

Objective { review: Maximum Principle (MP)
applications of MP
Energy method.

(I) Review.

$$\Delta u = 0 \text{ in } D \text{ (bounded)}$$

$$\text{weak MP} \begin{cases} \rightarrow \max_D(u) \leq \max_{\partial D}(u) \\ \rightarrow \min_D(u) \geq \min_{\partial D}(u) \end{cases}$$

$$\text{strong MP} \rightarrow \text{"=" implies } u(x,y) = c \text{ in } D$$

(II): uniqueness & stability of $\Delta u = F$

Thm: Suppose D is bounded.

$$\begin{cases} \Delta u = F & \text{in } D \\ u = g & \text{on } \partial D \end{cases}$$

Then, it has at most one solution in $C^2(D) \cap C(\bar{D})$

Proof: Assume there are two solutions u_1 & u_2

$$\begin{cases} \Delta u_1 = F, \text{ in } D \\ u_1 = g, \text{ on } \partial D \end{cases} \quad \begin{cases} \Delta u_2 = F, \text{ in } D \\ u_2 = g, \text{ on } \partial D \end{cases}$$

$$\text{Let } v = u_1 - u_2$$

$$\begin{cases} \Delta v = 0 & \text{in } D \\ v = 0 & \text{on } \partial D \end{cases}$$

By MP:

$$v(x,y) \leq \max_D(v) \leq \max_{\partial D}(v) = 0$$

$$v(x,y) \geq \min_D(v) \geq \min_{\partial D}(v) = 0$$

$$\Rightarrow v = 0 \text{ in } D$$

$$\Rightarrow u_1 = u_2$$

RK: boundedness is essential.

counterexample:

$$\begin{cases} \Delta u = 0, \text{ in } D \\ u = 0, \text{ on } \partial D \end{cases} \quad [x^2 + y^2 = 1]$$

$$u_1 = 0, \quad u_2 = -\frac{1}{2\pi} \ln(r)$$

$$u_3 = \ln(x^2 + y^2)$$

Thm: (stability) [Thm 7.13]

suppose D is bounded.

$$\begin{cases} \Delta u_1 = F & \text{in } D \\ u_1 = g_1 & \text{on } \partial D \end{cases}$$

$$\begin{cases} \Delta u_2 = F & \text{in } D \\ u_2 = g_2 & \text{on } \partial D \end{cases}$$

$$\text{then: } \max_D |u_1 - u_2| \leq \max_{\partial D} |g_1 - g_2|$$

Proof: [Exercise]

RK: MP \rightarrow Dirichlet problem ✓

\hookrightarrow Neumann problem

Robin problem X

(III) Energy method

(Green's identities)

recall: Gauss's formula.

$$\int_D \nabla \cdot \vec{F} \, dx dy = \int_{\partial D} \vec{F} \cdot \vec{n} \, ds \quad \begin{matrix} \text{1-D} \\ \int_a^b f_x \, dx \\ = f(b) - f(a) \end{matrix}$$

$$\vec{F} = \nabla u$$

$$(i) \int_D \Delta u \, dx dy = \int_{\partial D} \partial_n u \, ds \quad \begin{matrix} \int_a^b u_{xx} \, dx \\ = u_x(b) - u_x(a) \end{matrix}$$

$$(ii) \int_D \nabla u \cdot \nabla v \, dx dy$$

$$= \int_{\partial D} v \cdot \partial_n v \, ds$$

$$- \int_D (\nabla u) \cdot (\nabla v) \, dx dy = \int_a^b v u_{xx} \, dx = u_x v \Big|_a^b - \int_a^b u_x v_x \, dx$$

Green's identities (i) (ii)

RK: By $v=1$ in (i)

$$(ii) \Rightarrow (i)$$

Thm: (uniqueness of $\Delta u = F$)

Let D be bounded.

$$(a) \begin{cases} \Delta u = F, \text{ in } D \\ u = g \text{ on } \partial D \end{cases}$$

it has at most one solution

$$(b) \begin{cases} \Delta u = F & \text{in } D \\ \partial_n u = g, \text{ on } \partial D \end{cases}$$

if u is a solution, then any solution is of the form

$$w = u + C, \quad C \in \mathbb{R}$$

$$(c) \begin{cases} \Delta u = F & \text{in } D \\ u + \alpha \partial_n u = g, \text{ on } \partial D \end{cases}$$

If $\alpha \geq 0$, then it has at most one solution

Proof: Let u_1 and u_2 be two solutions.

$$v = u_1 - u_2$$

$$\xRightarrow{\text{PDE}} \Delta v = \Delta u_1 - \Delta u_2 = F - F = 0$$

$$\int_D \nabla v \cdot \nabla v \, dx dy = 0$$

$$\xRightarrow{\text{Green's}} \int_{\partial D} v \cdot \partial_n v \, ds - \int_D (\nabla v) \cdot (\nabla v) \, dx dy = 0$$

$$\Rightarrow (*) \int_D |\nabla v|^2 \, dx dy = \int_{\partial D} v \cdot \partial_n v \, ds$$

$$\text{For (a): } v = u_1 - u_2 = g - g = 0 \text{ on } \partial D$$

$$\text{By } (*): \int_D |\nabla v|^2 \, dx dy = 0$$

$$\nabla v = \vec{0} \Rightarrow v = C \text{ in } D$$

$$\text{since } v = 0 \text{ on } \partial D$$

$$v(x,y) = 0 \text{ in } D$$

For (b):

$$\partial_n v = \partial_n u_1 - \partial_n u_2 = g - g = 0, \text{ on } \partial D$$

$$\text{By } (*) \Rightarrow \int_D |\nabla v|^2 \, dx dy = 0$$

$$\Rightarrow \nabla v = \vec{0}$$

$$\Rightarrow v = C \text{ in } D$$

$$\Rightarrow u_1 - u_2 = C$$

For (c):

$$v + \alpha \partial_n v = u_1 + \alpha \partial_n u_1 - (u_2 + \alpha \partial_n u_2) = g - g = 0, \text{ on } \partial D$$

$$\Rightarrow v = -\alpha \partial_n v \text{ on } \partial D \leftarrow$$

$$\text{By } (*): \int_D |\nabla v|^2 \, dx dy = \int_{\partial D} v \partial_n v \, ds$$

$$= - \int_{\partial D} \alpha (\partial_n v)^2 \, ds \leq 0$$

$$\Rightarrow \begin{cases} \nabla v = \vec{0}, \text{ in } D \\ \partial_n v = 0, \text{ on } \partial D \end{cases}$$

$$\Rightarrow \begin{cases} v = C & \text{in } D \\ v = -\alpha \partial_n v = 0, \text{ on } \partial D \end{cases}$$

$$\Rightarrow v = 0 \text{ in } D$$

$$\Leftrightarrow u_1 = u_2$$

Thm: stability of heat Equation

$$\text{Let } u_t = k \Delta u, \quad (D, \partial D, \partial D)$$

$$\text{in } Q_T = D \times [0, T] \quad (x, y, z)$$

$$= \{ (x, y, z) \in D, t \in [0, T] \}$$

$$\partial Q_T = \{ D \times \{0\} \} \cup \{ \partial D \times [0, T] \}$$

for 1D space

$$x \in [0, L]$$

$$t \in [0, T]$$

$$Q_T = [0, L] \times [0, T]$$

$$= \{ x \in [0, L], t \in [0, T] \}$$

Thm: maximum principle

$$\text{If } u_t = k \Delta u, \text{ in } Q_T$$

$$\text{then } \max_{Q_T} u \leq \max_{\partial Q_T} u$$

Proof see textbook.

Thm: stability of heat Eq.

$$\text{Let } \begin{cases} (u_1)_t = k \Delta u_1 + F \\ u_1 = g_1 & \text{on } \partial D \times [0, T] \\ u_1 = f_1 & \text{at } t=0 \end{cases}$$

$$\begin{cases} (u_2)_t = k \Delta u_2 + F \\ u_2 = g_2 & \text{on } \partial D \times [0, T] \\ u_2 = f_2 & \text{at } t=0 \end{cases}$$

Then:

$$\max_{Q_T} |u_1 - u_2| \leq \max_D |f_1 - f_2| + \max_{\partial D \times [0, T]} |g_1 - g_2|$$

Proof: $v = u_1 - u_2$ & use MP for heat Eq.

RK: it implies uniqueness

$$\text{by } f_1 = f_2, \quad g_1 = g_2$$

To do list.

HW 10.

Next, §7.7