

3.A The Vector Space of Linear Maps

3.2 Definition

A linear map from V to W is a function $T: V \rightarrow W$ that satisfies:

- additivity: $T(u+v) = Tu + Tv$ for all $u, v \in V$
- homogeneity: $T(\lambda u) = \lambda Tu$ for all $\lambda \in \mathbb{F}$ and for all $u \in V$.

The set of all linear maps $T: V \rightarrow W$ is denoted $L(V, W)$.

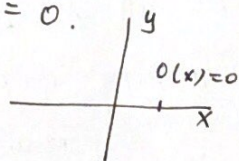
3.4 Examples:

(1) Zero map: Let $0 \in L(V, W)$ be the zero map, defined by $0v = 0$.

~~Let~~ $0 \in L(V, W)$

this is, 0 is a linear map because:

- additivity: If $u, v \in V$, then
$$\begin{aligned} 0(u+v) &= 0 \\ &= 0 + 0 \\ &= 0u + 0v \end{aligned}$$
- homogeneity: If $u \in V$ and $\lambda \in \mathbb{F}$, then
$$\begin{aligned} 0(\lambda u) &= 0 \\ &= \lambda \cdot 0 \\ &= \lambda 0u. \end{aligned}$$



(2) Identity map: Define $I: V \rightarrow V$ by $Iu = u$.

Then $I \in L(V, V)$ because:

• additivity: If $u, v \in V$, then

$$I(u+v) = u+v$$

$$= Iu + Iv$$

• homogeneity: If $\lambda \in \mathbb{F}$ and $u \in V$, then

$$I(\lambda u) = \lambda u$$

$$= \lambda Iu.$$

(3) Differentiation.

Define $D: P(\mathbb{R}) \rightarrow P(\mathbb{R})$ by $Dp = p'$.

Then $D \in L(P(\mathbb{R}), P(\mathbb{R}))$ because

• additivity: If $p, q \in P(\mathbb{R})$, then

$$\begin{aligned} D(p+q) &= (p+q)' \\ &= p' + q' \\ &= Dp + Dq \end{aligned}$$

• homogeneity: If $\lambda \in \mathbb{F}$ and $p \in P(\mathbb{R})$, then

$$\begin{aligned} D(\lambda p) &= (\lambda p)' \\ &= \lambda p' \\ &= \lambda Dp \end{aligned}$$

(4) Integration.

Define $T: P(\mathbb{R}) \rightarrow \mathbb{R}$ by $Tp = \int_0^1 p(x) dx$.

Then we have $T \in L(P(\mathbb{R}), \mathbb{R})$ because:

• Additivity: If $p, q \in P(\mathbb{R})$, then

$$\begin{aligned} T(p+q) &= \int_0^1 (p+q)(x) dx \\ &= \int_0^1 p(x) + q(x) dx \\ &= \int_0^1 p(x) dx + \int_0^1 q(x) dx \\ &= Tp + Tq. \end{aligned}$$

• Homogeneity: If $\lambda \in \mathbb{F}$ and $p \in P(\mathbb{R})$, then

$$\begin{aligned} T(\lambda p) &= \int_0^1 (\lambda p)(x) dx \\ &= \int_0^1 \lambda p(x) dx \\ &= \lambda \int_0^1 p(x) dx \\ &= \lambda Tp. \end{aligned}$$

(5) Multiplication by x^2 .

Define $T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$ by $(Tp)(x) = x^2 p(x)$.

For all $x \in \mathbb{R}$. Then $T \in L(P(\mathbb{R}), P(\mathbb{R}))$ because:

• Additivity: If $p, q \in P(\mathbb{R})$, then

For all $x \in \mathbb{R}$, we have

$$\begin{aligned} (T(p+q))(x) &= x^2 (p+q)(x) & \text{So } T(p+q) \\ &= x^2 (p(x) + q(x)) &= Tp + Tq \\ &= x^2 p(x) + x^2 q(x) \\ &= (Tp)(x) + (Tq)(x) = (Tp + Tq)(x) \end{aligned}$$

• Homogeneity: If $\lambda \in \mathbb{F}$ and $p \in P(\mathbb{R})$, then, for all $x \in \mathbb{R}$, we have

$$\begin{aligned} (T(\lambda p))(x) &= x^2 (\lambda p)(x) \\ &= x^2 (\lambda p(x)) \\ &= \lambda x^2 p(x) \\ &= \lambda (Tp)(x) \end{aligned}$$

(6) From $\mathbb{R}^3$ to $\mathbb{R}^2$:

Define $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ by $T(x, y, z) = (2x - y + 3z, 7x + 5y - 6z)$

Then $T \in L(\mathbb{R}^3, \mathbb{R}^2)$ because:

• Additivity: If $(x, y, z), (\tilde{x}, \tilde{y}, \tilde{z}) \in \mathbb{R}^3$, then

$$\begin{aligned} T(x, y, z) + T(\tilde{x}, \tilde{y}, \tilde{z}) &= T(x + \tilde{x}, y + \tilde{y}, z + \tilde{z}) \\ &= (2(x + \tilde{x}) - (y + \tilde{y}) + 3(z + \tilde{z}), 7(x + \tilde{x}) + 5(y + \tilde{y}) - 6(z + \tilde{z})) \\ &= ((2x - y + 3z) + (2\tilde{x} - \tilde{y} + 3\tilde{z}), (7x + 5y - 6z) + (7\tilde{x} + 5\tilde{y} - 6\tilde{z})) \\ &= (2x - y + 3z, 7x + 5y - 6z) + (2\tilde{x} - \tilde{y} + 3\tilde{z}, 7\tilde{x} + 5\tilde{y} - 6\tilde{z}) \\ &= T(x, y, z) + T(\tilde{x}, \tilde{y}, \tilde{z}). \end{aligned}$$

• Homogeneity: If $\lambda \in \mathbb{F}$ and $(x, y, z) \in \mathbb{R}^3$, then

$$\begin{aligned} T(\lambda(x, y, z)) &= T(\lambda x, \lambda y, \lambda z) \\ &= (2(\lambda x) - (\lambda y) + 3(\lambda z), 7(\lambda x) + 5(\lambda y) - 6(\lambda z)) \\ &= (\lambda(2x - y + 3z), \lambda(7x + 5y - 6z)) \\ &= \lambda(2x - y + 3z, 7x + 5y - 6z) \\ &= \lambda T(x, y, z). \end{aligned}$$

3.5 Linear maps and basis of domain

Suppose $v_1, \dots, v_n$ is a basis of V and $w_1, \dots, w_n \in W$

then there exists a unique linear map $T: V \rightarrow W$ such that

$$T v_j = w_j \quad \text{for each } j = 1, \dots, n.$$

Proof: First, we will prove that the linear map T exists.

Define $T: V \rightarrow W$ by $T(c_1 v_1 + \dots + c_n v_n) = c_1 w_1 + \dots + c_n w_n$.

for some $c_1, \dots, c_n \in \mathbb{F}$. Since $v_1, \dots, v_n$ is a basis of V , every vector in V is uniquely of the form $c_1 v_1 + \dots + c_n v_n$.

So this map T as we defined above indeed defines a function $T: V \rightarrow W$.

Furthermore, for each $j = 1, \dots, n$,

$$g_j = \begin{cases} 1 & \text{if } j = i \\ 0 & \text{if } j \neq i \end{cases} \quad (\text{otherwise}),$$

then T satisfies $Tg_j = w_j$.

Next, we will prove that T is linear, this is $T \in L(V, W)$.

• Additivity: If $u, v \in V$, then since $v_1, \dots, v_n$ is a basis of V , we can write

$$u = a_1 v_1 + \dots + a_n v_n$$

and

$$v = c_1 v_1 + \dots + c_n v_n$$

for some $a_1, \dots, a_n, c_1, \dots, c_n \in F$. So we have

$$\begin{aligned} T(u+v) &= T(a_1 v_1 + \dots + a_n v_n + c_1 v_1 + \dots + c_n v_n) \\ &= T((a_1 + c_1)v_1 + \dots + (a_n + c_n)v_n) \\ &= (a_1 + c_1)w_1 + \dots + (a_n + c_n)w_n \\ &= (a_1 w_1 + c_1 w_1) + \dots + (a_n w_n + c_n w_n) \\ &= (a_1 w_1 + \dots + a_n w_n) + (c_1 w_1 + \dots + c_n w_n) \\ &= T(a_1 v_1 + \dots + a_n v_n) + T(c_1 v_1 + \dots + c_n v_n) \\ &= Tu + Tv. \end{aligned}$$

• Homogeneity: If $\lambda \in F$ and $v \in V$ then we can write

$$v = c_1 v_1 + \dots + c_n v_n$$

for some $c_1, \dots, c_n \in F$. So we have

$$\begin{aligned} T(\lambda v) &= T(\lambda(c_1 v_1 + \dots + c_n v_n)) \\ &= T((\lambda c_1)v_1 + \dots + (\lambda c_n)v_n) \\ &= (\lambda c_1)w_1 + \dots + (\lambda c_n)w_n \\ &= \lambda c_1 w_1 + \dots + \lambda c_n w_n \\ &= \lambda(c_1 w_1 + \dots + c_n w_n) \\ &= \lambda T(c_1 v_1 + \dots + c_n v_n) \\ &= \lambda Tv. \end{aligned}$$

Therefore, $T: V \rightarrow W$ satisfies additivity and homogeneity.
Therefore, $T \in L(V, W)$.

Finally, we need to prove that T is unique.

Suppose we have $T \in L(V, W)$ and T satisfies $Tu_i = w_i$ for each $i = 1, \dots, n$. $b + c_1, \dots, c_n \in \mathbb{F}$, then the additivity and homogeneity of T gives us:

$$\begin{aligned} T(c_1 u_1 + \dots + c_n u_n) &\stackrel{\text{additivity}}{=} T(c_1 u_1) + \dots + T(c_n u_n) \\ &\stackrel{\text{homogeneity}}{=} c_1 T u_1 + \dots + c_n T u_n \\ &= c_1 w_1 + \dots + c_n w_n \end{aligned}$$

So T is uniquely determined on $\text{span}(u_1, \dots, u_n)$.

But $u_1, \dots, u_n$ is a basis of V , meaning we have $\text{span}(u_1, \dots, u_n) = V$.

So T is uniquely determined on V .

Addition and scalar multiplication on $L(V, W)$

3.6 Definition

Suppose $S, T \in L(V, W)$ and $\lambda \in \mathbb{F}$

- The sum $S+T$ is a linear map defined by $(S+T)(u) = Su + Tu$
- The product λT is a linear map defined by $(\lambda T)(u) = \lambda(Tu)$

3.7 $L(V, W)$ is a vector space

The set $L(V, W)$ is a vector space with respect to the operators defined in Definition 3.6 of Axler.

Proof: Let $R, S, T \in L(V, W)$ and $a, b \in \mathbb{F}$ be arbitrary.

- Commutativity For all $v \in V$, we have

$$\begin{aligned} (S+T)v &= Sv + Tv \\ &= Tv + Sv \\ &= (T+S)v \end{aligned}$$

$$\text{So } S+T = T+S$$

- Associativity For all $v \in V$, we have

$$\begin{aligned} ((R+S)+T)v &= (R+S)v + Tv \\ &= Rv + Sv + Tv \\ &= Rv + (S+T)v \\ &= (R+(S+T))v \end{aligned}$$

$$\text{So } (R+S)+T = R+(S+T)$$

- Additive identity

Let $0 \in L(V, W)$ be the zero vector.

For all $v \in V$, we have

$$\begin{aligned} (T+0)v &= Tv + 0v \\ &= Tv + 0 \\ &= Tv. \end{aligned}$$

$$\text{So } T+0 = T$$

- Additive inverse

Note that we have $-T \in L(V, W)$.

For all $v \in V$, we have

$$\begin{aligned} (T+(-T))v &= Tv + (-T)v \\ &= Tv - Tv \\ &= 0 \\ &= 0v. \end{aligned}$$

$$\text{So } T+(-T) = 0.$$

- Multiplicative identity

For all $v \in V$, we have

$$\begin{aligned} (1T)v &= 1Tv \\ &= Tv \end{aligned}$$

$$\text{So } 1T = T.$$

- Distributive properties

For all $a \in \mathbb{F}$, for all $v \in V$, we have

$$\begin{aligned} (a(S+T))v &= a(Sv + Tv) \\ &= aSv + aTv \\ &= (aS + aT)v \end{aligned}$$

$$\text{So } a(S+T) = aS + aT.$$

Therefore, $L(V, W)$ is a vector space with respect to the defined operations.

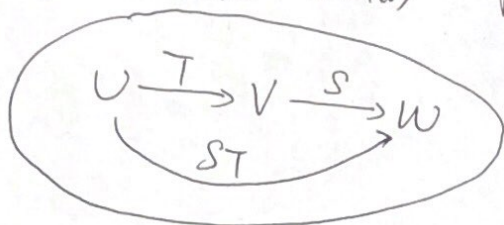
For all $a, b \in \mathbb{F}$, for all $v \in V$, we have

$$\begin{aligned} ((a+b)T)v &= (a+b)Tv \\ &= aTv + bTv \\ &= (aT + bT)v \end{aligned}$$

$$\text{So } (a+b)T = aT + bT.$$

3.8 Definition

If $S \in L(V, W)$, $T \in L(U, V)$, then the product $ST \in L(U, W)$ is defined by $(ST)u = S(Tu)$ for all $u \in U$



3.9 Algebras (properties of products of linear maps)

- Associativity If R, S, T are linear maps such that the product RST makes sense, then $(RS)T = R(ST)$.
- Identity If $T \in L(U, W)$ and $I: V \rightarrow V$ is an identity map, then $TI = T = IT$.
- Distributive properties If $T, T_1, T_2 \in L(U, V)$ and $S, S_1, S_2 \in L(V, W)$, then $(S_1 + S_2)T = S_1T + S_2T$ and $S(T_1 + T_2) = ST_1 + ST_2$.

3.11 Linear maps take 0 to 0

If $T \in L(V, W)$, then $T(0) = 0$.

Proof: Since T is linear, we can use additivity to get

$$\begin{aligned} \text{additivity of } T & \quad T(0) = T(0+0) \\ & \quad \rightarrow T(0) + T(0) \\ & \quad = 2T(0) \end{aligned}$$

Therefore, $T(0) = 0$, as defined.