

July. 08 Monday.

3A. The vector space of linear maps.

3.2 Definition

A linear map from V to W is a function

$T: V \rightarrow W$ that satisfies:

- additivity.

$$T(u+v) = T(u) + T(v) \quad \text{for all } u, v \in V$$

- homogeneity.

$$T(\lambda v) = \lambda T(v) \quad \text{for all } v \in V, \lambda \in \mathbb{F}$$

The set of all linear maps $T: V \rightarrow W$
is denoted $\mathcal{L}(V, W)$

3.4 Examples

Let 0 be the zero map defined by $0(v) = 0$.

$$0 \in \mathcal{L}(V, W)$$

that is, 0 is a linear map because:

- additivity: If $u, v \in V$, then

$$0(u+v) = 0$$

$$= 0 + 0$$

$$= 0u + 0v$$

- homogeneity: If $u \in V$ and $\lambda \in \mathbb{F}$, then

$$0(\lambda u) = 0$$

$$= \lambda \cdot 0$$

$$= \lambda T(u)$$

★ identity map:

Define $I: V \rightarrow V$ by $Iv = v$

Then $I \in \mathcal{L}(V, V)$ because

• additivity: If $u, v \in V$, then

$$I(u+v) = u+v$$

$$= Iu + Iv$$

• homogeneity: If $\lambda \in \mathbb{F}$ and $v \in V$, then

$$I(\lambda v) = \lambda v$$

$$= \lambda I(v)$$

★ Differentiation:

Define $D: P(\mathbb{R}) \rightarrow P(\mathbb{R})$ by

$$Dp = p'$$

Then $D \in \mathcal{L}(P(\mathbb{R}), P(\mathbb{R}))$ because:

additivity: If $p, q \in P(\mathbb{R})$, then

$$D(p+q) = (p+q)'$$

$$= p' + q'$$

$$= Dp + Dq$$

homogeneity: if $\lambda \in \mathbb{F}$, $p \in P(\mathbb{R})$, then

$$D(\lambda p) = (\lambda p)'$$

$$= \lambda D(p)$$

★ Integration:

Define $T: P(\mathbb{R}) \rightarrow \mathbb{R}$ by

$$Tp = \int_0^1 p(x) dx$$

Then we have $T \in \mathcal{L}(P(\mathbb{R}), \mathbb{R})$ because:

• Additivity: If $p, q \in P(\mathbb{R})$, then

$$\begin{aligned} T(p+q) &= \int_0^1 (p+q)(x) dx \\ &= \int_0^1 p(x) + q(x) dx \\ &= \int_0^1 p(x) dx + \int_0^1 q(x) dx \\ &= T_p + T_q \end{aligned}$$

• Homogeneity: If $\lambda \in \mathbb{F}$ and $p \in P(\mathbb{R})$, then

$$\begin{aligned} T(\lambda p) &= \int_0^1 (\lambda p)(x) dx \\ &= \int_0^1 \lambda p(x) dx \\ &= \lambda \int_0^1 p(x) dx \\ &= \lambda T_p \end{aligned}$$

★ • Multiplication by x^2

Define: $T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$ by $(T_p)(x) = x^2 p(x)$

for all $x \in \mathbb{R}$. Then $T \in \mathcal{L}(P(\mathbb{R}), P(\mathbb{R}))$ because:

• Additivity: If $p, q \in P(\mathbb{R})$, then for all $x \in \mathbb{R}$, we have

$$\begin{aligned} (T(p+q))(x) &= x^2 (p+q)(x) \\ &= x^2 (p(x) + q(x)) \\ &= x^2 p(x) + x^2 q(x) \\ &= (T_p)(x) + (T_q)(x) \\ &= ((T_p) + (T_q))(x) \end{aligned}$$

$$\therefore T(p+q) = T_p + T_q.$$

• Homogeneity: If $\lambda \in \mathbb{F}$, and $p \in P(\mathbb{R})$, then for all $x \in \mathbb{R}$, we have

$$\begin{aligned} (T(\lambda p))(x) &= x^2 (\lambda p)(x) \\ &= x^2 (\lambda p(x)) \\ &= \lambda x^2 p(x) \\ &= \lambda (T_p)(x) \end{aligned}$$

★ From \mathbb{R}^3 to \mathbb{R}^2 : Define $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by

$$T(x, y, z) = (2x - y + 3z, 7x + 5y - 6z).$$

Then $T \in \mathcal{L}(\mathbb{R}^3, \mathbb{R}^2)$ because:

• additivity: If $(x, y, z), (\tilde{x}, \tilde{y}, \tilde{z}) \in \mathbb{R}^3$, then

$$T((x, y, z) + (\tilde{x}, \tilde{y}, \tilde{z})) = T(x + \tilde{x}, y + \tilde{y}, z + \tilde{z})$$

$$= (2(x + \tilde{x}) - (y + \tilde{y}) + 3(z + \tilde{z}), 7(x + \tilde{x}) + 5(y + \tilde{y}) - 6(z + \tilde{z}))$$

$$= (2x - y + 3z) + (2\tilde{x} - \tilde{y} + 3\tilde{z}), (7x + 5y - 6z) + (7\tilde{x} + 5\tilde{y} - 6\tilde{z})$$

$$= T(x, y, z) + T(\tilde{x}, \tilde{y}, \tilde{z})$$

• homogeneity: If $\lambda \in \mathbb{F}$ and $(x, y, z) \in \mathbb{R}^3$, then

$$T(\lambda(x, y, z)) = T(\lambda x, \lambda y, \lambda z)$$

=

3.5 Linear maps and basis of domain

Suppose v_1, \dots, v_n is a basis of V and $w_1, \dots, w_n \in W$.

Then there exists a unique linear map $T: V \rightarrow W$ s.t.

$$T v_j = w_j \quad \text{for each } j = 1, \dots, n$$

Proof:

First, we will prove that the linear map T exists.

Define $T: V \rightarrow W$ by

$$T(c_1 v_1 + \dots + c_n v_n) = c_1 w_1 + \dots + c_n w_n.$$

for some $c_1, \dots, c_n \in \mathbb{F}$, Since v_1, \dots, v_n is a basis of V , every vector in V is uniquely of the form $c_1 v_1 + \dots + c_n v_n$. So this map T as we defined above indeed define a function $T: V \rightarrow W$.

Furthermore, for each $j=1, \dots, n$ if

$$c_j = \begin{cases} 1 & \text{if } j=i \\ 0 & \text{if } j \neq i \end{cases}$$

then, T satisfies $T v_j = w_j$.

Next, we will prove that T is linear, that is, $T \in \mathcal{L}(V, W)$.

• additivity: If $u, v \in V$, then since v_1, \dots, v_n is a basis of V , we can write

$$u = a_1 v_1 + \dots + a_n v_n \quad \text{and}$$

$$v = c_1 v_1 + \dots + c_n v_n$$

for some $a_1, \dots, a_n, c_1, \dots, c_n \in \mathbb{F}$, So we have

$$\begin{aligned} T(u+v) &= T((a_1 v_1 + \dots + a_n v_n) + (c_1 v_1 + \dots + c_n v_n)) \\ &= T((a_1 + c_1) v_1 + \dots + (a_n + c_n) v_n) \\ &= (a_1 + c_1) w_1 + \dots + (a_n + c_n) w_n \\ &= (a_1 w_1 + c_1 w_1) + \dots + (a_n w_n + c_n w_n) \\ &= (a_1 w_1 + \dots + a_n w_n) + (c_1 w_1 + \dots + c_n w_n) \\ &= T(a_1 v_1 + \dots + a_n v_n) + T(c_1 v_1 + \dots + c_n v_n) \\ &= Tu + Tv. \end{aligned}$$

• Homogeneity: If $\lambda \in \mathbb{F}$ and $v \in V$, then we can write

$$v = c_1 v_1 + \dots + c_n v_n$$

for some $c_1, \dots, c_n \in \mathbb{F}$. So we have

$$\begin{aligned}
T(\lambda v) &= T(\lambda(c_1 v_1 + \dots + c_n v_n)) \\
&= T(\lambda c_1 v_1 + \dots + \lambda c_n v_n) \\
&= (\lambda c_1) w_1 + \dots + (\lambda c_n) w_n \\
&= \lambda c_1 w_1 + \dots + \lambda c_n w_n \\
&= \lambda(c_1 w_1 + \dots + c_n w_n) \\
&= \lambda T(c_1 v_1 + \dots + c_n v_n) \\
&= \lambda T v
\end{aligned}$$

$\therefore T: V \rightarrow W$ satisfies additivity and homogeneity
 $\therefore T \in \mathcal{L}(V, W)$

Finally, we need to prove that T is unique.

Suppose we have $T \in \mathcal{L}(V, W)$ and T satisfies $T v_j = w_j$ for each $j=1, \dots, n$.

Let $c_1, \dots, c_n \in \mathbb{F}$, then the homogeneity and additivity of T give us:

$$\begin{aligned}
T(c_1 v_1 + \dots + c_n v_n) &= T(c_1 v_1) + \dots + T(c_n v_n) \\
&= c_1 T v_1 + \dots + c_n T v_n \\
&= c_1 w_1 + \dots + c_n w_n
\end{aligned}$$

So T is uniquely determined on $\text{span}(v_1, \dots, v_n)$

But v_1, \dots, v_n is a basis of V , meaning we have $\text{span}(v_1, \dots, v_n) = V$

So T is uniquely determined on V .

Addition and scalar multiplication on $\mathcal{L}(V, W)$

3.6 Definition

Suppose $S, T \in \mathcal{L}(V, W)$ and $\lambda \in \mathbb{F}$

- The sum $S+T$ is a linear map defined by $(S+T)(v) = Sv + Tv$.
- The product λT is a linear map defined by $(\lambda T)(v) = \lambda(Tv)$

3.7 $\mathcal{L}(V, W)$ is a vector space

The set $\mathcal{L}(V, W)$ is a vector space with respect to the operations defined in Definition 3.6 of Axler.

Proof: Let $R, S, T \in \mathcal{L}(V, W)$ and $\lambda \in \mathbb{F}$ be arbitrary.

• Commutativity:

For all $v \in V$, we have

$$\begin{aligned}(S+T)v &= Sv + Tv \\ &= Tv + Sv \\ &= (T+S)v\end{aligned}$$

$$\therefore S+T = T+S$$

• Associativity:

For all $v \in V$, we have:

$$\begin{aligned}((R+S)+T)v &= (R+S)v + Tv \\ &= Rv + Sv + Tv \\ &= Rv + (S+T)v \\ &= (R+(S+T))v\end{aligned}$$

$$\therefore (R+S)+T = R+(S+T)$$

• Additive identity:

Let $0 \in \mathcal{L}(V, W)$ be the zero function. For all $v \in V$, we

$$\begin{aligned}\text{have. } (T+0)v &= Tv + 0v \\ &= Tv + 0\end{aligned}$$

$$= Tv$$

$$\text{so } T+0=T$$

• Additive inverse:

Note that we have $-T \in \mathcal{L}(V, W)$. For all $v \in V$, we have

$$(T+(-T))v = Tv + (-T)v$$

$$= Tv - Tv$$

$$= 0$$

$$= 0v$$

$$\therefore T+(-T)=0$$

• Multiplicative identity:

For all $v \in V$, we have:

$$(1T)v = 1Tv$$

$$= Tv$$

$$\therefore 1T=T$$

• Distributive properties:

For all $a \in \mathbb{F}$, all $v \in V$, we have:

$$(a(S+T))v = a(Sv + Tv)$$

$$= aSv + aTv$$

$$= (aS+aT)v$$

$$\therefore a(S+T) = aS+aT$$

For all $a, b \in \mathbb{F}$, for all $v \in V$, we have

$$((a+b)T)v = (a+b)Tv$$

$$= aTv + bTv$$

$$= (aT+bT)v.$$

$$\therefore (a+b)T = aT+bT$$

Therefore, $\mathcal{L}(V, W)$ is a vector space with respect to the defined operations.

3.8 Definition

If $S \in \mathcal{L}(V, W)$, $T \in \mathcal{L}(V, W)$, then the product $ST \in \mathcal{L}(V, W)$ is defined by $(ST)u = S(Tu)$ for all $u \in V$,

3.9 Algebraic properties of products of linear maps.

- Associativity

If R, S, T are linear maps such that the product RST makes sense, then $(RS)T = R(ST)$

- Identity

If $T \in \mathcal{L}(V, W)$ and $I: V \rightarrow V$ is an identity map, then $T \cdot I = T = IT$

- Distributive properties

If $T, T_1, T_2 \in \mathcal{L}(U, V)$ and $S, S_1, S_2 \in \mathcal{L}(V, W)$, then

$$(S_1 + S_2)T = S_1T + S_2T \quad \text{and}$$

$$S(T_1 + T_2) = ST_1 + ST_2$$

3.11 Linear maps take 0 to 0 .

If $T \in \mathcal{L}(V, W)$, then $T(0) = 0$.

Proof: Since T is linear, we can use addition to get

$$T(0) = T(0 + 0)$$

$$= T(0) + T(0)$$

$$= 2T(0)$$

$\therefore T(0) = 0$, as desired.