

EXERCISES FOR MATHEMATICS 205A

SPRING 2016 — Part 2

The headings denote chapters of the text for the course:

J. Lee, *Introduction to Smooth Manifolds* (Second Edition), Springer-Verlag, 2012.

Exercises which appear throughout the text are numbered in the form $m.n$, and exercises at the end of the chapters are numbered in the form $m - n$. Except when explicitly noted otherwise, it will suffice to prove exercises for manifolds without boundary.

3 . Tangent spaces

RECOMMENDATION. Use the approach to constructing the tangent space described in the lectures and the document `amalgamation.pdf`. However, note that coordinate charts in that document are defined as maps from open subsets in \mathbb{R}^n into a manifold M , while in Lee and this course we have defined coordinate charts as maps from open sets in M to open sets in \mathbb{R}^n . The relationship between the two formulations is that the maps in Lee are inverses to the maps in `amalgamation.pdf`.

Lee, 3 – 3, 3 – 4, 3 – 5

Additional exercises

0. Prove the following statements; each is an immediate consequence of previous exercises.
 - (a) If M is a smooth submanifold of N and N is a smooth submanifold of P , then M is a smooth submanifold of P .
 - (b) If P is a smooth submanifold of M and Q is a smooth submanifold of N , then $P \times Q$ is a smooth submanifold of $M \times N$.
1. Suppose that $f : M \rightarrow N$ is a smooth homeomorphism. Prove that f is a diffeomorphism if and only if $T(f)$ is 1–1 and onto.
2. One can construct the Klein bottle KB using two smooth charts (U_i, h_i) for $i = 1, 2$ where $U_1 = U_2 = \mathbb{R}^2 - \{0\}$ such that the overlapping images are given by $V_{21} = V_{12} = \{ z \mid |z| < \frac{1}{2} \text{ or } |z| > 2 \}$ and the transition diffeomorphisms ψ_{ij} are both given by $\psi_{ij}(x, y) = (x, y)$ if $\sqrt{x^2 + y^2} > 2$ and $\psi_{ij}(x, y) = (x, -y)$ if $\sqrt{x^2 + y^2} < \frac{1}{2}$. What are the domains of the charts for the corresponding smooth atlas of the tangent space $T(KB)$, and what is the corresponding transition map for these charts?
3. A smooth curve γ from an open interval (a, b) to a smooth manifold M is said to be regular if its tangent vector at every point is nonzero, and a continuous curve γ from (a, b) to M is said to be *regularly piecewise smooth* if one can find a partition

$$a = s_0 < s_1 < \cdots < s_p = b$$

such that the restrictions of γ to the pieces $(s_0, s_1), [s_1, s_2] \cdots [s_{p-1}, s_p)$ all extend to regular smooth curves on open intervals containing the pieces.

(i) Prove that if M is connected, then every pair of points can be joined by a regular piecewise smooth curve $(-\varepsilon, 1 + \varepsilon)$; *i.e.*, for each $x, y \in M$ one can find such a curve γ so that $\gamma(0) = x$ and $\gamma(1) = y$.

(ii) Prove the following strengthening of (i): Every pair of points can be joined by a regular smooth curve. [*Hint:* start with the conclusion of (i) and use the construction on the last three pages of `nicecurves.pdf` to smooth out the corner points.]

4. Assume we are in the setting of Additional Exercise I.4, where we are given two smooth n -manifolds M and N such that there is a diffeomorphism Φ from an open subset $U \subset M$ to an open subset $V \subset N$. Then we can form the quotient space $P = M \cup_{\Phi} N$, which is given by $M \amalg N$ modulo the equivalence relation generated by $x \equiv \Phi(x)$ for all $x \in U$. If this space P is Hausdorff, then the cited exercise yields a smooth structure on P which contains open subsets diffeomorphic to M and N .

Prove that the space $T(M) \cup_{T(\Phi)} T(N)$ is Hausdorff, and with the smooth structure on it given in the earlier exercise it is diffeomorphic to $T(P)$.

5. Let M be a smooth manifold, let $p : E \rightarrow M$ be a Hausdorff covering space projection, and take the smooth structure on E given in the lectures. Prove that $T(p) : T(E) \rightarrow T(M)$ is also a smooth covering space projection of the same type, and if $h : M \rightarrow M$ is a covering space (deck) transformation then so is $T(h)$.

4 : Mersions and embeddings

CONVENTION. The word *mersion* refers to a map which is either an immersion or a submersion. There is also a related concept of k -mersion, which is a smooth mapping $f : M \rightarrow N$ such that for each $x \in M$ the tangent space mapping $T(f)_x : T_x(M) \rightarrow T_{f(x)}(N)$ has constant rank k .

Lee, 4.10, 4.38, 4 – 6, 4 – 8, 4 – 12, 4 – 13

Additional exercises

- 1.** (i) Prove that the composite of two smooth immersions is a smooth immersion.
(ii) Prove that the composite of two smooth submersions is a smooth submersion.
(iii) Prove that the composite of two smooth embeddings is a smooth embedding.
- 2.** Let $f : M \rightarrow M'$ and $g : N \rightarrow N'$ be smooth mappings.
(i) Prove that if f and g are immersions then so is $f \times g : M \times N \rightarrow M' \times N'$.
(ii) Prove that if f and g are submersions then so is $f \times g : M \times N \rightarrow M' \times N'$.
(iii) Prove that if f and g are smooth embeddings then so is $f \times g : M \times N \rightarrow M' \times N'$.
- 3.** Let X be the y -axis in the Cartesian plane, and let Y be the graph of $\sin \frac{1}{x}$ for $x > 0$. Prove that the map $X \amalg Y \rightarrow \mathbb{R}^2$ is an immersion but not an embedding; also show that the restrictions to the two pieces are embeddings.
- 4.** Prove that there is no immersion from a compact n -manifold into \mathbb{R}^n .

5. Prove that there is no submersion from a compact n -manifold into \mathbb{R} . [*Hint:* Such a map attains a maximum value. What does this mean if we look at a smooth chart at a point where the maximum is attained?]

Note. If M is connected and noncompact, then one can always construct a smooth submersion $M \rightarrow \mathbb{R}$.

6. Given an immersion from a 1-connected compact smooth manifold to a smooth manifold of the same dimension, prove that it is a covering space projection. Does the statement remain true if the manifolds are not necessarily compact? Prove this or give a counterexample.

7. Let U and V be open in \mathbb{R}^n , let $f : U \rightarrow V$ be a smooth *surjective* immersion/submersion, and suppose that $g : V \rightarrow \mathbb{R}^q$ is a continuous map such that $g \circ f$ is smooth. Prove that g is also smooth.

8. A continuous map $f : A \rightarrow X$ is a *retract* if there is a continuous map $g : X \rightarrow A$ such that $g \circ f = \text{id}_A$. Suppose that A and X smooth manifolds and f and g are smooth. Prove that f is an immersion.

9. Suppose that M is a noncompact smooth manifold and there is a smooth 1–1 immersion $f : M \rightarrow \mathbb{R}^N$. Prove that there is a smooth embedding $g : M \rightarrow \mathbb{R}^{N+1}$ such that $g[M]$ is a closed subset. [*Hint:* Recall that there is a proper map from M to \mathbb{R} .]

10. (i) Suppose that M and N are smooth manifolds. A smooth map $f : M \rightarrow N$ is said to be a *retract* if there is a smooth map $g : N \rightarrow M$ such that $g \circ f = \text{id}_M$. Prove that a smooth retract is a smooth immersion.

(ii) A smooth map of smooth manifolds $r : N \rightarrow M$ is said to be a smooth *retraction* if there is a smooth map $j : M \rightarrow N$ such that $r \circ j = \text{id}_M$. Prove that if r is a retraction, then the restriction of r to some neighborhood of $j(M)$ is a submersion.

(iii) A continuous map of topological spaces is said to be a continuous retract if it satisfies the condition in (i). Prove that if A and X are Hausdorff then j is a closed mapping. Why does this imply that j maps A homeomorphically onto its image? [*Hint:* To see that A is closed, show that it is the set of all points such that $x = j \circ r(x)$.]

11. Let $z : M \rightarrow T(M)$ be the map which sends each point $x \in M$ to the zero vector in the tangent space $T_x(M)$. Prove that z is a smooth embedding. [*Hint:* What does z look like in local coordinates, and why is $\tau_m \circ z$ the identity?]

12. Let $z : M \rightarrow T(M)$ be given as in the previous exercise. Prove that $z[M]$ is a strong deformation retract of $T(M)$ and τ_M is an associated deformation retraction.

13. Let n_1, \dots, n_k be positive integers and let N be their sum. Prove that there is a smooth embedding of $\prod_j S^{n_j}$ into S^{N+1} . [*Hint:* One always has smooth embeddings of $S^p \times \mathbb{R}^q$ in \mathbb{R}^{p+q} and embeddings of $S^{q-1} \times \mathbb{R}$ in \mathbb{R}^q . Use these as part of an inductive argument.]

14. Suppose we have smooth maps $i : M \rightarrow N$ and $j : N \rightarrow L$ such that $j \circ i$ is a smooth embedding. Prove that i is a smooth embedding.

15. Suppose that M is a connected smooth manifold and $f : M \rightarrow N$ is a smooth immersion. Prove that the diagonal Δ_M is a connected component of $(f \times f)^{-1}[\Delta_N]$. [*Hint:* Recall that f is locally 1–1.]

5 : Smooth submanifolds

Lee, 5 – 1, 5 – 3, 5 – 6, 5 – 7, 5 – 10, 5 – 11, 5 – 17, 5 – 19 (but disregard the last sentence)

Additional exercises

1. Suppose that U is open in \mathbb{R}^n and that $f : U \rightarrow \mathbb{R}^n$ and $g : U \rightarrow \mathbb{R}^m$ are smooth functions where $m < n$. Let $x \in U$ be a point on the level set L on which $g(x) = 0$, and suppose that $Dg(x)$ has rank m (\implies if we restrict to a suitable open neighborhood V of x in U , the set $L \cap V$ is a smooth submanifold of dimension $n - m$).

(i) Suppose that $f|_L$ has a local maximum at x . Prove that $\nabla f(x)$ is perpendicular to the tangent space $T_x(L)$. [*Hint:* What can we say about $D[f|_L](x)$ under the given hypothesis?]

(ii) If the coordinates of g are given by g_j (where $1 \leq j \leq m$), explain why the orthogonal complement of $T_x(L)$ is spanned by the vectors $\nabla g_j(x)$.

(iii) Using the preceding parts of this exercise, derive the **Lagrange Multiplier Rule**: One can find m constants (or Lagrange multipliers) λ_j such that $\nabla f(x) = -\sum_j \lambda_j \nabla g_j(x)$ or equivalently x (and the λ_j 's) determine a solution to the following system of equations:

$$\nabla \left(f + \sum_j \lambda_j g_j \right) = \mathbf{0} \quad \text{AND} \quad g(x) = 0$$

Note that this is a system of $m + n$ scalar equations in the n coordinates of x and the m multipliers λ_j .

2. Let $Q \subset \mathbb{R}^{n+1}$ be the unit cube consisting of all (x_0, \dots, x_n) such that $\max_i |x_i| = 1$. Prove that Q is homeomorphic to S^n , that Q has a smooth atlas for which Q is diffeomorphic to S^n , but Q is not a smooth submanifold of \mathbb{R}^{n+1} .

3. Let X be the y -axis in the Cartesian plane, and let Y be the graph of $\sin \frac{1}{x}$ for $x > 0$. Prove that $X \cup Y$ is an immersed but not embedded submanifold but that each of X and Y taken separately is an embedded submanifold.

4. Let A be a real nonsingular symmetric $n \times n$ matrix and let c be a nonzero real number. Show that the quadric hypersurface defined by the equation $\langle Ax, x \rangle = c$ is a smooth $(n - 1)$ -dimensional submanifold of \mathbb{R}^n .

5. Let M be a noncompact smooth manifold. Prove that there is a smooth embedding $f : (-\varepsilon, \infty) \rightarrow M$ such that the image of $[0, \infty)$ is a closed subset.

6. (i) Let V the set of points $(x, y, z) \in \mathbb{R}^3$ satisfying the equations $x + y + z = 0$ and $xyz = 2$, and let A be the three point set consisting of $(2, -1, -1)$, $(-1, 2, -1)$ and $(-1, -1, 2)$. Prove that $V - A$ is a smooth submanifold of \mathbb{R}^3 .

(ii) Let V be the set of points $(x, y, z) \in \mathbb{R}^3$ satisfying the equations $x^2 + 2xz - 2yz + z^2 = 0$ and $2x - y + z = 3$. Prove that V is a smooth submanifold of \mathbb{R}^3 .

7. Show that it is possible to make the subset of the plane defined by the equation $x^3 - y^2 = 0$ into a smooth manifold but that the set in question is not a smooth submanifold of \mathbb{R}^2 . What happens for the set $x^4 - y^2 = 0$?

8. Let $f : S^2 \rightarrow \mathbb{R}^4$ be the smooth map sending (x, y, z) to $(x^2 - y^2, xy, xz, yz)$. Show that $f(x, y, z) = f(-x, -y, -z)$ for all (x, y, z) and that the associated map $g : \mathbb{RP}^2 \rightarrow \mathbb{R}^4$ on the quotient manifold is a smooth embedding.

9. Let $A \subset \mathbb{R}^2$ be the graph of the function $f(t) = |t|$. Prove that A is a topologically locally flat submanifold of \mathbb{R}^2 but not a smooth submanifold. [*Hints:* Construct a homeomorphism from \mathbb{R}^2 to itself that sends A to the x -axis. To show A is not a smooth submanifold, derive a contradiction by finding two candidates for the tangent space at the origin.]

10. Consider the set $LF_{n,k}$ of labeled flexible n -gons in \mathbb{R}^k . These are the figures obtained by joining $n > 2$ straight line segments of unit length into a closed curve.

(i) Suppose that n is odd and $k = 2$. Prove that $LF_{n,2}$ is a smooth submanifold of $\mathbb{R}^2 \times T^{n-1}$ whose dimension is equal to n .

(ii) Prove that the set of all such objects with no self-intersections is a smooth manifold.

Exercises involving real projective spaces

We shall take the construction in Example 1.5 of Lee's book (see p. 6) as the basic definition for the n -dimensional real projective space \mathbb{RP}^n . As indicated in the hint for Exercise 1.7 on p. 7, if the quotient map $\mathbb{R}^{n+1} - \{\mathbf{0}\} \rightarrow \mathbb{RP}^n$ is denoted by π , then $\pi|_{S^n}$ is surjective, and in fact it follows that we can view \mathbb{RP}^n as the quotient of S^n by the equivalence relation $x \equiv y \iff x = \pm y$. If we view \mathbb{RP}^n in this way, there is a natural atlas given in terms of Examples 1.4 and 1.5 as follows: Let $\Omega_i \subset \mathbb{R}^{n+1} - \{\mathbf{0}\}$ be the set of points where the i^{th} coordinate is nonzero (this is called \widetilde{U}_i in Lee), and let $U_i^+ \subset S^n$ and $U_i \subset \mathbb{RP}^n$ be the open subsets described on p. 5 of Lee. It follows that the images of these two sets in \mathbb{RP}^n are equal to the same open subset, and it also follows that the charts given by the inverses to the mappings

$$N_1(\mathbf{0}, \mathbb{R}^n) \longrightarrow U_i^+ \longrightarrow U_i \longrightarrow \mathbb{RP}^n$$

form a compatible smooth atlas. The verification of this is straightforward (the user should be able to do this!), but it is a little messy.

Note that $S^n - \Omega_i$ is equal to $U_i^+ \cup U_i^-$ (where the two pieces are disjoint) and that the antipodal map $T : S^n \rightarrow S^n$ sending x to $-x$ sends each of these subsets to the other.

11. (i) Explain why the antipodal map is a diffeomorphism from S^2 to itself, and if $\pi : S^n \rightarrow \mathbb{RP}^n$ is the quotient map then $\pi \circ T = \pi$. [*Hint:* $T^2 = \text{identity}$ implies that $T = T^{-1}$.]

(ii) Let Q be a smooth manifold. Using the preceding material and discussion, explain why a map $f : \mathbb{RP}^n \rightarrow Q$ is smooth if and only if $f \circ \pi$ is smooth.

12. Let $f : S^2 \rightarrow \mathbb{R}^4$ be the smooth map sending (x, y, z) to $(x^2 - y^2, xy, xz, yz)$. Show that $f(x, y, z) = f(-x, -y, -z)$ for all (x, y, z) and that the associated map $g : \mathbb{RP}^2 \rightarrow \mathbb{R}^4$ on the quotient manifold is a smooth embedding. [*Note:* There is no smooth embedding $\mathbb{RP}^2 \rightarrow \mathbb{R}^3$.]

13. Let $p(x_1, \dots, x_{n+1})$ be a homogeneous polynomial of degree d with real coefficients, so that we have the following identity:

$$p(cx_1, \dots, cx_{n+1}) = c^d \cdot p(x_1, \dots, x_{n+1}), \quad \text{for all } c, x_j$$

(i) Suppose that (x_1, \dots, x_{n+1}) and (y_1, \dots, y_{n+1}) determine the same point of \mathbb{RP}^n . Explain why $p(x_1, \dots, x_{n+1}) = 0$ if and only if $p(y_1, \dots, y_{n+1}) = 0$, so that it is meaningful to discuss the projective zero set $\mathbb{P}V(p)$ of p in \mathbb{RP}^n .

(ii) Let $V(p)$ be the zero set of p in \mathbb{R}^{n+1} , so that the inverse image of $\mathbb{P}V(p)$ is $V(p) - \{\mathbf{0}\}$. Prove that if the derivative Dp is nonzero at every point of $V(p)$, then $\mathbb{P}V(p)$ is a smooth compact $(n - 1)$ -dimensional smooth submanifold of \mathbb{RP}^n . [*Hints:* Why is $\mathbb{P}V(p)$ a closed subset, and why does it suffice to show that the intersection with each U_i is a smooth submanifold?]

14. Determine whether the following homogeneous polynomial equations define smooth submanifolds of \mathbb{RP}^n :

(i) $x_1x_2x_3 - x_4^3 = 0$, where $n = 3$.

(ii) $x_1^2 + x_2^2 + x_3^2 - x_4^2 = 0$, where $n = 3$.

(iii) $x_1^d + x_2^d + x_3^d + x_4^d = 0$, where $d > 1$ is an odd integer and $n = 3$.

(iv) $x_1^3 - x_1x_2^2 - x_2^2x_3 = 0$, where $n = 2$.

[*Hint:* It might be helpful to look over each U_i separately and restrict to the sets where the i^{th} homogeneous coordinate is equal to 1.]

6 : Approximation and embedding theorems

Lee, 6 - 1, 6 - 3, 6 - 16abce

Additional exercises

1. For each of the statements below, either prove that it is true or give a counterexample to show it is false.

(a) If M is a smooth manifold and $A \subset M$ is a set of measure zero, then the closure $\bar{A} \subset M$ also has measure zero.

(b) If M is a smooth manifold with $B \subset A \subset M$ and A has measure zero, then B also has measure zero.

2. Sard's Theorem implies that if $f : M \rightarrow N$ is smooth and $\dim M < \dim N$, then $f[M] \subset N$ has measure zero. This exercise considers the possibilities if the dimensions are equal.

(i) Show that there are examples of smooth maps $f : M \rightarrow N$ such that $\dim M = \dim N$ and $f[M] \subset N$ has measure zero.

(ii) Suppose that $f : M \rightarrow N$ is smooth such that $\dim M = \dim N$. Prove that $f[M] \subset N$ has measure zero if and only if for each $x \in M$, the linear map of tangent spaces $T_x(f) : T_x(M) \rightarrow T_{f(x)}(N)$ is not invertible.

3. (i) Suppose that $\dim M < n$, where M is a compact smooth manifold, and let $f : M \rightarrow S^n$ be continuous. Prove that f is homotopic to a constant map. [*Hints:* First approximate f by a smooth map g which is homotopic to f ; this can be done by choosing $\varepsilon > 0$ sufficiently small. Use Sard's Theorem to show that f is not onto, so that the image lies in $S^n - \{\mathbf{p}\}$ for some \mathbf{p} . Why does this imply that g is homotopic to a constant?]

(ii) Give an example to show that a similar conclusion does not hold if we replace S^n with some other compact smooth n -manifold (*i.e.*, find N^n and M so that $\dim M < n$ and find a map $f : M \rightarrow N$ which is not homotopic to a constant).