply that the inverse image of $V$ is the subspace of $V \times E$ defined by $f(v)=p(e)$, and the inverse image is also the subspace of $V \times p^{-1}[U]$ defined by the same equation. If $h$ is the homeomorphism $p^{-1}[U] \rightarrow U \times A$ which exists by the assumption that $U$ is evenly covered, then under this homeomorphism the inverse image of $V$ corresponds to the set of all points $(v, u, a)$ in $V \times U \times A$ such that $f(v)=u$; i.e, the inverse image is given by the product of $A$ with the graph of $f \mid U$. Since the graph is homeomorphic to $U$, it follows that the inverse image is homeomorphic to $U$ via coordinate projection; one can check directly that all these maps are compatible with the appropriate projections onto $U$, and this shows that $U$ is evenly covered.

For the second part, if a lifting $\varphi$ exists, then the image of the map sending $y$ to $(y, \varphi(y))$ is contained in $Y \times_{X} E$ and hence determines a map $s: Y \rightarrow Y \times_{X} E$; by definition the composite of $s$ with projection onto $Y$ is the identity. Conversely, if there is a map $s: Y \rightarrow Y \times_{X} E$ such that $p_{(Y, f)} s=1_{Y}$, then the composite of $s$ with $j: Y \times_{X} E \subset E$ satisfies $p^{\circ} j^{\circ} s=f$, and therefore $j{ }^{\circ} s$ is a lifting of $f$.
(ii) If $f$ is a subspace inclusion then $Y \times_{X} E$ is just the set of all points $(y, e)$ in $Y \times p^{-1}[Y]$ such that $p(e)=y$. This maps homeomorphically to $p^{-1}[Y]$ by projection onto the second factor, and an explicit inverse is given by the map sending $e$ to $(p(e), e)$. Both of these maps are compatible with respect to the various projections onto $Y . ■$
4. Let $x \in X$ and let $U$ be an evenly covered open neighborhood of $x$. Since $X$ is totally disconnected there is an open subneighborhood $V \subset U$ such that $V$ is open and closed in $X$. By continuity $p^{-1}[V]$ is open and closed in $E$.

If $y \in Y$, let $p(y)=x$, so that $x$ has an evenly covered open neighborhood $V$ which is also closed in $X$. Now let $W$ be the sheet over $V$ which contains $y$. We claim that $W$ is open and closed in $Y$. Openness follows because $W$ is a sheet over an evenly covered open subset of $X$. To prove that $W$ is closed, let $W^{\prime}$ be the union of all the other sheets over $V$, so that $W^{\prime}$ is open and $E-W^{\prime}$ is closed. Then $W=p^{-1}[V] \cap\left(X-W^{\prime}\right)$ shows that $W$ is an intersection of two closed subsets and hence $W$ is closed in $Y$.n
5. (i) More generally, if $\mathcal{B}$ is a base for the topology of $X$ and $E \rightarrow X$ is a covering space projection, then the subset $\mathcal{B}^{\prime}$ of all evenly covered open subsets of $\mathcal{B}$ is also a base because every evenly covered open set is also a union of basic open subsets. Therefore if $X$ is second countable, then there is a countable base $\mathcal{B}$ of $X$ by evenly covered open subsets.

Let $\mathcal{A}$ be the family of all open subsets $W \subset E$ which are sheets over evenly covered open subsets $V \subset X$ such that $V \in \mathcal{B}$. We claim that $\mathcal{A}$ is a base for the topology on $E$. Since the number of sheets over each $V$ is countable by the countability assumption and the number of open sets in $\mathcal{B}$ is countable, it follows that $\mathcal{A}$ is a countable family. Therefore we need only show that $\mathcal{A}$ is a base for the topology.

Let $\mathcal{C}$ be the family of open subsets in $E$ such that $W \in \mathcal{C}$ if and only if $W$ is a sheet over an evenly covered open subset $V \subset X$. Then $\mathcal{C}$ is a base for the topology on $E$, so it will suffice to show that every subset in $\mathcal{C}$ is a union of open subsets in $\mathcal{A}$. Let $W \in \mathcal{C}$ as above, and assume it is a sheet over $V$. Then we can write $V=\cup_{j} U_{j}$ as a countable union of open sets $U_{j} \in \mathcal{B}$, and it follows that $W$ is the union of the open subsets $N_{j}=p^{-1}\left[U_{j}\right] \cap W$. By definition the sets $N_{j}$ belong to $\mathcal{A}$, so we have shown that $\mathcal{A}$ forms a base for the topology of $E$.
(ii) Follow the hint. By a previously proved exercise in Munkres we know that $E$ is $\mathbf{T}_{3}$, and by the first part of this exercise it is also second countable. Therefore the Urysohn Metrization Theorem implies that $E$ is metrizable. -

## VIII. 5 : Simply connected spaces

## Additional exercises

1. (i) We need to show that $g \cdot x=x$ for some $x$ only if $g=1$. Let $(u, v)$ denote a point of $S^{2} \times S^{3}$, and suppose that $g \cdot(u, v)=(u, v)$; i.e., $g \cdot u=u$ and $g \cdot v=v$. If $g \in C_{n}$ then $g \cdot(u, v)=(u, g \cdot v)$, and the second coordinate is equal to $v$ if and only if $g=1$. On the other hand, if $g \notin C_{n}$ then $g \cdot(u, v)=(-u, v) \neq(u, v)$, so that $g \cdot(u, v)=(u, v)$ implies that $g$ must be equal to 1 .
(ii) The preceding result yields a free action of $D(2 n)$ on the simply connected space $S^{2} \times S^{3}$, and by the results in this section of the notes the fundamental group of the quotient space $X_{n}=$ $S^{2} \times S^{3} / D(2 n)$ has a fundamental group isomorphic to $D(2 n) . ■$
(iii) Let $\Delta: D(2 n) \rightarrow \mathbb{Z}_{2}$ be the homomorphism defined in the exercise, and identify $\mathbb{Z}_{2}$ with $\pm 1$ as usual. Then the coordinate projection $p: S^{2} \times S^{3} \rightarrow S^{2}$ has the property that $p(g \cdot(u, v))=(\Delta(g) \cdot u)$, and this implies that $p$ passes to a map $q$ from $X_{n}$ to $\mathbb{R} \mathbb{P}^{2}$. Let $\gamma$ be a great circle curve in $S^{2}$ which joins a basepoint $z$ to its antipodal point $-z$, let $v_{0} \in S^{3}$, take $\beta(t)=\left(\gamma(t), v_{0}\right) \in S^{2} \times S^{3}$, and let $\rho: S^{2} \times S^{3} \rightarrow X$ be the quotient projection. Then $\rho^{\circ} \gamma$ is a closed durve in $X$, and its image $q^{\circ} \rho^{\circ} \gamma$ generates the fundamental group of $\mathbb{R} \mathbb{P}^{2}$. Therefore the map from $\pi_{1}(X)$ to $\pi_{1}()$ is nontrivial. Further analysis would show that the kernel of this map in fundamental groups is just $C_{n}$, but this was not asked for in the exercise.
2. If the inclusion $S^{1} \subset \mathbb{R}^{n}$ were a retract, then it would induce a monomorphism of fundamental groups. Since $\pi_{1}\left(S^{1}\right) \cong \mathbb{Z}$ and $\pi_{1}\left(\mathbb{R P}^{n}\right)$ is finite for $n \geq 2$, this cannot happen.■
3. (i) Under the given conditions, the result from this section imply that the map $p_{*} ; \pi_{1}(X) \rightarrow$ $\pi_{1}\left(\mathbb{R} \mathbb{P}^{n} \times \mathbb{R} \mathbb{P}^{n}\right) \cong \mathbb{Z}^{2} \times \mathbb{Z}_{2}$ is injective and the number of sheets in the covering is the index of the image of $p_{*}$. If there is only one sheet, then this map must be a homeomorphism (it is $1-1$, onto, continuous and open). Otherwise the number of sheets is the index of a subgroup of a group of order 4, and as such this number must be finite and even. (ii) If $E$ is a connected space covering space of $X$ satisfying the default hypotheses and $\pi_{1}(X)$ is finite of odd order, then $\pi_{1}(E)$ is isomorphic to a subgroup of $\pi_{1}(X)$ as in the first part of this exercise, but now the index of the subgroup
must divide the odd number $\left|\pi_{1}(X)\right|$ and hence the index, which equals the number of sheets in the covering, must be (finite and) odd. In particular, the index cannot be equal to 2 .

## VIII. 6 : Homotopy of paths and line integrals

## Additional exercises

1. Recall the definition of the winding number integral: If $p(z)$ is never zero on a circle $C_{R}$ of radius $R$ about the origin and $\Gamma(p, R)$ be the closed curve given by $p(\exp (R \cdot 2 \pi i t))$ for $0 \leq t \leq 1$, then the winding number integral is equal to

$$
\int_{\Gamma(p, R)} \frac{x d y-y d x}{x^{2}+y^{2}}
$$

and its value is an integral multiple of $2 \pi$. By the results of this section, the integral factor is equal to the degree of the following composite

$$
S^{1} \xrightarrow{R \times} C_{R} \xrightarrow{p} \mathbb{C}-\{0\} \xrightarrow{\mathbf{u}} S^{1}
$$

where $R \times$ denotes multiplication by $R$ and $\mathbf{u}$ sends $z$ to $|z|^{-1} \cdot z$.
The preceding sentence implies that if the winding number is not zero then the displayed map is not homotopic to a constant in $\mathbb{C}-\{0\}$ and hence that $\Gamma(p, R)$ does not extend to a continuous map from $D^{2}$ into $\mathbb{C}-\{0\}$. Now $p(r \cdot \mathbf{v})$ is a continuous extension of $\Gamma(p, R)$ to a map $D^{2} \rightarrow \mathbb{C}$, and by the preceding sentence we know that its image cannot be contained in $\mathbb{C}-\{0\}$. Therefore its image must contain the point 0 ; in other words there must be some $z_{0}$ such that $|z|<R$ and $p\left(z_{0}\right)=0$.
2. The underlying idea is to show that the winding number is defined for $p+q$ and it is equal to the winding number of $p$, which by hypothesis is nonzero.

First of all, the condition $|q|<|p|$ for $|z| \leq R$ implies that $|p+q| \geq|p|-|q|>0$ for $|z|=R$, and therefore the winding number of $p+q$ can be defined. To prove the winding numbers are equal, it is only necessary to show that $\Gamma(p, R)$ and $\Gamma(p+q, R)$ are homotopic as maps into $\mathbb{C}-\{0\}$. One obvious idea is to consider the straight line homotopy $p+t q$ where $0 \leq t \leq 1$ and show that its image lies in $\mathbb{C}=\{0\}$. The verification of this statement is a slight embellishment on what was already shown: $|p+t q| \geq|p|-t|q| \geq|p|-|q|>0$. $\quad$
3. We know that the value of the integral only depends upon the free homotopy class of $\gamma$, and since there are only countably many free homotopy classes in $\left[S^{1}, U\right]$ it follows that there are only countably many possible values for the integral. Furthermore, since the line integral of a concatenated curve is the sum of the line integrals of the two pieces, it follows that the line integral of $f$ defines a homomorphism $S(f)$ from $\pi_{1}(U)$ to the additive complex numbers, with the value of $S(f)$ only depending upon the image of a class in $\pi_{1}(U)$ in $\left[S^{1}, U\right]$.

If the line integral has only finitely many values, then $S(f)$ has a finite image, and since $S(f)$ is a homomorphism it follows that every element in the image has finite order. However, the only elment of finite additive order in $\mathbb{C}$ is 0 , and therefore it follows that the image of $S(f)$ must be $\{0\}$ and there is only one possible value for the line integral.

# SOLUTIONS TO EXERCISES FOR 

## MATHEMATICS 205A — Part 9

Fall 2014

## IX. Computing fundamental groups

## IX. 1 : Free groups

## Additional exercises

1. For the sake of definiteness, assume that $x$ and $y$ are free generators for $F$. If $H$ has index 2 in $F$, then $H$ is a normal subgroup and $F / H \cong \mathbb{Z}_{2}$. Therefore every such subgroup is the kernel of a surjection from $F$ to $\mathbb{Z}_{2}$. CLAIM 1: This is a $1-1$ correspondence.

We can check this directly. There are three nontrivial homomorphisms from $F$ into $\mathbb{Z}_{2}$, and they are completely determined by the values of a homomorphism on the generators. Consider the effect of each example on the set $S=\{x, x y, y\}$. For the homomorphism sending $(x, y)$ to $(1,0)$ the intersection of $S$ with the kernel is $\{x\}$, for the homomorphism sending $(x, y)$ to $(0,1)$ the the intersection of $S$ with the kernel is $\{y\}$, and for the homomorphism sending $(x, y)$ to $(1,1)$ the the intersection of $S$ with the kernel is empty.

Therefore there are exactly three subgroups of index 2 in $F$, one of which is normally generated by $x$ and $y^{2}$, another of which is normally generated by $y$ and $x^{2}$, and the last of which is normally generated by $x^{-1} y$ and $x^{2}$ (or $y^{-1} x$ and $x^{2}$, or $x y$ and $x^{2}$, etc.).
2. We shall verify that $F / H$ satisfies the appropriate Universal Mapping Property with free generators corresponding to the elements of $X-Y$. Let $G$ be a group, let $j: X \rightarrow F$ identify $X$ with a subset of $F$, and let $h: X-Y \rightarrow G$ be a map of sets. Extend $h$ to a mapping $h_{0}: X \rightarrow Y$ by setting $h(y)=1$ if $y \in Y$. Since $F$ is free on $X$, there is a homomorphism $\eta_{0}: F \rightarrow G$ such that $\eta_{0}{ }^{\circ} j(x)=h_{0}(x)$ for all $x \in X$. Since $y \in Y$ implies $h_{0}(y)=1$, the kernel of $\eta_{0}$ contains the normal subgroup $H$, and if $\pi: F \rightarrow F / H$ is the quotient map then there is a unique homomorphism $\eta: F / H \rightarrow G$ such that $\eta^{\circ} \pi=\eta_{0}$.

Before proving that $F / H$ has the Universal Mapping Property for $X-Y$, we need to check that the map $\pi^{\circ} j: X \rightarrow F / H$ is $1-1$. Perhaps the easiest way to do this is to let $A$ be the free group on $X-Y$ and take the homomorphism $F \rightarrow A$ which sends $X-Y$ to these free generators and sends $Y$ to $\{1\}$. Since the map $X-Y \rightarrow F \rightarrow F / H \rightarrow A$ is $1-1$, it follows that $X-Y \rightarrow F / H$ is also $1-1$, confirming what we expected.

To complete the proof of the Universal Mapping Property, identify $X-Y$ with a subset of $F / H$ via the map sending $x$ to $j^{\prime}(x)=\pi^{\circ} j(x)$, so that $\eta^{\circ} j^{\prime}(x)=\eta_{0}{ }^{\circ} j(x)=h_{0}(x)$ for all $x \in X-Y$. Therefore $F / H$ has the universal mapping property for $X-Y$.■
3. (i) Let $F_{n}^{\prime} \subset F_{n}$ be the commutator subgroup; then the quotient is isomorphic to the free abelian group $A_{n} \cong \mathbb{Z}^{n}$ on $n$ generators. If $T: F_{n} \rightarrow F_{n}$ is an automorphism and $h: F_{n} \rightarrow A_{n}$ is the quotient projection as in the statement of the exercise, then the kernel of $h^{\circ} T$ must contain the commutator subgroup $F_{n}^{\prime}=\left[F_{n}, F_{n}\right]$ because the image of the homomorphism is abelian. Therefore there is a unique homomorphism $\theta(T): A_{n} \rightarrow A_{n}$ such that $h^{\circ} T=\theta(T)^{\circ} h$.

Suppose now that we are given two automorphisms $T_{1}$ and $T_{2}$. By the uniqueness statement proved in the preceding paragraph, it is enough to show that $h{ }^{\circ} T_{1}{ }^{\circ} T_{2}=\theta\left(T_{1}\right)^{\circ} \theta\left(T_{2}\right)^{\circ} h$. This follows because $h^{\circ} T_{1}{ }^{\circ} T_{2}=\alpha\left(T_{1}\right)^{\circ} h^{\circ} T_{2}=\alpha\left(T_{1}\right)^{\circ} \alpha\left(T_{2}\right)^{\circ} h . ■$
(ii) The statement in the hint is true because $h{ }^{\circ} \mathrm{id}_{F_{n}}=h=\operatorname{id}_{A_{n}}{ }^{\circ} h$. Therefore if $S=T^{-1}$ we have

$$
\operatorname{id}_{A_{n}}=\theta\left(\operatorname{id}_{F_{n}}\right)=\theta\left(S^{\circ} T\right)=\theta(S)^{\circ} \theta(T)
$$

and by interchanging the roles of $S$ and $T$ we also have $\operatorname{id}_{A_{n}}=\theta(T)^{\circ} \theta(S)$. Therefore $\theta(T)$ is an automorphism, and predictably its inverse is $\theta(S)$.-
(iii) Again for definiteness, let $x$ and $y$ denote the generators of $F_{2}$ which project down to the elements $(1,0)$ and $(0,1)$ in $A_{2} \cong \mathbb{Z}^{2}$. Following the hint, we shall find automorphisms of $F_{2}$ which induce $\theta$ on $A_{2}$ for choices of $\theta$ corresponding to each one of the three given generators. To avoid space-consuming displays of $2 \times 2$ matrices we shall refer to the displayed matrices, in order from left to right, as the diagonal generator, the transposition generator, and the shear generator. For the diagonal generator, take the self-homomorphism $T$ of $F_{2}$ which sends $x$ to $x^{-1}$ and $y$ to itself; such a homomorphism exists because $F_{2}$ is free, and it is an automorphism because $T{ }^{\circ} T=\mathrm{id}$ (it is only necessary to check this on the free generators), so that $T$ is equal to its own inverse. For the transposition generator, take the self-homomorphism $T$ which interchanges $x$ and $y$; once again $T{ }^{\circ} T=\mathrm{id}$ implies that $T$ is its own inverse. Finally, for the shear generator, take the homomorphism $T$ sending $x$ to itself and $y$ to $x y$. For this example we claim that the inverse is the homomorphism sending $x$ to itself and $y$ to $x^{-1} y$. Once again, to prove that $S^{\circ} T$ and $T^{\circ} S$ are the identities, it is enough to do so on the standard set of free generators. Clearly we have $S{ }^{\circ} T(x)=x=T{ }^{\circ} S(x)$ since $S(x)=T(x)=x$, and we also have

$$
\begin{gathered}
S^{\circ} T(y)=S(x y)=S(x) S(y)=x \cdot\left(x^{-1} y\right)=y \\
T{ }^{\circ} S(y)=T\left(x^{-1} y\right)=T\left(x^{-1}\right) T(y)=x^{-1} \cdot(x y)=y
\end{gathered}
$$

and therefore we know that $S=T^{-1}$.
4. (i) Take the map from $F_{n-1}$ to $G$ with sends the free generator $x_{i} \in F_{n-1}$ to $g_{i} \in G$. The extension of this map to a homomorphism is onto, and therefore $G$ is isomorphic to a quotient of $F_{n-1}$.■
(ii) In any group $G$, if $g=g^{1}$ then either $g=1$ or else $g^{2}=1$. The latter cannot happen in an odd order group unless $G=1$, so this means that the nontrivial elements of $G$ can be decomposed into $\frac{1}{2}(|G|-1)$ pairs of the form $\left\{g_{i}, h_{i}=g_{i}^{-1}\right\}$, where $1 \leq i \leq k$ and $|G|=2 k+1$.

In this case take the map from $F_{k}$ to $G$ with sends the free generator $x_{i} \in F_{k}$ to $g_{i} \in G$. The extension of this map to a homomorphism is onto, and therefore $G$ is isomorphic to a quotient of $F_{k}$.

## IX.2 : Sums and pushouts of groups

## Problems from Munkres, § 68, p. 421

2. (a) Let $1 \neq x_{i} \in G_{i}$ for $i=1,2$; then $x_{1} x_{2} x_{1}^{-1} x_{2}^{-1}$ is a reduced word, and by Step 4 in the proof of Munkres, Theorem 68.2 we know that this element is not the identity in $G_{1} * G_{2}$. But this means that $x_{1} x_{2} \neq x_{2} x_{1}$ whenever $x_{1}$ and $x_{2}$ are nontrivial elements of $G_{1}$ and $G_{2}$ respectively.
(b) If $x$ is a reduced word of even length, write it in the form $a_{1} b_{1} \cdots a_{k} b_{k}$ where each $a_{j}$ lies in one of the groups $G_{i}$ and each $b_{j}$ lies in the other group. It follows that for each $n>0$ that $x^{n}$ corresponds to the reduced word $a_{1} b_{1} \cdots a_{n k} b_{n k}$ where the sequences satisfy the periodicity conditions $a_{j}=a_{j+k}$ and $b_{j}=b_{j+k}$ for $j \leq n k-k$. Since this is also a nontrivial word, it follows from the same reasoning as before that $x^{n} \neq 1$ in the free product. Therefore $x$ has infinite order.

Suppose now that we have a reduced word $x$ of odd length $\geq 3$ (this was not part of the problem as stated in Munkres, but clearly it is indispensable because a reduced word of length 1 cannot be conjugate to anything shorter). In analogy with the preceding paragraph, write $x$ in the form $b_{0} a_{1} b_{1} \cdots a_{k} b_{k}$ where $a_{j}$ and $b_{j}$ are as before. We can easily find a shorter word which is conjugate to the given one because $b_{0}^{-1} x b_{0}$ is equal to $a_{1} b_{1} \cdots a_{k}\left(b_{k} b_{0}\right)$. There are now two possibilities. If $b_{k} b_{0} \neq 1$, then we have shown that $x$ is conjugate to an element corresponding to a reduced word of even length $2 k$. If $b_{k} b_{0}=1$, then we have shown that $x$ is conjugate to an element corresponding to a reduced word of odd length $2 k-1$.
(c) By part (b) and induction, every nontrivial word is either conjugate to a word whose length is either an even number or 1 (look at the shortest word in the conjugacy class, and note that a nontrivial word cannot be conjugate to the empty word). If the word $x$ is conjugate to a word $y$ of even length, then the orders of $x$ and $y$ are equal, and since $y$ has infinite order it follows that the same holds for $x$. On the other hand, if $x$ is conjugate to a word $y$ of length 1 , we know that $y$ must correspond to a nontrivial element of $G_{1}$ or $G_{2}$, and if $x$ has finite order then $y$ must also have the same finite order..
3. The easiest way to solve this exercise might be to look at the images of everything in the direct product $G_{1} \times G_{2}$. The Universal Mapping Property for free products guarantees the existence of a homomorphism $\theta: G_{1} * G_{2} \rightarrow G_{1} \times G_{2}$ such that $\theta \circ i_{1}(a)=(a, 1)$ and $\theta \circ i_{2}(b)=(1, b)$, where $i_{t}$ denotes the standard injection of $G_{t}$ into $G_{1} \cap G_{2}$. The problem does not require a proof that $c G_{1} c^{-1}$ is a subgroup, but this follows quickly from the fact that the latter is the image of $G_{1}$ under the conjugation automorphism of $G_{1} * G_{2}$ sending $x$ to $c x c^{-1}$.

Suppose that $a \in G_{1}$ is such that $\mathrm{cac}^{-1} \in G_{2}$ It then follows that $\theta(a) \in G_{1} \times\{1\}$ and $\theta(c) \theta(a) \theta(c)^{-1} \in\{1\} \times G_{2}$. CLAIM: $\theta(c) \theta(a) \theta(c)^{-1} \in G_{1} \times\{1\}$, and this element corresponds to a conjugate of $a$ in $G_{1}$. - If this is true, then $\theta(c) \theta(a) \theta(c)^{-1}$ belongs to $\left(G_{1} \times\{1\}\right) \cap\left(\{1\} \times G_{2}\right)$, which is the trivial group, and furthermore $a$ is conjugate to this element in $G_{1}$. In particular, $a$ is conjugate in $G_{1}$ to the trivial element, and this implies that $a=1$. To summarize, the claim implies that if $\mathrm{cac}^{-1} \in G_{2}$ then $a=1$ and therefore also $\mathrm{cac}^{-1}=1$.

To prove the assertions regarding $\theta(c) \theta(a) \theta(c)^{-1}$, write $c=u_{1} v_{1} \cdots u_{k} v_{k}$ where $u_{j} \in G_{1} \times\{1\}$ and $v_{j} \in\{1\} \times G_{2}$. If $c \neq 1$ we can do this using either a reduced word of even length or taking a reduced word of odd length and setting $u_{1}=1$ (if the word starts and ends with something from $G_{2}$ ) or $v_{k}=1$ (if the word starts and ends with something from $G_{1}$ ). Since the images of $G_{1}$ and $G_{2}$ commute with each other, an inductive argument shows that

$$
\begin{gathered}
\theta(c) \theta(a) \theta(c)^{-1}=\theta\left(u_{1} v_{1} \cdots u_{k} v_{k}\right) \theta(a) \theta\left(u_{1} v_{1} \cdots u_{k} v_{k}\right)^{-1}= \\
\theta\left(u_{1} v_{1} \cdots u_{k-1} v_{k-1}\right) \theta\left(u_{k} a u_{k}^{-1}\right) \theta\left(u_{1} v_{1} \cdots u_{k-1} v_{k-1}\right)^{-1}=\cdots=\theta\left(u_{1} \cdots u_{k} a u_{k}^{-1} \cdots u_{k}^{-1}\right)
\end{gathered}
$$

where the expression in the last term is an element of $G_{1}$ which is conjugate (in $G_{1}$ ) to $a$. This is the claim in the preceding paragraph.

1. To simplify the notation, if $H$ is a group, then $\mathbf{A b}(H)$ will denote the quotient $H /[H, H]$, where $[H, H]$ is the commutator subgroup (which is normal in $H$ ). We shall also denote $G_{1} * G_{2}$ by $G$ as in the statement of the exercise.

Starting with the abelinization homomorphisms $\alpha_{i}: G_{i} \rightarrow \mathbf{A b}\left(G_{i}\right)$, we can define a homomorphism $\theta: G \rightarrow \mathbf{A b}\left(G_{1}\right) \oplus \mathbf{A b}\left(G_{2}\right)$ whose restriction to $G_{1} \subset G$ is the map sending $a$ to ( $a, 0$ ) and whose restriction to $G_{2} \subset G$ is the map sending $b$ to $(0, b)$. By construction $\theta$ is onto, and since the codomain is an abelian group the kernel of $\theta$ must contain the commutator subgroup. Therefore $\theta$ factors as a composite $G \rightarrow \mathbf{A b}(G) \rightarrow \mathbf{A b}\left(G_{1}\right) \oplus \mathbf{A b}\left(G_{2}\right)$, where the first arrow is abelianization and the second will be denoted by $\varphi$.

For the same general reasons, the composites $G_{i} \rightarrow G=G_{1} * G_{2} \rightarrow \mathbf{A b}(G)$ have factorizations $G_{i} \rightarrow \mathbf{A b}\left(G_{i}\right) \rightarrow \mathbf{A b}(G)$, and the induced maps of abelianizations will be denoted by $J_{i}$. Therefore we can define a homomorphism

$$
\psi: \mathbf{A b}\left(G_{1}\right) \oplus \mathbf{A b}\left(G_{2}\right) \longrightarrow \mathbf{A b}(G)
$$

such that $\psi(u, v)=J_{1}(u)+J_{2}(v)$. By construction the composites

$$
G_{i} \rightarrow \mathbf{A b}\left(G_{i}\right) \rightarrow \mathbf{A b}(G) \rightarrow \mathbf{A b}\left(G_{i}\right)=G_{i} \rightarrow G \rightarrow G_{i} \rightarrow \mathbf{A b}\left(G_{i}\right)
$$

are the abelianization mappings, and therefore the composites $\mathbf{A b}\left(G_{i}\right) \rightarrow \mathbf{A b}(G) \rightarrow \mathbf{A b}\left(G_{i}\right)$ are identity mappings. Similarly, if $i \neq j$ then the triviality of the composites $G_{i} \rightarrow G \rightarrow G_{j}$ implies that the abelianized mappings $\mathbf{A b}\left(G_{i}\right) \rightarrow \mathbf{A b}(G) \rightarrow \mathbf{A b}\left(G_{j}\right)$ are zero homomorphisms. If we combine these with the definitions of $\varphi$ and $\psi$, we see that $\varphi^{\circ} \psi$ is the identity on $\mathbf{A b}\left(G_{1}\right) \oplus \mathbf{A b}\left(G_{2}\right)$. We claim these maps are isomorphisms, and to prove this it will suffice to show that $\psi$ is onto. However, this follows quickly because we know that $G$ is generated by the images of $G_{1}$ and $G_{2}$, which implies that $\mathbf{A b}(G)$ is generated by the images of $\mathbf{A b}\left(G_{1}\right)$ and $\mathbf{A b}\left(G_{2}\right) .$.
3. For the sake of definiteness, we shall assume that $m \geq n$ (it will be clear that the case $m \leq n$ can be handled similarly).
(a) If $G_{1}$ and $G_{2}$ are abelian groups, then Exercise 1 implies that $\mathbf{A b}\left(G_{1} * G_{2}\right) \cong G_{1} \oplus G_{2}$. If we specialize to the case where $G_{1}=\mathbb{Z}_{m}$ and $G_{2}=\mathbb{Z}_{n}$, this implies that $\mathbf{A b}\left(G_{1} * G_{2}\right)$ is a finite group of order $m n$. -
(b) Follow the hint. By Exercise 68.2 in Munkres, the only elements of finite order in $G_{1} * G_{2}$ are those which are conjugate to elements in either $G_{1}$ or $G_{2}$, and thus if $g \in \mathbb{Z}_{m} * \mathbb{Z}_{n}$ has finite order, this order must divide either $m$ or $n$. Since we are assuming that $m \geq n$, the largest possible order is $m$, and in fact this order is realized by the generator of $\mathbb{Z}_{m}$..
(c) If $G=\mathbb{Z}_{m} * \mathbb{Z}_{n}$, then $|\mathbf{A b}(G)|=m n$ implies that $m n$ is uniquely determined by $G$, and by (b) we know that $m$ is uniquely determined by $G$. Therefore $n=(m n) / m$ is also uniquely determined by $G$.
4. The goal of the problem is to find finite abelian groups $G_{1}, G_{2}, H_{1}, H_{2}$ such that $\left|G_{1}\right| \neq\left|H_{1}\right|$ and $\left|G_{2}\right| \neq\left|H_{2}\right|$ such that $G_{1} \times G_{2} \cong H_{1} \times H_{2}$, and the hint is to use the abstract version of the Chinese Remainder Theorem: $\mathbb{Z}_{a} \times \mathbb{Z}_{b} \cong \mathbb{Z}_{a b}$ if $a$ and $b$ are relatively prime. - The latter can be found in nearly every upper level undergraduate textbook on abstract algebra or elementary number theory, so we shall not prove it here.

Since $2,3,5$ are pairwise relatively prime the Chinese Remainder Theorem and $(2 \cdot 3) \cdot 5=30=$ $2 \cdot(3 \cdot 5)$ imply that

$$
\mathbb{Z}_{30} \cong \mathbb{Z}_{6} \times \mathbb{Z}_{5}, \quad \mathbb{Z}_{30} \cong \mathbb{Z}_{2} \times \mathbb{Z}_{15}
$$

so we get the desired examples if we take $G_{1}=\mathbb{Z}_{6}, G_{2}=\mathbb{Z}_{5}, H_{1}=\mathbb{Z}_{2}$, and $H_{2}=\mathbb{Z}_{15}$.

## Additional exercises

1. We shall repeatedly use the fact that a free product of two groups $*_{i} L_{i}$ is uniquely characterized up to isomorphism by the fact that homomorphisms from $*_{i} L_{i}$ to another group $M$ correspond bijectively to homomorphisms from the summands $L_{i}$ into $M$, and the correspondence is given by restricting to the subgroups $L_{i}$.

For $(G * H) * K$, the preceding paragraph means that homomorphisms from this group to some other group $M$ are in 1-1 correspondence with homomorphisms from $G * H$ and $K$ into $M$. However, homomorphisms from $G * H$ into $M$ in 1-1 correspondence with homomorphisms from $G$ into $M$ and from $H$ into $M$. Combining these, we see that homomorphisms from $(G * H) * K$ into $M$ are in 1-1 correspondence with homomorphisms $G \rightarrow M, H \rightarrow M$ and $K \rightarrow M$. Since this is the defining condition for a free product of the three groups $G, H$ and $K$ it follows that $(G * H) * K$ is in fact a free product of these three groups. Similarly, homomorphisms from $G *(H * K)$ into some other group $M$ are in 1-1 correspondence with homomorphisms from $G$ and $H * K$ into $M$, and since homomorphisms from $H * K$ into $M$ in 1-1 correspondence with homomorphisms from $H$ into $M$ and from $K$ into $M$, we see that homomorphisms from $G *(H * K)$ into $M$ are in 1-1 correspondence with homomorphisms $G \rightarrow M, H \rightarrow M$ and $K \rightarrow M$; as before, this means that $G *(H * K)$ is in fact a free product of $G, H$ and $K$.

Finally, homomorphisms from both $G * H$ and $H * G$ into an arbitrary group $H$ correspond bijectively to homomorphisms $G \rightarrow M$ and $H \rightarrow M$, and this yields an isomorphism between $G * H$ and $H * G$.■
2. (i) Follow the hint and note that $K * K \cong K$ because $K * K$ is a free group on $\aleph_{0}+\aleph_{0}=\aleph_{0}$ generators if $K$ is a free group on $\aleph_{0}$ generators. If $H_{1}$ is finite but nontrivial and $H_{2}=H_{1} * K$, then $H_{1}$ is finite but $H_{2}$ is infinite. On the other hand, we have

$$
H_{2} * K \cong\left(H_{1} * K\right) * K \cong H_{1} *(K * K) \cong H_{1} * K
$$

which is what we wanted to prove.-
(ii) The underlying ideas are the same, but here we have $K \times K=K \oplus K$ is isomorphic to $K$ because $K \oplus K$ is a free abelian group on $\aleph_{0}$ generators if $K$ is. If $H_{1}$ is finite but nontrivial and $H_{2}=H_{1} * \times K$, then $H_{1}$ is finite but $H_{2}$ is infinite. On the other hand, we have

$$
H_{2} \times K \cong\left(H_{1} \times K\right) \times K \cong H_{1} \times(K \times K) \cong H_{1} \times K
$$

which is what we wanted to prove..
(iii) Once again, this is the same basic idea, but now we are working with topological spaces. An explicit isometry from $Y \times Y$ to $Y$ is given as follows: Let $\left\{\mathbf{e}_{j}\right\}$ denote the set of standard unit vectors in $Y$, and take the linear isomorphism from $Y \times Y$ to $Y$ which sends $\left(\mathbf{e}_{j}, \mathbf{0}\right)$ to $\mathbf{e}_{2 j-1}$ and $\left(\mathbf{0}, \mathbf{e}_{j}\right)$ to $\mathbf{e}_{2 j-1}$. This is clealy an invertible linear transformation, and if one imposes the metrics associated to the usual dot products (so that the unit vectors are orthonormal and $Y \times\{\mathbf{0}\}$ is orthogonal to $\{0\} \times Y$ ), then this linear isomorphism is an isometry of inner product spaces, which implies among other things that $Y \times Y$ is homeomorphic to $Y$.

Let $X_{1}$ be a compact metric space, and let $X_{2}=X_{1} \times Y$. Then $X_{1}$ is not homeomorphic to $X_{2}$ but $X_{1} \times Y$ is homeomorphic to $X_{2} \times Y$ because we have $X_{2} \times Y=X_{1} \times Y \times Y \cong X_{1} \times Y$.■
3. As before the proof that $h \times h$ is the identity reduces to showing that $h \times h$ maps the free generators $x$ and $y$ to them selves. Since $h(x)=y$ and $h(y)=x$, this follows immediately.

Suppose now that $h(w)=w$ for some nontrivial reduced word $w$ in $x$ and $y$. If $w$ begins with a power of $x$ then $h(w)$ begins with a power of $y$ and vice versa. By the unique factorization property for nontrivial reduced words, it follows that $h(w)$ cannot be equal to $w$.

Note. In contrast, the induced automorphism $\theta(h)$ of $\mathbb{Z}^{2}$ sends $(1,1)$ to itself.

## IX. 3 : The Seifert - van Kampen Theorem

$$
\text { Problems from Munkres, § 70, p. } 433
$$

1. By the Seifert-van Kampen Theorem it will suffice to show that

is a pushout diagram if $i_{1 *}$ and $i_{2 *}$ are trivial homomorphisms, where the maps from $\pi_{1}(U, p)$ and $\pi_{1}(V, p)$ to the respective quotients $\pi_{1}(U, p) / N_{1}$ and $\pi_{1}(V, p) / N_{2}$ followed by the usual injections $J_{1}$ and $J_{2}$ into the free product. Denote the quotient projections $\pi_{1}(U, p) \rightarrow \pi_{1}(U, p) / N_{1}$ and $\pi_{1}(V, p) \rightarrow \pi_{1}(V, p) / N_{2}$ by $q_{1}$ and $q_{2}$ respectively.

Suppose that we are given homomorphisms $A: \pi_{1}(U, p) \rightarrow G$ and $B: \pi_{1}(V, p) \rightarrow G$ such that $A{ }^{\circ} i_{1 *}=B{ }^{\circ} i_{2 *}$. Since $i_{1 *}$ and $i_{2 *}$ are trivial it follows that we have factorizations through the respective quotients; i.e., we have $A=A^{\prime}{ }^{\circ} q_{1}$ and $B=B^{\prime}{ }^{\circ} q_{2}$ for uniquely determined homomorphisms $A^{\prime}$ and $B^{\prime}$. By the Universal Mapping Property for free products, there is a unique homomorphism $C$ from the free product into $G$ whose restrictions to ${ }^{\circ} J_{1}$ and $C{ }^{\circ} J_{2}$ to $\pi_{1}(U, p) / N_{1}$ and $\pi_{1}(V, p) / N_{2}$ are equal to $A^{\prime}$ and $B^{\prime}$ respectively, and therefore we also have $C^{\circ}\left(J_{1}{ }^{\circ} q_{1}\right)=A^{\prime}{ }^{\circ} q_{1}=A$ and $C^{\circ}\left(J_{2}{ }^{\circ} q_{2}\right)=B^{\prime}{ }^{\circ} q_{2}=B$. To complete the proof, we need to show that if $D: \pi_{1}(U, p) / N_{1} * \pi_{1}(V, p) / N_{2}$ is an arbitrary homomorphism such that $D^{\circ}\left(J_{1}{ }^{\circ} q_{1}\right)=A$ and $D{ }^{\circ}\left(J_{2}{ }^{\circ} q_{2}\right) B$, then $D=C$. If $D$ satisfies these conditions then we have $D{ }^{\circ} J_{1}{ }^{\circ} q_{1}=C{ }^{\circ} J_{1}{ }^{\circ} q_{1}$ and $D{ }^{\circ} J_{2}{ }^{\circ} q_{2}=C{ }^{\circ} J_{2}{ }^{\circ} q_{2}$; since $q_{1}$ and $q_{2}$ are onto, the given equations imply that $D{ }^{\circ} J_{1}=C{ }^{\circ} J_{1}$ and $D^{\circ} J_{2}=C{ }^{\circ} J_{2}$. We can now use the uniqueness condition in the Universal Mapping Property for free products to conclude that $D=C$. This completes the proof that the diagram at the beginning of this solution is a pushout.
3. (a) If $G_{1}$ has a finite generator set $X_{1}$ with a finite relation set $R_{1}$ and $G_{2}$ has a finite generator set $X_{2}$ with a finite relation set $R_{2}$, then $G_{1} * G_{2}$ has a finite generator set $X_{1} \amalg X_{2}$ with a finite relation set $R_{1} \amalg R_{2}$, $\square$
(b) Follow the hint, but work more generally with a pushout

where $K$ is finitely generated and $H_{1}$ and $H_{2}$ are finitely presented.
The construction of pushouts in Section IX. 2 shows that $G$ is isomorphic to the quotient of $\Gamma=G_{1} * G_{2}$ by the normal subgroup $N$ which is generated by all elements of the form $i_{1}^{-1}(k) i_{2}(k)$, where $k$ runs through all the elements of $G$. CLAIM: If $k_{1}, \cdots, k_{r}$ generate $K$, then $N$ is also the smallest normal subgroup containing the finite set $S=\left\{i_{1}^{-1}\left(k_{t}\right) i_{2}\left(k_{t}\right) \mid 1 \leq t \leq r\right\}$.

If the claim is true, we can complete the solution as follows: By Exercise 1 we know that $G_{1} * G_{2}$ is finitely presented, and by the claim we know that $N$ is finitely normally generated, so if $G_{1} * G_{2}$ is presented with finite generating set $X$ and finite relation set $R$, then we obtain the quotient by expanding $R$ to a set which also includes a finite family of words in the generators which map to the elements in the set $S$.

We now prove the claim. Let $N_{0}$ be the subgroup normally generated by $S$, so that $N_{0} \subset N$. To prove the reverse inclusion, consider the map of quotient groups $\pi: \Gamma / N_{0} \rightarrow \Gamma / N$ which sends each coset of $N_{0}$ to the coset $N$ which contains it, and let $\rho: G \rightarrow G / N_{0}$ be the usual quotient space projection. By definition, $N_{0}$ is normally generated by the elements $i_{1}^{-1}\left(k_{t}\right) i_{2}\left(k_{t}\right)$, and therefore $\rho^{\circ} i_{1}\left(k_{t}\right)=\rho^{\circ} i_{2}\left(k_{t}\right)$ for all $t$. Since $\rho, i_{1}$ and $i_{2}$ are homomorphisms and the elements $k_{t}$ generate $K$, it follows that $\rho^{\circ} i_{1}(k)=\rho^{\circ} i_{2}(k)$ for all $k \in K$. But this means that the normal subgroup $N_{0}$ contains all elements of the form $i_{1}^{-1}(k) i_{2}(k)$ where $k \in K$, and since these elements normally generate $N$ it follows that all of $N_{0}$ is contained in $N$..

## Additional exercises

1. (i) For this part of the exercise, in the pushout diagram

we know that $\pi_{1}(U, p)$ is trivial and $\pi_{1}(V, p)$ is abelian. It will suffice to prove that the map $\pi_{1}(V, p) \rightarrow \pi_{1}(X, p)$ is onto. We know that $\pi_{1}(X, p)$ is generated by the images of $\pi_{1}(U, p)$ and $\pi_{1}(V, p)$ and since the image of the first group must be trivial it follows that $\pi_{1}(V, p)$ generates $\pi_{1}(X, p)$, which means that $\pi_{1}(V, p) \rightarrow \pi_{1}(X, p)$ is onto.
(ii) Let $X$ be the Figure Eight Space which is a union of two closed subspaces $C_{1} \cup C_{2}$ such that each is homeomorphic to $S^{1}$ and $C_{1} \cap C_{2}$ consists only of the basepoint $p$. Choose points $q_{i} \in C_{i}-\{p\}$, and let $U_{1}$ and $U_{2}$ be $X-\left\{q_{2}\right\}$ and $X-\left\{q_{1}\right\}$ respectively (note the switch in subscripts - this is not a misprint). Then $C_{i}$ is a strong deformation retract of $U_{i}$ and $U_{1} \cap U_{2}$ is contractible, so that the pushout diagram associated to $\pi_{1}\left(X=U_{1} \cup U_{2}\right.$ is given as follows:


In this example the fundamental groups of $U$ and $V$ are abelian but the fundamental group of $X$ is not.
2. (i) Once again we know that $\pi_{1}(X)$ is generated by the images of $\pi_{1}(U)$ and $\pi_{1}(V)$. Since $\pi_{1}(U \cap V)$ maps onto both of the latter groups, it follows that all the generators for $\pi_{1}(X)$ actually lift back to $\pi_{1}(U \cap V)$..
(ii) As in $(i)$ if $A$ and $B$ denote generating sets for $\pi_{1}(U)$ and $\pi_{1}(V)$ respectively and $A^{\prime}$ and $B^{\prime}$ denote their images in $\pi_{1}(X)$, then $A^{\prime} \cup B^{\prime}$ generates $\pi_{1}(X)$. But if $A$ and $B$ are finite, then so is $A^{\prime} \cup B^{\prime}$.
3. We begin with a general statement. Suppose that we have a group $G$ presented as a quotient $F / N$ where $F$ is freely generated by $X$ and $N$ is normally generated by relations $R \subset F$. Then $\mathbf{A} \mathbf{b}(G)$ is isomorphic to $F / N[F, F]$, which is isomorphic to

$$
(F /[F, F]) /(N[F, F] /[F, F])
$$

in which $N[F, F] /[F, F]$ is the image of $N \subset F \rightarrow F /[F, F]$.
For the example in this exercise, the preceding observation shows that the abelianization $\mathbf{A b}(G)$ is the quotient of $\mathbb{Z}^{2}$ modulo the subgroup generated by the single abelianized relation $(3,-2)$ because the abelianizations of the other two relations are trivial. One easy way of seeing that the quotient is infinite cyclic is to observe that the homomorphism $\mathbb{Z}^{2} \rightarrow \mathbb{Z}$ sending $(x, y)$ to $2 x+3 y$ is onto and its kernel is the cyclic subgroup generated by $(3,-2)$.
(ii) Let $\rho: G \rightarrow G / N$ be the quotient group projection. Since $x y^{-1} \in N$ it follows that $\rho(x)=\rho(y)$. By definition we know that $x^{3}=y^{2}$, so that $\rho(x)^{3}=\rho(y)^{2}$. If we combine the preceding two sentences we find that $\rho(x)^{3}=\rho(x)^{2}$, which means that $\rho(x)=1$ and hence also that $\rho(y)=\rho(x)=1$; i.e., we have $x, y \in N$. Since $x$ and $y$ generate $G$, this means that $N=G$.■
4. By the Seifert-van Kampen Theorem, it will suffice to prove the following algebraic result about pushout diagrams of groups: If we are given an onto homomorphism $i_{1}: K \rightarrow H_{1}$ and an isomorphism $i_{2}: K \rightarrow H_{2}$, then the following square is a pushout diagram:


This square commutes because both composites from $K$ to $H_{1}$ are equal to $i_{1}$.
As usual, we shall prove the given square is a pushout by verifying that it has the Universal Mapping Property. So let $f_{1}: H_{1} \rightarrow M$ and $f_{2}: H_{2} \rightarrow M$ satisfy $f_{1}{ }^{\circ} i_{1}=f_{2}{ }^{\circ} i_{2}$. We need to find a unique map $h: H_{1} \rightarrow M$ such that $h^{\circ} j_{i}=f_{i}$, where $j_{1}$ is the identity and $j_{2}=i_{1}{ }^{\circ} i_{2}^{-1}$. If we take $h=f_{1}$, then $h^{\circ} j_{1}=h^{\circ} \mathrm{id}=f_{1}$ and $h^{\circ} j_{2}=h^{\circ} i_{1}{ }^{\circ} i_{2}^{-1}=f_{1}{ }^{\circ} i_{2}^{-1}=f_{2}{ }^{\circ} i_{2}{ }^{\circ} i_{2}^{-1}=f_{2}$, so there is a map from $H_{1}$ to $M$ with the right properties. To show that a map with the right properties is unique, note that if $k \circ j_{i}=f_{i}$ for $i=1,2$ then $k=k \circ \mathrm{id}=k \circ j_{1}=f_{1}$, so that $k=h$.
5. Consider the associated pushout diagram:


Since $p_{1}$ and $p_{2}$ are onto, it follows that the composite $\mathbb{Z} \times \mathbb{Z} \rightarrow A$ is also onto (see Exercise 2); note that $A$ is abelian because it is a homomorphic image of $\mathbb{Z} \times \mathbb{Z}$. Since $(1,0)$ and $(0,1)$ are in the
kernels of $p_{2}$ and $p_{1}$ respectively, it follows that both these elements map to zero in $A$, and since the two elements in question generate $\mathbb{Z} \times \mathbb{Z}$, it follows that everything in $\mathbb{Z} \times \mathbb{Z}$ maps to zero in $A$. If we combine this with the conclusion of the previous paragraph, we see that $A$ must be the trivial group.■
6. Follow the hint; let $U=M-Y$ and $V=M-X$. Then $U$ is homeomorphic to $X \amalg[0,1)$ with $x \in X$ identified to 0 , and $V$ is homeomorphic to $(0,1] \amalg Y$ with 1 identified to $y \in Y$. Both $U$ and $V$ are open in $M$, and their intersection is homeomorphic to the open interval $(0,1)$. Furthermore, $X$ and $Y$ are strong deformation retracts of $U$ and $V$ respectively. Therefore the Seifert-van Kampen Theorem implies that the fundamental group of $M$ is the free product of the fundamental groups of $X$ and $Y$ (we have not been careful about the basepoints because the isomorphism type of the fundamental groups of the spaces in this exercise are isomorphic for all choices of basepoints).■

## IX. 4 : Examples and computations

## Additional exercises

1. (i) One can also model $X$ topologically as the subspace $C \subset \mathbb{R}^{3}$ given by $S^{2} \cup\{(0.0)\} \times[-1,1]$. We shall prove that this space is homeomorphic to the subspace of $\mathbb{R}^{4}$ described in the exercise as follows: Take the identity map on $S^{2}$, and map a point of the form $(0,0, t)$, where $-1 \leq t \leq 1$, to the point $\left(0,0, t, \sqrt{1-t^{2}}\right)$. One can check directly that this map is continuous and $1-1$ onto, so it is a homeomorphism because $X$ is compact Hausdorff.
(ii) Follow the hint. The space which interests us is $S^{2} \cup A$, and $D^{3} \cup A$ is formed from it by regularly attaching a 3 -cell, so by Proposition 3 IX. 4.2 we know that $\pi_{1}\left(S^{2} \cup A\right) \cong \pi_{1}\left(D^{3} \cup A\right)$.
(iii) If $B \subset \mathbb{R}^{3}$ is the straight line segment described in the exercise which joins the north and south poles of $S^{2}$, then a retraction $D^{3} \rightarrow B$ is defined by sending $(x, y, z)$ to $z$; if we also take the straight line homotopy between these two points (which stays inside $D^{3}$ by convexity), we obtain deformation retract data for $B \subset D^{3}$. Now $A \cap B$ consists of the two points $\pm \mathbf{e}_{3}$, and by an exercise from Unit VII it follows that $B \cup A$ is a strong deformation retract of $D^{3} \cup A$. Since $B \cup A$ is the union of two closed subspaces homeomorphic to $[-1,1]$ which meet at their endpoints, the space $A \cup B$ is homeomorphic to $S^{1}$; for the sake of completeness, we note that an explicit homeomorphism is given by sending one copy of $[-1,1]$ to the upper semicircle by the mapping $t \rightarrow\left(t, \sqrt{1-t^{2}}\right)$ and sending the other copy of $[-1,1]$ to the lower semicircle by the mapping $t \rightarrow\left(t,-\sqrt{1-t^{2}}\right)$.

Finally, the preceding observations combine to yield the fundamental group relationships $\pi_{1}\left(S^{2} \cup A\right) \cong \pi_{1}\left(D^{3} \cup A\right) \cong \pi_{1}(B \cup A) \cong \pi_{1}\left(S^{1}\right) \cong \mathbb{Z}$, as asserted in the statement of the exercise.■ 2. The intersection of $D^{2} \times\{0\}$ with $S^{2}$ is equal to $S^{1} \times\{0\}$, so if we take $A=S^{2}$ and $B=D^{2}$ then we have an example with the properties described in the discussion before the statement of Proposition IX.4.2. Therefore we can apply this result to conclude that the map of fundamental groups $\pi_{1}\left(S^{2}\right) \rightarrow \pi_{1}(X)$ is onto. Since $\pi_{1}\left(S^{2}\right)$ is trivial, it follows that $\pi_{1}(X)$ must also be trivial..
3. (i) Follow the hint. The data in the problem yield the following commutative diagram, in which the vertical arrows $j_{k}$ are isomorphisms:


If we define $\varphi_{k}: c_{k}^{-1} \mathbb{Z} \rightarrow G$ by $g_{k}{ }^{\circ} j_{k}$, then we have the recursive property

$$
\varphi_{k+1}\left|c_{k}^{-1} \mathbb{Z}=g_{k+1} \circ j_{k+1}\right| c_{k}^{-1} \mathbb{Z}=g_{k+1} \circ h_{k} \circ j_{k}=g_{k} \circ j_{k}=\varphi_{k}
$$

and therefore we can assemble these mappings to produce a homomorphism $\varphi: \mathbb{Q} \rightarrow G$. This map is onto, for each $a \in G$ has the form $g_{k}(b)$ for some $k$ and $b \in A_{k}$, so if $j_{k}\left(b^{\prime}\right)=b$ we have $\varphi_{k}\left(b^{\prime}\right)=a$. In particular, this implies that $G$ is abelian, so we shall use 0 to denote the neutral element in $G$. To see that $\varphi$ is $1-1$, suppose that $x \in \mathbb{Q}$ maps to 0 , and choose $k$ such that $x \in c_{k}^{-1} \mathbb{Z}$. Then $j_{k}(x) \in A_{k}$ maps to 0 in $G$, and therefore there is some $M \geq 0$ such that $j_{k}(x)$ maps to 0 in $A_{k+M}$. But the map $A_{k} \rightarrow A_{k+M}$ is equivalent to a nonzero map $\mathbb{Z} \rightarrow \mathbb{Z}$, so if $j_{k}(x)$ maps to 0 in some $A_{k+M}$ then we must have $j_{k}(x)=0$. Since $j_{k}$ is an isomorphism we must have $x=0$. Therefore $\varphi: \mathbb{Q} \rightarrow G$ is an isomorphism.■
(ii) The mapping $j[d]$ is $1-1$ because the composite of $j[d]$ with projection onto the $D^{2}$ factor is the standard inclusion of $S^{1}$ in $D^{2}$, and the map $j[d]_{*}$ in fundamental groups corresponds to multiplication by $d$ because the composite of $j[d]$ with projection onto the $S^{1}$ factor has degree $d$ and this coordinate projection map induces an isomorphism $\pi_{1}\left(S^{1} \times D^{2}\right) \rightarrow \pi_{1}\left(S^{1}\right)$. .
(iii) A more concrete approach to constructing $E$ is to describe it as a subspace of $\mathbb{R}^{5}=$ $\mathbb{C} \times \mathbb{C} \times \mathbb{R}$; more precisely, we shall realize each $S_{k}$ as a subset of $\mathbb{C}^{2} \times[k, k+1]$ such that the continuous mapping $S_{k} \rightarrow[k+1]$ corresponds to the last coordinate. Consider the subspace $T_{k}$ of $\mathbb{C}^{2} \times[k, k+1]$ consisting of $S^{1} \times D^{2} \times\{k+1\}$ together with the image of $S^{1} \times[0,1]$ under the continuous mapping $\theta_{k}$ defined by

$$
\theta_{k}(z, t)=\left(t z^{d_{k}}+(1-t) z, t z, t+k\right) .
$$

We claim that $\theta_{k}$ is $1-1$, and from this it follows that the standard quotient map from $S_{k}$ to $T_{k}$ is a homeomorphism onto its image. So suppose that $\theta_{k}(z, t)=\theta_{k}\left(z^{\prime}, t^{\prime}\right)$. Equating the third coordinates, we see that $t+k=t^{\prime}+k$, so that $t=t^{\prime}$. Now equating the second coordinates, we see that $t z=t z^{\prime}$ so that either $t=0$ (and hence $t^{\prime}=0$ or else $z=z^{\prime}$; in the second case we are finished, so assume that $t=0$ and look at the first coordinates. When $t=0$ the first coordinate equation reduces to $z=z^{\prime}$, so we have shown that $(z, t)=\left(z^{\prime}, t^{\prime}\right)$ must always hold. - Continuing, we see that the union $\cup_{j \leq k} T_{k}$ is homeomorphic to $E_{k}$, and if we set $T=\cup_{k} T_{k}$ we have a 1-1 onto continuous mapping $E \rightarrow T$. Projection onto the final coordinate in $\mathbb{R}^{5}=\mathbb{C} \times \mathbb{C} \times \mathbb{R}$ yields a continuous mapping from $T$ to $[0, \infty)$ such that the composite $E \rightarrow T \rightarrow[0, \infty)$ has all the right properties. Furthermore, this mapping sends the inverse image of $[0, k)$ homeomorphically to the inverse image of $[0, k)$ for all $k$, and from this one can prove that the map $E \rightarrow T$ is actually a homeomorphism (but this will not be needed to carry out the computations).

We now need to verify the assertion about the maps in fundamental groups associated to the inclusions $E_{k} \rightarrow E_{k+1}$. To start, we claim that for each $k$ the inclusion $S^{1} \times\{0\} \times\{k+1\} \subset S_{k}$ is a deformation retract. Since we know that the inclusion $S^{1} \times\{0\} \times\{k+1\} \subset S^{1} \times D^{2} \times\{k+1\}$ is a deformation retract, it will suffice to show that $S^{1} \times D^{2} \times\{k+1\} \subset S_{k}$ is a deformation retract. This follows because $S_{k}=F_{1} \cup F_{1}$, where $F_{1}=S^{1} \times D^{2} \times\{k+1\}$ and $F_{2}$ is homeomorphic to $S^{1} \times[0,1]$ such that $S^{1} \times\{1\}$ corresponds to $F_{1} \cap F_{2}$. We can now proceed by induction on $j$ to show that the inclusion

$$
S^{1} \times\{0\} \times\{k+1\} \subset \bigcup_{i=j}^{k} E_{i}
$$

is a deformation retract for $j=k, k-1, \cdots, 1$. Furthermore, it also follows that $S_{k+1} \subset E_{k+1}$ is a deformation retract.

The algebraic implication of the preceding paragraph is that the homomorphism $\pi_{1}\left(E_{k}\right) \rightarrow$ $\pi_{1}\left(E_{k+1}\right)$ is equivalent to the homomorphism $\pi_{1}\left(S^{1} \times\{0\} \times\{k+1\}\right) \rightarrow \pi_{1}\left(S_{k+1}\right)$ induced by inclusion. Since the composite of this inclusion with the retraction $E_{k+1} \rightarrow S^{1} \times\{0\} \times\{k+2\}$ has degree $d$, it follows that all the homomorphisms of fundamental groups in this paragraph are equivalent to multiplication by $d_{k}$ on $\mathbb{Z}$.

Note. Some of the mappings constructed in (iii) do not preserve basepoints particularly well, but this will not cause problems because in all cases the spaces are homotopy equivalent to $S^{1}$. This means that their fundamental groups are abelian and there are unique change of basepoint isomorphisms.
(iv) Each subset $S_{k}$ is compact, and since $E_{k}$ is a quotient of a finite union of subsets homeomorphic to $S_{1}, \cdots, S_{k}$, it follows that $E_{k}$ is also compact. Furthermore, if $K \subset E$ is compact then its image in $[0, \infty)$ will also be compact, and since this image is contained in some closed interval $[0, M]$ it follows that $K \subset E_{M}$ for some $M$. The statements about the topology of $E$ all follow from the fact that $E$ is homeomorphic to $T$ (but we shall not need these in the next step, which is the last one).
$(v)$ We have shown that the diagram of fundamental group maps is the same as the algebraic diagram considered in $(i)$, so by $(i)$ it is only necessary to check that it satisfies properties (2) and (3) in (i). These follow from the Compact Supports Property for fundamental groups (Proposition VIII.1.12) and the fact that every compact subset of $E$ is contained in some $E_{k}$..
(vi) Everything will go through if we modify the definition of the integer sequence $d_{k}$; specifically, if we are only interested in fractions which are monomials in $S$ we can take $d_{k}$ to be the product of the first $k$ primes in $S$ if $|S| \geq k$ and taking $d_{k}$ to be the product of all the primes in $S$ if $|S|<k$. If we now define $c_{k}$ as before to be $d_{1} \cdots d_{k-1}$ for the new sequence $\left\{d_{k}\right\}$, then $S^{-1} \mathbb{Z}$ will be the union of the sets $c_{k}^{-1} \mathbb{Z}$.

