

## Extra lecture : Chapter 5

### Eigen values, Eigen vectors, and Invariant Subspaces

#### 5A. Invariant subspaces.

##### 5.2 Definition.

Suppose  $T \in \mathcal{L}(V)$ . A subspace  $U$  of  $V$  is called invariant under  $T$  if  $u \in U$  implies  $Tu \in U$ .

##### 5.3 Example

•  $\{0\}$ : if  $u \in \{0\}$ , then  $u=0$ . So we have

$$\begin{aligned} T(u) &= T(0) \\ &= 0 \in \{0\} \end{aligned}$$

So  $\{0\}$  is invariant under  $T$ .

•  $V$ : If  $u \in V$ , then  $Tu \in V$

So  $V$  is invariant under  $T$ .

•  $\text{null } T$ : If  $u \in \text{null } T$ , then  $Tu=0$ . So we have:

$$\begin{aligned} T(Tu) &= T(0) \\ &= 0 \end{aligned}$$

$\therefore Tu \in \text{null } T$ , and so  $\text{null } T$  is invariant under  $T$ .

•  $\text{range } T$ : If  $u \in \text{range } T$ , then  $u = Tv$  for some  $v \in V$ .

So we have:

$$Tu = T(Tv)$$

Since  $Tv \in V$ , we get  $Tu \in \text{range } T$ .

$\therefore T$  is invariant under  $T$ .

## Eigenvalues and eigenvectors

### 5.5 Definition

Suppose  $T \in \mathcal{L}(V)$ , A scalar  $\lambda \in \mathbb{F}$  is called an **eigenvalue** of  $T$  if there exists  $v \in V$  s.t.  $v \neq 0$  and  $Tv = \lambda v$ .

Such a vector  $v \in V$  is called an **eigenvector** of  $T$  corresponding to the eigen value of  $\lambda$

### 5.6 Equivalent conditions to be an eigenvalue.

Suppose  $V$  is finite-dimensional,  $T \in \mathcal{L}(V)$  and  $\lambda \in \mathbb{F}$ .

Then the following are equivalent:

- $\lambda$  is an eigen value of  $T$ .
- $T - \lambda I$  is not injective.
- $T - \lambda I$  is not surjective.
- $T - \lambda I$  is not invertible.

Proof: (a) is equivalent to (b): a implies b, b implies a.

The equation  $Tv = \lambda v$  is equivalent to the equation.

$$(T - \lambda I)v = 0$$

$$Tv = \lambda v \quad \text{iff} \quad Tv - \lambda v = 0$$

$$\text{iff} \quad Tv - \lambda Iv = 0$$

$$\text{iff} \quad (T - \lambda I)v = 0$$

(b), (c), (d) are equivalent to each other

By 3.69, the following are equivalent:

$T - \lambda I$  is not invertible.

$T - \lambda I$  is not injective,  
 $T - \lambda I$  is not surjective.

b implies a.

Conversely,  $\because T - \lambda$  is not injective,  $Tv = \lambda v$ .

So  $\lambda$  is an eigenvalue of  $T$ .

### 5.7 Definition

Suppose  $T \in \mathcal{L}(V)$  and  $\lambda \in \mathbb{F}$  is an eigenvalue of  $T$ . A vector  $v \in V$  is called an eigenvector of  $T$  corresponding to  $\lambda$  if  $v \neq 0$  and  $Tv = \lambda v$ .

### 5.8 Example

Define  $T \in \mathcal{L}(\mathbb{C}^2)$  by

$$T(w, z) = (-z, w)$$

Find the eigenvalues and eigenvectors of  $T$ .

Solution: Let  $\lambda \in \mathbb{F}$  satisfy

$$T(w, z) = \lambda(w, z)$$

Since  $T(w, z) = (-z, w)$ , we obtain

$$\begin{aligned} (-z, w) &= \lambda(w, z) \\ &= (\lambda w, \lambda z) \end{aligned}$$

From  $(-z, w) = (\lambda w, \lambda z)$ , we get a system of equations

$$-z = \lambda w$$

$$w = \lambda z$$

Substitute  $w = \lambda z$  into  $-z = \lambda w$ , we get

$$-z = \lambda w$$

$$= \lambda(\lambda z)$$

$$= \lambda^2 z$$

If  $z=0$ , then  $w=0$ , so  $(w, z) = (0, 0)$ . If  $(w, z)$  is an eigenvector of  $T$ , then  $z \neq 0$

So  $-z = \lambda^2 z$  implies  $-1 = \lambda^2$  or

$$\lambda = i, \lambda = -i$$

So  $i, -i$  are our eigenvalues of  $T$ .

$$\lambda = i$$

$T(w, z) = i(w, z)$  implies

$$(-z, w) = (iw, iz)$$

So

$$-z = iw$$

$$w = iz$$

$\therefore (w, z) = (w, -iw)$  is an eigenvector of  $T$  for all  $w \in \mathbb{C}$ .

$$\lambda = -i$$

$$T(w, z) = -i(w, z)$$

implies  $(-z, w) = (-iw, -iz)$

So  $-z = -iw$ ,  $w = -iz$

$\therefore (w, z) = (w, iw)$  is an eigenvector of  $T$  corresponding to  $\lambda = -i$ , for all  $w \in \mathbb{C}$ .

Alternate method:  $F(w)$

$$M(T) = M(T, \text{standard basis of } \mathbb{C}^2, \text{standard basis of } \mathbb{C}^2)$$

Find  $a, b, c, d \in \mathbb{F}$  that satisfy:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} w \\ z \end{bmatrix} = \begin{bmatrix} -z \\ w \end{bmatrix}$$

$$\begin{bmatrix} aw + bz \\ cw + dz \end{bmatrix} = \begin{bmatrix} -z \\ w \end{bmatrix}$$

$$a=0 \quad b=-1$$

$$c=1 \quad d=0$$

$$M(T - \lambda I) = M(T) - \lambda M(I)$$

$$= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix}$$

$$\det(M(T - \lambda I)) = 0$$

$$\det \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix} = 0$$

$$\lambda^2 + 1 = 0 \Rightarrow \lambda = i \text{ or } -i$$

$$M(T - iI)(w, z) = (0, 0)$$

$$\begin{pmatrix} -i & -1 \\ 1 & i \end{pmatrix} \begin{pmatrix} w \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$iw - z = 0$$

$$w + iz = 0$$

$$-z = iw$$

$$w = iz$$

$$(w, z) = (w, iw)$$

$$M(T - iI)(w, z) = (0, 0)$$

$$\begin{pmatrix} i & -1 \\ 1 & i \end{pmatrix} \begin{pmatrix} w \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\therefore iw - z = 0$$

$$W + iz = 0$$

$$z = iW$$

$$W = -iz$$

$$(W, z) = (W, iW)$$

5.10 Linear independent eigenvectors.

Let  $T \in \mathcal{L}(V)$ . Suppose  $\lambda_1, \dots, \lambda_m$  are distinct eigenvalues of  $T$  and  $v_1, \dots, v_m$  are the corresponding eigenvectors. Then  $v_1, \dots, v_m$  is linearly independent.

Proof:

Suppose by contradiction that  $v_1, \dots, v_m$  is linearly dependent. By the linear dependence lemma (2.21), there exists the smallest positive integer  $k \in \{1, \dots, m\}$  s.t.

$$v_k \in \text{span}(v_1, \dots, v_{k-1})$$

So there exist  $a_1, \dots, a_{k-1} \in \mathbb{F}$  s.t.

$$v_k = a_1 v_1 + \dots + a_{k-1} v_{k-1}$$

So we have

$$\begin{aligned} T v_k &= T(a_1 v_1 + \dots + a_{k-1} v_{k-1}) \\ &= a_1 T v_1 + \dots + a_{k-1} T v_{k-1} \\ &= a_1 (\lambda_1 v_1) + \dots + a_{k-1} (\lambda_{k-1} v_{k-1}) \\ &= a_1 \lambda_1 v_1 + \dots + a_{k-1} \lambda_{k-1} v_{k-1} \end{aligned}$$

Multiply by  $\lambda_k$  both sides of  $v_k = a_1 v_1 + \dots + a_{k-1} v_{k-1}$  to write

$$T v_k = \lambda_k v_k = a_1 \lambda_k v_1 + \dots + a_{k-1} \lambda_k v_{k-1}$$

So we get

$$0 = T v_k - T v_k$$

$$\begin{aligned}
 &= (a_1 \lambda_1 v_1 + \dots + a_{k-1} \lambda_{k-1} v_{k-1}) - (a_1 \lambda_k v_1 + \dots + a_{k-1} \lambda_k v_{k-1}) \\
 &= a_1 (\lambda_1 - \lambda_k) v_1 + \dots + a_{k-1} (\lambda_{k-1} - \lambda_k) v_{k-1}
 \end{aligned}$$

Since  $k$  is the smallest positive integer for which  $v_k \in \text{span}(v_1, \dots, v_{k-1})$

It follows that  $v_1, \dots, v_{k-1}$  is linearly independent.

$$a_1 (\lambda_1 - \lambda_k) = 0, \dots, a_{k-1} (\lambda_{k-1} - \lambda_k) = 0$$

But  $\lambda_1, \dots, \lambda_m$  are distinct so  $a_1 = 0, \dots, a_{k-1} = 0$

So each  $v_k$  is zero, which contradicts our hypothesis that  $v_k$  is an eigenvector.

So  $v_1, \dots, v_m$  is linearly independent.