

Homework 7 solutions

1. Find the general solution of

$$y'' + y = \sec(x).$$

Solution. First, we will find the homogeneous solution y_h , which solves

$$y_h'' + y_h = 0.$$

Let $y_h = e^{\lambda x}$, where λ is a number. Then we obtain the first and second derivatives

$$\begin{aligned}y_h' &= \lambda e^{\lambda x}, \\y_h'' &= \lambda^2 e^{\lambda x}.\end{aligned}$$

So we have

$$\begin{aligned}0 &= y_h'' + y_h \\&= \lambda^2 e^{\lambda x} + e^{\lambda x} \\&= e^{\lambda x}(\lambda^2 + 1).\end{aligned}$$

Since we know $e^{\lambda x} \neq 0$, we must conclude $\lambda^2 + 1 = 0$, which gives the imaginary roots $\lambda_1 = i$ and $\lambda_2 = -i$. So the homogeneous solution is

$$\begin{aligned}y_h &= C_1 e^{\lambda_1 x} + C_2 e^{\lambda_2 x} \\&= C_1 e^{ix} + C_2 e^{-ix} \\&= C_1 \cos(x) + C_2 \sin(x),\end{aligned}$$

where C_1, C_2 are constants. Next, we will find the particular solution y_p , which solves

$$y_p'' + y_p = \sec(x),$$

using variation of parameters. We compute the Wronskian matrix

$$\begin{bmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx} \cos(x) & \frac{d}{dx} \sin(x) \end{bmatrix} = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

and hence the Wronskian

$$\begin{aligned}W(\cos(x), \sin(x)) &= \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix} \\&= (\cos(x))(\cos(x)) - (-\sin(x))(\sin(x)) \\&= \cos^2(x) + \sin^2(x) \\&= 1.\end{aligned}$$

We also obtain

$$\begin{aligned}W_1 &= \begin{vmatrix} 0 & \sin(x) \\ \sec(x) & \cos(x) \end{vmatrix} \\&= (0)(\cos(x)) - (\sec(x))(\sin(x)) \\&= -\frac{\sin(x)}{\cos(x)} \\&= -\tan(x)\end{aligned}$$

and

$$\begin{aligned}W_2 &= \begin{vmatrix} \cos(x) & 0 \\ -\sin(x) & \sec(x) \end{vmatrix} \\&= (\cos(x))(\sec(x)) - (-\sin(x))(0) \\&= \frac{\cos(x)}{\cos(x)} \\&= 1.\end{aligned}$$

So we have

$$v_1' = \frac{W_1}{W} = \frac{-\tan(x)}{1} = -\tan(x),$$

$$v_2' = \frac{W_2}{W} = \frac{1}{1} = 1,$$

which imply

$$v_1 = \int v_1' dx = \int -\tan(x) dx = \ln(|\cos(x)|),$$

$$v_2 = \int v_2' dx = \int 1 dx = x,$$

respectively. So our particular solution is

$$y_p = v_1 \cos(x) + v_2 \sin(x)$$

$$= \ln(|\cos(x)|) \cos(x) + x \sin(x).$$

Therefore,

$$y = y_h + y_p$$

$$= \boxed{C_1 \cos(x) + C_2 \sin(x) + \ln(|\cos(x)|) \cos(x) + x \sin(x)}$$

is the general solution to the problem. □

2. Find the general solution of

$$(x^2 - 1)y'' - 2xy' + 2y = (x^2 - 1)^2$$

if two solutions to the associated homogeneous equation are x and $x^2 + 1$.

Solution. First, we rewrite the ordinary differential equation in its standard form

$$y'' - \frac{2x}{x^2 - 1}y' + \frac{2}{x^2 - 1}y = x^2 - 1.$$

As we are given in the problem statement that the two solutions to the associated homogeneous equation are x and $x^2 + 1$, our homogeneous solution is

$$y_h = C_1x + C_2(x^2 + 1),$$

where C_1, C_2 are arbitrary constants. Next, we will find the particular solution y_p , which solves

$$y_p'' - \frac{2x}{x^2 - 1}y_p' + \frac{2}{x^2 - 1}y_p = x^2 - 1,$$

using variation of parameters. We compute the Wronskian matrix

$$\begin{bmatrix} x & x^2 + 1 \\ \frac{d}{dx}x & \frac{d}{dx}(x^2 + 1) \end{bmatrix} = \begin{bmatrix} x & x^2 - 1 \\ 1 & 2x \end{bmatrix}$$

and hence the Wronskian

$$W(x, x^2 + 1) = \begin{vmatrix} x & x^2 + 1 \\ 1 & 2x \end{vmatrix}$$

$$= (x)(2x) - (1)(x^2 + 1)$$

$$= x^2 - 1.$$

We also obtain

$$W_1 = \begin{vmatrix} 0 & x^2 + 1 \\ x^2 - 1 & 2x \end{vmatrix}$$

$$= (0)(2x) - (x^2 - 1)(x^2 + 1)$$

$$= -(x^2 - 1)(x^2 + 1)$$

and

$$W_2 = \begin{vmatrix} x & 0 \\ 1 & x^2 - 1 \end{vmatrix}$$

$$= (x)(x^2 - 1) - (1)(0)$$

$$= x(x^2 - 1).$$

So we have

$$v_1' = \frac{W_1}{W} = \frac{-(x^2 - 1)(x^2 + 1)}{x^2 - 1} = -x^2 - 1,$$
$$v_2' = \frac{W_2}{W} = \frac{x(x^2 - 1)}{x^2 - 1} = x,$$

which imply

$$v_1 = \int v_1' dx = \int -x^2 - 1 dx = -\frac{1}{3}x^3 - x,$$
$$v_2 = \int v_2' dx = \int x dx = \frac{1}{2}x^2,$$

respectively. So our particular solution is

$$y_p = v_1x + v_2(x^2 + 1)$$
$$= \left(-\frac{1}{3}x^3 - x\right)x + \frac{1}{2}x^2(x^2 + 1)$$
$$= \frac{1}{6}x^4 - \frac{1}{2}x^2.$$

Therefore,

$$y = y_h + y_p$$
$$= \boxed{C_1x + C_2(x^2 + 1) + \frac{1}{6}x^4 - \frac{1}{2}x^2}$$

is the general solution to the problem. □

3. Solve the initial value problem

$$y'' + y = x,$$
$$y(1) = 0,$$
$$y'(1) = 1.$$

Solution. We have already established in our solution to Exercise 1 that the homogeneous solution is

$$y_h = C_1 \cos(x) + C_2 \sin(x),$$

where C_1, C_2 are constants. We will find the particular solution y_p , which solves

$$y_p'' + y_p = x,$$

using the method of undetermined coefficients. The particular solution takes the form $y_p = Ax + B$, where A, B are constants. We obtain the derivatives

$$y_p' = A,$$
$$y_p'' = 0.$$

So we have

$$x = y_p'' + y_p$$
$$= 0 + (Ax + B)$$
$$= Ax + B,$$

from which we can equate the coefficients to deduce $A = 1$ and $B = -0$. So our particular solution is

$$y_p = Ax + B$$
$$= 1x + 0$$
$$= x.$$

Therefore, our general solution is

$$y = y_h + y_p$$
$$= C_1 \cos(x) + C_2 \sin(x) + x.$$

Next, we consider the initial conditions $y(1) = 0$ and $y'(1) = 1$. We recall

$$\begin{aligned}y &= C_1 \cos(x) + C_2 \sin(x) + x, \\y' &= -C_1 \sin(x) + C_2 \cos(x) + 1.\end{aligned}$$

At $x = 1$, this becomes

$$\begin{aligned}0 &= C_1 \cos(1) + C_2 \sin(1) + 1, \\1 &= -C_1 \sin(1) + C_2 \cos(1) + 1,\end{aligned}$$

from which we can solve simultaneously to obtain $C_1 = -\cos(1)$ and $C_2 = -\sin(1)$. Therefore,

$$\begin{aligned}y &= C_1 \cos(x) + C_2 \sin(x) + x \\&= -\cos(1) \cos(x) - \sin(1) \sin(x) + x \\&= -(\cos(1) \cos(x) + \sin(1) \sin(x)) + x \\&= -(\cos(-1) \cos(x) - \sin(-1) \sin(x)) + x \\&= -\cos(-1 + x) + x \\&= \boxed{x - \cos(x - 1)}\end{aligned}$$

is the solution to the initial value problem. □

4. A 20 lb weight is suspended from the end of a vertical spring having a spring constant of 40 lb/ft and is allowed to reach equilibrium. It is then set into motion by stretching the spring 2 in from its equilibrium position and releasing the mass from rest. Find the position of the weight at any time t if there is no external force and no air resistance.

Solution. The differential equation of free undamped motion is

$$\frac{d^2x}{dt^2} + \frac{k}{m}x = 0,$$

where, m is the mass and k is the spring constant. We are given that the spring constant of a vertical spring is $k = 40$ lb/ft. The mass can be found from the equation $W = mg$, where $W = 20$ lb is the weight and $g = 32$ ft/s² is the acceleration of gravity; we find

$$\begin{aligned}m &= \frac{W}{g} \\&= \frac{20 \text{ lb}}{32 \text{ ft/s}^2} \\&= \frac{5}{8} \text{ slug}.\end{aligned}$$

So our differential equation is

$$\frac{d^2x}{dt^2} + \frac{40}{\frac{5}{8}}x = 0,$$

or

$$\frac{d^2x}{dt^2} + 64x = 0.$$

Finally, by pulling a mass on a spring down 2 in = $\frac{1}{6}$ ft below the equilibrium position, holding it until $t = 0$, and then releasing it from rest, we obtain the initial conditions $x(0) = \frac{1}{6}$ and $x'(0) = 0$. So we have formulated the initial value problem

$$\begin{aligned}x'' + 64x &= 0, \\x(0) &= \frac{1}{6}, \\x'(0) &= 0.\end{aligned}$$

Now, we will now need to solve the initial value problem. Let $x = e^{\lambda t}$, where λ is a number. Then we obtain the first and second derivatives

$$\begin{aligned}x' &= \lambda e^{\lambda t}, \\x'' &= \lambda^2 e^{\lambda t}.\end{aligned}$$

So we have

$$\begin{aligned}0 &= x'' + 64x \\&= \lambda^2 e^{\lambda t} + 64e^{\lambda t} \\&= e^{\lambda t}(\lambda^2 + 64).\end{aligned}$$

Since we know $e^{\lambda x} \neq 0$, we must conclude $\lambda^2 + 64 = 0$, which gives the imaginary roots $\lambda_1 = 8i$ and $\lambda_2 = -8i$. So the general solution is

$$\begin{aligned}x(t) &= C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t} \\&= C_1 e^{8it} + C_2 e^{-8it} \\&= C_1 \cos(8t) + C_2 \sin(8t),\end{aligned}$$

where C_1, C_2 are constants. We also obtain the derivative

$$x'(t) = -C_1 \sin(8t) + C_2 \cos(8t).$$

Now, we can apply the initial condition $x(0) = \frac{1}{6}$ and $x'(0) = 0$ to deduce $C_1 = \frac{1}{6}$ and $C_2 = 0$. Therefore,

$$\begin{aligned}x(t) &= C_1 \cos(8t) + C_2 \sin(8t) \\&= \frac{1}{6} \cos(8t) + 0 \sin(8t) \\&= \boxed{\frac{1}{6} \cos(8t)},\end{aligned}$$

is the solution to the initial value problem.

□