## July. 16.2019.

3D

22		
326	Invertibility is equivalent to surjectivity and injectivity	
	A linear map T-Vow invertible iff T is injective and surjective.	
	Proot:	
	Let T: V=>W be a linear map.	
	Forward direction? If T is invertible, then T is injective &	
surjective. Suppose T is invertible. Then it's inverse T <sup>-1</sup> exists.		
Suppose there exist uver that sortisfy Tu=Tr.		
Then u=Iu		
=(T-'1)~		
= T-'(Tu)		
- ד <sup>-</sup> יתי)		
	= (T-'T)v	
	= Iv	
	= 1	
	T is injective.	
	Next, we will show that T is surjective.	
	Suppose we have an arbitrary vector well (We will argue	
	for all weW)	

Then we have :



In other words,

SOT=IV

Finally, we will show that S: w-1/ is linear (show Se Liw,v))

• Suppose we have w., wzeW, Then, since T is linear, we have T(Sw.+Sws) = T(Sw.)+T(Sws)

= WITW2

Since Sw. and Sw. are unique elements of V that T maps to w. and w. respectively. it follows that Sw. + Sw. is a unique element of V that T maps to w. + w.

Fur ther more, we have

 $S(w_1+w_2) = S(T(Sw_1+Sw_2))$ = (SoT)(Sw\_1+Sw\_2)

= Iv (Sw. + Swz)

= Switsw.

· Satisfying additivity.

· Honogeneity:

Suppose we have wEW and AGIF, Then, since T is linear. we have TIRSW)= ATISW)

=YM

Since Sw is the unique element of V that T maps to w, it follows that  $\Lambda Sw$  is the unique element of V that T maps to  $\Lambda W$ .

Furthermore, we have

S(~~)= S(T(~~)) = (SoT) (~Sw)

= IU (2Sw)

= 3Sw

satisfying homogeneity

## ... SEL(W,V) ... Tis invertible.

Isomorphic Vector Spaces

3.58 Definition

- · An isomorphism is an invertible linear map.
- Two vector spaces V and W are called isomorphic if there exists an isomorphism T: y-w.

3.59 Dimension chows whether vector spaces are isomorphic. Let V and W be finite-dimensional vector spaces over F. Then V and W are isomorphic iff alm V=dim W. Proof:

⇒ Forward direction:

If V and W are isomorphic, then dim V = dim W.

Suppose V and W are isomorphic, there exists an isomorphism T: V=W. Since T is isomorphism, it is invertible. By 3.56, T is injective and surjective. In other words, we have nullT=foj and range T=W. By the Fundamental Theorem of Linear Maps. We obtain:

dimV= dim null It dim range T

- = dim foit dim W
- = OtdimW
- = dimW.

E Backward direction:

If dim V= dim W. then V and W are isomorphic.

Since V and W are finite-dimensional, by 2.32, there exist a basis V.,..., Vn of V and W.,..., Wn of W. where n=dimV=dimW Define T: V=W by

$$T(C_iV_it...+C_nV_n) = C_iW_i+...+C_nW_n$$

Then T is linear and well-defined, according to the proof of 3.5 Since W.,..., What is a basis of W, it spans W. Since every vector in W can be written uniquely as C.W.t...t CnWh. T is surjectue. Since W.,..., What is a basis of W, it is linearly independent. In other words, if (.,..., Cheff satisfy

C.W. + ... + CnWn=0

then

$$C_{1}=0$$
,...,  $C_{n}=0$   
Suppose  $C_{1}V_{1}+C_{n}V_{n} \in null T$ . Then  
 $T(C_{1}V_{1}+...+C_{n}V_{n})=0$ ,  
or

C.W. + ... + C. W. = 0

Consegnently,

CiVit... + CnVn= OV. + ... + OVn

## =0

... nullTcf0]. Also, since T(0)=0, we have foll null T.
... nullT={0}. By 3.16 Axler, T is injective.
Finally, as T is both injective and surjective.
By3.56, T is an isomorphism.
Note: If n=dimV, then dimV=n=dim F<sup>n</sup>

## And 3.39 says that V is isomorphic to F?

Linear maps thought of as Matrix multiplication.  
3.62 Definition  
Suppose 
$$v \in V$$
 and  $v_1, ..., v_n$  is a basis of  $V$ .  
Then the matrix of a vector  $v$  with respect to this basis  
is the n×1 matrix  
 $M(v) = \begin{pmatrix} C \\ \vdots \\ cn \end{pmatrix}$ 

.

. - -

3.63 Example  
• The matrix of 2-70×+5×° with respect to the standard  
basis 
$$1.x_1X_1^1, X_1^3$$
 of  $P_3(\mathbb{R})$  is  
 $M(2-70×+5x^3) = \binom{3}{2}$ 

The matrix of XEIF" with respect to the standard basis of F" is M((X,..., Xn))= (X,)

Linear maps act like matrix multiplication 3.65 Suppose TEL(V.W) and VEV. Suppose V.,..., Vn is a basis of V and W1,..., Wm is a basis of W. Then  $M(T_v) = M(T)M(v)$ Proof: Since V.,..., Vn is a basis of V, we can write every ve V uniquely as V= C.V. + ... + CnVn for some C.,..., Cn eff. Then we have  $T_v = I(c, v, t, + c_n v_n)$ = T(C, Vilt ... T(Cn Vn) = C.TV. + ... + CnTVn Therefore, as (MIT))., ..., (MIT))., n is a basis of IFM.A M(Tu)= M(C.TV, 1...+ CATVA) = MICiTu, ) + ... + MicaTun) = C.M(TU.) + ... + C.M(TU) by 3.64  $= C_1 (M(T))_{1} + \dots + C_n (M(T_u))_{n}$ = M(T) M(V)by \$.52

3.67	Operators
	and the second second
	Definition

·A linear map T: V->V is called an operator. ·L(V) denotes the set of all operators on V: L(V): L(V,V)

3.69 Injectivity is equivalent to surjectivity in finite dimensions. Suppose U is a finite-dimensional vector space and TELW). Then the following are equivalent. c). Tis invertible. b). T is injective. C). T is surjective. Proof: (a) implies (b). Suppose (a) holds, suppose T to invertible. By 3.56 -> (b) (b) implies (C). Suppose (b) holds, suppose T is injective. By 3.16, null T=fol By 3.22, we have dimrange T=dimV- dum nallT = dim V- dim (9) = dimU By 2C.1 we have range T=V. so T is surjective. which is 1CL (C) implies (a). Suppose (C) holds; suppose T is surjective. Then range T=V By 3.22. we have dim null T= dim V- dim range T = dimV-dimV = 0 = dim fo)

By 2C.1. we have null T= {0} By 3.16, T is injective. So T is both injective and surjective, which is (2).