

Since we introduced u_1, \dots, u_m to be a basis of $U \cap U_2$, we can write

$$c_1 w_1 + \dots + c_k w_k = d_1 u_1 + \dots + d_m u_m$$

for some $d_1, \dots, d_m \in \mathbb{F}$. This means

$$c_1 w_1 + \dots + c_k w_k - d_1 u_1 - \dots - d_m u_m = 0$$

Since $u_1, \dots, u_m, w_1, \dots, w_k$ is lin indep, all the scalars are zero; $c_1 = 0, \dots, c_k = 0, d_1 = 0, \dots, d_m = 0$. In particular

$$c_1 = 0, \dots, c_k = 0.$$

So the original eqn,

$$a_1 u_1 + \dots + a_m u_m + b_1 v_1 + \dots + b_j v_j + c_1 w_1 + \dots + c_k w_k = 0$$

reduces to

$$a_1 u_1 + \dots + a_m u_m + b_1 v_1 + \dots + b_j v_j = 0$$

Since $u_1, \dots, u_m, v_1, \dots, v_j$ is a basis of U_1 , it is lin indep, so $a_1 = 0, \dots, a_m = 0, b_1 = 0, \dots, b_j = 0$.

So all scalars are zero. So $u_1, \dots, u_m, v_1, \dots, v_j, w_1, \dots, w_k$ is lin indep. Then by 2.39 of Axler, it is also a basis of $U_1 + U_2$.

Therefore, we have

$$\begin{aligned} \dim(U_1 + U_2) &= m + j + k \\ &= (m + j) + (m + k) - m \\ &= \dim U_1 + \dim U_2 - \dim(U_1 \cap U_2) \end{aligned}$$

7/8/19 week 3 Mon.

3.1 The vector space of linear maps

3.2 definition: A linear map from V to W is a function $T: V \rightarrow W$ that satisfies:

• additivity

$$T(u+v) = Tu + Tv \text{ for all } u, v \in V$$

• homogeneity

$$T(\lambda v) = \lambda Tv \text{ for all } \lambda \in \mathbb{F} \text{ \& for all } v \in V$$

The set of all linear maps $T: V \rightarrow W$ is denoted $\mathcal{L}(V, W)$.

3.4 Example: Let 0 be the zero map defined by $0v = 0$.
 $0 \in \mathcal{L}(V, W)$ that is 0 is a linear map b/c:

additivity: If $u, v \in V$, then $0(u+v) = 0$
 $= 0 + 0$

homogeneity: If $u \in V$ & $\lambda \in \mathbb{F}$ then $0(\lambda u) = 0$
 $= \lambda \cdot 0$
 $= \lambda \cdot 0(u)$

• identity maps

define $I: V \rightarrow V$ by
 $Iv = v$

Then $I \in \mathcal{L}(V, V)$ b/c:

additivity: if $u, v \in V$, then

$$I(u+v) = u+v$$

$$= Iu + Iv$$

homogeneity: if $\lambda \in F$ & $v \in V$, then

$$I(\lambda v) = \lambda v$$

$$= \lambda Iv$$

• Differentiation

Define $D: P(\mathbb{R}) \rightarrow P(\mathbb{R})$ by

$$Dp = p'$$

Then $D \in \mathcal{L}(P(\mathbb{R}), P(\mathbb{R}))$ because:

additivity: if $p, q \in P(\mathbb{R})$, then

$$D(p+q) = (p+q)'$$

$$= p' + q'$$

$$= Dp + Dq$$

homogeneity: if $\lambda \in F$ & $p \in P(\mathbb{R})$ then

$$D(\lambda p) = (\lambda p)'$$

$$= \lambda p'$$

$$= \lambda Dp$$

• Integration:

Define $T: P(\mathbb{R}) \rightarrow \mathbb{R}$ by

$$Tp = \int_0^1 p(x) dx$$

Then we have $T \in \mathcal{L}(P(\mathbb{R}), \mathbb{R})$ b/c:

additivity: if $p, q \in P(\mathbb{R})$, then

$$T(p+q) = \int_0^1 (p+q)(x) dx$$

$$= \int_0^1 p(x) + q(x) dx$$

$$= \int_0^1 p(x) dx + \int_0^1 q(x) dx$$

$$= Tp + Tq$$

Homogeneity: if $\lambda \in F$ & $p \in P(\mathbb{R})$, then $T(\lambda p) = \int_0^1 (\lambda p)(x) dx =$

$$\int_0^1 \lambda p(x) dx = \lambda \int_0^1 p(x) dx = \lambda Tp.$$

Multiplication by x^2

Define $T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$ by $(Tp)(x) = x^2 p(x)$ for all $x \in \mathbb{R}$. Then

$T \in \mathcal{L}(P(\mathbb{R}), P(\mathbb{R}))$ b/c:

additivity: if $p, q \in P(\mathbb{R})$, then for all $x \in \mathbb{R}$, we have

$$(T(p+q))(x) = x^2(p+q)(x)$$

$$= x^2(p(x) + q(x))$$

$$= x^2 p(x) + x^2 q(x)$$

$$= (Tp)(x) + (Tq)(x)$$

$$= ((Tp) + (Tq))(x)$$

So $T(p+q) = Tp + Tq$

homogeneity: If $\lambda \in \mathbb{F}$ & $p \in P(\mathbb{R})$, then for $x \in \mathbb{R}$ we have

$$\begin{aligned} (T(\lambda p))(x) &= x^2(\lambda p)(x) \\ &= x^2(\lambda p(x)) \\ &= \lambda x^2 p(x) \\ &= \lambda (Tp)(x) \end{aligned}$$

• From \mathbb{R}^3 to \mathbb{R}^2 : Define $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by

$$T(x, y, z) = (2x - y + 3z, 7x + 5y - 6z)$$

Then $T \in \mathcal{L}(\mathbb{R}^3, \mathbb{R}^2)$ b/c:

Additivity: If $(x, y, z), (\tilde{x}, \tilde{y}, \tilde{z}) \in \mathbb{R}^3$, then

$$\begin{aligned} T((x, y, z) + (\tilde{x}, \tilde{y}, \tilde{z})) &= T(x + \tilde{x}, y + \tilde{y}, z + \tilde{z}) \\ &= (2(x + \tilde{x}) - (y + \tilde{y}) + 3(z + \tilde{z}), 7(x + \tilde{x}) + 5(y + \tilde{y}) - 6(z + \tilde{z})) \\ &= ((2x - y + 3z) + (2\tilde{x} - \tilde{y} + 3\tilde{z}), (7x + 5y - 6z) + (7\tilde{x} + 5\tilde{y} - 6\tilde{z})) \\ &= (2x - y + 3z, 7x + 5y - 6z) + (2\tilde{x} - \tilde{y} + 3\tilde{z}, 7\tilde{x} + 5\tilde{y} - 6\tilde{z}) \\ &= T(x, y, z) + T(\tilde{x}, \tilde{y}, \tilde{z}) \end{aligned}$$

Homogeneity: If $\lambda \in \mathbb{F}$ & $(x, y, z) \in \mathbb{R}^3$, then

$$\begin{aligned} T(\lambda(x, y, z)) &= T(\lambda x, \lambda y, \lambda z) \\ &= (2(\lambda x) - (\lambda y) + 3(\lambda z), 7(\lambda x) + 5(\lambda y) - 6(\lambda z)) \end{aligned}$$

3.5 Linear Maps & basis of Domain

Suppose v_1, \dots, v_n is a basis of V & $w_1, \dots, w_n \in W$

Then there exists a unique linear map $T: V \rightarrow W$ such that

$$T v_j = w_j \text{ for each } j = 1, \dots, n$$

Proof: First, we will prove that the linear map T exists.

Define $T: V \rightarrow W$ by

$$T(c_1 v_1 + \dots + c_n v_n) = c_1 w_1 + \dots + c_n w_n \text{ for some } c_1, \dots, c_n \in \mathbb{F}$$

Since v_1, \dots, v_n is a basis of V , every vector in V is uniquely of the form $c_1 v_1 + \dots + c_n v_n$. So this map T as we defined above indeed define a function $T: V \rightarrow W$

Furthermore for each $j = 1, \dots, n$, if $c_j = \begin{cases} 1 & \text{if } j = i \\ 0 & \text{if } j \neq i \text{ (otherwise)} \end{cases}$ then T satisfies $T v_j = w_j$

Next we will prove that T is linear; that is $T \in \mathcal{L}(V, W)$.

• Additivity: If $u, v \in V$, then since v_1, \dots, v_n is a basis of V , we can write $u = a_1 v_1 + \dots + a_n v_n$ & $v = c_1 v_1 + \dots + c_n v_n$ for some $a_1, \dots, a_n, c_1, \dots, c_n \in \mathbb{F}$, so we have $T(u+v) =$

$$\begin{aligned} &T((a_1 v_1 + \dots + a_n v_n) + (c_1 v_1 + \dots + c_n v_n)) \\ &= T((a_1 + c_1) v_1 + \dots + (a_n + c_n) v_n) \\ &= (a_1 + c_1) w_1 + \dots + (a_n + c_n) w_n \\ &= (a_1 w_1 + c_1 w_1) + \dots + (a_n w_n + c_n w_n) \end{aligned}$$

$$\begin{aligned}
&= (a_1 w_1 + \dots + a_n w_n) + (c_1 w_1 + \dots + c_n w_n) \\
&= T(a_1 v_1 + \dots + a_n v_n) + T(c_1 v_1 + \dots + c_n v_n) \\
&= T u + T v
\end{aligned}$$

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Homogeneity: If $\lambda \in F$ & $v \in V$, then we can write

$v = c_1 v_1 + \dots + c_n v_n$ for some $c_1, \dots, c_n \in F$. So we have

$$\begin{aligned}
T(\lambda v) &= T(\lambda(c_1 v_1 + \dots + c_n v_n)) \\
&= T((\lambda c_1) v_1 + \dots + (\lambda c_n) v_n) \\
&= (\lambda c_1) w_1 + \dots + (\lambda c_n) w_n \\
&= \lambda c_1 w_1 + \dots + \lambda c_n w_n \\
&= \lambda(c_1 w_1 + \dots + c_n w_n) \\
&= \lambda T(c_1 v_1 + \dots + c_n v_n) \\
&= \lambda T v
\end{aligned}$$

Finally we need to prove that T is unique. Suppose we have $T \in \mathcal{L}(V, W)$ & T satisfies $T v_j = w_j$ for each $j = 1, \dots, n$. Let $c_1, \dots, c_n \in F$, then the additivity & homogeneity of T gives us:

$$\begin{aligned}
T(c_1 v_1 + \dots + c_n v_n) &= T(c_1 v_1) + \dots + T(c_n v_n) \\
&\stackrel{\text{additivity}}{=} c_1 T v_1 + \dots + c_n T v_n \\
&\stackrel{\text{homogeneity}}{=} c_1 T v_1 + \dots + c_n T v_n \\
&= c_1 w_1 + \dots + c_n w_n
\end{aligned}$$

So T is uniquely determined on $\text{span}(v_1, \dots, v_n)$. But v_1, \dots, v_n is a basis of V , meaning we have $\text{span}(v_1, \dots, v_n) = V$, so T is uniquely determined on V .

3.6 Definition

Addition & scalar multi. on $\mathcal{L}(V, W)$

Suppose $S, T \in \mathcal{L}(V, W)$ & $\lambda \in F$

- The sum $S+T$ is a linear map defined by $(S+T)(v) = S v + T v$
- The product λT is a linear map defined by $(\lambda T)(v) = \lambda(T v)$

3.7 $\mathcal{L}(V, W)$ is a vector space

The set $\mathcal{L}(V, W)$ is a vector space w/ respect to the operations defined in Def. 3.6 of $\mathcal{L}(V, W)$

Proof: Let $\lambda, \mu \in F, S, T \in \mathcal{L}(V, W)$ & $a, b \in F$ be arbitrary

commutativity for all $v \in V$, we have

$$\begin{aligned}
(S+T)v &= S v + T v \\
&= T v + S v \\
&= (T+S)v
\end{aligned}$$

So $S+T = T+S$

Associativity

For all $v \in V$, we have

$$\begin{aligned}((R+S)+T)v &= (R+S)v + Tv \\ &= Rv + Sv + Tv \\ &= Rv + (S+T)v \\ &= (R+(S+T))v \quad \text{so } (R+S)+T = R+(S+T).\end{aligned}$$

Additive Identity

Let $0 \in \mathcal{L}(V, W)$ be the zero function. For all $v \in V$, we have

$$\begin{aligned}(T+0)v &= Tv + 0v \\ &= Tv + 0 \\ &= Tv \quad \text{so } T+0 = T\end{aligned}$$

Add. Inverse

Note that we have $-T \in \mathcal{L}(V, W)$. For all $v \in V$, we have

$$\begin{aligned}(T+(-T))v &= Tv + (-T)v \\ &= Tv - Tv \\ &= 0 \\ &= 0v \quad \text{so } T+(-T) = 0\end{aligned}$$

Multiplicative Identity

For all $v \in V$, we have

$$\begin{aligned}(1T)v &= 1Tv \\ &= Tv \\ \text{so } 1T &= T\end{aligned}$$

Distributive Property

for all $a \in \mathbb{F}$, for all $v \in V$, we have

$$\begin{aligned}(a(S+T))v &= a(Sv + Tv) \\ &= aSv + aTv \\ &= (aS + aT)v \\ \text{so } a(S+T) &= aS + aT\end{aligned}$$

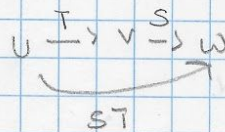
for all $a, b \in \mathbb{F}$, for all $v \in V$, we have

$$\begin{aligned}((a+b)T)v &= (a+b)Tv \\ &= aTv + bTv \\ &= (aT + bT)v \\ \text{so } (a+b)T &= aT + bT\end{aligned}$$

Therefore, $\mathcal{L}(V, W)$ is a vector space w/ respect to the defined operations.

§.8 Definition

If $S \in \mathcal{L}(V, W)$, $T \in \mathcal{L}(U, V)$, then the product $ST \in \mathcal{L}(U, W)$ is defined by $(ST)u = S(Tu)$ for all $u \in U$



3.9 Algebraic Prop. of products of linear maps

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• Associativity

If R, S, T are linear maps such that the product RST makes sense, then $(RS)T = R(ST)$

• Identity

If $T \in \mathcal{L}(V, W)$ & $I : V \rightarrow V$ is an Identity map, then $TI = T = I$

• Distributive

If $T, T_1, T_2 \in \mathcal{L}(U, V)$ & $S, S_1, S_2 \in \mathcal{L}(V, W)$, then
 $(S_1 + S_2)T = S_1T + S_2T$ & $S(T_1 + T_2) = ST_1 + ST_2$

3.11 Linear maps take 0 to 0

If $T \in \mathcal{L}(V, W)$, then $T(0) = 0$

Proof: since T is linear, we can use additivity to get

$$\begin{aligned} T(0) &= T(0+0) \\ &= T(0) + T(0) \\ &= 2T(0) \end{aligned}$$

Therefore $T(0) = 0$, as defined.

7/9/19 week 3 Tues.

3.B Null Spaces & Ranges

3.12 Definition

If we have $T \in \mathcal{L}(V, W)$, then the null space of T is the subset of V consisting of vectors in V that T maps to 0 : $\text{null } T = \{v \in V : Tv = 0\}$

3.13 example

• consider the zero map $0 \in \mathcal{L}(V, W)$. For all $v \in V$, we have $0v = 0$.

Therefore, $\text{null } 0 = \{v \in V : 0v = 0\}$
 $= V$

• Define $P \in \mathcal{L}(\mathbb{R}^3, \mathbb{R})$ by $P(z_1, z_2, z_3) = z_1 + 2z_2 + 3z_3$

Then we have

$$\begin{aligned} \text{null } P &= \{(z_1, z_2, z_3) \in \mathbb{R}^3 : P(z_1, z_2, z_3) = 0\} \\ &= \{(z_1, z_2, z_3) \in \mathbb{R}^3 : z_1 + 2z_2 + 3z_3 = 0\} \end{aligned}$$

The basis of $\text{null } P$ is $(-2, 1, 0)$, $(-3, 0, 1)$