

~

# Mathematics 205C, Spring 2016, Examination 2

## Answer Key

1. [25 points] Let  $M$  and  $N$  be connected smooth manifolds, let  $p : \tilde{N} \rightarrow N$  be a universal covering space projection where  $\tilde{N}$  has the smooth structure induced from  $N$ , let  $f : M \rightarrow N$  be a smooth map, and assume that there is a continuous lifting  $F : M \rightarrow \tilde{N}$ , so that  $f = p \circ F$ . Prove that the lifting  $F$  is also smooth.

### SOLUTION

For each  $x \in M$  we need to find an open neighborhood  $V$  of  $x$  such that  $F|_V$  is smooth.

Let  $W$  be a connected open neighborhood of  $f(x)$  such that there is a coordinate chart  $f : W \rightarrow \Omega$ , where  $\Omega$  is open in  $\mathbb{R}^n$ , with  $n = \dim N$ , and  $W$  is evenly covered with respect to the covering space projection  $p$ . Let  $W'$  be the sheet of  $p^{-1}[W]$  containing  $F(x)$ . By continuity there is a connected open neighborhood  $V$  of  $x$  such that  $f[V] \subset W$ . By connectedness,  $F$  must map all of  $V$  into the sheet  $W'$ . Since  $W'$  maps diffeomorphically to  $W$ , it follows that  $F|_V$  is defined by the composite of  $W|_f|V : V \rightarrow W$  with the inverse to the diffeomorphism  $W'|_p|W$ , and therefore  $F|_V$  is smooth. ■

2. [25 points] Suppose that  $f : M \rightarrow N$  and  $g : N \rightarrow P$  are smooth immersions. Prove that the composite  $g \circ f$  is also an immersion.

### SOLUTION

Let  $x \in M$ . Since  $f$  and  $g$  are immersions, the linear maps of tangent spaces  $T_x(f) : T_x(M) \rightarrow T_{f(x)}(N)$  and  $T_{f(x)}(g) = T_{f(x)}(N) \rightarrow T_{g(f(x))}(P)$  are both 1-1. Therefore their composite  $T_x(g \circ f) = T_{f(x)}(g) \circ T_x(f)$  is 1-1, which means that  $g \circ f$  is also an immersion. ■

3. [25 points] Let  $\omega \subset \mathbb{R}^n$  be the first orthant, which consists of all point  $x = (x_1, \dots, x_n)$  such that  $x_i > 0$  for all  $i$ , and let  $f : \Omega \rightarrow \mathbb{R}$  be the function  $f(x) = x_1 \cdots x_n - 1$ . show that the set of points  $V \subset \Omega$  which satisfy  $f(x) = 0$  is a smooth submanifold.

### SOLUTION

We need to show that if  $f(x) = 0$  then  $Df(x) \neq 0$ ; the latter is equivalent to the nonvanishing of one of the partial derivatives

$$\frac{\partial f}{\partial y_i}(x).$$

Now the displayed partial derivative is equal to  $\prod_{j \neq i} x_j$ , and since  $x \in \Omega$  it follows that all of the factors in such a product is positive. In particular, if  $x \in \Omega$  then all of the partial derivatives vanish, and therefore 0 is a regular value: If  $f(x) = 0$  then  $Df(x) \neq 0$ . ■

4. [25 points] Suppose that  $f : M \rightarrow N$  is a smooth map of smooth manifolds and  $\dim M < \dim N$ . Explain why  $N - f[M]$  is dense in  $N$ .

### SOLUTION

Given  $x \in N$ , we need to show that every sufficiently small open neighborhood  $U$  of  $x$  contains at least one point which is not in  $f[M]$ . In this context, we shall interpret “sufficiently small” to mean that  $U$  is contained in some open set  $W$  such that there is a smooth chart  $h : W \rightarrow \Omega$ .

By the easy case of Sard’s Theorem we know that  $f[M]$  has measure zero. It follows that if  $U \subset W$  then  $h[U \cap f[M]] \subset h[U]$  has measure zero. Now a subset of measure zero in an open subset of  $\mathbb{R}^n$  must have a dense complement (if the subset contained an open neighborhood of a point, then it would not have measure zero), and therefore there is some point  $y \in h[U] - hf[M]$ . If we choose  $z$  such that  $h(z) = y$ , then we have  $z \in U - f[M]$ , and as noted above this implies that  $N - f[M]$  is dense in  $N$ . ■

5. [25 points] If  $U$  is open in  $\mathbb{R}^n$  and  $h : U \rightarrow \mathbb{R}$  is smooth, then its gradient vector field is defined in the usual fashion as

$$\mathbf{X}_h = \sum_j \frac{\partial h}{\partial y_j} \frac{\partial}{\partial x_j}.$$

Given two smooth functions  $f$  and  $g$  on  $U$ , compute the Lie bracket vector field  $[\mathbf{X}_f, \mathbf{X}_g]$ .

### SOLUTION

Write  $\partial_j = \frac{\partial}{\partial x_j}$ . Since the Lie bracket is distributive with respect to addition, it follows that

$$[\mathbf{X}_f, \mathbf{X}_g] = \sum_{i,j} [\partial_i f \cdot \partial_i, \partial_j g \cdot \partial_j].$$

We can now apply the identity  $[aY, bZ] = a(Yb)Z - b(Za)Y + ab[X, Y]$  to each summand and use the vanishing of the brackets  $[\partial_i, \partial_j]$  to expand and simplify each term in the sum. These considerations show that the right hand side is equal to

$$\sum_{i,j} (\partial_i f \cdot \partial_i \partial_j g) \partial_j - (\partial_j g \cdot \partial_j \partial_i f) \partial_i$$

and by interchanging the roles of  $i$  and  $j$  in the second terms we may rewrite this in the form

$$\sum_j \left( \sum_i \partial_i f \cdot \partial_i \partial_j g - \partial_i g \cdot \partial_i \partial_j f \right) \partial_j \quad \blacksquare$$

6. [25 points] Let  $UT(3, \mathbb{R})$  be the set of all upper unitriangular matrices having the form

$$A = \begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix}$$

where  $x, y, z \in \mathbb{R}$ .

(i) Prove that  $UT(3, \mathbb{R})$  is a Lie group with respect to ordinary matrix multiplication. [Hint: The inverse can be found either by solving the matrix equation  $AX = I$ , where  $X$  is assumed to be unitriangular, or by taking determinants of  $2 \times 2$  submatrices.]

(ii) Let  $A \in UT(3, \mathbb{R})$  be the matrix

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Find a second matrix  $B$  such that  $AB \neq BA$ .

### SOLUTION

(i) We shall take the obvious diffeomorphism from  $UT(3; \mathbb{R})$  to  $\mathbb{R}^3$  where the displayed matrix goes to  $(x, y, z)$ . The smoothness of the multiplication map follows immediately from writing out the matrix product of two elements in  $UT(3; \mathbb{R})$ :

$$\begin{pmatrix} 1 & x & y \\ 0 & 1 & z \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & u & v \\ 0 & 1 & w \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & x+u & v+xw+y \\ 0 & 1 & z+w \\ 0 & 0 & 1 \end{pmatrix}$$

If we set the right hand side equal to the identity matrix or use determinants, we can check that the inverse of the matrix with nontrivial entries  $(x, y, z)$  is the matrix with nontrivial entries  $(-x, xz - y, -z)$ , and therefore the inverse mapping on  $UT(3; \mathbb{R})$  is also smooth. ■

(ii) Let  $B \in UT(3; \mathbb{R})$  be the matrix with nontrivial entries  $(x, y, z)$ . Then the product  $AB$  is the matrix with nontrivial entries  $(x+1, y+z, z)$ , and the product  $BA$  is the matrix with nontrivial entries  $(x+1, y, z)$ . Therefore  $AB = BA$  if and only if  $z = 0$ , and accordingly  $AB \neq BA$  if  $z \neq 0$ . Perhaps the simplest explicit example of a matrix  $B$  with  $AB \neq BA$  is given by

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \blacksquare$$